Cooperative Bug Isolation

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Build and Monitor









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The Goal: Analyze Reality



- Where is the black box for software?
 - Historically, some efforts, but spotty
 - Now it's really happening: crash reporting systems
- Actual runs are a vast resource
 - Number of real runs >> number of testing runs
 - And the real-world executions are most important
- This talk: post-deployment bug hunting

Engineering Constraints



- Big systems
 - Millions of lines of code
 - Mix of controlled, uncontrolled code
 - Threads
- · Remote monitoring
 - Limited disk & network bandwidth
- · Incomplete information
 - Limit performance overhead
 - Privacy and security

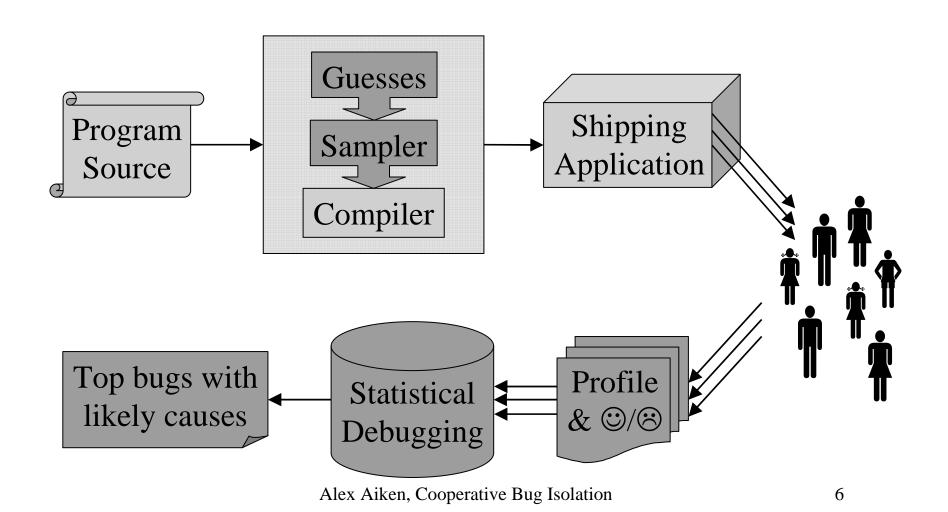
The Approach



- 1. Guess "potentially interesting" behaviors
 - Compile-time instrumentation
- 2. Collect sparse, fair subset of these behaviors
 - Generic sampling transformation
 - Feedback profile + outcome label
- 3. Find behavioral changes in good/bad runs
 - Statistical debugging

Bug Isolation Architecture









We assume any interesting behavior is expressible as a predicate P on program state at a particular program point.

Observation of behavior = observing P

Branches Are Interesting



```
if (p) ...
```

else ...

Branch Predicate Counts



```
++branch_17[!!p];
if (p) ...
else ...
```

- Predicates are folded down into counts
- · C idiom: !!p ensures subscript is 0 or 1





```
n = fprintf(...);
```



Returned Value Predicate Counts

• Track predicates: n < 0, n == 0, n > 0

Scalar Relationships



```
int i, j, k;
...
i = ...;
```

The relationship of \pm to other integer-valued variables in scope after the assignment is potentially interesting . . .



Pair Relationship Predicate Counts

Test i against all other constants & variables in scope.

Summarization and Reporting



- Instrument the program with predicates
 - We have a variety of instrumentation schemes
- Feedback report is:
 - Vector of predicate counters
 - Success/failure outcome label

P1	P2	Р3	P4	P5	•	• •
0	0	4	0	1 .	•	•

- · No time dimension, for good or ill
- Still quite a lot to measure
 - What about performance?

Sampling



- · Decide to examine or ignore each site...
 - Randomly
 - Independently
 - Dynamically
- Why?
 - Fairness
 - We need accurate picture of rare events.

Problematic Approaches



- Sample every kth predicate
 - Violates independence
- Use clock interrupt
 - Not enough context
 - Not very portable
- Toss a coin at each instrumentation site
 - Too slow

Amortized Coin Tossing



- Observation
 - Samples are rare, say 1/100
 - Amortize cost by predicting time until next sample
- Randomized global countdown
 - Small countdown ⇒ upcoming sample
- Selected from geometric distribution
 - Inter-arrival time for biased coin toss
 - How many tails before next head?

