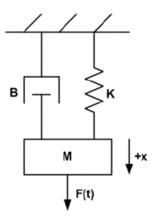
# **ENG2009 – Modelling of Engineering Systems**

# **Tutorial 1**

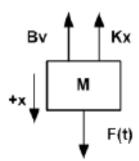
# **Mechanical Systems (Translational)**

**Example:** Write the mathematical equation for the following mechanical system



# Answer:

Free body diagram:



Math model:

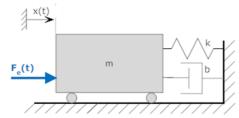
$$\sum_{-Bv - Kx + F = Ma} F_y = Ma$$

$$a = \frac{1}{M}(-Bv - Kx + F)$$
Let  $a = \ddot{x}$ ,  $v = \dot{x}$ 

$$\ddot{x} = \frac{1}{M}(-B\dot{x} - Kx + F)$$

**Example:** (Mass spring damper from Lecture 2)

Write the mathematical equation for the following mechanical system, where the input is the external force  $F_e$  and the outpus is position x(t).



### Answer:

Free body diagram:



Math model:

$$\sum_{all} F = 0$$

$$F_e(t) - ma(t) - bv(t) - kx(t) = 0$$

or

$$m\frac{d^2x(t)}{dt^2} + b\frac{dx(t)}{dt} + kx(t) = F_e(t)$$

Or dot notation

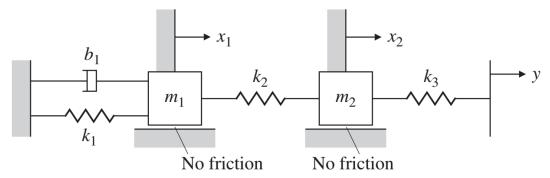
$$m\ddot{x}(t) + b\dot{x}(t) + kx(t) = F_e(t)$$

### Remark:

This equation is in our standard form (input-output notation): Left hand side: system outputs (the unknown variables) right hand side: system inputs (the known variables)

# **Excercise:**

**Q1)** Write the differential equations for the mechanical systems shown below. Assume that there are nonzero initial conditions for both masses and there is no input.



#### **Electrical systems**

Notes:

**Kirchhoff's voltage law:** the algebraic sum of all voltages taken around any closed path in a circuit is zero.

$$\sum_{i} v_j = 0$$

where  $v_j$  denotes the voltage across the  $j_{th}$  element in the loop

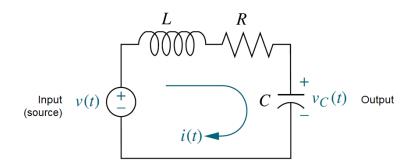
**Kirchhoff's current law**: the algebraic sum of the currents at **any junction** is zero.

$$\sum_{j} i_{j} = 0$$

where  $i_i$  denotes the current at the  $j_{th}$  node.

# **Example:**

Find the differential equation relating the capacitor voltage  $v_c(t)$  (output voltage), to the input voltage, v(t)



#### **Answer:**

 Summing the voltages around the loop, assuming zero initial conditions, yields the integraldifferential equation:

$$v_{inductor} + v_{resistor} + v_{capacitor} = v_{in}$$

$$L\frac{di(t)}{dt} + i(t)R + \frac{1}{C} \int_0^t i(\tau) d\tau = v(t)$$

· Changing variables from current to charge using

$$i = \frac{dq}{dt}$$

(see Table 1 in lecture notes) yields:

$$L\frac{d^2q(t)}{dt^2} + R\frac{dq(t)}{dt} + \frac{1}{C}q(t) = v(t)$$

• Changing variables from voltage to charge using

$$q = C v_c$$

(see Table 1 in lecture notes) yields:

$$LC\frac{d^2v_c(t)}{dt^2} + RC\frac{dv_c(t)}{dt} + v_c(t) = v(t)$$

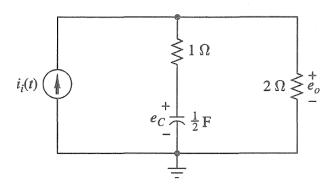
Where v(t) is the input voltage (source)

and  $v_c(t)$  is the output voltage

# **Excercises:**

**Q1)** Find the input-output differential equation relating the output voltage  $e_o(t)$ , to the input current,  $i_i(t)$  for the following circuit

Remark: change of notation as compared to lecture notes. Iinstead of voltage v here voltage is represented by e



**Q2)** Find the input-output differential equation relating the output voltage  $e_o(t)$ , to the input voltage,  $e_i(t)$  for the following circuit

Remark: change of notation as compared to lecture notes. Iinstead of voltage v here voltage is represented by e

