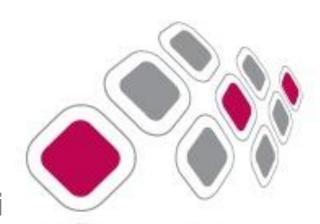


HLS AXI master and Yocto kernel device driver module for Zynq

A complete flow example



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Agenda



- The need for Axi master
- A template for multiple applications
- # HLS Axi master project
- Vivado IPIntegrator project
- Yocto Kernel Module
- Demo

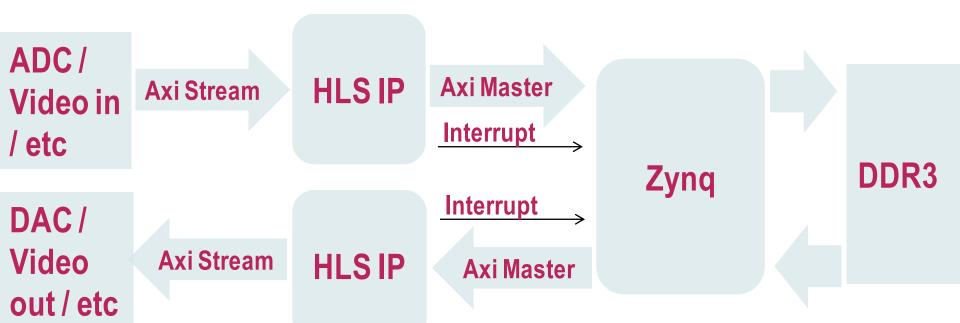
The need for Axi master



- Frequent request from customers
- Axi master allows a data elaboration flow in parallel to CortexA9
 - Video acquisition to memory / Video output from memory
 - ADC data acquisiton to memory / DAC output driving from memory
 - Data filtering / elaboration on the fly or directly on memory
- Need a sync method to coordinate with CortexA9
 - Interrupt generation / handling
- Sw Device Driver recommended

