

# VLSI DESIGN FLOW: RTL TO GDS

Lecture 21  
Technology Library



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# Lecture Plan

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Till now....

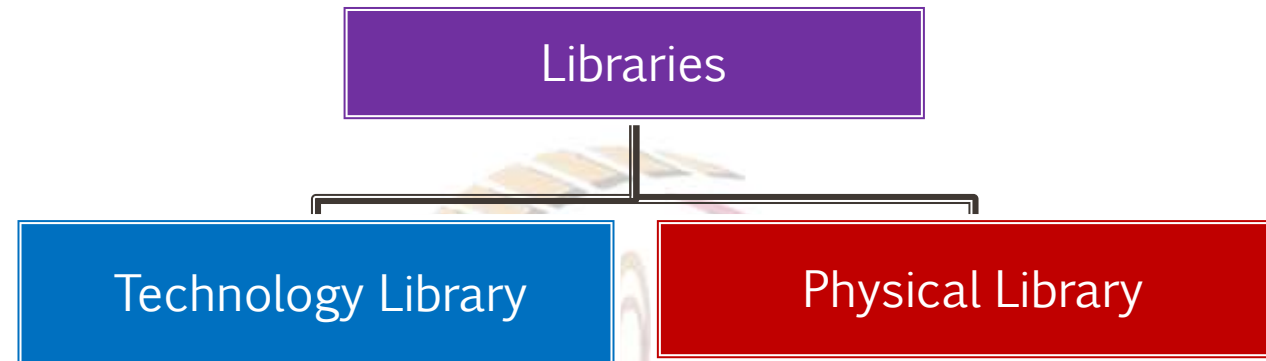
- Logic Synthesis:
  - Transformation of RTL to netlist of generic logic gate
  - Logic optimization

Subsequently ....

- Map generic logic gates to the cells of a given technology library
  - Perform timing analysis and other types of verification
- 
- Need information of the cells contained in a given technology library

# Libraries in VLSI Design Flow

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## Technology Library:

- Introduced for logic synthesis
- Evolved to support various design tasks
  - Timing verification, physical implementation, and test activities
  - Also referred to as timing library.
- Liberty format
  - ASCII files (.lib extension)

## Physical Library:

- Contains abstract information about the layout of the cells and technology.
- Library Exchange Format (LEF)
  - ASCII files (.lef extension)

# Motivation for using Libraries

- Simplifies design task by decomposing the overall design process into two steps:
  - Creating Library
  - Using Library

## Creating Library:

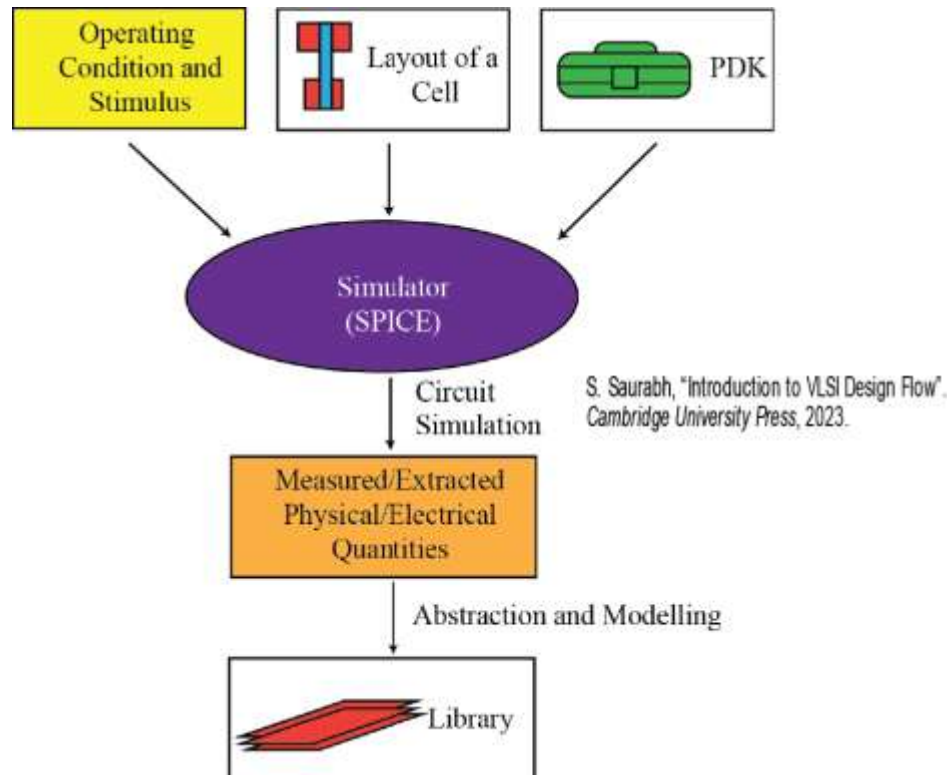
- Design each cell at the transistor level
  - Determine its optimal layout.
- Extract essential information about the cells and write them in the library.
- Many designs can employ the same library
  - Cost of developing a high-quality library gets distributed over multiple designs

