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EDUCATION

Degree/Certificate	${\bf Institute/Board}$	CGPA/Percentage	Year
M.Tech. (RMS)	Indian Institute of Technology, Jodhpur	8.02 (Current)	2023-Present
B.Tech. (ME)	Guru Nanak Dev Engineering College, Ludhiana	7.58	2016-2020
Senior Secondary	PSEB Board	90.00%	2015
Secondary	PSEB Board	91.84%	2013

PROJECTS

- M.Tech Thesis: Development of Multi-Agent Control for Surface and Underwater Vehicles May 2024 Github YouTube
 - This project focuses on developing a control and decision-making framework for autonomous amphibious vehicles, integrating multi-agent coordination for task allocation, role switching, and obstacle avoidance to enhance mission efficiency.
 - Tools & Technologies: Matlab, Solidworks, ROS, Arduino, Sensor Integration, Python, C++
- ROS2-based Bin-Picking System: Integrating RGB and Point Cloud Data for Object Detection, Pose Estimation, and Grasp Planning

 Github YouTube
 - This project presents an integrated robotic bin- picking system that uses advanced computer vision techniques and ROS2 for real-time object detection, pose estimation, and grasp planning.
 - Skills: Motion Planning, ROS2, CV, Camera Calibration, Kinematics and Dynamics
 - Tools:YOLO,GPD,PCL,Gazebo,RViz

• Leader-Follower Formation Control of Non-Holonomic Mobile Robots

Github YouTube

- Modeled leader-follower formation of differential drive WMRs, designed Lyapunov-based controllers, and simulated formations.
- Skills: Robotic Kinematics, Formation Control, Lyapunov Stability, Matlab Simulation

• 2D Admittance Control: From Concept to Hardware Implementation

Github YouTube

- Designed and implemented a complete 2D admittance control system, spanning theoretical modeling, simulation in Gazebo, and hardware integration.
- Skills: Robotic Kinematics, Formation Control, Lyapunov Stability, Matlab Simulation

• Multi-Vehicle Simulation Environment for AUVs and ASVs

Github YouTube

an integrated simulation platform enabling simultaneous testing and interaction of Autonomous Underwater Vehicles (AUVs) and Autonomous Surface Vehicles (ASVs) to enhance multi-agent coordination. Skills: Robotic Kinematics, Formation Control, Lyapunov Stability, Matlab Simulation

• Turtlebot Control Using Motor Cortex Signals (BCI Hackathon)

Github YouTube

Led a BCI hackathon project in which a Turtlebot was controlled using motor cortex signals acquired via an OpenBCI device, demonstrating novel integration of brain signals and robotic control. Skills: Robotic Kinematics, Formation Control, Lyapunov Stability, Matlab Simulation

• Voice-Controlled Smart Home Automation System with Sensor Integration

Github YouTube

- Developed a voice-controlled smart home system using Arduino Nano 33 BLE Sense, integrating environmental sensors and machine learning models.
- Skills: Hardware-Software Integration, Voice Recognition, ML Integration, Sensor Integration, Embedded System Design

• Designing a Lightweight Neural Network for Crop Disease Detection

Github YouTube

- In this project, we focus on designing a lightweight Neural Network model capable of running on edge devices to assist in detecting crop diseases on-site.
- **Skills**:PyTorch,CNN,MobileNet,Python

KEY COURSES TAKEN

• Introduction to Robotics, Mobile Robots, Artificial Intelligence, Computer Vision, Autonomous Systems, Embedded System Design, Fundamentals of Machine Learning, Robot Operating System, Introduction to Medical Robotics

TECHNICAL SKILLS

- **Programming:** C,C++,Python,Matlab, Shell Scripting
- Tools & OS: Git, Jupyter Notebook, Google Colab, Linux, Windows, ROS, Docker, Solidworks
- Libraries/Frameworks: Pandas, Numpy, scikit-learn, Open-CV, Matplotlib, TensorFlow, PyTorch
- Sensors Hardware: IMU, Depth Camera, Lidar, Load Cell, Common Motors, Micro- controllers, Basic Motor Control

CERTIFICATIONS

- MathWorks Certification on Matlab Fundamentals, Linear Algebra, ODE
- SWCAD1.0: SOLIDWORKS CAD Fundamentals
- CS50 Introduction to Programming Using Python Certification
- LinkedIn : Additive Manufacturing Optimizing 3D Prints
- LinkedIn: Numpy, Matplotlib, Pandas, Bash Scripting