

# Technical breakdown of position based fluid

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This paper will implement a parallel version of Position Based Fluids (PBF) method [Miles Macklin et al. 2013] for real-time fluid simulation and discuss the effects of different confinement in the original paper. Compare to BPF, the widely used Lagrangian methods often sacrifice the incompressibility of fluids for better performance, which cause the result to be inaccurate compare to the behavior of real fluids. To address this issue, PBF method numerically integrate quantities from the neighbouring particles with a smoothing kernel to calculate displacement while enforcing the incompressible constraint of fluid for the Navier-Stokes equations. This paper uses CUDA framework in our implementation to achieve real-time, accurate result.

CCS Concepts: • **Computer methodologies** → **Physical simulation**.

Additional Key Words and Phrases: Fluids, Physically Based Animation

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## 1 INTRODUCTION

Fluids such as water or gases, has played a important role in the field of computer based physical animations. Although fluid may look simple, but they are much more complicate to simulate than solids. The motion of fluids are governed by the Navier-Stokes equations. The solutions of the Navier-Stokes equations often include turbulence which makes finding a analytical solution extremely hard in three dimensions. Although countless efforts are put into this field, the progress is still limited. Currently numerical simulation remains the most effective way to approximate a complex Navier-Stokes systems. In this report, we'll breakdown the Position based method and discuss the significans and effects of all the constraint it proposed. In positioned based fluid, fluids are divided into particles and then compute the interactions between the fluid particles such as density and viscosity confinement, combine with external forces, we then update the velocities and positions of the fluid particle. To optimize for better performance,

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we divided the simulation spaces into grids so that particles only interact with other particles in the neighbouring grid.

## 2 RELATE WORK

According to simulation method, algorithm can generally be divide to two different categories: Euler and Lagrangian methods. Euler methods split the space into grids and uses finite differential method to evaluate the model. One of the example is Stam's stable fluid [Stam 1999]. The Lagrangian methods divide the fluid into free particles under constraints. One of the most known method of this kind is the SPH method [Smoothed Particle Hydrodynamics]. Both category has its own drawbacks: Euler methods easily effected by numerical dissipation during simulation and Lagrangian methods needs smaller steps each iteration to ensure the stability of the algorithm. Current fluid simulation methods such as Position Based Fluid methods uses a hybrid of both method to achieve high level of accuracy while having reasonable performance.

## 3 PBF METHOD

For any arbitrary fluid, its motion is governed by the Navier-Stokes equation:

$$\rho \frac{\partial \mathbf{v}}{\partial t} = \rho \mathbf{g} - \nabla p + \mu \nabla^2 \mathbf{v} \quad (1)$$

where  $\rho$  is the density of the fluid,  $\mu$  is the viscosity constant of the fluid,  $p$  is the pressure and  $\mathbf{v}$  denote the velocity. However, the above equation does not satisfy the incompressible property of fluids, so an additional constraints needs to be added:

$$\nabla \cdot \mathbf{v} = 0 \quad (2)$$

In PBF method, we represent the fluid with  $N$  particles, and their positions is denote as  $\mathbf{P} = \{\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_2\}$ .

### 3.1 Density confinement

Since we are simulating a fluid, we have to satisfy the incompressible property of the fluid. Instead of satisfying equation (2) directly, BPF uses density constraint to satisfy the requirement:

$$C_i(\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_2) = \frac{\rho_i}{\rho_0} - 1 \quad (3)$$

Where  $\rho_0$  is the rest density of the fluid and  $\rho_i$  is given by the standard SPH estimator:

$$\rho_i = \sum_j m_j W(\mathbf{p}_i - \mathbf{p}_j, h) \quad (4)$$

where  $m_j$  is the mass of the neighboring particles and  $W$  is the poly6 smoothing kernel as given in [Müller et al. 2003]. In this paper, we assume all the particles have a mass of 1. Since a fluid is incompressible, intuitively this means that

the density for any given part of the fluid should equal to the rest density of the fluid, which means the result of (3) should be equal to zero at all time:

$$C_i(\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_2) = 0 \quad (5)$$

Furthurmore, when there is an displacement in the fluid particle, the density should also reamins the same, this property is statisfied through the following constraint:

$$C(\mathbf{p} + \Delta\mathbf{p}) = 0 \quad (6)$$

We can estimate a proper  $d\Delta p$  equation (6) with Newton steps along the gradient of equation(5):

$$\Delta p = \nabla C(\mathbf{p})\lambda \quad (7)$$

And we can approximate the value of equation (6) with linear approximation:

$$C(\mathbf{p} + \Delta\mathbf{p}) \approx C(\mathbf{p}) + \nabla C^T \nabla C \lambda \quad (8)$$