## Using Library:

- Instantiate cells from a library to achieve desired functionality
- Allows focusing on their instantiations
  - Design time and effort decrease.
  - Reduce the chances of errors within the cells.
- Raises the abstraction from the transistor level to the cell level
  - Makes complex synthesis, static timing analysis (STA), and physical design tasks feasible

# Library : How are libraries created? (1)

Library Characterization: process of creating the library (at foundry or design house)



- Design each cell optimally and verify
- SPICE simulations of each cells for:
  - Given operating condition and stimulus
  - Transistor model, process (retrieved from PDKs)
- Measure/extract the parameters of interest such as delay, slew, voltage, capacitance, power, etc.
- Build an abstract model and write in the given format

# Library Models

Why are SPICE simulations using PDKs not directly used for delay/power computation?

- SPICE simulations are time taking
  - Differential equations are formulated and typically solved using iterative techniques

## Library models:

- Relevant information from SPICE simulation are extracted and modelled in the library
- EDA tools use library models instead of SPICE simulations for computing delay, slew, power, voltage variations, etc.
  - Order of magnitude faster than SPICE simulation and of reasonable accuracy

## Requirement of library models:

- Speed and Accuracy
- Robustness
- Portability
- Variety and Uniformity:
  - Multiple cells for same function
  - Low Power, High Performance, High Density, Low-VT, High-VT
  - Height uniform, width variable

# Library: Content

- Process parameters, Voltage, Temperature (collectively called PVT conditions)
- Cell data:
  - Pins, functionality
  - Timing, area and power information

- Libraries typically contains cells with hundreds of different logic functions:
  - Combinational/sequential standard cells
  - I/O Pads
  - Memories, macros

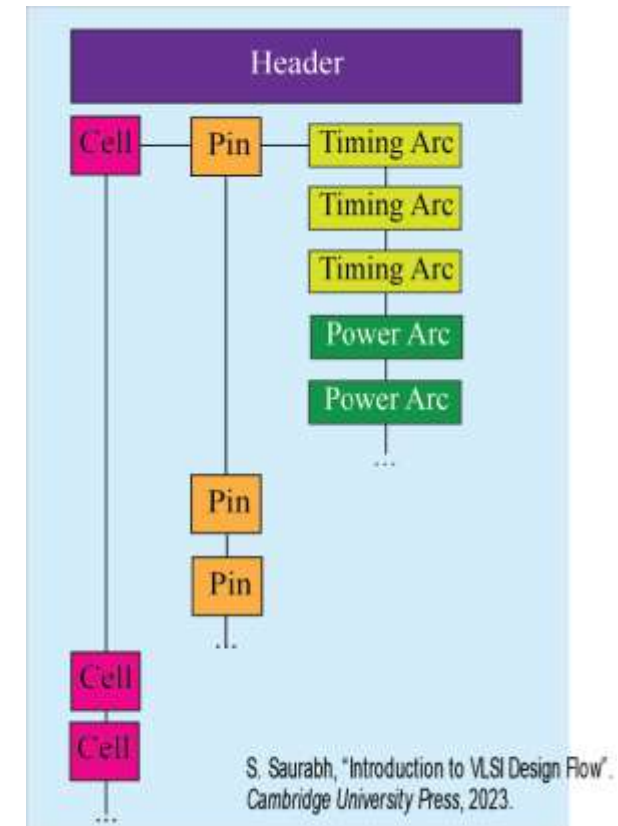
## When do we use libraries?