A template for multiple applications

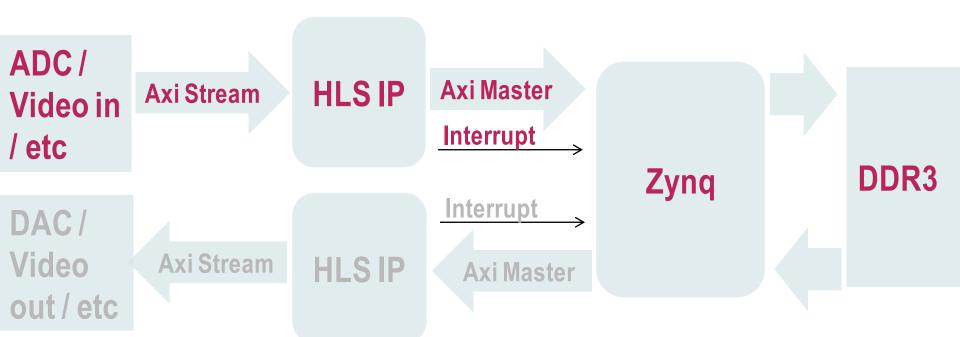




A template for multiple applications



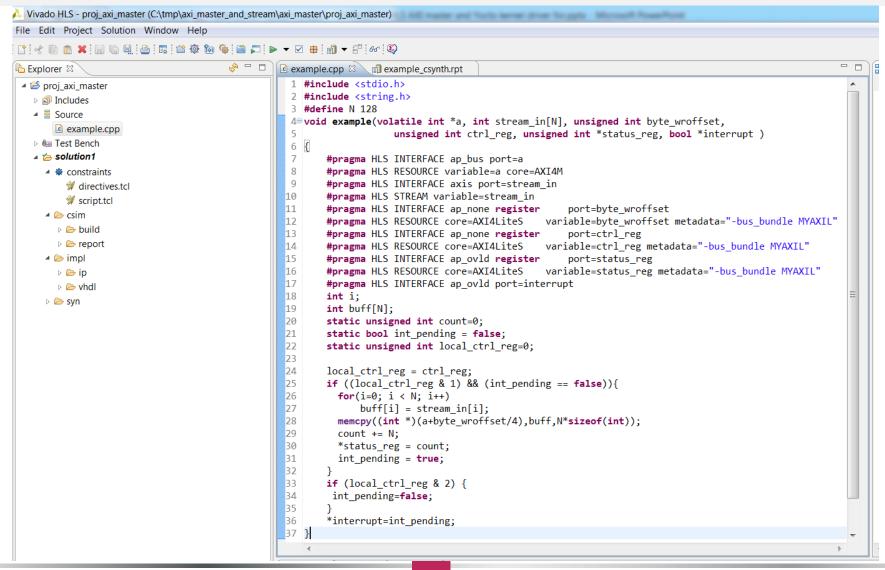
What is available now



HLS Axi master project



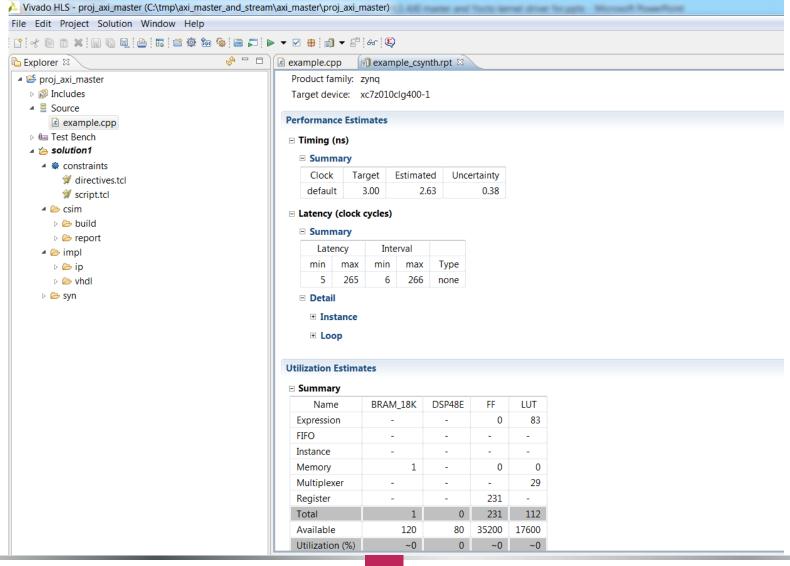
The ANSIC source code



HLS Axi master project



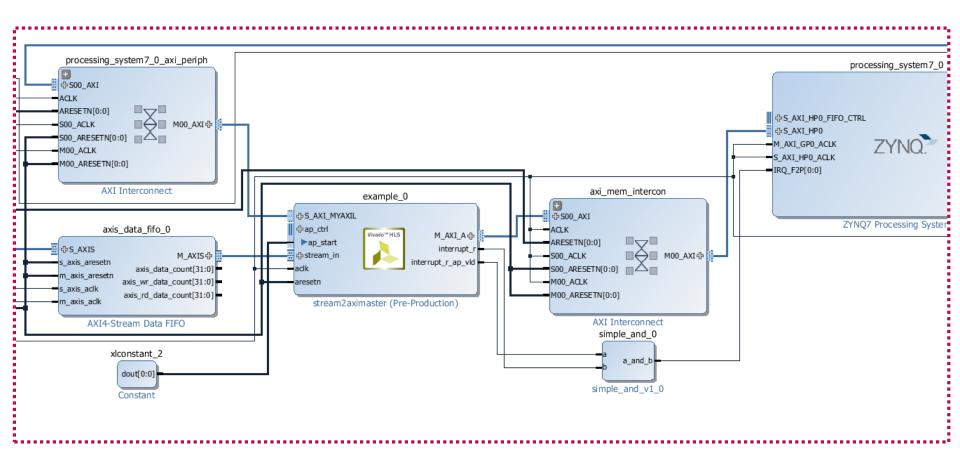
HLS compilation to VHDL (/Verilog) => 333Mhz estimated IP clock



