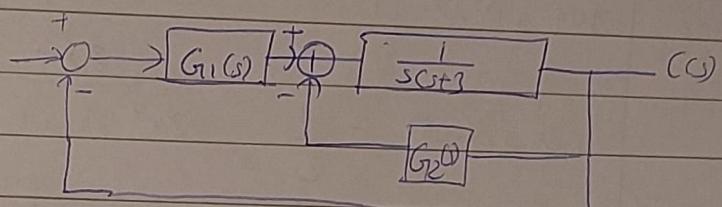


EE 302 - (cont & sol) Assignment - 2

Question 2

Part 4



$$C(s) = \frac{1}{sC+3} G_1(s)$$

$$(C(s)) = R(s) \left\{ G_1(s) \left\{ \frac{1}{sC+3} \right\} \right\}$$

$$= R(s) \left\{ \frac{G_1(s)}{sC+3 + G_2(s)} \right\}$$

$$= R(s) \left\{ \frac{G_1(s)}{s(s+3) + G_2(s)} \right\}$$

$$= R(s) \left(\frac{G_1(s)}{s(s+3) + G_2(s)} + G_2(s) + G_1(s) \right)$$

$$= R(s) \cdot \frac{G_1(s)}{G_1(s) + s(s+3) + G_2(s)}$$

R Part 18

$$(C(s)) = \frac{R(s) G_1(s)}{G_1(s) + G_2(s) + s(s+3)}$$

$$\lim_{s \rightarrow 0} s(C(s)) = 0 \quad \text{for } R(s) = 1$$

$$\lim_{s \rightarrow \infty} s \left(\frac{1}{s^2} - \frac{1}{s^2} \frac{G_1(s)}{G_1(s) + G_2(s)} \right) = 1$$

$$\lim_{s \rightarrow 0} s \left(\frac{G_1(s)}{G_1(s) + G_2(s) + s(s+3)} \right) = 1$$

$$\lim_{s \rightarrow \infty} \frac{G_1(s)}{G_1(s) + G_2(s) + s(s+3)} = 1$$

$$G_1(s) = s(s+3)$$

Assume.

Part 2 :-

b) $\frac{as+1}{as^2+s(s-2)+s(s+1)}$ $a=1$

for $R(s) = 1$

$$\lim_{s \rightarrow 0} s \cdot (Cs) = \frac{1}{2} \quad \frac{as+1}{2s^2+2s+1} = \frac{s+1}{2s^2+2s+1}$$

$$\frac{1}{2} \left(\frac{s+1}{s^2+s+1} \right) \quad \% OS = 4.33\% \\ T_s = 8s \quad T_\theta = 2.22 \\ T_p = 6.28s$$

Part 2

The unit ramp and unit step response is exactly $\frac{1}{2}$

$$\lim_{s \rightarrow 0} s \cdot \frac{1}{s} \frac{G_1(s)}{G_1(s) + G_2(s) + G_3(s)} = \frac{1}{2}$$

$$G_1(s) = \frac{s+3}{s+5}$$

$$G_2(s) = \frac{2s+3}{2s+5}$$

$$(s) = R(s) \frac{s+5}{s+5+2s+5+s(s+1)}$$

$$= R(s) \frac{s+5}{s^2+6s+10}$$

$$s^2+3s+5+2s+2s^2+10$$

$$4s^2+6s+15 = \frac{s+5}{s^2+6s+10}$$

b)

