



Select Board

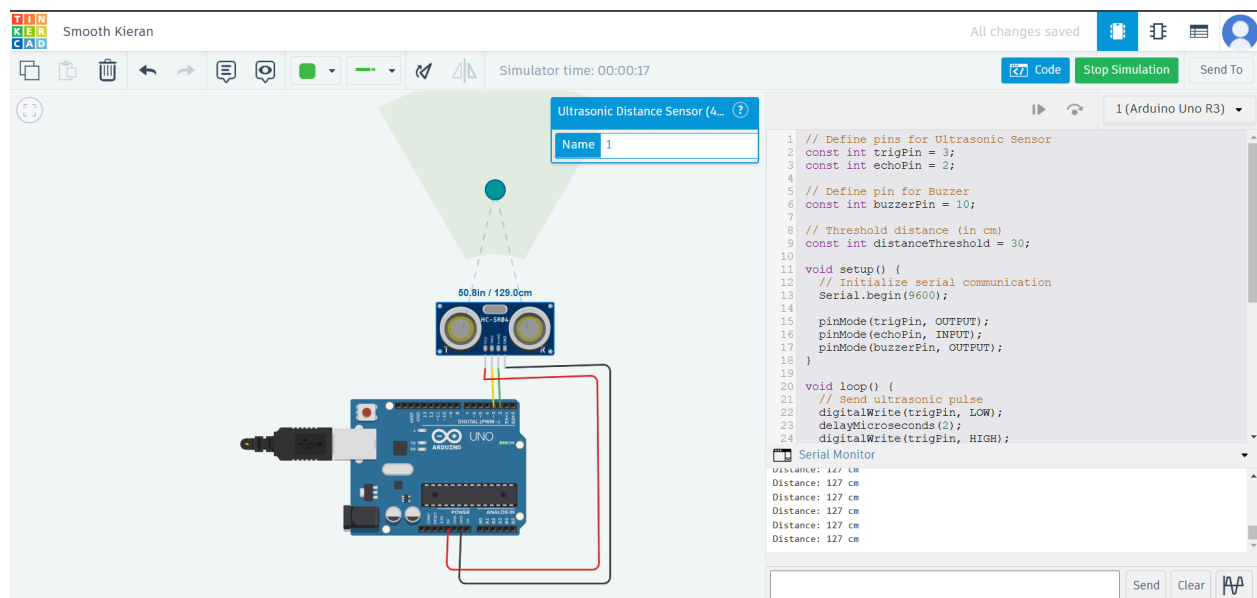


sketch_dec8a.ino



```
1 // Define pins for Ultrasonic Sensor
2 const int trigPin = 3;
3 const int echoPin = 2;
4
5 // Define pin for Buzzer
6 const int buzzerPin = 10;
7
8 // Threshold distance (in cm)
9 const int distanceThreshold = 30;
10
11 void setup() {
12     // Initialize serial communication
13     Serial.begin(9600);
14
15     pinMode(trigPin, OUTPUT);
16     pinMode(echoPin, INPUT);
17     pinMode(buzzerPin, OUTPUT);
18 }
19
20 void loop() {
21     // Send ultrasonic pulse
22     digitalWrite(trigPin, LOW);
23     delayMicroseconds(2);
24     digitalWrite(trigPin, HIGH);
25     delayMicroseconds(10);
26     digitalWrite(trigPin, LOW);
27
28     // Measure the echo pulse duration
29     long duration = pulseIn(echoPin, HIGH);
30
31     // Calculate distance in cm
32     int distance = duration * 0.034 / 2;
33
34     // Display distance in serial monitor
35     Serial.print("Distance: ");
36     Serial.print(distance);
```

```
37 Serial.println(" cm");
38 Close
39 // Trigger buzzer if distance is below the threshold
40 if (distance > 0 && distance < distanceThreshold) {
41   digitalWrite(buzzerPin, HIGH); // Turn on buzzer
42 } else {
43   digitalWrite(buzzerPin, LOW); // Turn off buzzer
44 }
45
46 // Add a small delay
47 delay(100);
48 }
49
```



Smooth Kieran

Simulator time: 00:00:37

1 (Arduino Uno R3)

Ultrasonic Distance Sensor (4... ?)

Name 1

67.3in / 170.8cm

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20 void loop() {
21   // Send ultrasonic pulse
22   digitalWrite(trigPin, LOW);
23   delayMicroseconds(2);
24   digitalWrite(trigPin, HIGH);
```

Serial Monitor

Distance: 168 cm

Distance: 168 cm

Distance: 168 cm

Distance: 168 cm

Distance: 168 cm

Distance: 168 cm

Smooth Kieran

Simulator time: 00:00:55

1 (Arduino Uno R3)

Ultrasonic Distance Sensor (4... ?)

Name 1

9.6in / 24.4cm

```
1 // Define pins for Ultrasonic Sensor
2 const int trigPin = 3;
3 const int echoPin = 2;
4
5 // Define pin for Buzzer
6 const int buzzerPin = 10;
7
8 // Threshold distance (in cm)
9 const int distanceThreshold = 30;
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11 void setup() {
12   // Initialize serial communication
13   Serial.begin(9600);
14 }
15
16 pinMode(trigPin, OUTPUT);
17 pinMode(echoPin, INPUT);
18 pinMode(buzzerPin, OUTPUT);
19
20 void loop() {
21   // Send ultrasonic pulse
22   digitalWrite(trigPin, LOW);
23   delayMicroseconds(2);
24   digitalWrite(trigPin, HIGH);
```

Serial Monitor

Distance: 24 cm

Distance: 24 cm

Distance: 24 cm

Distance: 24 cm

Distance: 24 cm

Distance: 24 cm