

# LiDAR Data Preprocessing

- Quality Control
  - Data Evaluation
- Data Management
  - Data Statistics
  - Data Classification
  - Data Rasterization
- LiDAR Data Tools
  - ArcGIS 10 Tools
  - LAS Tools

# Common Errors

- LiDAR Data Gaps

- Represents the lack of data that should be there

- Results in missing data within the coverage area

- Causes of data gaps:

- Non-overlapping LiDAR swaths

- Shadowing Effect

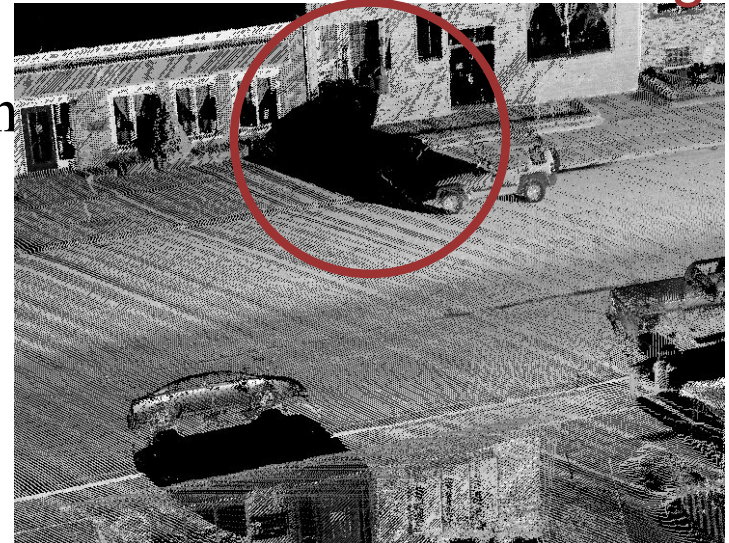
- Large vertical obstructions
      - e.g. Buildings, Ridges, etc...