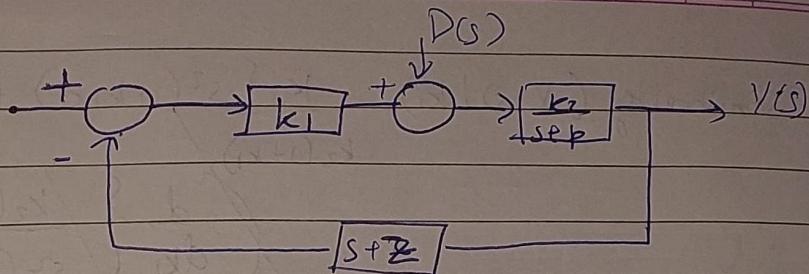
$$\therefore OS = 0.94\%$$

$$\therefore \text{Settling time} = 1.33$$

$$\text{peak} = 3.141$$

$$\text{Rise time} = 0.496s$$

3



$$Y(s) = \frac{k_2}{s+p} \left\{ D(s) + k_1 \left\{ R(s) - Y(s)(s+p) \right\} \right\}$$

$$= \frac{k_2 D(s)}{s+p} + \frac{k_1 k_2}{s+p} \left\{ R(s) - Y(s)(s+p) \right\}$$

$$Y(s) \left\{ 1 + (s+p) \frac{k_1 k_2}{s+p} \right\} = \frac{k_2}{s+p} \left\{ \frac{1}{s} + \frac{k_2}{s} \right\}$$

$$Y(s) = \frac{k_2 (1+k_1)}{(s+p)s} \left\{ \frac{(s+p) + k_1 k_2 (s+p)}{(s+p)} \right\}$$

$$Y(s) = \frac{k_2 (1+k_1)}{s \{ s(1+k_1 k_2) + p \} + k_1 k_2 s^2}$$

Steady state error = $\lim_{s \rightarrow 0} s \left\{ \frac{1 - k_2 (1+k_1)}{s^2 (1+k_1 k_2) + p + k_1 k_2 s^2} \right\}$

$$\lim_{s \rightarrow 0} 1 - \frac{k_2 (1+k_1)}{p + k_1 k_2 s^2}$$

$$1 - \frac{0.1 \times 10}{2+10}$$

$$1 - \frac{10.1}{12} = \frac{19}{12} = 0.1583.$$

a) Sensitivity ($\frac{\partial Y(s)}{\partial k_1}$) = $\frac{k_2}{s^2 (1+k_1 k_2) + p + k_1 k_2 s^2}$

a) Sensitivity ($\frac{d}{dk_1} \{ s^2(1+k_1 k_2) + p(p+k_1 k_2 z) \}$)

$$\frac{d}{dk_1} \left\{ \frac{k_2(1+k_1)}{s^2(1+k_1 k_2) + ps + sk_1 k_2 z} \right\}$$

$$= \frac{k_1 \{ s^2(1+k_1 k_2) + p(p+k_1 k_2 z) \}}{k_2(1+k_1)} \times \frac{k_2 - \{ s^2 k_2 \}}{\{ s^2(1+k_1 k_2) + ps + sk_1 k_2 z \}^2}$$

a) Sensitivity ($\frac{d}{dk_1} \{ F_{0000} | k_1 \} = \frac{d}{dk_1} \left(1 - \frac{k_2(1+k_1)}{p+k_1 k_2 z} \right) \times \frac{k_1}{p+k_1 k_2 z}$)

$$= \frac{k_1 \{ -\frac{k_2}{p+k_1 k_2 z} \}}{(p+k_1 k_2 z)^2} \times \frac{k_1 + k_2(1+k_1) k_2 z}{(p+k_1 k_2 z)^2}$$

$$= \frac{k_1 \{ (1+k_1) k_2^2 z - k_2(p+k_1 k_2 z) \}}{(p+k_1 k_2 z)^2}$$

$$= \frac{100 \times 12}{1-a} \left\{ (1.01 \times 1 - 0.1 \{ 2 + 10 \}) \right\}$$

$$= \frac{100}{1-a} \left\{ 1.01 - 1.2 \right\}$$

$$= -\frac{100}{1-a} \left\{ \frac{0.19}{12} \right\} = -\frac{10}{12} = -\frac{5}{6} = -0.83$$

b) Sensitivity ($\frac{d}{dk_2} \{ F_{0000} | k_2 \} = \frac{d}{dk_2} \left(1 - \frac{k_2(1+k_1)}{p+k_1 k_2 z} \right) \frac{k_2}{p+k_1 k_2 z}$)

