

Next Steps for Reproducible Testing and Deployment

“The attempt to rewrite the foundations of mathematics in terms of category theory is evil and wrong.” –Walt Pohl¹

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¹Attribution: (Pohl 2005)

Outline

- 1. Why Nix? Some Arguments.**
2. The Great Nixification. An Overview.
3. Related Research Directions
4. References

1.1 Nix as the Purely Functional, Monadic Build Tool

- Software directly controls hardware

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**We want a way to tell computers how to run software,
and we want software to run the same way on any system, regardless of its
internal state.**

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- Software has dependencies (for compilation, development, and in production), configurations, targets (supported systems), feasibility relations, and a bunch of other stuff we don't know about ("the world")
- Dealing with dependencies is a very serious problem (packages will require conflicting versions of the same package)



Eelco Dolstra, original Nix theorist

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- We have a new package Z that depends on Y but doesn’t care about all this random junk produced in the process of building Y
 - It has a build function that looks like $g : Y \rightarrow FZ$

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 - The so-called “monadic bind”
- We want a **monadic** build system (“The Postmodern Build System” 2023)
- We want **optimized incremental** builds (i.e. the bind operation should be fast and builds should be **pure**)
 - Same input, same output

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 - Distributed builds
 - all systems produce the same binaries

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- Nix is the unique existing build system satisfying both a **reproducibility criterion** and having **high interpretability**

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Figure 1: This is absolutely not true

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- Build twice. Any system, anywhere, any time, any [insert here].
Same result.

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1.2.3 Reproducibility

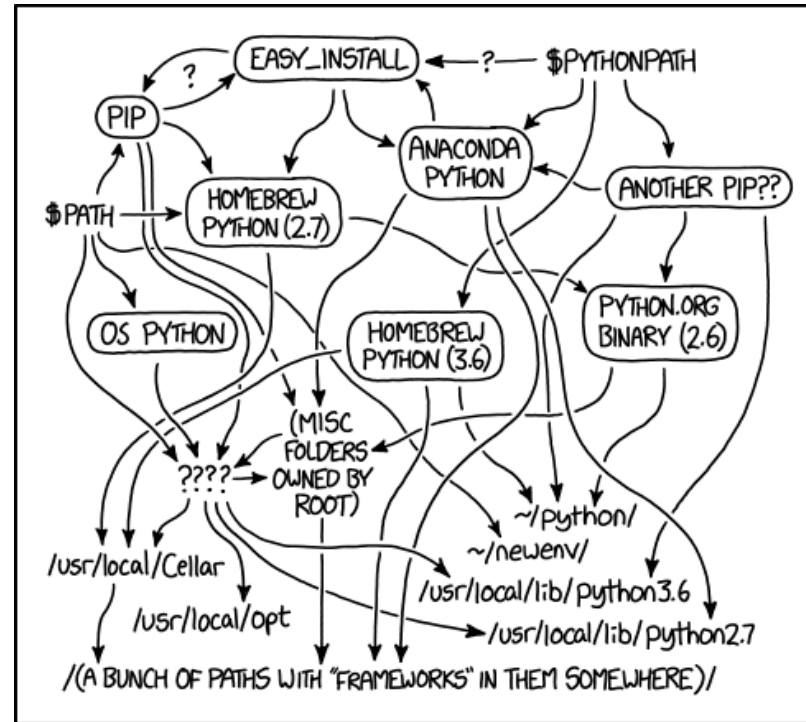
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1.2.4 Reproducibility

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- Build twice. Any system, anywhere, any time, any [insert here].
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 - Critical for OPSEC
- Stuff just works.™

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MY PYTHON ENVIRONMENT HAS BECOME SO DEGRADED
THAT MY LAPTOP HAS BEEN DECLARED A SUPERFUND SITE.

Figure 2: Other so-called "package managers"

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 - About 10x faster compared to the ROS development environment (Purvis and Wanders 2022)

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- Docker is **stateful**, Nix is **stateless**

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1.2.10 Docker

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Reproduce, exactly, the entire system **state** of a working environment

For Arcturus, this isn't even the same as our deployment environment! This is **very bad**!

We don't know **why or how stuff works**, only that it works on a given system.

Equivalently, any change to the system state (Docker configuration) could lead to critical build failures.

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Reproduce, exactly, the minimum set of **components** (packages and related configurations) that define a working environment

We can ask questions like *which packages does this module depend on?* or *why did this new build fail?*

1.3 Nix as the Universal Build Tool

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Nix is often described as a bad implementation of a good theory, mainly because it has actually been implemented and no longer exists in the minds of category theorists

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- Any project, any dependency, any version
- Nix is extensible enough to describe build recipes for a wide variety of projects, and ROS is no exception
- However, ROS uses infamously bad dependency specifications and runtime environments

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- **Non-invasive** (using Nix does not interfere with existing working build environments)
- **Isolated** (self-contained, use it only when you want)
- **Verifiable** (benefit from safe binary caching and reproduce tests on other systems)

2.1 Non-invasive, isolated, and verifiable

Flakes aren't real and cannot hurt you: a guide to using Nix flakes the non-flake way

January 02, 2024 - 26 minute read

Inflammatory title out of the way, let's go.

Figure 1: tl;dr: you should be using Nix already

2.2 Where we are in relation to the literature

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- Clear dependency specifications for each module in the main codebase
- A reproducible testing environment for individual nodes
- Preliminary implementation of a binary cache

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2.2.4 The literature:



Figure 2: Grade A level trolling by Motorsports

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- Presented at ROSCon 2022 (Purvis and Wanders 2022)
- Work undergoing to rewrite [ros2nix](#) in Motorsports
- Failure to keep pace with these developments reduces our research competitiveness, puts our build system in jeopardy of deprecation, and leaves our OPSEC vulnerable to upstream security issues

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 - Will add unit testing and formal verification
- **Gazebo/VRX simulation natively in Nix**

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 - Docking will be a good case study
- Formal verification with Deal
 - Use Haskell or another functional language for rapid theorizing and testing, independent of main codebase
- Fully vision-based autonomous systems
 - Station keeping would make a good R&D study of the feasibility of this

R&D subteam?

3.3 Further Reading

More to come on this in the future...

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This report is entirely open-access and open-source. You are welcome to contribute.

<https://github.com/arcturusNavigation/tdr>

4. References

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Crane, Dana. 2022. “Trust, Security and the Reproducibility Crisis in Software”. February 2022. <https://www.activestate.com/blog/trust-security-and-the-reproducibility-crisis-in-software/>.

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