- Highly reflective surfaces

- Absorption by water surfaces

- Verify with aerial or satellite imagery data

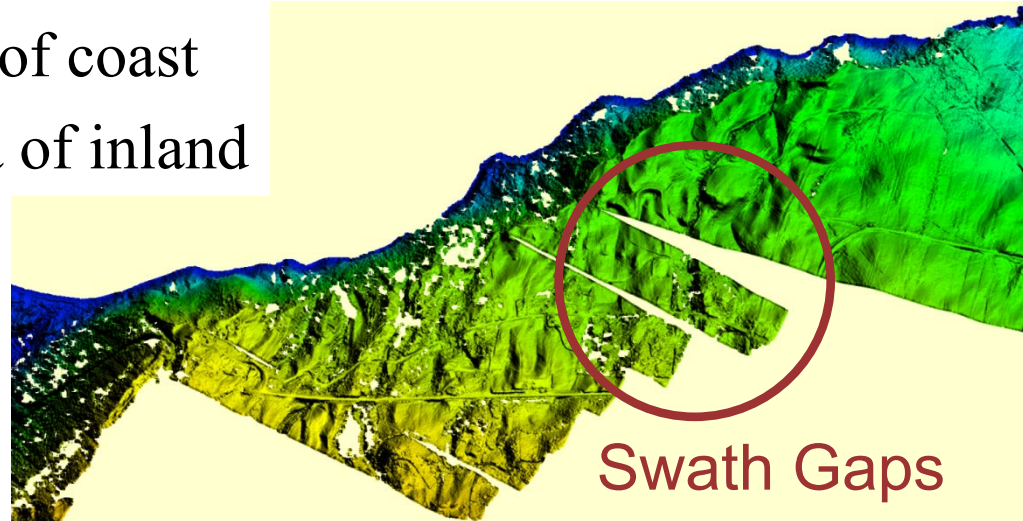
Shadowing



<https://www.LiDARusa.com/shadowing.html>

# Common Errors

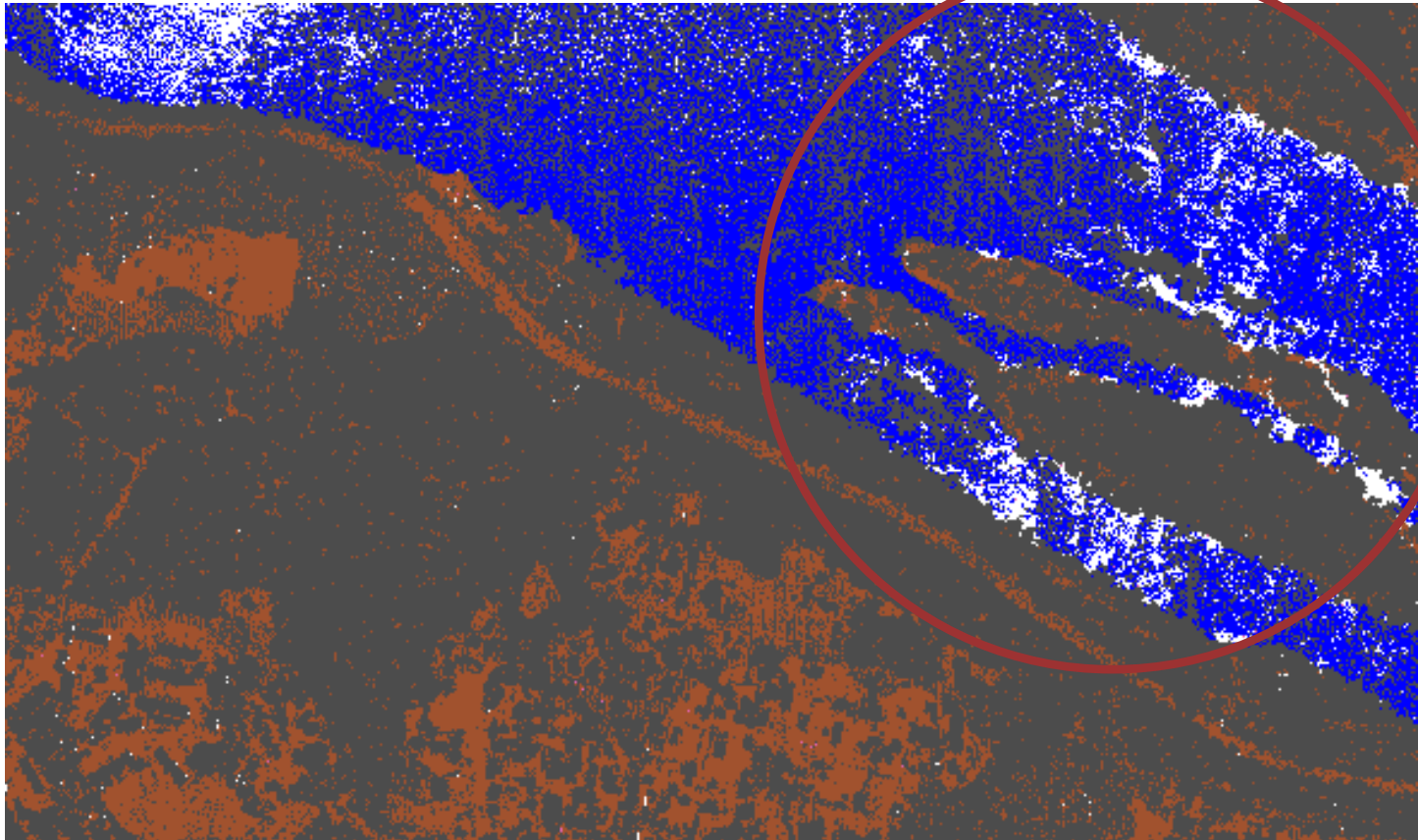
- LiDAR Data Gaps
  - Download imagery data for the site and compare
  - Does the LiDAR dataset cover the area of interest?
  - Are there any gaps in the dataset?
  - Ex: 2007 USACE LiDAR – Hawaiian Islands
    - Complete coverage of coast
    - Gaps and noisy data of inland