$$= \left\{ -\frac{(1+k_1)}{p+k_1 k_2 z} + \frac{k_2(1+k_1) k_2 z}{(p+k_1 k_2 z)^2} \right\} \frac{k_2}{p+k_1 k_2 z}$$

$$= \left\{ \frac{-101 \times 12 + 6.1 \times 101 \times 100}{12 \times 12} \right\} \frac{\frac{0.1}{1-a}}{x+2}$$

$$= \left\{ \frac{-101 \times 12}{12 \times 12} \right\} \frac{1}{19}$$

$$= \frac{-101}{144} = -0.886$$

Q) $P(s) = s^6 - s^4 - 7s^2 + 7s - 6$

Reverse co-eff

Epsilon method

$$\begin{array}{r}
 s^6 - 6s^5 - 7s^4 - 1s^3 + 7s^2 + 7s - 6 \\
 \text{---} \\
 s^5 7s^4 0 0 0 \\
 \text{---} \\
 s^4 -7 -1 1 \\
 \text{---} \\
 s^3 -1 1 0 \\
 \text{---} \\
 s^2 -8 +1 \\
 \text{---} \\
 s 7 \\
 \text{---} \\
 1 -1
 \end{array}
 \quad
 \begin{array}{r}
 s^6 1 -1 -7 -6 \\
 \text{---} \\
 s^5 \epsilon 0 7 0 \\
 \text{---} \\
 s^4 -1 -7 \epsilon -7 -6 \\
 \text{---} \\
 s^3 -7 \epsilon -7 6 \epsilon -7 \\
 \text{---} \\
 s^2 (7\epsilon + 7) - (6\epsilon - 7) - 6 \\
 \text{---} \\
 s (7 - 6\epsilon) \left\{ \frac{(7\epsilon + 7)^2 - (6\epsilon - 7)}{-(7\epsilon + 7)} \right\} - 6(7\epsilon + 7)
 \end{array}$$

3 R.H.P

3 L.H.P

$$\frac{(7\epsilon + 7)^2 - (6\epsilon - 7)}{-(7\epsilon + 7)}$$

$$s^0 -6$$

11) Routh Table

a) $s^5 + 2s^4 + 3s^3 + 6s^2 + 5s + 3$

Reversal

$$\begin{array}{r} s^5 \\ s^4 \\ s^3 \end{array} \begin{array}{r} 1 \\ 2 \\ 0 \end{array} \begin{array}{r} 3 \\ 6 \\ 7 \end{array} \begin{array}{r} 3 \\ 3 \\ 0 \end{array}$$

$$s^2 \frac{6\epsilon - 14}{\epsilon} 3$$

$$s \frac{7\left\{\frac{6 - 14}{\epsilon}\right\} - 3\epsilon}{\left(\frac{6\epsilon - 14}{\epsilon}\right)}$$

$$\begin{array}{r} s^5 \\ s^4 \\ s^3 \end{array} \begin{array}{r} 3 \\ 5 \\ 3 \end{array} \begin{array}{r} 6 \\ 3 \\ 1 \end{array} \begin{array}{r} 3 \\ 0 \\ 0 \end{array}$$