- Libraries are used throughout RTL to GDS flow
  - Synthesis, timing and power analysis, verification, Design For Test (DFT), physical design



# Library: Liberty format (1)

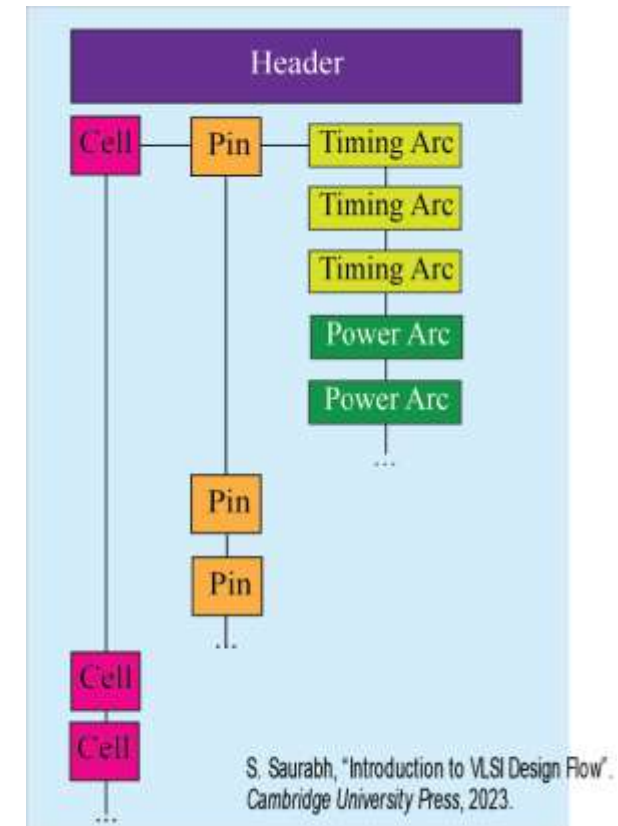
- Liberty format is simple ASCII/text format
- Data is primarily stored as attributes
  - Mapping between an attribute name and its value
  - Example: time\_unit : “10ps”;
- Information is organized as a hierarchy of groups
- At the top level it has a Header
- Header contains:
  - PVT conditions, scaling factors, units
  - Information that are valid for all the cells/pins/arcs
  - List of cells





# Library: Liberty format (2)

- Cell contains:
  - Area
  - Cell Leakage Power
  - List of pins
- Pin contains:
  - Direction
  - Capacitance
  - Functionality (for output pins)
  - List of timing arcs
  - List of power arcs
- Timing arcs are used to perform timing analysis or computing delays of the arcs
- Power arcs are used to perform power analysis



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Technology Library



Modelling Delay

# Library : Timing Arcs

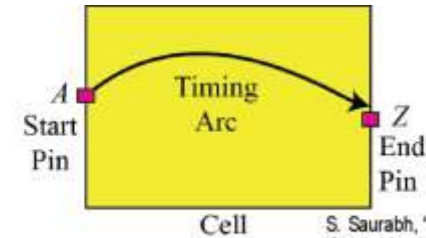
- Timing Arcs are used to model timing attributes for combinational or sequential cells in a library

Each Timing Arc has:

- Start Pin and End Pin
- Timing arc is specified on the End Pin
- Start Pin is specified using the attribute **related\_pin**

Timing Arcs can be of type:

- Delay Arc
- Constraints Arc (setup check, hold check etc.)