# Common Errors

- LiDAR Data Gaps

Water Absorption



# Common Errors

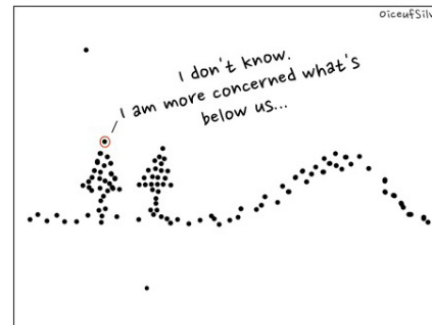
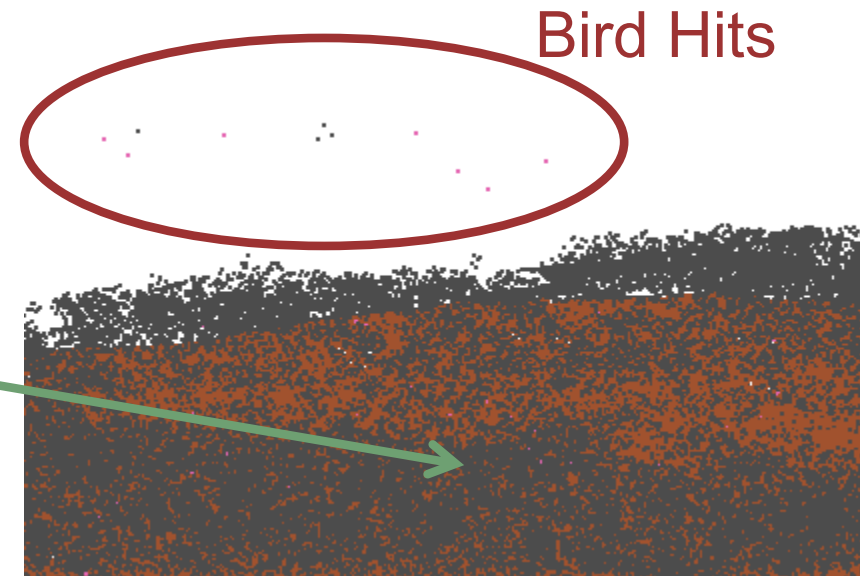
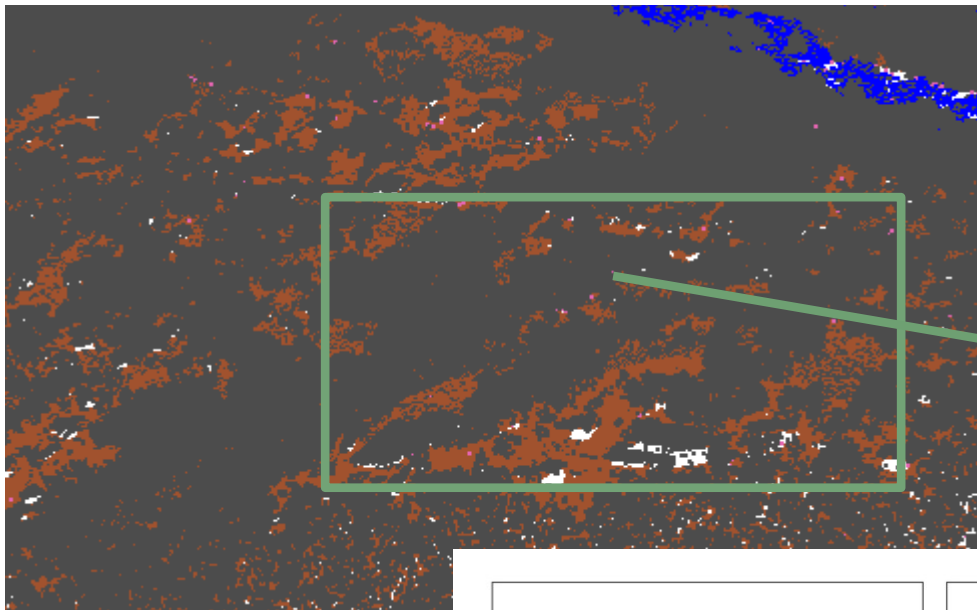
- LiDAR Data Artifacts
  - Represents data noise that should not be there
    - Results in unwanted data that could affect analysis
  - Causes of data artifacts:
    - Atmospheric aerosols (dust, moisture, etc.)
    - Birds and other moving objects (AKA Bird Hits)
  - Need to be filtered out of LiDAR datasets
    - Manual selection and removal
    - Automatic classification
  - Do not delete! Use LAS Class Code = 7 (Noise)

<https://geonet.esri.com/blogs/larry-zhang/2014/10/29/noise-removal-and-manual-classification-in-las-cloud-points>



# Common Errors

- LiDAR Data Artifacts



LiDAR Points

# Data Management

- Some simple tools and methods we can use to get the most of out our LiDAR datasets
  1. Data Statistics (This Lecture)
    - Ways that LiDAR data can be summarized
  2. Data Classification (Lecture 6)
    - Makes further analysis easier if done accurately
    - Manual (This Lecture) vs. Automated (Lecture 6)
  3. Data Rasterization (Lecture 3)
    - Creating digital elevation models from point clouds

# Data Statistics

- Basic LiDAR Statistics in ArcGIS
  - Found in the LAS Dataset Properties
    - Return Numbers
    - Classifications
    - Elevation Range
    - Intensity Range
    - Scan Angle Range
  - ArcGIS Tools
    - LAS Dataset Statistics
    - LAS Point Statistics As Raster
  - LAStools - LASinfo

LAS Dataset Properties

General LAS Files Surface Constraints **Statistics** XY Coordinate System Z Coordinate System

Returns

Return	Point Count	%	Z Min	Z Max
Unknown	925,038	0.09	0.00	0.00
First	789,600,181	73.67	50.83	4499.50
Second	281,245,024	26.24	-188.83	4252.75
Last	789,662,489	73.68	-188.83	3986.00
Single	563,105,016	52.54	50.83	3898.00
First of Many	226,495,165	21.13	284.00	4499.50

