Lab 1 实验报告

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1、功能实现

实验要求: 实现模型问题三种迭代方法求解, 并对比不同初始估计的影响。

代码结构:

main1.m 主程序脚本-复现书上配图[调用 iteration] main2.m 主程序脚本-初始估计研究[调用 iteration] iteration.m 迭代方法实现

2、算法简述

对模型问题

$$-v'' + \sigma v = f$$
$$v(0) = v(1) = 0$$

离散后,假设步长 h,格点处 v 与 f 为 v_i , f_i ,且 $v_0 = v_n = 0$ 。

权重 ω 的 Jacobi 迭代算法为(v 上标 k 表示第 k 次迭代后)

$$v_i^{j+1} = (1 - \omega)v_i^j + \omega \frac{v_{i-1}^j + v_{i+1}^j - h^2 f_i}{2 + \sigma h^2}$$

取定权重为 2/3。

Gauss-Seidel 迭代为

$$v_i^{j+1} = \frac{v_{i-1}^{j+1} + v_{i+1}^j - h^2 f_i}{2 + \sigma h^2}$$

实际实现通过按下标从小到大进行更新即可。

红黑 Gauss-Seidel 迭代分为

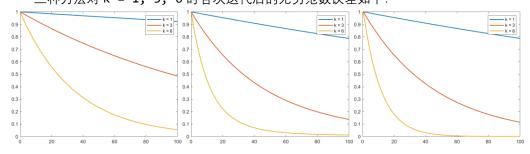
$$\begin{aligned} v_{2i}^{j+1} &= \frac{v_{2i-1}^{j} + v_{2i+1}^{j} - h^{2} f_{2i}}{2 + \sigma h^{2}} \\ v_{2i+1}^{j+1} &= \frac{v_{2i}^{j+1} + v_{2i+2}^{j+1} - h^{2} f_{2i+1}}{2 + \sigma h^{2}} \end{aligned}$$

两步。

考虑 $f=\sigma=0$ 的问题,精确解为v=0,波数为 k 的初始估计是指 $v_0(x)=\sin k\pi x$ 。取 网格步长 h = 0.015625。

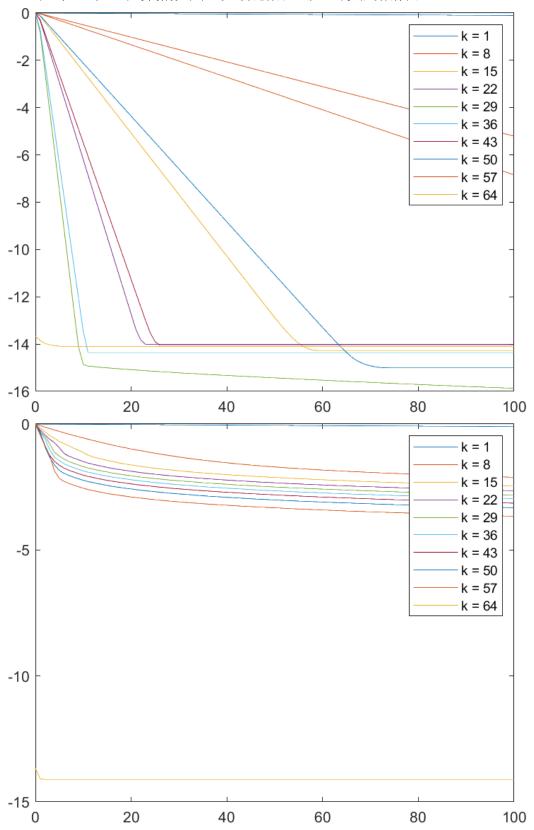
3、结果展示

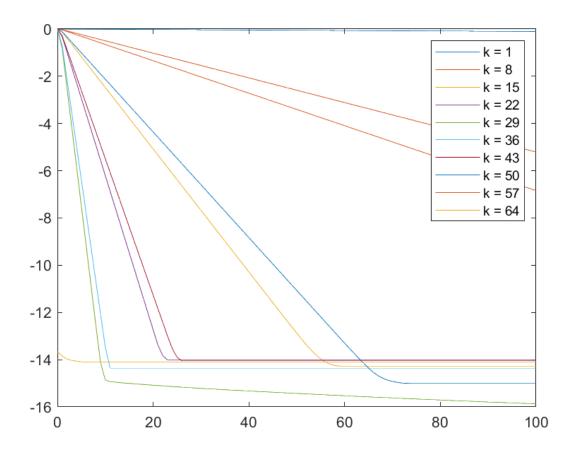
三种方法对 k = 1, 3, 6 时各次迭代后的无穷范数误差如下:



此结果与书中图 2.3 一致。

令 k 在 1 到 64 中等间隔变化,对无穷范数误差以 10 为底对数作图:





4、讨论

从复现图 2.3 的结果可以直观看出,三种方法的收敛速率逐渐加快。但在 k 增大时可以看出,GS 迭代由于每次更新都会累计 N 次误差,很快就达到了精度上限 1e-4,而加权 Jacobi 迭代和红黑 GS 迭代则能接近机器精度。由于红黑 GS 迭代收敛更快,且原地迭代不需要额外的空间,一般来说是更好的选择。

附录-代码

```
x = 0:1/64:1;
f = 0 * x;
res = 0 * x;
sigma = 0;
steps = 100;
method = "weighted-Jacobi";
omega = 2/3;
k = 1;
v0 = sin(k * x * pi);
loss1 = iteration(v0, f, sigma, steps, method, res, omega);
k = 3;
v0 = sin(k * x * pi);
```

```
loss2 = iteration(v0, f, sigma, steps, method, res, omega);
k = 6;
v0 = sin(k * x * pi);
loss3 = iteration(v0, f, sigma, steps, method, res, omega);
figure;
plot(0:steps, loss1, 0:steps, loss2, 0:steps, loss3, "linewidth", 1.5);
legend("k = 1", "k = 3", "k = 6");
method = "Gauss-Seidel";
omega = 2/3;
k = 1;
v0 = sin(k * x * pi);
loss1 = iteration(v0, f, sigma, steps, method, res, omega);
k = 3;
v0 = sin(k * x * pi);
loss2 = iteration(v0, f, sigma, steps, method, res, omega);
k = 6;
v0 = sin(k * x * pi);
loss3 = iteration(v0, f, sigma, steps, method, res, omega);
figure;
plot(0:steps, loss1, 0:steps, loss2, 0:steps, loss3, "linewidth", 1.5);
legend("k = 1", "k = 3", "k = 6");
method = "red-black";
omega = 2/3;
k = 1;
v0 = sin(k * x * pi);
loss1 = iteration(v0, f, sigma, steps, method, res, omega);
k = 3;
v0 = sin(k * x * pi);
loss2 = iteration(v0, f, sigma, steps, method, res, omega);
k = 6;
v0 = sin(k * x * pi);
loss3 = iteration(v0, f, sigma, steps, method, res, omega);
figure;
plot(0:steps, loss1, 0:steps, loss2, 0:steps, loss3, "linewidth", 1.5);
legend("k = 1", "k = 3", "k = 6");
x = 0:1/64:1;
f = 0 * x;
res = 0 * x;
sigma = 0;
steps = 100;
method = "weighted-Jacobi";
```

```
omega = 2/3;
figure;
for k = 1:7:64
   v0 = sin(k * x * pi);
   loss = iteration(v0, f, sigma, steps, method, res, omega);
   plot(0:steps, log(loss) / log(10), 'DisplayName', "k = " + num2str(k));
   hold on;
end
legend;
hold off;
method = "Gauss-Seidel";
figure;
for k = 1:7:64
   v0 = sin(k * x * pi);
   loss = iteration(v0, f, sigma, steps, method, res, omega);
   plot(0:steps, log(loss) / log(10), 'DisplayName', "k = " + num2str(k));
   hold on;
end
legend;
hold off;
method = "red-black";
figure;
for k = 1:7:64
   v0 = sin(k * x * pi);
   loss = iteration(v0, f, sigma, steps, method, res, omega);
    plot(0:steps, log(loss) / log(10), 'DisplayName', "k = " + num2str(k));
   hold on;
end
legend;
hold off;
function loss = iteration(v0, f, sigma, steps, method, res, omega)
   loss = zeros(1, steps + 1);
   v = v0;
   loss(1) = max(abs(v - res));
   for i = 1:steps
       if method == "weighted-Jacobi"
          v = wJacobiIter(v, f, sigma, omega);
       end
       if method == "Gauss-Seidel"
           v = GaussSeidel(v, f, sigma);
       end
       if method == "red-black"
```

```
v = RBGaussSeidel(v, f, sigma);
       end
       loss(i + 1) = max(abs(v - res));
   end
end
function v = wJacobiIter(v, f, sigma, omega)
   h = 1 / (length(v) - 1);
   v(2:end-1) = (1 - omega) * v(2:end-1) + omega * ...
       (v(1:end-2) + v(3:end) + h^2 * f(2:end-1)) / (2 + sigma * h^2);
end
function v = GaussSeidel(v, f, sigma)
   h = 1 / (length(v) - 1);
   for i = 2:length(v)-1
       v(i) = (v(i-1) + v(i+1) + h^2 * f(i)) / (2 + sigma * h^2);
   end
end
function v = RBGaussSeidel(v, f, sigma)
   h = 1 / (length(v) - 1);
   v(3:2:end-1) = (v(2:2:end-2) + v(4:2:end) + h^2 * f(3:2:end-1)) / ...
       (2 + sigma * h^2);
   v(2:2:end-1) = (v(1:2:end-2) + v(3:2:end) + h^2 * f(2:2:end-1)) / ...
       (2 + sigma * h^2);
end
```