$$s^2 \frac{4\epsilon - 3}{\epsilon} 3$$

12 RHP - 3 LHP

b) $3s^7 + 9s^6 + 6s^5 + 4s^4 + 7s^3 + 8s^2 + 2s + 6$

$$s^7 \ 3 \ 6 \ -7 \ 2$$

$$s^6 \ 9 \ 4 \ 8 \ 6$$

$$s^5 \frac{14}{3} \ 1 \frac{13}{3} \ 0 \ 0$$

$$s^4 \frac{-61}{14} \ 14 \ 8 \ 6 \ 14$$

$$s^3 \frac{2361}{61} \ 14 \ 6$$

$$s^2 \frac{112056}{787} \ 84 \ 787$$

$$s^1 \ -216 \cdot 88$$

$$s^0 \ 84 \ 787$$

4 RHP

3 LHP

9. H. 88

9. H. 18

$$C) s^5 + 7s^4 + 6s^3 + 4s^2 + 8s + 56$$

$$\begin{array}{r} s^5 \\ s^4 \\ s^3 \\ s^2 \\ s \\ s^0 \end{array} \begin{array}{r} 1 \\ \cancel{7} \\ \cancel{1} \\ 12 \\ 3 \\ 8 \end{array} \begin{array}{r} 6 \\ \cancel{2} \\ 12 \\ 8 \\ 8 \end{array} \begin{array}{r} 8 \\ 8 \\ 8 \\ 8 \\ 8 \\ 8 \end{array} \begin{array}{l} (s+7)(s^4 + 6s^2 + 8) \\ \text{stable. } (s^3 + 3) \rightarrow \end{array}$$

$$\begin{array}{r} s^3 \\ s^2 \\ s \\ s^0 \end{array} \begin{array}{r} \cancel{1} \\ 3 \\ 8 \end{array}$$

$$s - \frac{1}{3}$$

OR HP SLHP

$$s^0 \quad 8$$

14

$$\frac{1}{(s+2)(s+4)} \quad \frac{s+8}{(s+7)(s+6)(s+2)}$$

15

$$a) \frac{1}{(s+2)(s+4)}$$

$$b) \frac{s-3}{s+2}$$

$$c) \frac{s-3}{(s-2)(s+3)}$$

$$d) \frac{(s+2)}{(s+3)(s+7)(s+8)}$$

$$e) \frac{s+8}{(s+7)(s+2)(s+3)}$$

$$f) \frac{(s+8)(s+7)}{(s+2)(s+3)}$$

$$g) \frac{1}{(s+2)(s+3)(s+5)}$$

$$h) \frac{s^2 + 4s + 5}{(s+2)(s+4)}$$

$$i) \frac{s^2 + 4s + 5}{s^2 + 6s + 10}$$

j)

B

$$Y = \frac{C_G}{1 + CG} = \frac{k}{(s+q)(s+l) + k} = \frac{k}{s^2 + (q+l)s + qlk}$$

$$\omega_n^2 = a + k \quad f_s = \frac{4}{2\omega} = 5$$

$$2.8 \omega_n^2 = a + 1 \quad 2\omega = \frac{4}{5}$$

$$\frac{8}{5} = a + 1 \quad \Delta Y = 10\%$$

$$a = \frac{3}{5} \quad 3+2 = 100 e^{-\frac{8\pi}{5}}$$

$$\omega = \frac{4}{3} \times 0.591 \quad \frac{\sin \theta}{\sqrt{1 - g^2}} = \ln 10$$

$$\omega_n = 1.35 \quad \frac{g^2 \pi^2}{(1.10)^2} = (4.42)(5+2)$$

$$k = 1.2225 \quad (6) \quad \frac{1}{(\sin \theta)^2} = \frac{4\pi^2 g^2}{((1.10)^2)}$$

$$g = 0.591$$

$$(4.42)(8+2) \quad (7) \quad \frac{1}{(\sin \theta)^2} = \frac{4\pi^2 g^2}{((1.10)^2)}$$

$$2 + 2 = 4 \quad (8) \quad \frac{1}{(\sin \theta)^2} = \frac{4\pi^2 g^2}{((1.10)^2)}$$

$$0.643 + 5$$

19

$$G(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

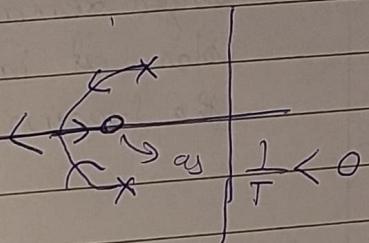
$$\omega_n = 2 \quad \zeta = 0.5$$

$$P_1 = -1 + j\sqrt{0.75}$$

$$P_2 = -1 - j\sqrt{0.75}$$

a) A break in P_T becomes.

