ENG2009 - Modelling of Engineering Systems

Tutorial 2

Higher order and Coupled ODE

Higher order and coupled ODE - Examples

Example 1

Rewrite the following differential equation as a set of first order differential equations.

$$3\frac{d^2y}{dx^2} + 2\frac{dy}{dx} + 5y = e^{-x}, y(0) = 5, y'(0) = 7$$

Solution

The ordinary differential equation would be rewritten as follows. Assume

$$\frac{dy}{dx} = z,$$

Then

$$\frac{d^2y}{dx^2} = \frac{dz}{dx}$$

Substituting this in the given second order ordinary differential equation gives

$$3\frac{dz}{dx} + 2z + 5y = e^{-x}$$

$$\frac{dz}{dx} = \frac{1}{3}(e^{-x} - 2z - 5y)$$

The set of two simultaneous first order ordinary differential equations complete with the initial conditions then is

$$\frac{dy}{dx} = z, y(0) = 5$$

$$\frac{dz}{dx} = \frac{1}{3}(e^{-x} - 2z - 5y), z(0) = 7.$$

Now one can apply any of the numerical methods used for solving first order ordinary differential equations.

Example 2

Given

$$\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + y = e^{-t}, y(0) = 1, \frac{dy}{dt}(0) = 2, \text{ find by Euler's method}$$

- a) y(0.75)
- b) the absolute relative true error for part(a), if $y(0.75)|_{exact} = 1.668$
- c) $\frac{dy}{dt}$ (0.75)

Use a step size of h = 0.25.

Solution

First, the second order differential equation is written as two simultaneous first-order differential equations as follows. Assume

$$\frac{dy}{dt} = z$$

then

$$\frac{\frac{dz}{dt} + 2z + y = e^{-t}}{\frac{dz}{dt}} = e^{-t} - 2z - y$$

So the two simultaneous first order differential equations are

$$\frac{dy}{dt} = z = f_1(t, y, z), y(0) = 1$$

$$\frac{dz}{dt} = e^{-t} - 2z - y = f_2(t, y, z), z(0) = 2$$
(E2.1)

Using Euler's method on Equations (E2.1) and (E2.2), we get

$$y_{i+1} = y_i + f_1(t_i, y_i, z_i)h$$

$$z_{i+1} = z_i + f_2(t_i, y_i, z_i)h$$
(E2.3)
(E2.4)

a) To find the value of y(0.75) and since we are using a step size of 0.25 and starting at t=0, we need to take three steps to find the value of y(0.75).

For
$$i = 0, t_0 = 0, y_0 = 1, z_0 = 2$$
,
From Equation (E2.3)
$$y_1 = y_0 + f_1(t_0, y_0, z_0)h$$

$$y_1 = y_0 + f_1(t_0, y_0, z_0)h$$

= 1 + f_1(0,1,2)(0.25)
= 1 + 2(0.25)

= 1.5

 y_1 is the approximate value of y at

$$t = t_1 = t_0 + h = 0 + 0.25 = 0.25$$

 $y_1 = y(0.25) \approx 1.5$

From Equation (E2.4)

$$z_1 = z_0 + f_2(t_0, y_0, z_0)h$$

= 2 + f_2(0,1,2)(0.25)
= 2 + (e^{-0} - 2(2) - 1)(0.25)
= 1

 z_1 is the approximate value of z (same as $\frac{dy}{dt}$) at t=0.25

$$z_1 = z(0.25) \approx 1 \label{eq:z1}$$
 For $i=1, t_1=0.25, y_1=1.5, z_1=1,$

From Equation (E2.3)

$$y_2 = y_1 + f_1(t_1, y_1, z_1)h$$

= 1.5 + f_1(0.25, 1.5, 1)(0.25)
= 1.5 + (1)(0.25)
= 1.75

 y_2 is the approximate value of y at

$$t = t_2 = t_1 + h = 0.25 + 0.25 = 0.50$$

$$y_2 = y(0.5) \approx 1.75$$

From Equation (E2.4)

