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**Introduction to Magnetic Island Theory.**

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# Introduction to Magnetic Island Theory<sup>a</sup>

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<sup>a</sup>Lectures based on work of R. Fitzpatrick, F.L. Waelbroeck, and F. Militello.

## **Outline**

**Lecture 1:** Introduction. MHD theory.

**Lecture 2:** Neoclassical effects. Drift-MHD theory. Subsonic islands.

**Lecture 3:** Supersonic islands. Further work.

# Lecture 1

## Introduction: Toroidal Magnetic Confinement

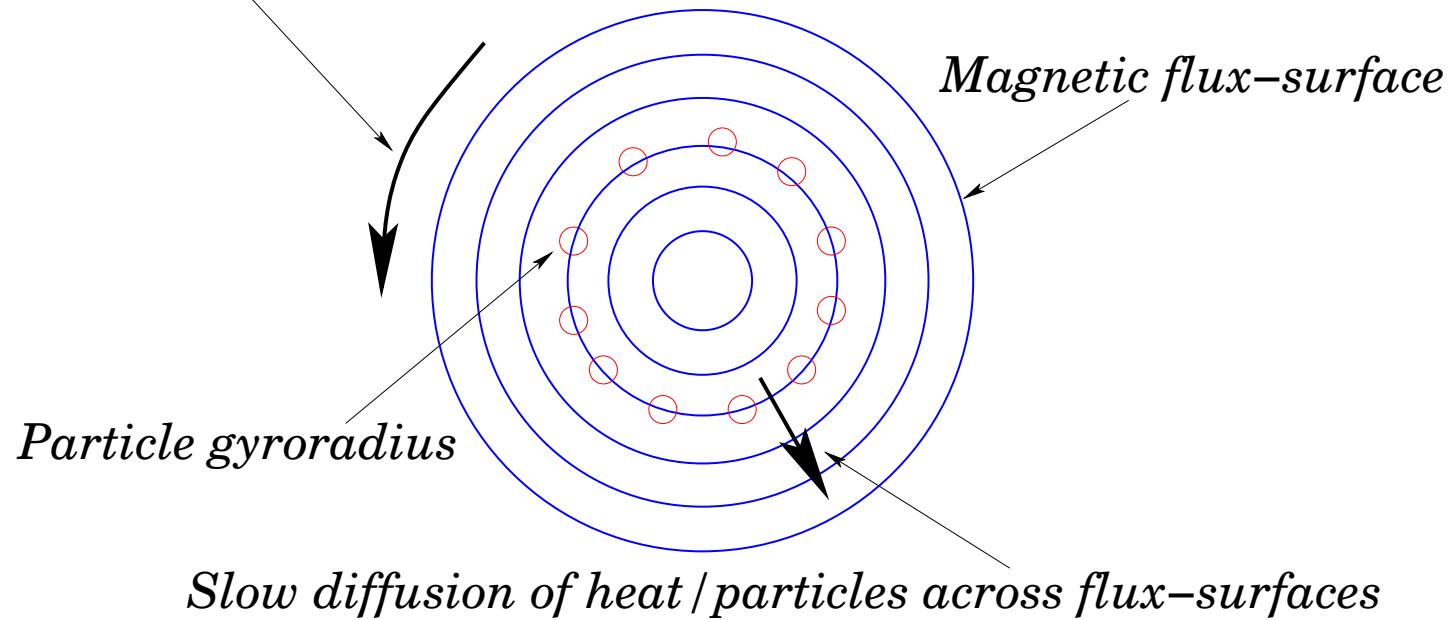
- Toroidal magnetic confinement devices designed to trap hot plasma within set of toroidally nested magnetic flux-surfaces.<sup>a</sup>
- Basic idea—charged particles free to stream along field-lines, but “stick” to magnetic flux-surfaces due to their (relatively) small gyroradii.
- Heat/particles flow rapidly along field-lines, but can only diffuse relatively slowly across flux-surfaces. Diffusion rate controlled by small-scale plasma turbulence.

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<sup>a</sup> *Tokamaks*, 3rd Edition, J. Wesson (Oxford University Press, 2004). *Ideal Magnetohydrodynamics*, J.P. Freidberg (Springer, 1987).