Vivado IPIntegrator project



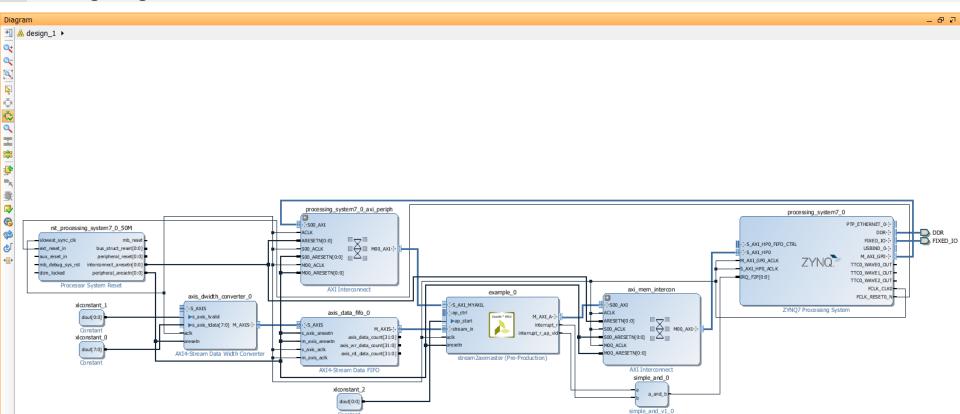
Targeting Microzed board



Vivado IPIntegrator project



Targeting Microzed board





A code sample to start from

- There is a lack of complete flow (HLS->Vivado->Linux->Yocto->Zynq eval board) on Web resources
- The supplied driver is
 - A Linux Kernel Module (vs User Space approach)
 - Simplified, bare minimal to addess open/read/write/close and single interrupt
 - Provided as Yocto recipe
 - Added to the same Architech VM used for Yocto trainings
 - Tested on Microzed



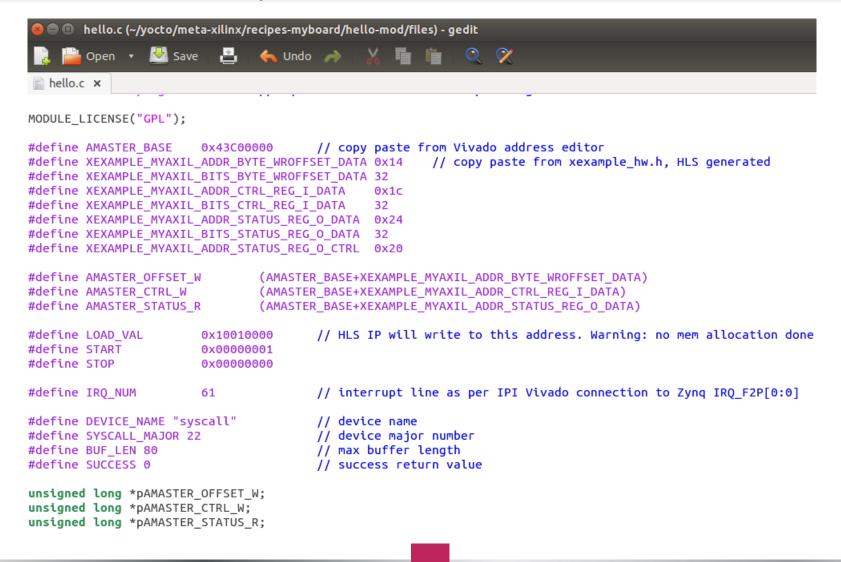
A code sample to start from

The supplied driver is NOT

- Using Device Tree model
 - It will map to a fixed 22 major number device, easier to read
 - A Device Tree based version will be available later
- Allocating dynamic kernel memory
 - It will write to absolute address 0x1001 0000, easier to read, must instruct kernel to avoid this memory area at boot time
 - It's the right approach when big memory space is required
 - A dynamic allocation version will be available later
- Including the header files automatically generated by HLS/Vivado
 - Registers and interrupt are hard coded in the source code
 - Easier to read, a cleaner version will be available later