$$z_2 = z_1 + f_2(t_1, y_1, z_1)h$$
= 1 + f_2(0.25, 1.5, 1)(0.25)
= 1 + (e^{-0.25} - 2(1) - 1.5)(0.25)
= 1 + (-2.7211)(0.25)
= 0.31970

 z_2 is the approximate value of z at

$$t = t_2 = 0.5$$

$$z_2 = z(0.5) \approx 0.31970$$

For
$$i = 2$$
, $t_2 = 0.5$, $y_2 = 1.75$, $z_2 = 0.31970$,

From Equation (E2.3)

$$y_3 = y_2 + f_1(t_2, y_2, z_2)h$$

= 1.75 + f_1(0.50,1.75,0.31970)(0.25)
= 1.75 + (0.31970)(0.25)
= 1.8299

 y_3 is the approximate value of y at

$$t = t_3 = t_2 + h = 0.5 + 0.25 = 0.75$$

 $y_3 = y(0.75) \approx 1.8299$

From Equation (E2.4)

$$z_3 = z_2 + f_2(t_2, y_2, z_2)h$$

= 0.31972 + f_2(0.50,1.75,0.31970)(0.25)
= 0.31972 + (e^{-0.50} - 2(0.31970) - 1.75)(0.25)
= 0.31972 + (-1.7829)(0.25)

$$= -0.1260$$

 z_3 is the approximate value of z at

$$t = t_3 = 0.75$$

$$z_3 = z(0.75) \approx -0.12601$$
 $y(0.75) \approx y_3 = 1.8299$ b) The exact value of $y(0.75)$ is

$$y(0.75)|_{exact} = 1.668$$

$$y(0.75)|_{exact} = 1.668$$
 The absolute relative true error in the result from part (a) is
$$|\epsilon_t| = \left|\frac{1.668 - 1.8299}{1.668}\right| \times 100$$

$$= 9.7062\%$$

c)
$$\frac{dy}{dx}(0.75) = z_3 \approx -0.12601$$

Exercises

Q1) Given
$$\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + y = e^{-t}, y(0) = 1, \frac{dy}{dt}(0) = 2,$$
 find by Heun's method a) $y(0.75)$ b) $\frac{dy}{dx}(0.75)$. Use a step size of $h = 0.25$.

Solutions

First, the second order differential equation is rewritten as two simultaneous first-order differential equations as follows. Assume

$$\frac{dy}{dt} = z$$

then

$$\frac{dz}{dt} + 2z + y = e^{-t}$$
$$\frac{dz}{dt} = e^{-t} - 2z - y$$

So the two simultaneous first order differential equations are

$$\frac{dy}{dt} = z = f_1(t, y, z), y(0) = 1$$

$$\frac{dz}{dt} = e^{-t} - 2z - y = f_2(t, y, z), z(0) = 2$$
Using Heun's method on Equations (1) and (2), we get (E3.2)

$$y_{i+1} = y_i + \frac{1}{2} (k_1^y + k_2^y) h$$

$$k_1^y = f_1 (t_i, y_i, z_i)$$

$$k_2^y = f_1 (t_i + h, y_i + hk_1^y, z_i + hk_1^z)$$

$$z_{i+1} = z_i + \frac{1}{2} (k_1^z + k_2^z) h$$

$$k_1^z = f_2 (t_i, y_i, z_i)$$

$$k_2^z = f_2 (t_i + h, y_i + hk_1^y, z_i + hk_1^z)$$
(E3.4a)
(E3.4b)
(E3.5)

For i = 0, $t_o = 0$, $y_o = 1$, $z_o = 2$

From Equation (E3.4a)

$$k_1^y = f_1(t_o, y_o, z_o)$$

= $f_1(0,1,2)$
= 2

From Equation (E3.6a)

$$k_1^z = f_2(t_0, y_0, z_0)$$

= $f_2(0,1,2)$
= $e^{-0} - 2(2) - 1$
= -4

From Equation (E3.4b)

$$k_2^y = f_1(t_0 + h, y_0 + hk_1^y, z_0 + hk_1^z)$$

= $f_1(0 + 0.25, 1 + (0.25)(2), 2 + (0.25)(-4))$
= $f_1(0.25, 1.5, 1)$
= 1

From Equation (E3.6b)