## ***Poloidal Cross-Section of Toroidal Confinement Device***

*Rapid flow of heat/particles along field-lines*



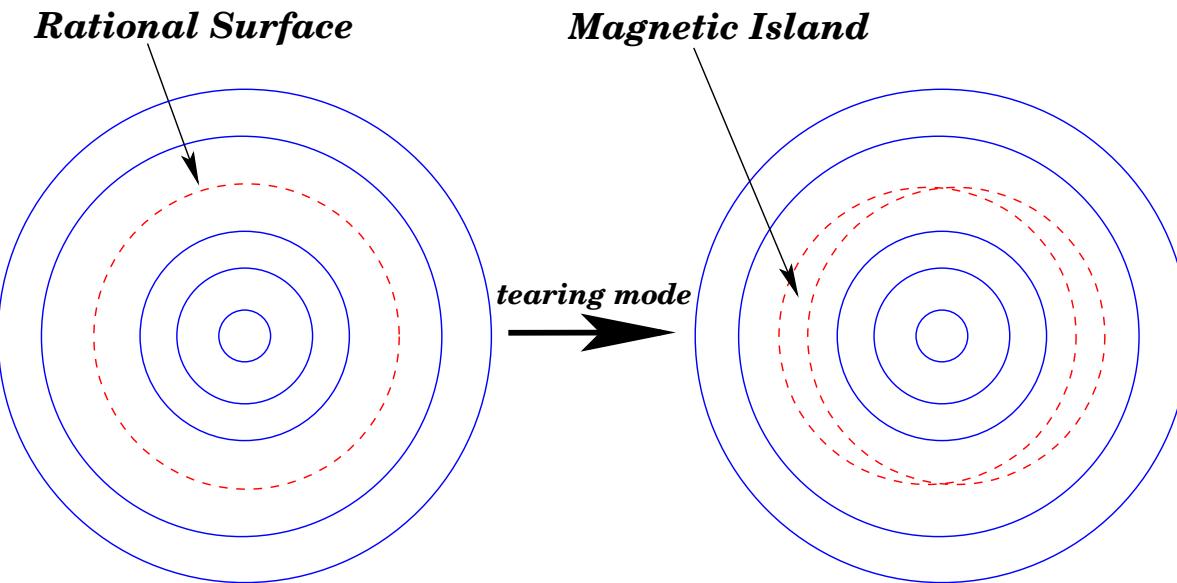
## Introduction: Macroscopic Instabilities

- Two main types of macroscopic instabilities<sup>a</sup> in toroidal magnetic confinement devices:
  - Catastrophic “ideal” (*i.e.*, non-reconnecting) instabilities, which destroy plasma in matter of micro-seconds—we know how to avoid these.
  - Slowly growing “tearing” instabilities, which reconnect magnetic flux-surfaces to form *magnetic islands*, thereby degrading their confinement properties—much harder to avoid.

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<sup>a</sup>*MHD Instabilities*, G. Bateman (MIT, 1978).

## Introduction: Magnetic Islands



- Centered on *rational flux-surfaces* which satisfy  $\vec{k} \cdot \vec{B} = 0$ , where  $\vec{k}$  is wave-number of mode, and  $\vec{B}$  is equilibrium magnetic field.
- Effectively “short-circuit” confinement by allowing heat/particles to transit island region by rapidly flowing along field-lines, rather than slowly diffusing across flux-surfaces.

## Introduction: Need for Magnetic Island Theory

- Magnetic island formation associated with *nonlinear* phase of tearing mode growth (*i.e.*, when island width becomes greater than linear layer width at rational surface).
- In very hot plasmas found in modern-day magnetic confinement devices, linear layers so thin that tearing mode already in nonlinear regime when first detected.
- Linear tearing mode theory largely irrelevant. Require nonlinear magnetic island theory to explain experimental observations.

