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/*
 * lab6Demo.c
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 *
 * MCU backend for Lab 6. Generates webpages as requested by the ESP8266, and
 * interfaces with the onboard PIO and ADC peripherals to allow user control of
 * an LED and to display the voltage on ADC channel 2.
 *
 * The LED on PA17 is controlled by the webpage, active low
 * The LED on PA18 is active when the webpage is transmitted to the ESP8266
 * from the MCU
 *
 * In more detail:
 * 1) The MCU initializes peripherals
 * 2) The MCU loads any incoming bytes from UART into a buffer, and scans for
 * the sequence '< ... >' Held within the angle brackets is the request from the
 * microcontroller. Steps 3-5 are executed if a request is detected
 * 3) The MCU turns on PA17 if 'on' is within the request, and turns off PA17
 * if 'off' is within the request
 * 4) The MCU reads the CH2 ADC voltage
 * 5) The MCU generates and sends the webpage to the ESP8266 over UART
 */

#include "easySamIO.h" //peripheral header file
#include <string.h> //string operations for parsing incoming requests
#include <stdio.h> //float -> string conversion for ADC
#define LED_PIN 17 //LED controlled by webpage. Active low
#define TRANSMIT_PIN 18 //LED indicated webpage transmission. Active low
#define VOLTAGE_CHARS_TO_TRANSMIT 5 //The number of characters in the string
representation of the CH2 voltage to transmit as a part of the webpage

//The webpage is separated into a 'start' and 'end' section. These sandwich the
CH2 voltage, which is inserted between the two webpage arrays. The webpage is
raw HTML
//Note: as " terminates the string, we escape the " with \". This is
interpreted as the raw character '"' rather than as an escape character
const char* webpageStart = "<!DOCTYPE html><html>\n <head>\n
<title>E155 Web Server Demo Webpage</title>\n </head>\n <body>\n
<h1>E155 Web Server Demo Webpage</h1>\n <p>Current Microcontroller ADC:
</p>\n ";
//ADC CH2 voltage is printed between these
const char* webpageEnd = "\n <p>LED Control:</p>\n <form
action=\"on\">\n <input type=\"submit\" value=\"Turn the LED on!
\" />\n </form>\n <form action=\"off\">\n <input
type=\"submit\" value=\"Turn the LED off!\" />\n </form>\n </
body>\n</html>\n";

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//as we do not dynamically calculate webpage size for the constant start and
end arrays, it is given as constant
const int webpageStartChars = 215;
const int webpageEndChars = 264;

void transmitWebpage() {
    digitalWrite(TRANSMIT_PIN, LOW);
    //first transmitting the initial section of the webpage
    for (int charCount = 0; charCount < webpageStartChars; charCount++) {
        uartTx(webpageStart[charCount]);
        if (webpageStart[charCount] == '\n') {uartTx('\r');} //some
        interpreters want a carriage return and line feed. Adding a carriage
        return if line feed is detected
    }

    //reading the ADC
    float ch2Voltage;
    char ch2VoltageStr[VOLTAGE_CHARS_TO_TRANSMIT];
    ch2Voltage = adcRead(CH2);
    //converting ADC voltage as a float to a string
    snprintf(ch2VoltageStr, VOLTAGE_CHARS_TO_TRANSMIT, "%f", ch2Voltage);
    //Transmitting the voltage string to the webpage. Note: snprintf transmits
    a null terminator as its last character. This breaks many string parsing
    functions, so we do not transmit it.
    for (int charCount = 0; charCount < VOLTAGE_CHARS_TO_TRANSMIT-1; charCount+
        +) {
        uartTx(ch2VoltageStr[charCount]);
    }
    //finally transmitting the final section of the webpage
    for (int charCount = 0; charCount < webpageEndChars; charCount++) {
        uartTx(webpageEnd[charCount]);
        if (webpageEnd[charCount] == '\n') {uartTx('\r');}
    }
    digitalWrite(TRANSMIT_PIN, HIGH);
}

int main(void) {
    /* Initialize the SAM system */
    samInit(); //peripheral initialization. See easySamIO.h
    pinMode(LED_PIN, OUTPUT); //LED_PIN is controlled by the webpage
    digitalWrite(LED_PIN, HIGH);
    pinMode(TRANSMIT_PIN, OUTPUT); //TRANSMIT_PIN is active when a webpage is
    being transmitted
    digitalWrite(TRANSMIT_PIN, HIGH);
    uartInit(4, 25); //initializing the UART with no parity, 9600 baud
    adcInit(ADC_BITS_12); //initializing the ADC with a precision of 12 bits
    adcChannelInit(CH2, ADC_GAIN_X1, ADC_OFFSET_OFF); //initializing channel 2
    of the ADC with no gain or offset
}

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int currentRxState = 0;           //1 when there is an unread byte in
    the UART RX register, 0 otherwise
char character;                  //character read by the UART
char request[14] = "             "; //14-character buffer to store the
    webpage request
int requestFound = 0;           //0 only if '<...>' not in the
    request
int currentRequestChar = 0;      //The number of valid characters in
    request
const char requestStart = 0x3c;  //hex representation of character
    '<'
const char requestEnd = 0x3e;    //hex representation of character
    '>'

transmitWebpage();              //on boot, transmit the webpage.
    This mitigates any potential request - response timing errors on system
    initialization

while (1)
{
    //checking whether there is a byte to read in the UART RX buffer
    currentRxState = UART_REGS->UART_SR.RXRDY;
    //process if there is an unread byte
    if (currentRxState == 1) {
        if(currentRequestChar == 14) {
            //if buffer is filled, wrap to start
            currentRequestChar = 0;
        }
        //read in unread character
        character = uartRx();
        //add character to buffer
        request[currentRequestChar] = character;
        //searching for substring
        int startInString = strchr(request, requestStart); //0 only if '<'
            not in the request
        int endInString = strchr(request, requestEnd); //0 only if '>'
            not in the request
        //if a request start character is past the start of the buffer,
        empty the buffer with the start character in position 0
        if (startInString != 0 && currentRequestChar >= 2 && request[0] !=
            requestStart) { //SHOULD THIS BE >=1??
            request[0] = '<';
            for (int i = 1; i < 14; i++) {
                request[i] = ' ';
            }
            currentRequestChar = 0;
        }
        //if the buffer contains both the start and end characters, then
        the request is loaded. Process the request and return a webpage
    }
}

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    if (startInString != 0 && endInString != 0) {
        int ledOnInString = strstr(request, "on");    //Turn LED on if
        'on' is in the request
        int ledOffInString = strstr(request, "off"); //Turn LED on if
        'off' is in the request
        if(ledOnInString != 0) {
            digitalWrite(LED_PIN, LOW);
        }
        if(ledOffInString != 0) {
            digitalWrite(LED_PIN, HIGH);
        }
        //the request has been processed, and is therefore cleared
        for (int i = 0; i < 14; i++) {
            request[i] = ' ';
        }
        //finally, transmitting the webpage
        transmitWebpage();
    }
    currentRequestChar += 1; //preparing to write in the next buffer
    index
}

}

}

```