Addresses, offsets, interrupt number definition





Write syscall: allow to enable/disable interrupt generation from HLS IP

```
🔊 🖨 🗊 hello.c (~/yocto/meta-xilinx/recipes-myboard/hello-mod/files) - gedit
       Open 🔻 🔼 Save 💾
                              ← Undo →
hello.c x
// write routine (called when write() is used in user-space)
ssize_t syscall_write(struct file *flip, const char *buf, size_t length, loff_t *offset)
        printk("syscall write.\n");
                                                                 // debug: procedure call message
        if (length > BUF LEN)
                        length = BUF LEN;
                        printk ("length cut to %d \n", BUF LEN);
        if (copy from user(msg, buf, length) != 0)
                                                                // read buffer from user space
                                                                 // return error if it failed
                return -EFAULT;
        printk("Received: %s \n",msg);
                                                                 // debug: what string is received
        if (msg[0] == '1') //(strcmp(msg,"1") == 0)
                                                                                 // enable IP interrupt
                printk("Driver enables master.\n");
                iowrite32(LOAD_VAL,pAMASTER_OFFSET_W);
                iowrite32(START,pAMASTER_CTRL_W);
                return length;
        else if (msq[0] == '0') // (strcmp(msq,"0") == 0)
                                                                                         // disable IP interrupt
                printk("Driver disables master.\n");
                iowrite32(STOP,pAMASTER CTRL W);
                return length;
        else
                printk("Driver received wrong value.\n");
                                                                 // Print error message
                return - EFAULT:
                                                                 // unknown value received
                                                                                         C ▼ Tab Width: 8 ▼
                                                                                                              Ln 29, Col 1
```



Read syscall: return total write transactions done by HLS IP to memory

```
// read routine (called when read() is used in user-space)
ssize t syscall read(struct file *flip, char *buf, size t length, loff t *offset)
        unsigned long tval:
        unsigned int msq len;
        // read status value
        printk("syscall read.\n");
                                                                // debug: procedure call message
        tval = ioread32(pAMASTER STATUS R);
                                                                // read status register from HLS IP = transactions count
        printk("Read() call value : %lu Cycles\n",tval);
                                                                // display status register value
        printk("length=%d\n",length);
        sprintf(msg,"%d",tval);
                                                                //return tval as a string
        msg_len=strlen(msg);
        if (length < msg_len)</pre>
                msq len = length;
         * If file position is non-zero, then assume the string has
         * been read and indicate there is no more data to be read.
        if (*offset != 0)
                return 0:
        * Tell the user how much data we wrote.
        *offset = msg_len;
        if (copy_to_user(buf, &msg, msg_len) != 0)
                                                              // send counter value
                return -EFAULT;
        else
                return msq len:
```



Irq handler routine: clear HLS IP pending interrupt and disable it after 100 calls

```
hello.c (~/yocto/meta-xilinx/recipes-myboard/hello-mod/files) - gedit
                                 👆 Undo 🧀
 🖺 hello.c 🗴
// interrupt handler
static irgreturn_t irg_handler(int irg,void*dev_id)
        unsigned long temp;
        unsigned long statusvalue;
        statusvalue = ioread32(pAMASTER STATUS R);
        printk("Interrupt! Status counter value : %lu Cycles\n",statusvalue );
        iowrite32(2 ,pAMASTER_CTRL W); //clear int while int gen disabled
        intcount++:
                                                                  // after 100 interrupts
        if (intcount>=100)
        {
                printk("100 interrupts have been registered.\nDisabling master");// print status message
                iowrite32(STOP,pAMASTER_CTRL_W);
        else
                iowrite32(START,pAMASTER_CTRL_W);
        return IRQ HANDLED;
```