Geometric Distribution



$$next = \left\lfloor \frac{\log(rand(0,1))}{\log(1 - \frac{1}{D})} \right\rfloor + 1$$

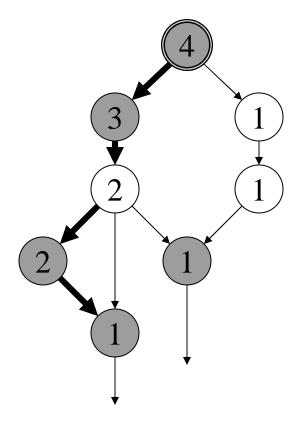
D = mean of distribution

= expected sample density

Weighing Acyclic Regions



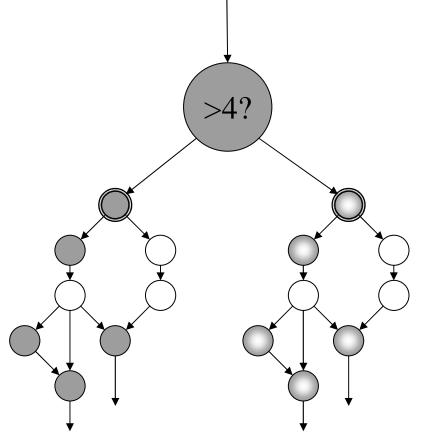
- An acyclic region has:
- · a finite number of paths
- a finite max number of instrumentation sites executed



Weighing Acyclic Regions



- Clone acyclic regions
 - "Fast" variant
 - "Slow" variant
- Choose at run time based on countdown to next sample



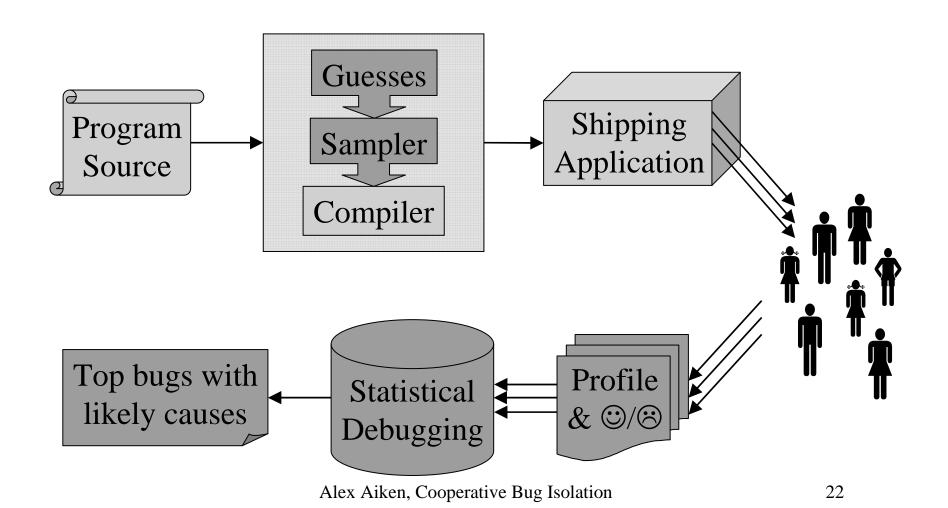
Summary: Feedback Reports



- Subset of dynamic behavior
 - Counts of true/false predicate observations
 - Sampling gives low overhead
 - · Often unmeasurable at 1/100
 - Success/failure label for entire run
- Certain of what we did observe
 - But may have missed some events
- Given enough runs, samples ≈ reality
 - Common events seen most often
 - Rare events seen at proportionate rate







Find Causes of Bugs



- We gather information about many predicates.
 - 298,482 for BC
- Most of these are not predictive of anything.
- How do we find the useful predicates?





How likely is failure when P is observed true?

F(P) = # failing runs where P observed true S(P) = # successful runs where P observed true

Failure(P) =
$$\frac{F(P)}{F(P) + S(P)}$$

Not Enough . . .



```
if (f == NULL) {
    x = 0;
    *f;
}
Failure(f == NULL) = 1.0

Failure(x == 0) = 1.0

*f;
```

- Predicate x == 0 is an innocent bystander
 - Program is already doomed

Context



What is the background chance of failure, regardless of P's value?