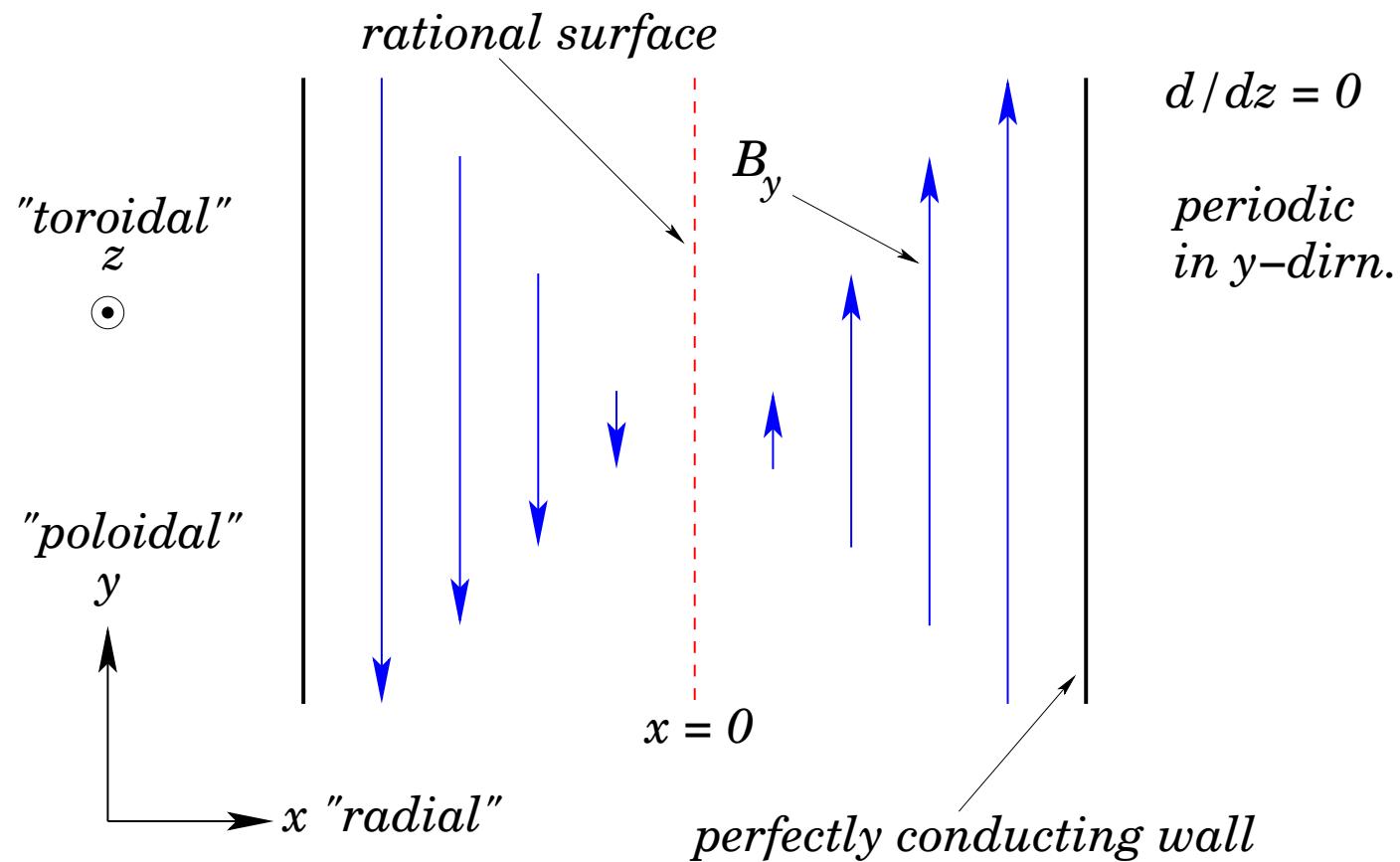
## MHD Theory: Introduction

- Tearing modes are macroscopic instabilities which affect whole plasma. Natural to investigate them using some form of *fluid-theory*.
- Simplest fluid theory is well-known *magnetohydrodynamical approximation*,<sup>a</sup> which effectively treats plasma as *single-fluid*.
- Shall also use *slab approximation* to simplify analysis.

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<sup>a</sup>*Plasma Confinement*, R.D. Hazeltine, and J.D. Meiss (Dover, 2003).

