# Arek Sredzki - Autonomy Software Engineer

http://arek.io

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# Summary of Qualifications

- Proficient in C++ and Python
- Proven experience with Robotics and Motion Planning
- Bachelor of Science in Computer Science. UBC, 2017
- Experience with team management roles

## **Experience**

## NIO, Senior Autonomous Controls Engineer (August 2017 - Present)

http://nio.com

- Developed an efficient, real-time-safe robotics software framework and middleware that replaced ROS in the L4 system. Created rich developer-facing tooling for real-time diagnostics as well as data recording, replay, processing, and visualization, enabling teams to iterate at a rapid pace
- Architected and implemented many of the core L4 stack libraries
- Acted as the de facto software engineering/C++ expert for all AD/AI SW teams
- Optimized algorithm designs and implementations across the full AD stack
- Designed and implemented the base object fusion solution (multi-modal, multi-target)
- Established and co-managed the L4 SW testing release process

## Google, Software Developer Intern (May – August 2016)

http://google.com

- Contributed to improving Chrome Autofill for 100M+ users
- Created an automated integration testing suite for Autofill in Chrome
  - o Removed the need for tedious manual reliability/website compatibility testing
- Experimental investigation of future directions for Autofill
  - o Prototyped a next-gen automated checkout solution during an internal two-day hackathon

### Tesla Motors, Software Engineering Intern (January – April 2016)

http://tesla.com

- Co-developed a new CAN requirement spec. format for company-wide usage w/ Model 3
  - o Replacement for DBC, designed for data de-duplication, flexibility, and auto-optimization
- Created a fully-featured JCAN editor application (Canode), used by all firmware teams
  - o Natively multi-platform, fully asynchronous, loosely coupled and highly cohesive
  - o Provides instantaneous bus analysis results and input feedback for improved workflow
- Advised on and enabled data driven decision-making for Model 3 CAN architecture
- First week: built and deployed a release artifact service with LDAP authenticated web app

#### UBC Sailbot, Software Lead (Sept 2013 - Aug 2017) Autonomous Sailboat http://ubcsailbot.org

- Record for the furthest fully autonomous boat crossing of the Atlantic Ocean
- Won the International Robotic Sailing Regatta in 2014, 2013, and 2012
- Optimal real-time motion planning with dynamic obstacles in the complex sailing domain
- Efficient, optimal global path planning considering weather data for performance and risk
- Created a novel marine obstacle detection system using thermal imaging & CV
- Developed a fully redundant sensor system with intelligent failure-resistant firmware
- Managed a 17-person software team with Agile methods (Scrum)

#### Vparg, Founder, CTO (May 2015 - Present) Digital replacement for parking passes http://vparg.com

- Designed a distributed stack consisting of Angular.js, Node.js, PostgreSQL, Redis
- Created a responsive real-time single page application using Angular.js and Socket.io
- Allowed for scalable deployment with a stateless RESTful API backend using JWT auth

#### Vikom Media, Lead Developer & Founder (Sept 2011 – Present)

http://vikom.jo

- Reached 2.5 million unique users in 5 months with an MVC web app (AdCraft.co 2011)
- Created and deployed a fast, scalable and responsive image sharing website
- PostgreSQL & MongoDB optimization and management
- Long-term software consulting to Water Wall Turbine Inc. (Web Development / Graphics)

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### **Education**

The University of British Columbia, Vancouver, BC, 2013 – 2017

Bachelor of Science (Computer Science)

Coursera (Stanford), Summer 2015 Intro to Machine Learning – Andrew Ng Udacity (Georgia Tech), Summer 2014 Artificial Intelligence for Robotics – Sebastian Thrun

## **Scholarships and Awards**

3x You Rock Award - NIO

**Top Oral Presentation** – UBC Multidisciplinary Undergraduate Research Conference, 2015 **Dean's Honors List** – UBC, 2014

Lions Bay Community Foundation Scholarship, 2013 Rotary Sunrise Scholarship – Rotary West Vancouver, 2013

Outstanding Youth Team Award - West Vancouver District, 2012 & 2013

Recognized for 350+ hours of total school service, 2013

**Technical Skills** 

Programming: C++, Node.js, Python, Java, Haskell, CUDA

System architecture, embedded firmware, data structures, algorithms Proven experience with implementing AI, ML, CV in real-time systems

Data & Statistics:

R, statistical analysis, particle filters, Kalman filters

Networking:

TCP/IP, AVB/TSN, CAN, RS232, WebSocket, routing

Markup: HTML, CSS, Markdown

Databases: PostgreSQL, MongoDB, database schema design

Other: Proficiency with UNIX shell

Graphical Design: Extensive experience with UI/UX design principles & Adobe CC

# Other Relevant Experience

Hackathons

- Google Code Jam 2014 Passed Qualification Round, travel prevented further progression
- EA Code Wars 2014 Developed a simple Android game in 12 hours

# **Management Skills**

Project management: Effective communicator, highly organized and detail-oriented

Experience with hands-on management of large teams

Inspiring teams to be scrappy in implementing ambitious visions Mentoring researchers and junior engineers into software experts

Constructing teams of exceptional engineers Negotiating sponsorships and partnerships

Long-term project planning