Module init:link ISR to interrupt, map IP registers, write dest address and create device num. 22

```
🔊 🖨 🗊 hello.c (~/yocto/meta-xilinx/recipes-myboard/hello-mod/files) - gedit
                Save Save
                                ← Undo →
🖺 hello.c 🗙
static int __init mod_init(void)
        unsigned long temp;
        printk(KERN ERR "Init syscall module. \n");
        if (request irq(IRO NUM,irq handler,IROF DISABLED, DEVICE NAME, NULL)) //request interrupt
                printk(KERN ERR "Not Registered IRO. \n");
                return -EBUSY;
        printk(KERN_ERR "Registered IRQ. \n");
        pAMASTER STATUS R = ioremap nocache(AMASTER STATUS R.0x4);
        pAMASTER OFFSET W = ioremap nocache(AMASTER OFFSET W.0x4);
        pAMASTER CTRL W = ioremap nocache(AMASTER CTRL W, 0x4);
        iowrite32(LOAD_VAL,pAMASTER_OFFSET_W);
        iowrite32(START,pAMASTER CTRL W):
                                                 //uncomment for HLS IP transations autostart
        intcount = 0;
                                                         // set interrupt count to 0, driver will unload on 100 interrupts
        /* => to be completed, allocation of memory, Here's the allocation of a single quantum */
               if (! PAGE_SIZE<<log2()) {</pre>
            dptr->data[s_pos] =
              (void *)__get_free_pages(GFP_KERNEL, dptr->order);
            if (!dptr->data[s pos])
                goto nomem:
            memset(dptr->data[s_pos], 0, PAGE_SIZE << dptr->order);
        // manual node creation => easier to understand, but in future adopt device tree model
        if (register chrdev(SYSCALL MAJOR, DEVICE NAME, &syscall fops))
                printk("Error: cannot register to major device 22.\n");
        if (irq_set_irq_type(IRQ_NUM, IRQ_TYPE_EDGE_RISING))
                printk("Error: cannot enable rising edged on interrupt %d\n",IRO_NUM);
        else
                printk("Rising edge enabled on interrupt %d\n".IRO NUM):
        printk("Type: mknod /dev/%s c %d 0\n",DEVICE_NAME, SYSCALL_MAJOR);
        printk("And remove it after unloading the module.\n");
        return SUCCESS;
                                                                                         C * Tab Width: 8 *
                                                                                                              Ln 169, Col 51
```



Recompiling hello-mod recipe

bitbake hello-mod

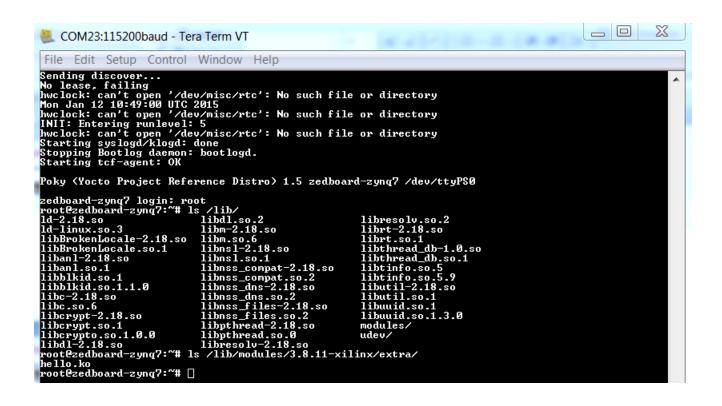
 Will create \$HOME/yocto/build/tmp/sysroots/zedboardzynq7/lib/modules/3.8.11-xilinx/extra/hello.ko

bitbake core-image-minimal

 Will create the sysroot image containing the hello.ko module at /lib/modules/3.8.11-xilinx/extra