## *Slab Approximation*



## MHD Theory: Slab Model

- Cartesian coordinates:  $(x, y, z)$ . Let  $\partial/\partial z \equiv 0$ .
- Assume presence of dominant uniform “guide-field”  $\vec{B}_z \hat{z}$ .
- All field-strengths normalized to  $B_z$ .
- All lengths normalized to equilibrium magnetic shear-length:

$$L_s = B_z / B'_y(0).$$

- All times normalized to shear-Alfvén time calculated with  $B_z$ .
- Perfect wall boundary conditions at  $x = \pm a$ .
- Wave-number of tearing instability:  $\vec{k} = (0, k, 0)$ , so  $\vec{k} \cdot \vec{B} = 0$  at  $x = 0$ . Hence, rational surface at  $x = 0$ .

## MHD Theory: Model MHD equations

- Let  $\vec{B}_\perp = \nabla\psi \times \vec{z}$  and  $\vec{V} = \nabla\phi \times \vec{z}$ , where  $\vec{V}$  is  $\vec{E} \times \vec{B}$  velocity.
- $\vec{B} \cdot \nabla\psi = \vec{V} \cdot \nabla\phi = 0$ , so  $\psi$  maps magnetic flux-surfaces, and  $\phi$  maps stream-lines of  $\vec{E} \times \vec{B}$  fluid.
- Incompressible MHD equations:<sup>a</sup>

$$\frac{\partial\psi}{\partial t} = [\phi, \psi] + \eta J,$$

$$\frac{\partial U}{\partial t} = [\phi, U] + [J, \psi] + \mu \nabla^2 U,$$

where  $J = \nabla^2\psi$ ,  $U = \nabla^2\phi$ , and  $[A, B] = A_x B_y - A_y B_x$ . Here,  $\eta$  is resistivity, and  $\mu$  is viscosity. In normalized units:  $\eta, \mu \ll 1$ .

- First equation is  $z$ -component of Ohm's law. Second equation is  $z$ -component of curl of plasma equation of motion.

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<sup>a</sup>*Plasma Confinement*, R.D. Hazeltine, and J.D. Meiss (Dover, 2003).

## MHD Theory: Outer Region

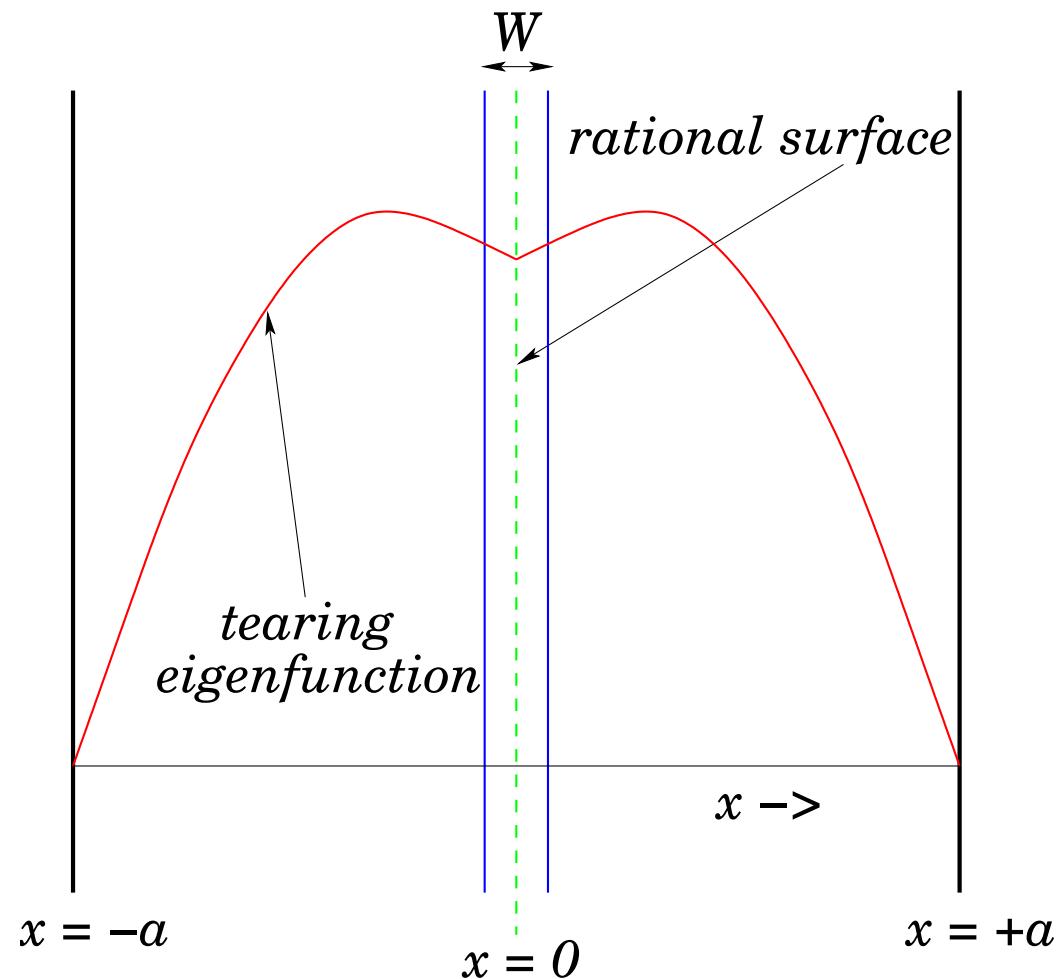
- In “outer region”, which comprises most of plasma, non-linear, non-ideal ( $\eta$  and  $\mu$ ), and inertial effects ( $\partial/\partial t$  and  $\vec{V} \cdot \nabla$ ), negligible.
- Vorticity equation reduces to