F(P observed) = # failing runs observing P S(P observed) = # successful runs observing P

Context(P) =
$$\frac{F(P \text{ observed})}{F(P \text{ observed}) + S(P \text{ observed})}$$

A Useful Measure



Does the predicate being true increase the chance of failure over the background rate?

Increase(P) = Failure(P) - Context(P)

A form of likelihood ratio testing . . .



Increase() Works . . .

```
if (f == NULL) {
  x = 0;
  *f;
}
```

$$Increase(f == NULL) = 1.0$$

$$Increase(x == 0) = 0.0$$

A First Algorithm



- 1. Discard predicates having Increase(P) \leq 0
 - E.g. dead, invariant, bystander predicates
 - Exact value is sensitive to small F(P)
 - Use lower bound of 95% confidence interval

- 2. Sort remaining predicates by Increase(P)
 - Again, use 95% lower bound
 - Likely causes with determinacy metrics



Isolating a Single Bug in BC

```
void more_arrays ()
{
    ...
    /* Copy the old arrays. */
    for (indx = 1; indx < old_count; indx
        arrays[indx] = old_ary[indx];
    /* Initialize the new elements. */
    for (; indx < v_count; indx++)
        arrays[indx] = NULL;
    ...
}
#1: indx > scale
#2: indx > use_math
#3: indx > opterr
#4: indx > next_func
#5: indx > i_base
```

It Works!



Well... at least for a program with 1 bug.

- But
 - Need to deal with multiple, unknown bugs.
 - Redundancy in the predicate list is a major problem.

Using the Information



- Multiple predicate metrics are useful
 - Increase(P), Failure(P), F(P), S(P)

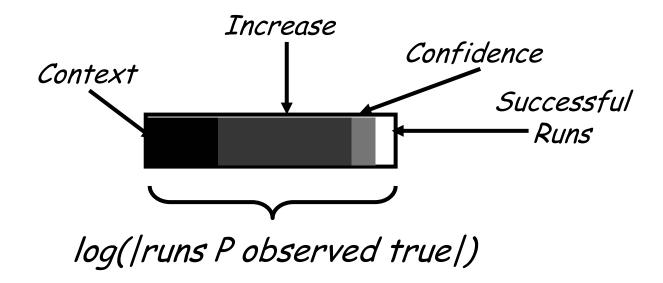
$$ext(P) = .25$$



$$F(P) + S(P) = 349$$

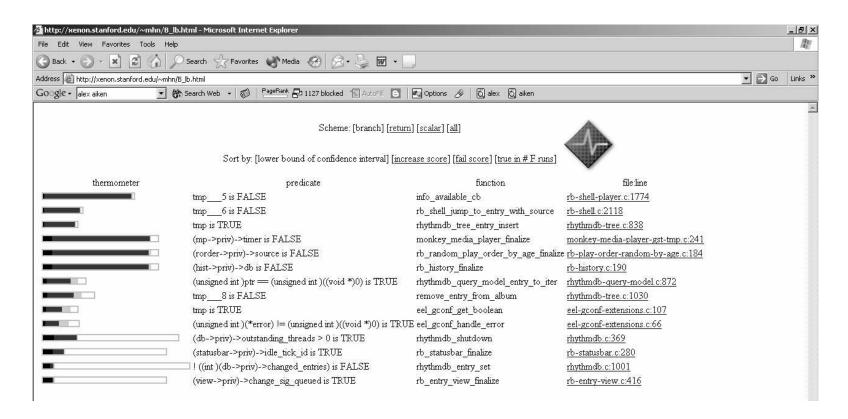


The Bug Thermometer









Multiple Bugs: The Goal



Isolate the best predictor for each bug, with no prior knowledge of the number of bugs.

Multiple Bugs: Some Issues



- · A bug may have many redundant predictors
 - Only need one
 - But would like to know correlated predictors
- Bugs occur on vastly different scales
 - Predictors for common bugs may dominate, hiding predictors of less common problems

An Idea



- Simulate the way humans fix bugs
- Find the first (most important) bug
- Fix it, and repeat

An Algorithm



Repeat the following:

- 1. Compute Increase(), Context(), etc. for all preds.
- 2. Rank the predicates
- 3. Add the top-ranked predicate P to the result list
- 4. Remove P & discard all runs where P is true
 - Simulates fixing the bug corresponding to P
 - Discard reduces rank of correlated predicates



Bad Idea #1: Ranking by Increase(P)

Thermometer	Context	Increase	S	F
	0.065	0.935 ± 0.019	0	23
	0.065	0.935 ± 0.020	0	10
	0.071	0.929 ± 0.020	0	18
	0.073	0.927 ± 0.020	0	10
	0.071	0.929 ± 0.028	0	19
	0.075	0.925 ± 0.022	0	14
	0.076	0.924 ± 0.022	0	12
	0.077	0.923 ± 0.023	0	10

High Increase() but very few failing runs!

