```
function main(path)
path = strcat(path, '\clustering.csv');
data = load(path);
functionRepeatCount = 15;
acc = zeros(functionRepeatCount,1);
predictions = zeros(functionRepeatCount,200);
% Main loop for different starting points
for k = 1:functionRepeatCount
    [prediction] = KM(data);
    predictions(k,:) = prediction;
    labels = data(:,3);
    errors = (labels ~= prediction);
    errors = sum(errors);
    acc(k,1) = 1 - errors/200;
    [m index] = max(acc);
    bestAccDecisions = predictions(index,:);
end
disp(' ');
disp(' ');
disp(' ');
disp('Accuracy is:');
disp(m);
% Drawing the cluster plot with best accuracy
figure()
prediction = bestAccDecisions;
x = data(prediction==1,1);
y = data(prediction==1,2);
plot(x,y,'g o');
hold on
x1 = data(prediction==2,1);
y1 = data(prediction==2,2);
plot(x1,y1,'r o');
x1 = data(prediction == 1, 1);
y1 = data(prediction == 1, 1);
x2 = data(prediction == 2, 2);
y2 = data(prediction == 2, 2);
c1x = sum(x1,1)./size(x1,1);
cly = sum(y1,1)./size(y1,1);
c2x = sum(x2,1)./size(x2,1);
c2y = sum(y2,1)./size(y2,1);
plot(c1x,c1y, 'b x')
```

```
hold on
plot(c2x,c2y, 'b o')
title('Question 2)B cluster prediction plot')
%Confusion matrix
ConfusionM = zeros(2,2);
for i=1:200
   ConfusionM(labels(i), prediction(i)) =
 ConfusionM(labels(i),prediction(i)) + 1;
disp('Confusion matrix is as follows:');
disp(ConfusionM);
function [decision] = KM(cluster)
x1 = (rand()*20-10).^2;
y1 = sqrt(2)*((rand()*20-10).*(rand()*20-10));
z1 = (rand()*20-10).^2;
x2 = (rand()*20-10).^2;
y2 = sgrt(2)*((rand()*20-10).*(rand()*20-10));
z2 = (rand()*20-10).^2;
center1 = [x1 y1 z1];
center2 = [x2 y2 z2];
clusterKernel = zeros(200,4);
clusterKernel(:,1) = cluster(:,1).^2;
clusterKernel(:,2) = sqrt(2)*(cluster(:,1).*cluster(:,2));
clusterKernel(:,3) = cluster(:,2).^2;
clusterKernel(:,4) = cluster(:,3);
for j = 1:2
     distance1 = sqrt((clusterKernel(:,1)-center1(1)).^2 +
 (clusterKernel(:,2)-center1(2)).^2 + (clusterKernel(:,3)-
center1(3)).^2);
     distance2 = sqrt((clusterKernel(:,1)-center2(1)).^2 +
 (clusterKernel(:,2)-center2(2)).^2 + (clusterKernel(:,3)-
center2(3)).^2);
    decision = zeros(size(distance1,1),1);
    decision(distance1 > distance2) = 1;
    decision(distance1 < distance2) = 2;</pre>
    class1Sum = sum(decision);
    class2Sum = 200 - class1Sum;
    x = find(decision);
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```
class1 = clusterKernel(x,1:3);
    class1 = sum(class1)/class1Sum;
    xx = find(decision==0);
    class2 = clusterKernel(xx,1:3);
    class2 = sum(class2)/class2Sum;
    center1 = class1;
    center2 = class2;
    end
end
end
Accuracy is:
     1
Confusion matrix is as follows:
   100
     0
         100
```