$$[J, \psi] \simeq 0.$$

- When linearized, obtain  $\psi(x, y) = \psi^{(0)}(x) + \psi^{(1)}(x) \cos(ky)$ , where  $B_y^{(0)} = -d\psi^{(0)}/dx$ , and

$$\left( \frac{d^2}{dx^2} - k^2 \right) \psi^{(1)} - \left( \frac{d^2 B_y^{(0)}}{dx^2} / B_y^{(0)} \right) \psi^{(1)} = 0.$$

- Equation is *singular* at rational surface,  $x = 0$ , where  $B_y^{(0)} = 0$ .



## MHD Theory: Tearing Stability Index

- Find tearing eigenfunction,  $\psi^{(1)}(x)$ , which is continuous, has tearing parity [ $\psi^{(1)}(-x) = \psi^{(1)}(x)$ ], and satisfies boundary condition  $\psi^{(1)}(a) = 0$  at conducting wall.
- In general, eigenfunction has *gradient discontinuity* across rational surface (at  $x = 0$ ). Allowed because tearing mode equation singular at rational surface.
- Tearing stability index:

$$\Delta' = \left[ \frac{d \ln \psi^{(1)}}{dx} \right]_{0-}^{0+}.$$

- According to conventional MHD theory,<sup>a</sup> tearing mode is unstable if  $\Delta' > 0$ .

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<sup>a</sup>H.P. Furth, J. Killeen, and M.N. Rosenbluth, Phys. Fluids **6**, 459 (1963).

## MHD Theory: Inner Region

- “Inner region” centered on rational surface,  $x = 0$ . Of extent,  $W \ll 1$ , where  $W$  is magnetic island width (in  $x$ ).
- In inner region, non-ideal effects, non-linear effects, and plasma inertia can all be important.
- Inner solution must be asymptotically matched to outer solution already obtained.

## MHD Theory: Constant- $\psi$ Approximation

- $\psi^{(1)}(x)$  generally does not vary significantly in  $x$  over inner region:

$$|\psi^{(1)}(W) - \psi^{(1)}(0)| \ll |\psi^1(0)|.$$

- *Constant- $\psi$  approximation*: treat  $\psi^{(1)}(x)$  as constant in  $x$  over inner region.
- Approximation valid provided

$$|\Delta'| W \ll 1,$$

which is easily satisfied for conventional tearing modes.