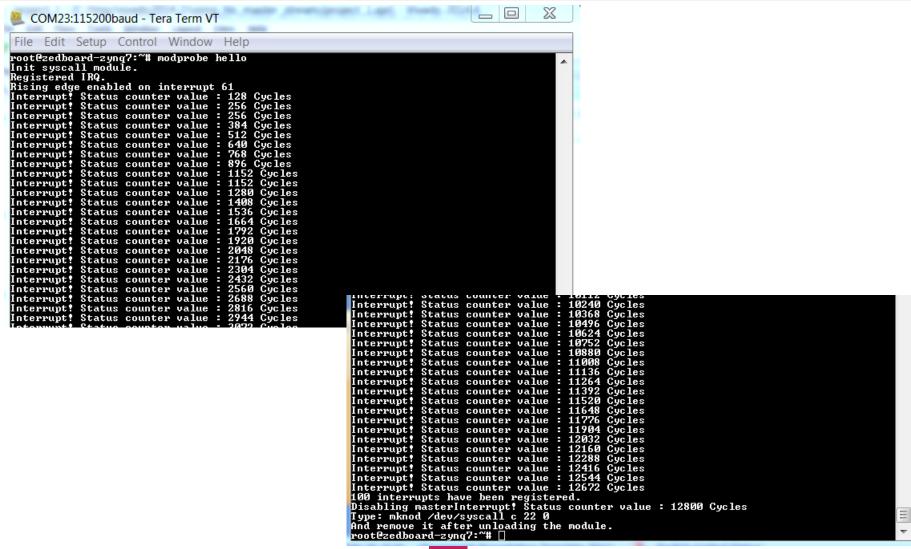


Microzed: Architech Yocto booting from SD card, kernel module already included by recipe





Microzed: loading kernel module, the IP transactions and interrupt generation are triggered





Microzed: making node and sending '1' to re-trigger 128 transactions and interrupt IP

```
root@zedboard-zynq7:~# mknod /dev/syscall c 22 0
root@zedboard-zynq7:~# echo 1 > /dev/syscall
syscall_write.
Received: 1
u tried to open the syscall module.

Driver enables master.
Interrupt! Status counter value : 12928 Cycles
100 interrupts have been registered.
Disabling master
```

```
Disabling masterroot@zedboard-zyng7:~# echo 1 > /dev/syscall
syscall write.
Received: 1
u tried to open the syscall module.
Driver enables master.
Interrupt! Status counter value : 13056 Cycles
100 interrupts have been registered.
Disabling masterInterrupt! Štatus counter value : 13056 Cycles
100 interrupts have been registered.
Disabling masterroot@zedboard-zyng7:~# echo 1 > /dev/syscall
syscall_write.
Received: 1
u tried to open the syscall module.
Driver enables master.
Interrupt! Status counter value : 13184 Cycles
100 interrupts have been registered.
Disabling masterroot@zedboard-zyng7:~# Interrupt! Status counter value : 13184 Cycles
100 interrupts have been registered.
Disabling master∏
```



Microzed: making sure expected addresses have been written

- The HLS IP has been sw initialized to write DDR from address 0x10010000
- When triggered, the IP will write N=128 words (=32bit) from Axi Stream to DDR
- The Axi Stream is fed by a const value, 0xCA = 0xb11001010
- We expect address range 0x10010000 0x100101FF filled by 0xCA
- We'll use rwmem utility (see Architech Yocto Training) to dump absolute memory address

```
root@zedboard-zynq7:"#
root@zedboard-zynq7:"# rwmem 0x10010000
0x000000010010000 = 0xcacacac
root@zedboard-zynq7:"# rwmem 0x100101f0
0x0000000100101f0 = 0xcacacaca
root@zedboard-zynq7:"# rwmem 0x10010200
0x000000010010200 = 0xf77ffdff
root@zedboard-zynq7:"# []
```