S. Saurabh, "Introduction to VLSI Design Flow",  
Cambridge University Press, 2023.

```
pin(Z) {  
    direction      : output ;  
    ...  
    timing() {  
        related_pin : "A" ;  
    }  
    ...  
}
```

# Slew Definition

- Slew of a signal quantifies how steeply or sharply transition occurs from “0”  $\rightarrow$  “1” or “1”  $\rightarrow$  “0”

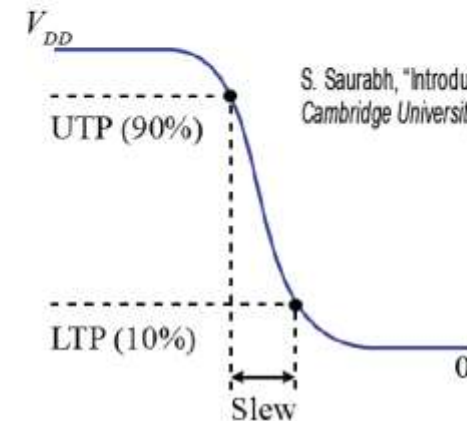
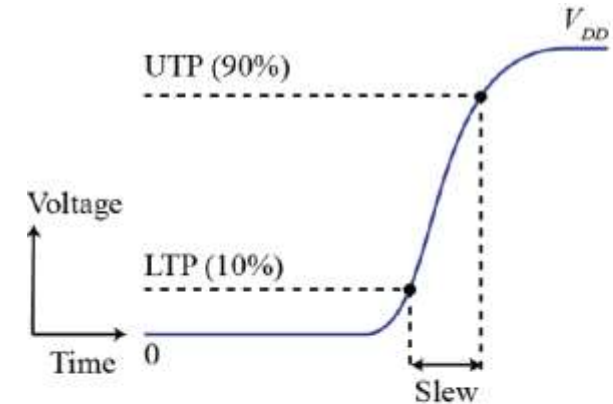
Slew measured by defining two transition points:

- Lower threshold percentage (LTP)
- Upper threshold percentage (UTP)

10-90 Threshold:

- **Rise slew:** time taken for a signal to reach from 10% to 90% of supply voltage
- **Fall slew:** time taken for a signal to reach from 90% to 10% of supply voltage

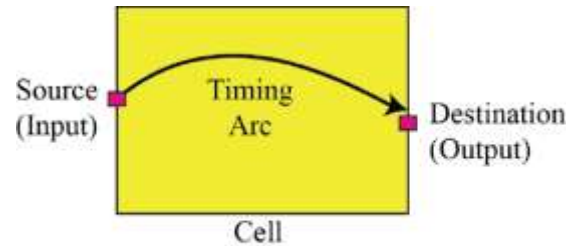
- Slew threshold of 20-80, 30-70 can also be used
- Also called: **rise transition time, fall transition time, rise time, fall time**



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# Delay Definition

- Quantifies how much time it takes for the change in input to propagate to the output



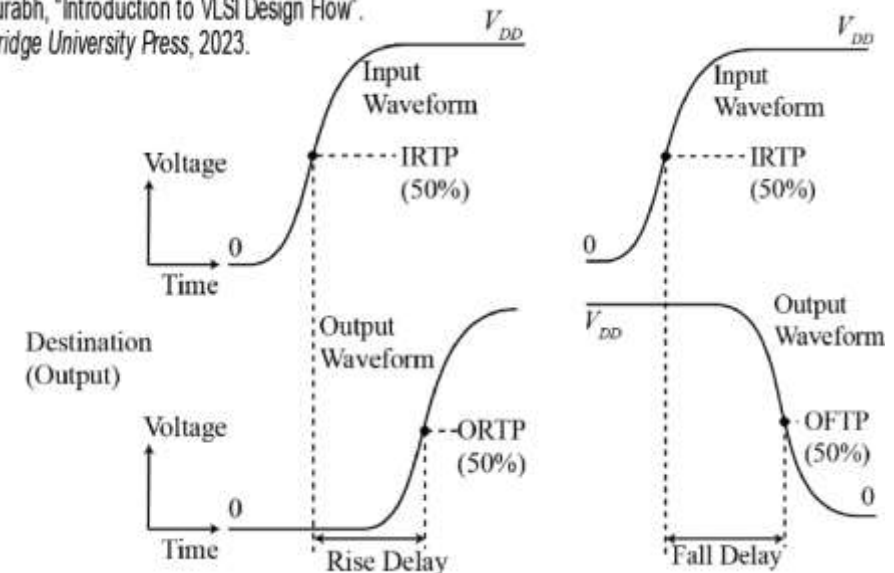
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Delay can depend on the direction of transition (rising/falling)