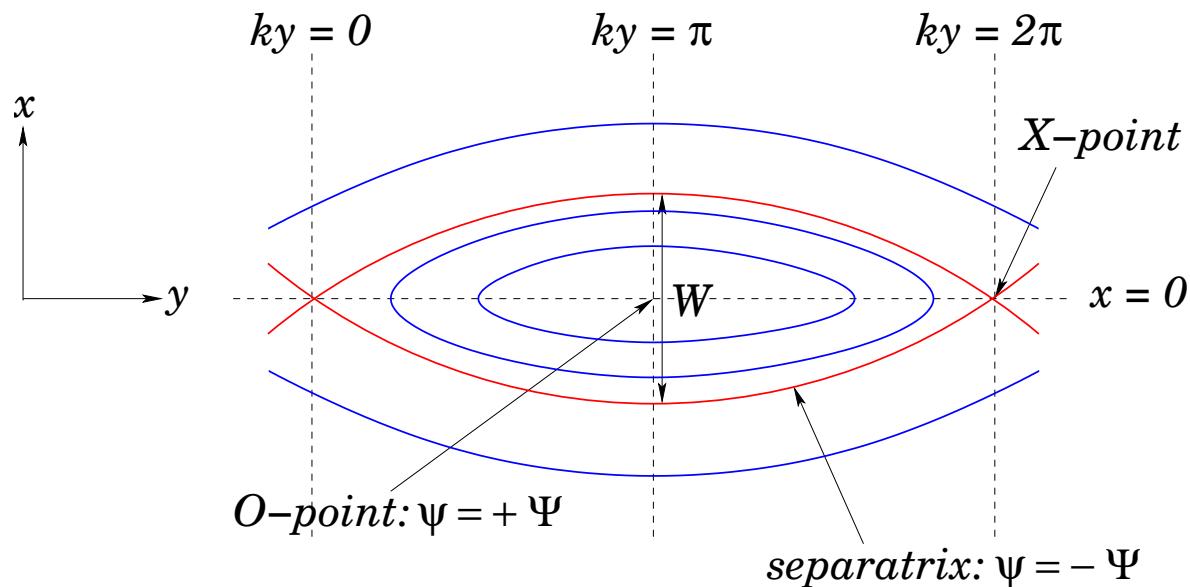
## MHD Theory: Constant- $\psi$ Magnetic Island

- In vicinity of rational surface,  $\psi^{(0)} \rightarrow -x^2/2$ , so

$$\psi(x, y, t) \simeq -x^2/2 + \Psi(t) \cos \theta,$$

where  $\Psi = \psi^{(1)}(0)$  is “reconnected flux”, and  $\theta = ky$ .

- Full island width,  $W = 4\sqrt{\Psi}$ .



## MHD Theory: Flux-Surface Average Operator

- Flux-surface average operator is annihilator of Poisson bracket  
 $[A, \psi] \equiv \vec{B} \cdot \nabla A \equiv kx (\partial A / \partial \theta)_\psi$  for any  $A$ : i.e.,

$$\langle [A, \psi] \rangle \equiv 0.$$

- Outside separatrix:

$$\langle f(\psi, \theta) \rangle = \oint \frac{f(\psi, \theta)}{|x|} \frac{d\theta}{2\pi}.$$

- Inside separatrix:

$$\langle f(s, \psi, \theta) \rangle = \int_{-\theta_0}^{\theta_0} \frac{f(s, \psi, \theta) + f(-s, \psi, \theta)}{2|x|} \frac{d\theta}{2\pi},$$

where  $s = \text{sgn}(x)$ , and  $x(s, \psi, \theta_0) = 0$ .

## MHD Theory: MHD Flow -I

- Move to island frame. Look for steady-state solution:  $\partial/\partial t = 0$ .<sup>a</sup>
- Ohm's law:

$$0 \simeq [\phi, \psi] + \eta J.$$

- Since  $\eta \ll 1$ , first term potentially much larger than second.
- To lowest order:

$$[\phi, \psi] \simeq 0.$$

- Follows that

$$\phi = \phi(\psi) :$$

i.e., MHD flow constrained to be around flux-surfaces.

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<sup>a</sup>F.L. Waelbroeck, and R. Fitzpatrick, Phys. Rev. Lett. **78**, 1703 (1997).

## MHD Theory: MHD Flow - II

- Let

$$M(\psi) = \frac{d\phi}{d\psi}.$$

- Easily shown that

$$V_y = x M.$$

- By symmetry,  $M(\psi)$  is *odd* function of  $x$ . Hence,

$$M = 0$$

inside separatrix: *i.e.*, no flow inside separatrix in island frame.