Lab 2 实验报告

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1、功能实现

实验要求:实现 V-cycle 迭代方法。

代码结构:

main.m 主程序脚本[调用 V_cycle.m] V cycle.m 递归 V cycle 算法实现

2、算法简述

对模型问题

$$-v'' + \sigma v = f$$
$$v(0) = v(1) = 0$$

离散后,假设步长 h,格点处 v 与 f 为 v_i , f_i ,且 $v_0 = v_n = 0$ 。

递归的 V-cycle 迭代方法伪代码如下:

- 1、初始化估计 v = 0
- 2、以初始 v 根据 f, sigma 迭代 nu1 次
- 3、若层数为 0、跳至步骤 9、否则:
 - a) 计算余项 r = f Av
 - b) 将余项 r 合并为间距两倍的情况
 - c) 以r, sigma与减1的层数, 在间距2h下递归
 - d) 将返回值 r 插值到当前间距的情况
 - e) v = v + r
- 4、以 v 根据 f, sigma 迭代 nu2 次并返回

另一个值得注意处为 Av 同样不需要显式构造矩阵,这是由于 A 的三对角性,有

$$r_i = f_i - \frac{(2 + \sigma h^2)v_i - v_{i-1} - v_{i+1}}{h^2}, i = 1, \dots, n-1$$

此外, 在 n 为偶数的前提下, 合并的方法为

$$r_{2i} = \frac{1}{2}r_{2i} + \frac{1}{4}(r_{2i-1} + r_{2i+1}), i = 1, \dots, \frac{n}{2} - 1$$

并取所有 r_{2i} ; 将迭代后的结果重新写回 r_{2i} 后, 插值的方法为(注意 $r_0 = r_n = 0$)

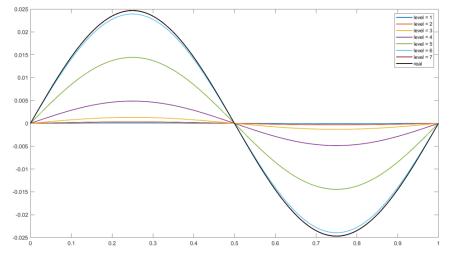
$$r_{2i-1} = \frac{r_{2i-2} + r_{2i}}{2}$$
, $i = 1, ..., \frac{n}{2}$

这样就得到了完整的数组 r_i 。

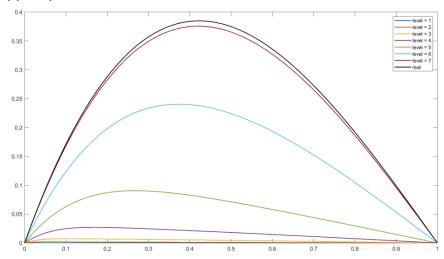
3、结果展示

取定网格大小 2^{-11} , $v_1 = v_2 = 100$, 对 $f(x) = \sin 2\pi x$, $\sigma = 1$ 在不同层次迭代效果如下,

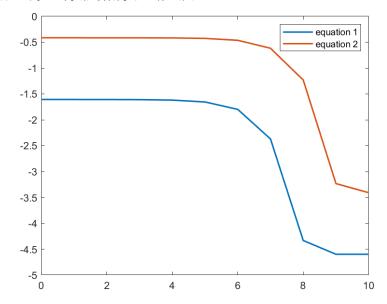
其中黑线为精确解 $\frac{\sin 2\pi x}{4\pi^2+1}$



而对 $f(x)=6-4x-3x^2+x^3, \sigma=1$ 在不同层次迭代效果如下,其中黑线为精确解x(x-1)(x-2):