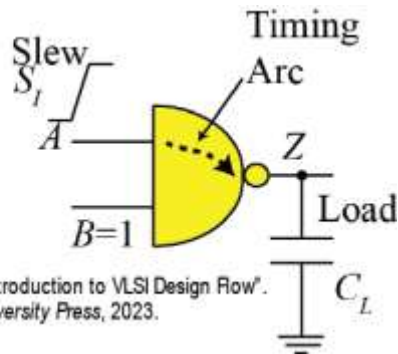
- Rise delay: output rising
- Fall delay: output falling

- Predefined threshold points on the input waveform and the output waveform.
- For the input signal:
  - input rise threshold percentage (IRTP)
  - input fall threshold percentage (IFTP).
- For the output signal:
  - output rise threshold percentage (ORTP)
  - output fall threshold percentage (OFTP)

S. Saurabh, "Introduction to VLSI Design Flow".  
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# CMOS : Characteristics of Slew and Delay



S. Saurabh, "Introduction to VLSI Design Flow".  
Cambridge University Press, 2023.

- Modelled approximately as two dimensional discrete point tables

- In general, the **delay** ( $D$ ) and **output slew** ( $S_{OUT}$ ) of a given **timing arc** depend on:
  - Input Slew ( $S_{IN}$ )
  - Output Load ( $C_L$ )

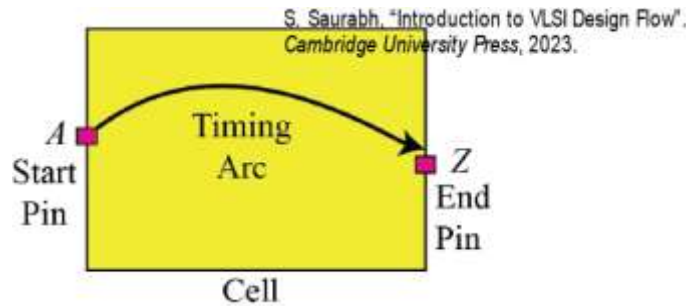
- The relationship may be non-linear:
  - $D = f(S_{IN}, C_L)$
  - $S_{OUT} = g(S_{IN}, C_L)$
  - $f, g$  are non-linear function (typically monotonically increasing with  $S_{IN}$  and  $C_L$ )

$T(i,j)$	$C_{L,1}$	$C_{L,2}$			$C_{L,N}$
$S_{I,1}$					
$S_{I,2}$					
$S_{I,M}$					

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- Intermediate values are *interpolated* from closest match
- Different tables for delay and output-slew

# Non-linear Delay Model (NLDM)



```
u_table_template(index_1) {  
    variable_1 : input_net_transition ;  
    variable_2 : total_output_net_capacitance ;  
    index_1( "10, 20, 30" ) ;  
    index_2( "1.2, 5.0,15.0, 37.5" ) ;  
}  
...  
pin(Z) {  
    timing() {  
        related_pin      : "A" ;  
        timing_sense      : positive_unate ;  
        cell_rise(index_1) {  
            values( " 4, 5, 7, 12, ...3x4 table);  
        }  
        ...  
    }  
}
```