Plasma *trapped* within magnetic separatrix.

## MHD Theory: MHD Flow - III

- Vorticity equation:

$$0 \simeq [-\mathcal{M} \mathbf{U} + \mathbf{J}, \psi] + \mu \nabla^4 \phi.$$

- Flux-surface average, recalling that  $\langle [\mathbf{A}, \psi] \rangle = 0$ :

$$\langle \nabla^4 \phi \rangle \equiv -\frac{d^2}{d\psi^2} \left( \langle x^4 \rangle \frac{d\mathcal{M}}{d\psi} \right) \simeq 0.$$

- Solution outside separatrix:

$$\mathcal{M}(\psi) = \text{sgn}(x) \mathcal{M}_0 \left/ \int_{-\Psi}^{\Psi} d\psi / \langle x^4 \rangle \right. \left/ \int_{-\infty}^{-\Psi} d\psi / \langle x^4 \rangle \right..$$

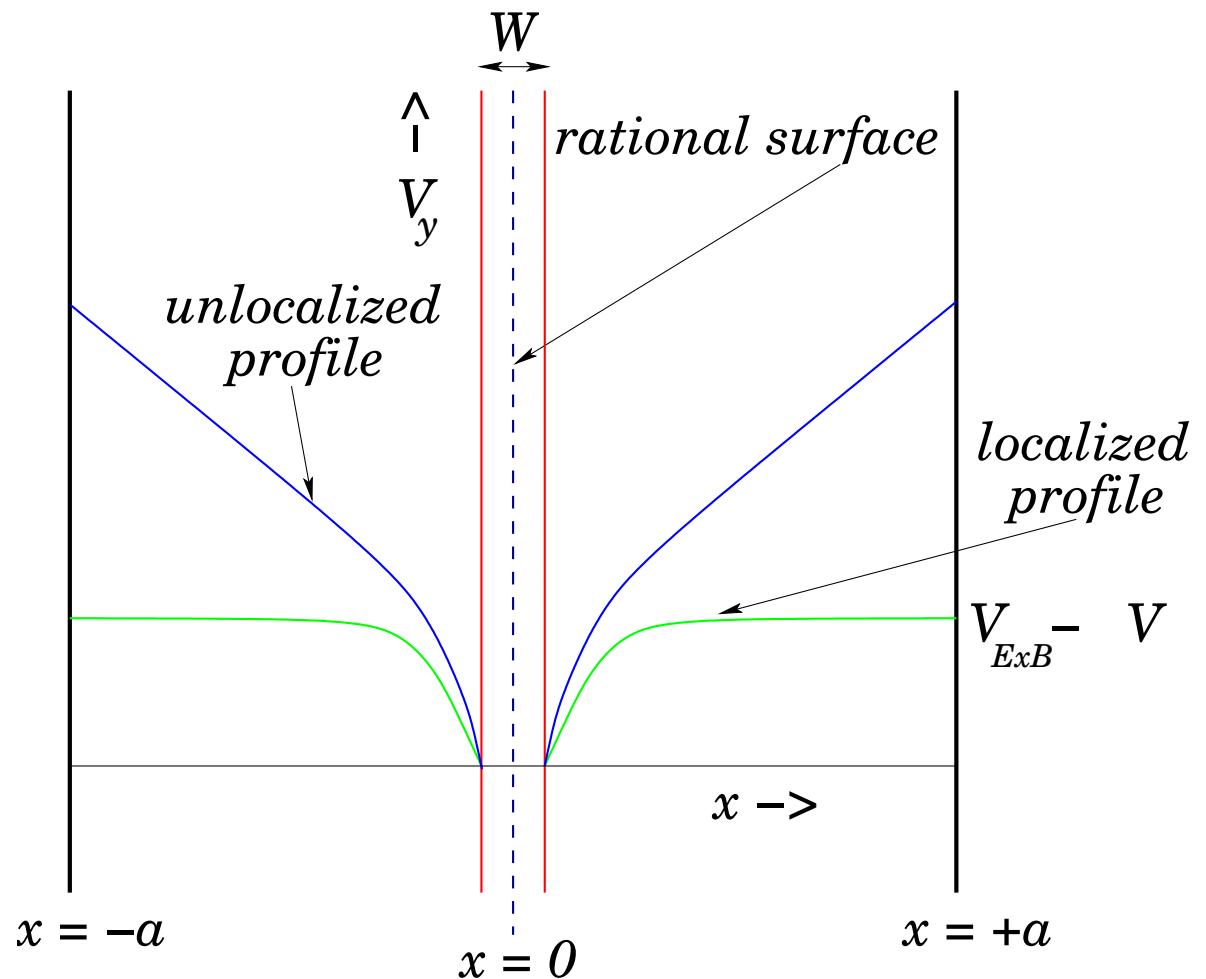
## MHD Theory: MHD Flow - IV

- Note

$$V_y = x M \rightarrow |x| M_0$$

as  $|x|/W \rightarrow \infty$ .

- V-shaped velocity profile which extends over whole plasma.
- Expect *isolated* magnetic island to have *localized* velocity profile.  
Suggests that  $M_0 = 0$  for isolated island.
- Hence, zero MHD flow in island frame: *i.e.*, island propagates at local  $\vec{E} \times \vec{B}$  velocity.



## MHD Theory: Rutherford Equation - I

- Asymptotic matching between inner and outer regions yields:

$$\Delta' \Psi = -4 \int_{+\Psi}^{-\infty} \langle J \cos \theta \rangle d\psi.$$

- In island frame, in absence of MHD flow, vorticity equation reduces to

$$[J, \psi] \simeq 0.$$

- Hence,

$$J = J(\psi).$$

## MHD Theory: Rutherford Equation - II

- Ohm's law:

$$\frac{d\Psi}{dt} \cos \theta \simeq [\phi, \psi] + \eta J(\psi).$$

- Have shown there is no MHD-flow [i.e.,  $\phi \sim O(1)$ ], but can still be *resistive flow* [i.e.,  $\phi \sim O(\eta)$ ].
- Eliminate resistive flow by flux-surface averaging:

$$\frac{d\Psi}{dt} \langle \cos \theta \rangle \simeq \eta J(\psi) \langle 1 \rangle.$$

- Hence,

$$\Delta' \Psi \simeq -\frac{4}{\eta} \frac{d\Psi}{dt} \int_{+\Psi}^{-\infty} \frac{\langle \cos \theta \rangle^2}{\langle 1 \rangle} d\psi.$$

## MHD Theory: Rutherford Equation - III

- Use  $W = 4\sqrt{\Psi}$ , and evaluate integral. Obtain *Rutherford island width evolution equation*:<sup>a</sup>

$$\frac{0.823}{\eta} \frac{dW}{dt} \simeq \Delta'.$$

- According to Rutherford equation, island grows *algebraically* on *resistive time-scale*.
- Rutherford equation does not predict island saturation.

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<sup>a</sup>P.H. Rutherford, Phys. Fluids **16**, 1903 (1973).

## MHD Theory: Rutherford Equation - IV

- Higher order asymptotic matching between inner and outer regions yields:<sup>a</sup>

$$\frac{0.823}{\eta} \frac{dW}{dt} \simeq \Delta' - 0.41 \left( -\frac{d^4 B_y^{(0)} / dx^4}{d^2 B_y^{(0)} / dx^2} \right)_{x=0} W.$$

- Hence, saturated ( $d/dt = 0$ ) island width is

$$W_0 = \frac{\Delta'}{0.41} \left( -\frac{d^2 B_y^{(0)} / dx^2}{d^4 B_y^{(0)} / dx^4} \right)_{x=0}.$$

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<sup>a</sup>F. Militello, and F. Porcelli, Phys. Plasmas **11**, L13 (2004). D.F. Escande, and M. Ottaviani, Physics Lett. A **323**, 278 (2004).

## MHD Theory: Summary

- Tearing mode unstable if  $\Delta' > 0$ .
- Island propagates at local  $\vec{E} \times \vec{B}$  velocity at rational surface.
- Island grows algebraically on resistive time-scale.
- Saturated island width:

$$W_0 = \frac{\Delta'}{0.41} \left( -\frac{d^2 B_y^{(0)} / dx^2}{d^4 B_y^{(0)} / dx^4} \right)_{x=0} .$$