Poles go towards ∞ till damping increases.



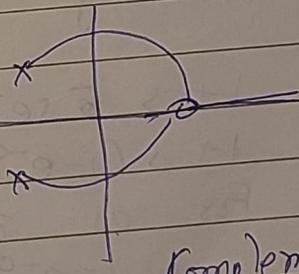
Then it reaches critical damping.

Then over damped. One pole moves towards zero. It gets nullified by the zero thereby changing the system to 1st order

Settling time is proportional inversely proportional to the pole nearer to the imaginary axis

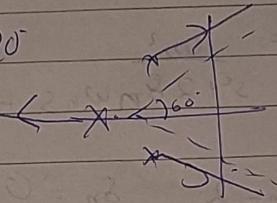
$K_{inc} \rightarrow$ T_s dec till critical time, then increases, until pole is cancelled by zero,

b) On increasing k , the settling time inc till the poles reach imaginary axis, and then it oscillates infinitely; after that it is unstable



complementary root locus

c) 3 poles, each asymptote at 120°



the poles go from to
imaginary and then to
RHP to become constab
if p

d) if p_3 moves further left, the median inc,
angle remaining same the intersection of
poles at imaginary axis increases increasing
the frequency of oscillations

Q2)

$$1 + s + se^{-s} = 0$$

assume s to be $\sigma + j\omega$

$$1 + s + se^{-\sigma} e^{-j\omega} = 0$$

$$|e^{-j\omega}| = 1 \text{ and } e^{-j\omega} \text{ can be at } -1$$

assuming $e^{-j\omega}$ to be -1

$$1 + s + se^{-\sigma} = 0 \quad \text{for real part}$$

$$1 + s(1 - e^{-\sigma}) = 0 \Rightarrow 1 + \sigma(1 - e^{-\sigma})$$

For σ as zero in RHP $\sigma > 0$

$1 - e^{-\sigma}$ is always +ve

$\sigma(1 - e^{-\sigma})$ is always +ve

∴ No zero in RHP

b) $p(s) = (2 \cdot 04 + 6q_1 + 6q_2 + 2q_1q_2)s + (2+q_1+q_2)s^2 + s^3$

$$\begin{aligned} s^3 & 1 & 2+q_1+q_2 \\ s^2 & 2+q_1+q_2 & 2 \cdot 04 + 6q_1 + 6q_2 + 2q_1q_2 \\ s & 4+q_1^2+q_2^2 + 2q_1q_2 + 4q_1 + 6q_2 - 2 \cdot 04 - 6q_1 - 6q_2 - 2q_1q_2 \\ s^0 & 1 \cdot 96 + q_1^2 + q_2^2 - 2q_1 - 2q_2 \\ & (q_1 - 1)^2 + (q_2 - 1)^2 = 0.04 \\ s^0 & 2q_1q_2 + 6q_1 + 6q_2 + 2 \cdot 04 \end{aligned}$$

For stability

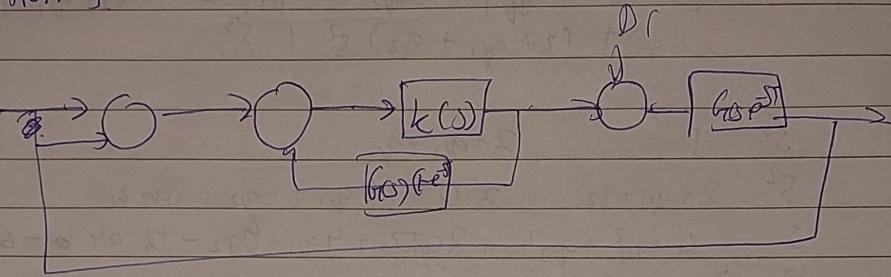
$$2+q_1+q_2 > 0$$

$$2q_1q_2 + 3q_1 + 3q_2 + 9 > 15.96$$

$$(q_1 + 3)(q_2 + 3) > 7.98$$

Question 4)

