source	: http:/	/bigoch	neatsh	eet.con	n/				
Search	ing	_							
Algorithm	Data Structure	Time Complex	kity	Space Comple	exity				
		Average	Worst	Worst					
Depth First Search (DFS)	Graph of V vertices and E edges	-	O(E + V)	O(V)					
Breadth First Search (BFS)	Graph of V vertices and E edges	-	O(E + V)	O(V)					
Binary search	Sorted array of n elements	O(log(n))	O(log(n))	O(1)					
Linear (Brute Force)	Array	O(n)	O(n)	O(1)					
Shortest path by Dijkstra, using a Min- heap as priority queue	Graph with V vertices and E edges	(V + E) log	(V + E) log	O(V)					
Shortest path by Dijkstra, using an unsorted array as priority queue	Graph with V vertices and E edges	O(V ^2)	O(V ^2)	O(V)					
Shortest path by Bellman- Ford	Graph with V vertices and E edges	O(V E)	O(V E)	O(V)					
Sorting	3								
Algorithm	Data Structure	Time Complex	city	Worst Case A	uxiliary Space	Complexity			
		Best	Average	Worst	Worst				
Quicksort	Array	O(n log(n))	O(n log(n))	O(n^2)	O(n)				
Mergesort	Array	O(n log(n))	O(n log(n))	O(n log(n))	O(n)				
Heapsort	Array	O(n log(n))	O(n log(n))	O(n log(n))	O(1)				
Bubble Sort	Array	O(n)	O(n^2)	O(n^2)	O(1)				
Insertion Sort	Array	O(n)	O(n^2)	O(n^2)	O(1)				
Select Sort	Array	O(n^2)	O(n^2)	O(n^2)	O(1)				

Bucket Sort	Array	O(n+k)	O(n+k)	O(n^2)	O(nk)						
Radix Sort	Array	O(nk)	O(nk)	O(nk)	O(n+k)						
Data St	tructur	es									
Data Structure	Time Complexity								Space Comple	exity	
		Ave	rage			Wo	orst		Worst		
	Indexing	Search	Insertion	Deletion	Indexing	Search	Insertion	Deletion			
Basic Array	O(1)	O(n)	-	-	O(1)	O(n)	-	-	O(n)		
Dynamic Array	O(1)	O(n)	O(n)	O(n)	O(1)	O(n)	O(n)	O(n)	O(n)		
Singly-Linked List	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)		
Doubly-Linked List	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)		
Skip List	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n log(n))		
Hash Table	-	O(1)	O(1)	O(1)	-	O(n)	O(n)	O(n)	O(n)		
Binary Search Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n)		
Cartresian Tree	-	O(log(n))	O(log(n))	O(log(n))	-	O(n)	O(n)	O(n)	O(n)		
B-Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)		
Red-Black Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)		
Splay Tree	-	O(log(n))	O(log(n))	O(log(n))	-	O(log(n))	O(log(n))	O(log(n))	O(n)		
AVL Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)		
Heaps											
Heaps	Time Complexity										
	Heapify	Find Max	Extract Max	Increase Key	Insert	Delete	Merge				
Linked List (sorted)	-	O(1)	O(1)	O(n)	O(n)	O(1)	O(m+n)				
Linked List (unsorted)	-	O(n)	O(n)	O(1)	O(1)	O(1)	O(1)				
Binary Heap	O(n)	O(1)	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(m+n)				

Binomial Heap	-	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))
Fibonacci Heap	-	O(1)	O(log(n))*	O(1)*	O(1)	O(log(n))*	O(1)
Graphs	6						
Node / Edge Management	Storage	Add Vertex		Remove Verte	x		
Adjacency list	O(V + E)	O(1)	O(1)	O(V + E)	O(E)	O(V)	
Incidence list	O(V + E)	O(1)	O(1)	O(E)	O(E)	O(E)	
Adjacency matrix	O(V ^2)	O(V ^2)	O(1)	O(V ^2)	O(1)	O(1)	
Incidence matrix	O(V · E)	O(E)					