$$k_2^z = f_2(t_0 + h, y_0 + hk_1^y, z_0 + hk_1^z)$$

$$= f_2(0 + 0.25, 1 + (0.25)(2), 2 + (0.25)(-4))$$

$$= f_2(0.25, 1.5, 1)$$

$$= e^{-0.25} - 2(1) - 1.5$$

$$= -2.7212$$

From Equation (E3.3)

$$y_1 = y_0 + \frac{1}{2} (k_1^y + k_2^y) h$$

= $1 + \frac{1}{2} (2 + 1)(0.25)$
= 1.375

 y_1 is the approximate value of y at

$$t = t_1 = t_0 + h = 0 + 0.25 = 0.25$$

 $y_1 = y(0.25) \approx 1.375$

```
From Equation (E3.5)
        z_1 = z_0 + \frac{1}{2}(k_1^z + k_2^z)h
= 2 + \frac{1}{2}(-4 + (-2.7212))(0.25)
z_1 is the approximate value of z at
         t = t_1 = 0.25
         z_1 = z(0.25) \approx 1.1598
For i = 1, t_1 = 0.25, y_1 = 1.375, z_1 = 1.1598
From Equation (E3.4a)
        k_1^y = f_1(t_1, y_1, z_1)
             = f_1(0.25, 1.375, 1.1598)
             = 1.1598
From Equation (E3.6a)
        k_1^z = f_2(t_1, y_1, z_1)
= f_2(0.25, 1.375, 1.1598)
= e^{-0.25} - 2(1.1598) - 1.375
            = -2.9158
From Equation (E3.4b)
         k_2^y = f_1(t_1 + h, y_1 + hk_1^y, z_1 + hk_1^z)
             = f_1(0.25 + 0.25, 1.375 + (0.25)(1.1598), 1.1598 + (0.25)(-2.9158))
           = f_1(0.50, 1.6649, 0.43087)
             = 0.43087
From Equation (E3.6b)
         k_2^z = f_2(t_1 + h, y_1 + hk_1^y, z_1 + hk_1^z)
             = f_2(0.25 + 0.25, 1.375 + (0.25)(1.1598), 1.1598 + (0.25)(-2.9158))
             = f_2(0.50, 1.6649, 0.43087)
             =e^{-0.50}-2(0.43087)-1.6649
             = -1.9201
From Equation (E3.3)
        y_2 = y_1 + \frac{1}{2} (k_1^y + k_2^y) h
                  = 1.375 + \frac{1}{2}(1.1598 + 0.43087)(0.25)
                  = 1.5738
y_2 is the approximate value of y at
         t = t_2 = t_1 + h = 0.25 + 0.25 = 0.50
         y_2 = y(0.50) \approx 1.5738
From Equation (E3.5)
        z_2 = z_1 + \frac{1}{2}(k_1^z + k_2^z)h
            = 1.1598 + \frac{1}{2}(-2.9158 + (-1.9201))(0.25)
z_2 is the approximate value of z at
         t = t_2 = 0.50
         z_2 = z(0.50) \approx 0.55533
For i = 2, t_2 = 0.50, y_2 = 1.57384, z_2 = 0.55533
From Equation (E3.4a)
         k_1^y = f_1(t_2, y_2, z_2)
             = f_1(0.50, 1.5738, 0.55533)
             = 0.55533
From Equation (E3.6a)
         k_1^z = f_2(t_2, y_2, z_2)
```

$$=f_2(0.50,1.5738,0.55533)\\ =e^{-0.50}-2(0.55533)-1.5738\\ =-2.0779$$
 From Equation (E3.4b)
$$k_2^y=f_2\big(t_2+h,y_2+hk_1^y,z_2+hk_1^z\big)\\ =f_1\big(0.50+0.25,1.5738+(0.25)(0.55533),0.55533+(0.25)(-2.0779)\big)\\ =f_1\big(0.75,1.7126,0.035836\big)\\ =0.035836$$
 From Equation (E3.6b)
$$k_2^z=f_2\big(t_2+h,y_2+hk_1^y,z_2+hk_1^z\big)\\ =f_2\big(0.50+0.25,1.5738+(0.25)(0.55533),0.55533+(0.25)(-2.0779)\big)\\ =f_2\big(0.75,1.7126,0.035836\big)\\ =e^{-0.75}-2\big(0.035836\big)-1.7126\\ =-1.3119$$
 From Equation (E3.3)
$$y_3=y_2+\frac{1}{2}\big(k_1^y+k_2^y\big)h\\ =1.5738+\frac{1}{2}\big(0.55533+0.035836\big)(0.25)\\ =1.6477$$