a)



$$Y(s) = R(s) \frac{k(G(s)e^{-sT})}{1 + kG(1 - e^{-sT})}$$

$$1 + k \frac{G(s)e^{-sT}}{1 + kG(1 - e^{-sT})}$$

$$\text{at } D(s) \frac{G(s)e^{-sT}}{1 + kG(s)e^{-sT}}$$

$$\frac{1 + kG(s)e^{-sT}}{1 + kG(1 - e^{-sT})}$$

$$X(s) = R(s) \frac{kG e^{-sT}}{1 + kG} + D(s) \frac{G s e^{-sT} (1 + kG(1 - e^{-sT}))}{1 + kG}$$

$$\lim_{s \rightarrow 0} \left\{ X(s) - R(s) \frac{kG e^{-sT}}{1 + kG} \right\} = 0$$

$$\lim_{s \rightarrow 0} 1 - \frac{kG e^{-sT}}{1 + kG}$$

$$\lim_{s \rightarrow 0} 1 - \frac{(s k_p + k_i) G e^{-sT}}{s + (s k_p + k_i) G} \approx 1 - 1 = 0$$

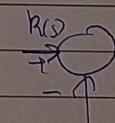
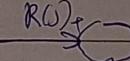
$\lim_{s \rightarrow 0}$

$\lim_{s \rightarrow 0}$

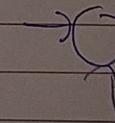
$\lim_{s \rightarrow 0}$

If will no

b)



$Y(s) =$



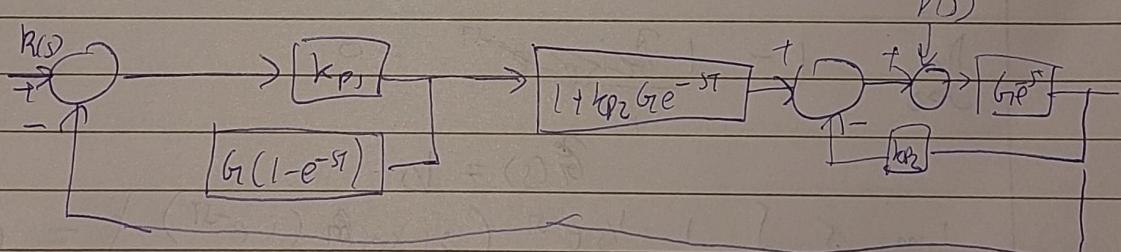
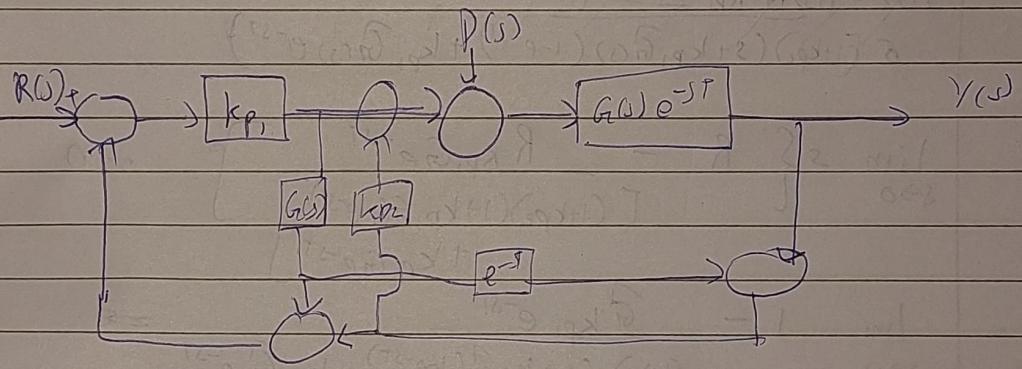
$$\lim_{s \rightarrow 0} \frac{G e^{-sT} (1 + k_G(1 - e^{-sT}))}{1 + k_G}$$

$$\lim_{s \rightarrow 0} \frac{G e^{-sT} (s + (s k_p + k_i) G (sT - (sT)^3 \dots))}{s + (s k_p + k_i) G}$$

