ASSIGNMENT 4

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Write code and connections in wokwi for ultrasonic sensor. Whenever the distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

```
code:
#include <WiFi.h>
#include < PubSubClient.h>
WiFiClient wifClient;
String data3;
#defne ORG "x0fxss"
#defne DEVICE_TYPE "Noder"
#defne DEVICE_ID "1234"
#defne TOKEN "987654321"
#defne speed 0.034
#defne led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; char
publishTopic[] = "iot-2/evt/shanmugam_assignment4/fmt/json"; char topic[] =
"iot-2/cmd/home/fmt/String"; char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifClient);
const int trigpin=5;
const int echopin=18;
String command;
```

```
String data="";
long duration;
foat dist;
void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifConnect();
  mqttConnect();
}
void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led, isNearby);
  publishData();
  delay(500);
  if (!client.loop()) {
     mqttConnect();
  }
}
void wifConnect() {
  Serial.print("Connecting to "); Serial.print("Wif");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED)
     { delay(500);
    Serial.print(".");
  }
```

```
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP()); }
void mqttConnect() {
  if (!client.connected()) {
     Serial.print("Reconnecting MQTT client to "); Serial.println(server); while
     (!client.connect(clientId, authMethod, token)) {
        Serial.print(".");
        delay(500);
     }
     initManagedDevice();
     Serial.println();
  }
}
void initManagedDevice() {
  if (client.subscribe(topic)) {
     // Serial.println(client.subscribe(topic));
     Serial.println("IBM subscribe to cmd OK");
  } else {
     Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseln(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){
     String payload = "{\"Alert Distance\":";
     payload += dist;
     payload += "}";
```

```
Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str()))
     { Serial.println("Publish OK");
  }
}
  if(dist>100){
  String payload = "{\"Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
   if(client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish OK");
  }else {
     Serial.println("Publish FAILED");
  }
}
}
```

OUTPUT:- i) When distance greater than 100 cm