 y_3 is the approximate value of y at

$$t = t_3 = t_2 + h = 0.50 + 0.25 = 0.75$$

 $y_3 = y(0.75) \approx 1.6477$

b) From Equation (E3.5)

$$z_3 = z_2 + \frac{1}{2}(k_1^z + k_2^z)h$$

= 0.55533 + \frac{1}{2}(-2.0779 + (-1.3119))(0.25)
= 0.13158

 z_3 is the approximate value of z at

$$t = t_3 = 0.75$$

 $z_3 = z(0.75) \approx 0.13158$

The intermediate and the final results are shown in Table 1.

 Table 1
 Intermediate results of Heun's method.

i	0	1	2
t_i	0	0.25	0.50
y_i	1	1.3750	1.5738
z_i	2	1.1598	0.55533
k_1^y	2	1.1598	0.55533
k_1^z	-4	-2.9158	-2.0779
k_2^y	1	0.43087	0.035836
k_2^z	-2.7211	-1.9201	-1.3119
y_{i+1}	1.3750	1.5738	1.6477
z_{i+1}	1.1598	0.55533	0.13158

Recall Tutorial 5 - Python code example:

From differential eq:

$$m\frac{d^2y(t)}{dt^2} + b\frac{dy(t)}{dt} + ky(t) = u(t).$$

Rearrange to yield

$$\frac{d^2y(t)}{dt^2} = \frac{1}{m} \left(-b \frac{dy(t)}{dt} - ky(t) + u(t) \right)$$

Assume

$$\frac{dy}{dt} = z(t)$$

Therefore

$$\frac{dz}{dt} = \frac{1}{m} \left(-bz(t) - ky(t) + u(t) \right)$$

Therefore the python code:

```
#import numpy, integrate and pyplot
import numpy as np
from scipy import integrate
from matplotlib import pyplot as plt
#sim data
m=1 #mass of the oscillator
b=0.2 #damper of the oscillator
k=1 #stiffness of the oscillator
omega = (k/m)**0.5 #angular frequency of the oscillator
T=2*np.pi/omega #period of the oscillator
#create 1000 unifirmply distributed points in the interval [0,10T]
t = np.linspace(0, 10*T, 1000)
#lambda returning the force
force = lambda t:t<=0.1</pre>
#lambda with the RHS of the equation, it evaluates the force and returns a list
f = lambda X, t: [X[1], 1/m*(force(t)-k*X[0]-b*X[1])]
\#solve equation using odeint, now the values of X for t=0 are given by a list
XOdeint = integrate.odeint(f,[0,0],t)
ti = np.linspace(0,10*T,1000)
#plot force
plt.plot(ti,force(ti))
plt.title('Force (input)')
plt.grid()
plt.xlabel('$t$')
plt.ylabel('$input$')
plt.show()
#plot displacements from both solutions (first column of each solution)
plt.plot(t, XOdeint[:,0])
plt.legend(['Odeint'])
plt.title('Displacement')
plt.grid()
plt.xlabel('$t$')
plt.ylabel('$x$')
plt.show()
```

```
#plot velocities from both solutions (first column of each solution)
plt.plot(t, XOdeint[:,1])
plt.legend(['Odeint'])
plt.title('Velocitie')
plt.grid()
plt.xlabel('$t$')
plt.ylabel('$\dot{x}$')
plt.ylabel('$\dot{x}$')
plt.show()

#Save data
np.savetxt('t.txt',t)
np.savetxt('x.txt', XOdeint[:,0])
```