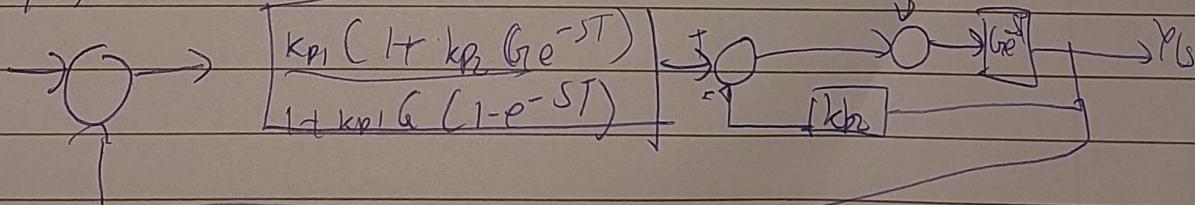
$$\lim_{s \rightarrow 0} \frac{s G e^{-sT} (1 + (s k_p + k_i) G (T - \frac{1}{3} F^2 \dots))}{s + (s k_p + k_i) G} = 0$$

If it will not work for G of type I

b)



$Y(s) =$



$$Y = \frac{R - Y}{1 + k_{p_2}} \frac{k_{p_1} G e^{-sT}}{(1 + k_{p_1} G(1 - e^{-sT}))} + \frac{D G e^{-sT}}{1 + k_{p_2}}$$

$$Y(s) = \left\{ 1 + \frac{k_{p_1} G e^{-sT}}{(1 + k_{p_2})(1 + k_{p_1} G(1 - e^{-sT}))} \right\} = \frac{R k_{p_1} G e^{-sT}}{(1 + k_{p_2})(1 + k_{p_1} G(1 - e^{-sT}))}$$

$$+ \frac{D G e^{-sT}}{1 + k_{p_2} G e^{-sT}}$$

$$Y(s) = \frac{R k_{p_1} G e^{-sT}}{\left[(1 + k_{p_2})(1 + k_{p_1} G(1 - e^{-sT})) + k_{p_1} G e^{-sT} \right]} + \frac{D G e^{-sT} (1 + k_{p_2}) (1 + k_{p_1} G(1 - e^{-sT}))}{(1 + k_{p_2} G e^{-sT}) \left[(1 + k_{p_2})(1 + k_{p_1} G(1 - e^{-sT})) + k_{p_1} G e^{-sT} \right]}$$

$$Y(s) = R \cancel{k_{p_1} G} e^{-sT} \cancel{\left[(1 + k_{p_2})(1 + k_{p_1} G(1 - e^{-sT})) + k_{p_1} G e^{-sT} \right]}$$

$$\lim_{s \rightarrow 0} s \left\{ R - \frac{R k_{p_1} G e^{-sT}}{\left[(1 + k_{p_2})(1 + k_{p_1} G(1 - e^{-sT})) + k_{p_1} G e^{-sT} \right]} \right\} = 0$$

$$\lim_{s \rightarrow 0} 1 - \frac{G k_{p_1} e^{-sT}}{\left[(1 + k_{p_2})(1 + k_{p_1} G(1 - e^{-sT})) + k_{p_1} G e^{-sT} \right]} = 0$$

~~$$\lim_{s \rightarrow 0} 1 - \frac{G k_{p_1} e^{-sT}}{\left[(1 + k_{p_2})(1 + k_{p_1} G(1 - e^{-sT})) + k_{p_1} G e^{-sT} \right]} = 0$$~~

$$\lim_{s \rightarrow 0} s \left\{ \frac{1}{s} \left[s e^{-sT} \left(s + k_{p_1} G(1 - e^{-sT}) \right) \right] \right\} = 0$$