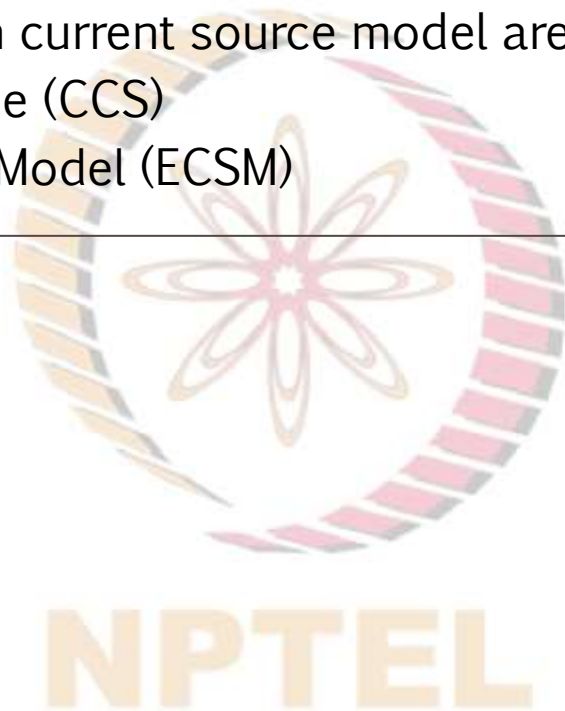
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# Library : Advanced Delay Model

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- At advanced process nodes simple NLDM model is not accurate
- Other delay models based on current source model are employed
  - Composite Current Source (CCS)
  - Effective Current Source Model (ECSM)



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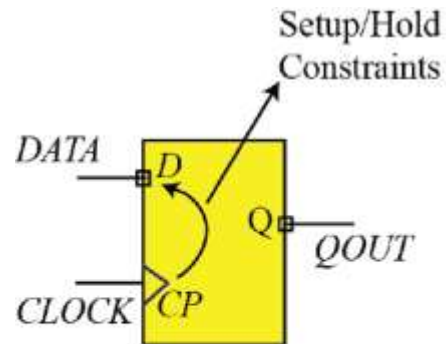
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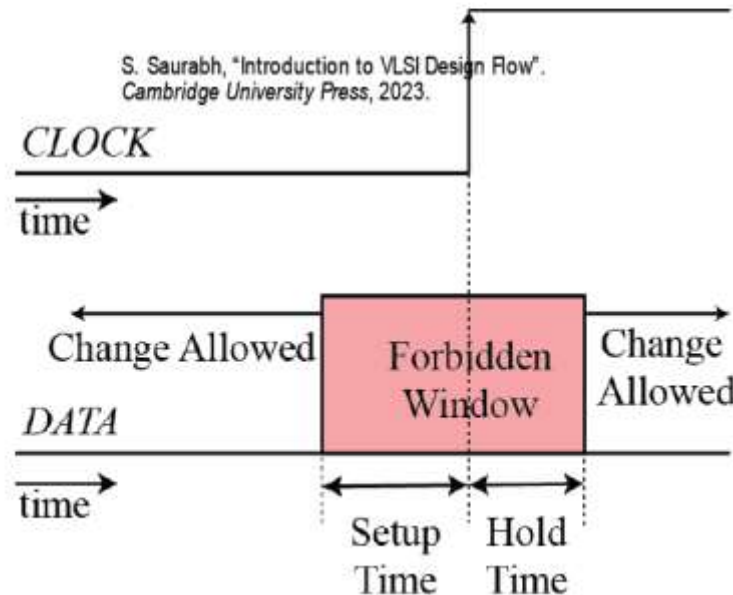
Technology Library

Modelling  
Setup/Hold

# Setup/Hold Time : Definition



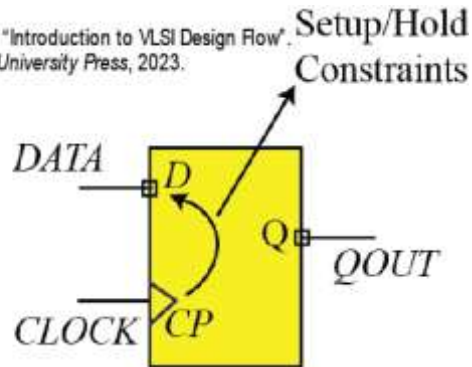
- **Setup time:** minimum amount of time the DATA signal should be held steady **before the CLOCK edge** so that the DATA is sampled correctly and deterministically