These are all sub-bug predictors: they cover a special case of a more general problem.

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Bad Idea #2: Ranking by Fail(P)

Thermometer	Context	Increase	S	F
	0.176	0.007 ± 0.012	22554	5045
	0.176	0.007 ± 0.012	22566	5045
	0.176	0.007 ± 0.012	22571	5045
	0.176	0.007 ± 0.013	18894	4251
	0.176	0.007 ± 0.013	18885	4240
	0.176	0.008 ± 0.013	17757	4007
	0.177	0.008 ± 0.014	16453	3731
	0.176	0.261 ± 0.023	4800	3716

Many failing runs but low Increase()!

Tend to be super-bug predictors: predicates that cover several different bugs rather poorly.

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A Helpful Analogy



- In the language of information retrieval
 - Increase(P) has high precision, low recall
 - Fail(P) has high recall, low precision
- Standard solution:
 - Take the harmonic mean of both
 - Rewards high scores in both dimensions



Ranking by the Harmonic Mean

Thermometer	Context	Increase	S	F
	0.176	0.824 ± 0.009	0	1585
	0.176	0.824 ± 0.009	0	1584
	0.176	0.824 ± 0.009	0	1580
	0.176	0.824 ± 0.009	0	1577
	0.176	0.824 ± 0.009	0	1576
	0.176	0.824 ± 0.009	0	1573
	0.116	0.883 ± 0.012	1	774
	0.116	0.883 ± 0.012	1	776

It works!





Initial	Effective	Predicate
		i < 0 maxlen > 1900
		o + s > buf size is TRUE

- Three predicates selected from 156,476
- · Each predicate predicts a distinct crashing bug
- ·We found the bugs quickly using these predicates



Experimental Results: Rhythmbox

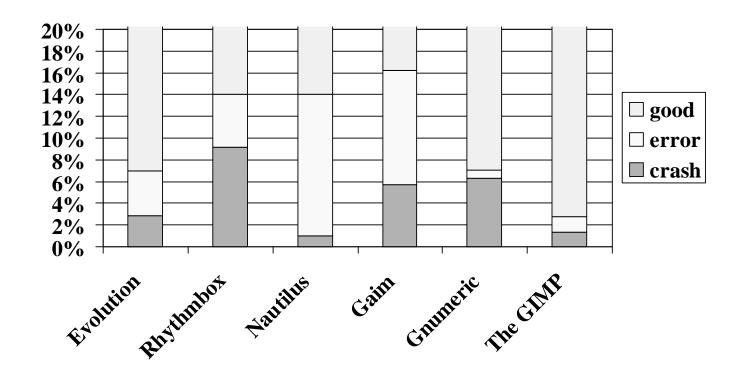
Initial	Effective	Predicate
		<pre>tmp is FALSE (mp->priv)->timer is FALSE (view->priv)->change_sig_queued is TRUE (hist->priv)->db is TRUE rb_playlist_manager_signals[0] > 269 (db->priv)->thread_reaper_id >= 12 entry == entry fn == fn klass > klass genre < artist vol <= (float)0 is TRUE (player->priv)->handling_error is TRUE (statusbar->priv)->library_busy is TRUE shell < shell len < 270</pre>

- ·15 predicates from 857,384
- Also isolated crashing bugs . . .

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Public Deployment in Progress





Lessons Learned



- A lot can be learned from actual executions
 - Users are executing them anyway
 - We should capture some of that information
- · Crash reporting is a step in the right direction
 - But doesn't characterize successful runs
 - Stack is useful for only about 50% of bugs
- Bug finding is just one possible application
 - Understanding usage patterns
 - Understanding performance in different environments

Related Work



- · Gamma
 - Georgia Tech
- Daikon
 - MIT/U. Washington
- · Diduce
 - Stanford

The Cooperative Bug Isolation Project http://www.cs.wisc.edu/cbi/