取网格大小 2^{-13} , $\nu_1 = \nu_2 = 200$, 重新对上方两问题在不同层次迭代, 并以层数为横坐标无穷范数误差的 10 为底对数为纵坐标绘图:



4、讨论

从前两张图中,可以直观看出结果的正确性,也表明了层数增大时逼近效果的良好。注意到,由于每层网格数除以 2,实际的时间复杂度不会超过 $2h^{-1}(\nu_1 + \nu_2)T$,其中 T 为某常数,而若直接在原网格迭代,实验可发现至少需要 $1000h^{-1}(\nu_1 + \nu_2)$ 才能达到按层分解的效果,因此 V-cycle 大量节省了时间。

由于两结果函数自身的量级差异,第二张图中的形状一致已经表明了 V-cycle 方法的误差特点:在层数增加时,误差会先相对平稳地减少,而在某个特定层数开始大幅下降,直到收敛。值得注意的是,误差收敛的量级远没有达到机器精度,这意味着 V-cycle 方法节省时间的代价除了空间复杂度外还有精度的上限。

附录-代码

```
function v = V cycle(f, sigma, omega, N, nu1, nu2, level)
   L = 2^N;
   h = 1 / L;
   v = zeros(1, L + 1);
   for i = 1:nu1
       v = wJacobiIter(v, f, sigma, omega);
   end
   if level > 0
       r = v;
       r(2:L) = f(2:L) - ((2 + sigma * h^2) * r(2:L) ...
           - r(1:L-1) - r(3:L+1)) / h^2;
       r(3:2:L-1) = r(3:2:L-1) / 2 + (r(2:2:L-2) + r(4:2:L)) / 4;
       r(1:2:L+1) = ...
           V_cycle(r(1:2:L+1), sigma, omega, N-1, nu1, nu2, level-1);
       r(2:2:L) = (r(1:2:L-1) + r(3:2:L+1)) / 2;
       v = v + r;
   end
   for i = 1:nu2
       v = wJacobiIter(v, f, sigma, omega);
   end
end
function v = wJacobiIter(v, f, sigma, omega)
   h = 1 / (length(v) - 1);
   v(2:end-1) = (1 - omega) * v(2:end-1) + omega * ...
       (v(1:end-2) + v(3:end) + h^2 * f(2:end-1)) / (2 + sigma * h^2);
end
omega = 2/3;
sigma = 1;
```

```
N = 11;
x = 0:(1/2^N):1;
f = sin(2 * pi * x);
y = \sin(2 * pi * x) / (pi^2 * 4 + sigma);
figure;
for 1 = 1:7
   res = V_cycle(f, sigma, omega, N, 100, 100, 1);
   plot(x, res, "linewidth", 1.5, "DisplayName", "level = " + num2str(l));
   hold on;
end
plot(x, y, "black", "linewidth", 1.5, "DisplayName", "real");
legend;
N = 13;
x = 0:(1/2^N):1;
f = sin(2 * pi * x);
y = \sin(2 * pi * x) / (pi^2 * 4 + sigma);
err1 = zeros(1, 11);
for 1 = 0:10
   res = V_cycle(f, sigma, omega, N, 200, 200, 1);
   err1(l+1) = log(max(abs(y - res))) / log(10);
end
N = 11;
x = 0:(1/2^N):1;
f = 6 - 4 * x - 3 * x.^2 + x.^3;
y = x .* (1 - x) .* (2 - x);
figure;
for 1 = 1:7
   res = V_cycle(f, sigma, omega, N, 100, 100, 1);
   plot(x, res, "linewidth", 1.5, "DisplayName", "level = " + num2str(l));
   hold on;
end
plot(x, y, "black", "linewidth", 1.5, "DisplayName", "real");
legend;
N = 13;
x = 0:(1/2^N):1;
f = 6 - 4 * x - 3 * x.^2 + x.^3;
y = x .* (1 - x) .* (2 - x);
err2 = zeros(1, 11);
for 1 = 0:10
   res = V_cycle(f, sigma, omega, N, 200, 200, 1);
   err2(1+1) = log(max(abs(y - res))) / log(10);
```

```
figure;
plot(0:10, err1, 0:10, err2, "linewidth", 1.5);
legend("equation 1", "equation 2");
```