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Table 1. Frequency of Special Characters

Non-English or Math	Frequency	Comments
Ø	1 in 1,000	For Swedish names
π	1 in 5	Common in math
\$	4 in 5	Used in business
Ψ <sub>1</sub> <sup>2</sup>	1 in 40,000	Unexplained usage

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Your work should use standard L<sup>A</sup>T<sub>E</sub>X sectioning commands: **section**, **subsection**, **subsubsection**, and **paragraph**. They should be numbered; do not remove the numbering from the commands.

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Immediately following this sentence is the point at which Table ?? is included in the input file; compare the placement of the table here with the table in the printed output of this document.

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Always use **midrule** to separate table header rows from data rows, and use it only for this purpose. This enables assistive technologies to recognise table headers and support their users in navigating tables more easily.

Table 2. Some Typical Commands

Command	A Number	Comments
<code>\author</code>	100	Author
<code>\table</code>	300	For tables
<code>\table*</code>	400	For wider tables

## 8 MATH EQUATIONS

You may want to display math equations in three distinct styles: inline, numbered or non-numbered display. Each of the three are discussed in the next sections.

### 8.1 Inline (In-text) Equations

A formula that appears in the running text is called an inline or in-text formula. It is produced by the `math` environment, which can be invoked with the usual `\begin... \end` construction or with the short form `$...$`. You can use any of the symbols and structures, from  $\alpha$  to  $\omega$ , available in L<sup>A</sup>T<sub>E</sub>X [?]; this section will simply show a few examples of in-text equations in context. Notice how this equation:  $\lim_{n \rightarrow \infty} x = 0$ , set here in in-line math style, looks slightly different when set in display style. (See next section).

### 8.2 Display Equations

A numbered display equation—one set off by vertical space from the text and centered horizontally—is produced by the `equation` environment. An unnumbered display equation is produced by the `displaymath` environment.

Again, in either environment, you can use any of the symbols and structures available in L<sup>A</sup>T<sub>E</sub>X; this section will just give a couple of examples of display equations in context. First, consider the equation, shown as an inline equation above:

$$\lim_{n \rightarrow \infty} x = 0 \quad (9)$$

Notice how it is formatted somewhat differently in the `displaymath` environment. Now, we'll enter an unnumbered equation:

$$\sum_{i=0}^{\infty} x + 1$$

and follow it with another numbered equation:

$$\sum_{i=0}^{\infty} x_i = \int_0^{\pi+2} f \quad (10)$$

just to demonstrate L<sup>A</sup>T<sub>E</sub>X's able handling of numbering.

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```
\begin{teaserfigure}
\includegraphics[width=\textwidth]{sampleteaser}
\caption{figure caption}
\Description{figure description}
\end{teaserfigure}
```

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```
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```

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```
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```

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## 11 ACKNOWLEDGMENTS

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This section has a special environment:

```
\begin{acks}
...
\end{acks}
```

so that the information contained therein can be more easily collected during the article metadata extraction phase, and to ensure consistency in the spelling of the section heading.

Authors should not prepare this section as a numbered or unnumbered `\section`; please use the “acks” environment.

## 12 APPENDICES

If your work needs an appendix, add it before the “`\end{document}`” command at the conclusion of your source document.

Start the appendix with the “appendix” command:

```
\appendix
```

and note that in the appendix, sections are lettered, not numbered. This document has two appendices, demonstrating the section and subsection identification method.

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The “sigchi-a” template style (available only in  $\text{\LaTeX}$  and not in Word) produces a landscape-orientation formatted article, with a wide left margin. Three environments are available for use with the “sigchi-a” template style, and produce formatted output in the margin:

- **sidebar**: Place formatted text in the margin.
- **marginfigure**: Place a figure in the margin.
- **marginable**: Place a table in the margin.

## ACKNOWLEDGMENTS

To Robert, for the bagels and explaining CMYK and color spaces.

## A RESEARCH METHODS

### A.1 Part One

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### A.2 Part Two

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