- **Hold time:** the minimum amount of time the DATA signal should be held steady **after the CLOCK edge** so that the DATA is sampled correctly and deterministically

# CMOS : Setup/Hold Characteristics

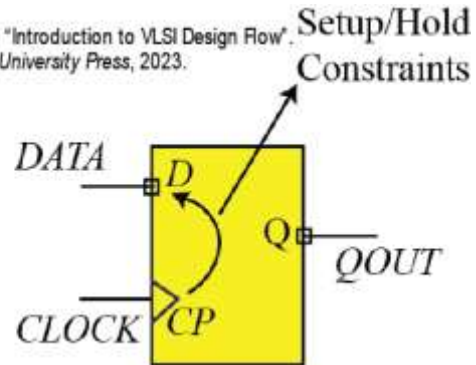
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Cambridge University Press, 2023.



- In general, the **setup** (SU) and **hold** (H) constraints depend on:
  - Data Slew ( $S_D$ )
  - Clock Slew ( $S_{CLK}$ )
- The relationship may be non-linear:
  - $SU = f(S_D, S_{CLK})$
  - $H = g(S_D, S_{CLK})$
  - $f, g$  are non-linear functions
- Modelled as two dimensional discrete point tables
- There are different tables for setup and hold

# Library : Modelling Setup/Hold Constraints

S. Saurabh, "Introduction to VLSI Design Flow",  
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- Intermediate values are interpolated from closest match

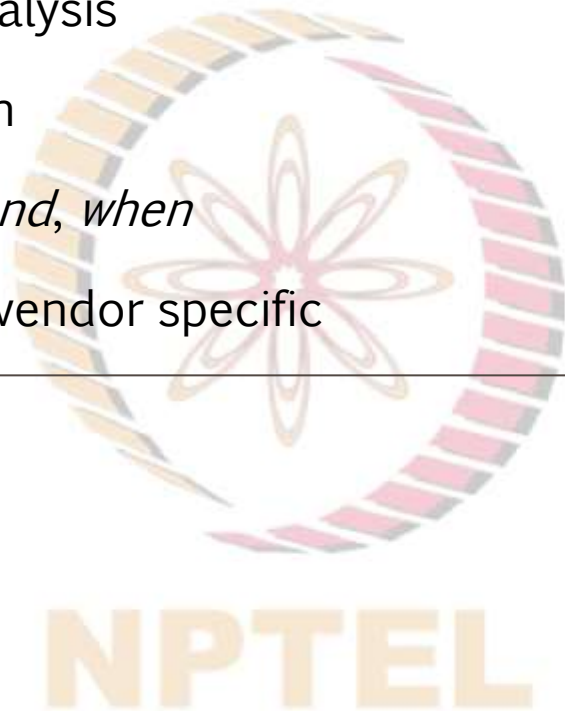
```
u_table_template(index_1) {  
    variable_1 : constrained_pin_transition;;  
    variable_2 : related_pin_transition;  
    index_1( "10, 20, 30" );  
    index_2( "10, 20, 30, 40" );  
}  
...  
pin(D) {  
  
    timing() {  
        related_pin      : "CP" ;  
        timing_type : "setup_rising";  
        rise_constraint(index_1) {  
            values( " 4, 5, 7, 12,  
...3x4 table);  
        }  
        ...  
    }  
}
```

S. Saurabh, "Introduction to VLSI Design Flow",  
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# Library : Other information contained in library

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- Power Models
- Models for crosstalk noise analysis
- Power/Ground Pin Information
- State dependent arcs: *sdf\_cond*, *when*
- Other attributes that may be vendor specific



# References

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- Synopsys Inc. “Liberty.” <https://www.synopsys.com/community/interoperability-programs/tap-in.html>.
- S. Saurabh, “Introduction to VLSI Design Flow”. Cambridge: *Cambridge University Press*, 2023.
- Bhasker, Jayaram, and Rakesh Chadha. *Static timing analysis for nanometer designs: A practical approach*. Springer Science & Business Media, 2009.