Classification Codes

Classification	Point Count	%	Z Min	Z Max	Min Int...	Max Int...	Synthe...
0 Never Classified	925,038	0.09	0.00	0.00	0	0	0
1 Unassigned	530,315,903	49.48	267.42	4417.08	0	255	0
2 Ground	433,698,207	40.47	265.42	883.17	0	255	0
7 Noise	106,831,095	9.97	-188.83	4499.50	0	255	0

Classification Flags

Name	Point Count	%
Model Key	0	0.00
Synthetic	0	0.00
Withheld	0	0.00

Check Status Update ☐ Force recalculate

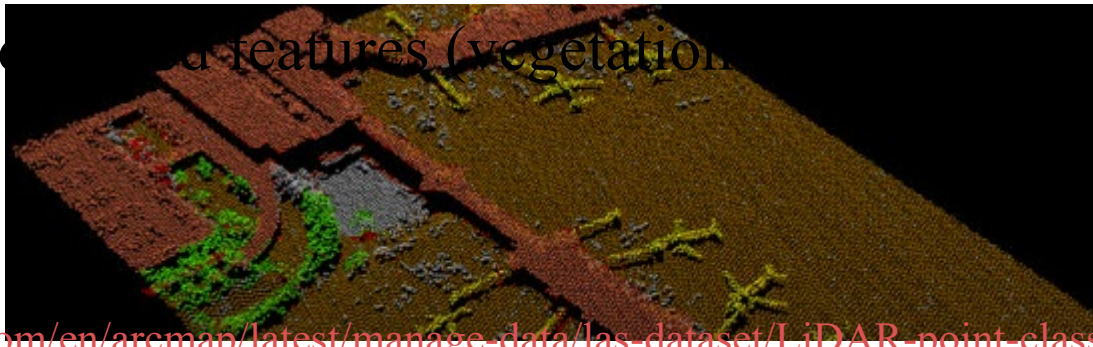
Statistics up to date.

OK Cancel Apply



# Data Classification

- Overview
  - Stored per point as the LAS Classification Code
  - LiDAR vendor will perform some basic classification
    - Usually results in ground and "unclassified"
  - Up to the user to further classify the data
    - Reclassify data (ground vs. non-ground)
    - Add new features (vegetation)

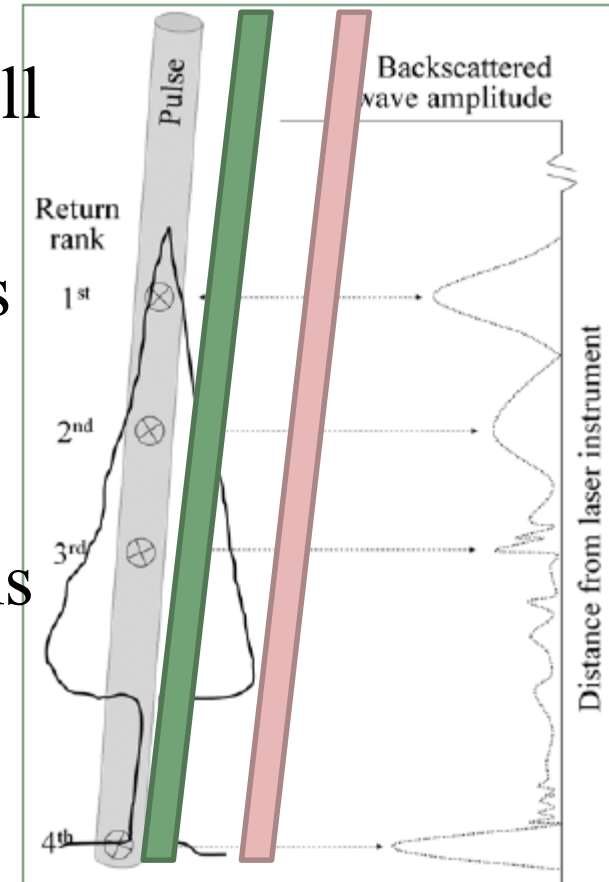


- ☒ Las Dataset.lasd
  - Data percentage: 100
  - Classification
    - 0 Never Classified
    - 1 Unassigned
    - 2 Ground
    - 3 Low Vegetation
    - 4 Medium Vegetation
    - 5 High Vegetation
    - 6 Building
    - 7 Noise
    - 8 Model Key/Reserved
    - 9 Water
    - 10 Rail
    - 11 Road Surface
    - 12 Overlap/Reserved
    - 13 Wire - Guard
    - 14 Wire - Conductor
    - 15 Transmission Tower
    - 16 Wire - Connector
    - 17 Bridge Deck
    - 18 High Noise

<http://desktop.arcgis.com/en/arcmap/latest/manage-data/las-dataset/LiDAR-point-classification.htm>

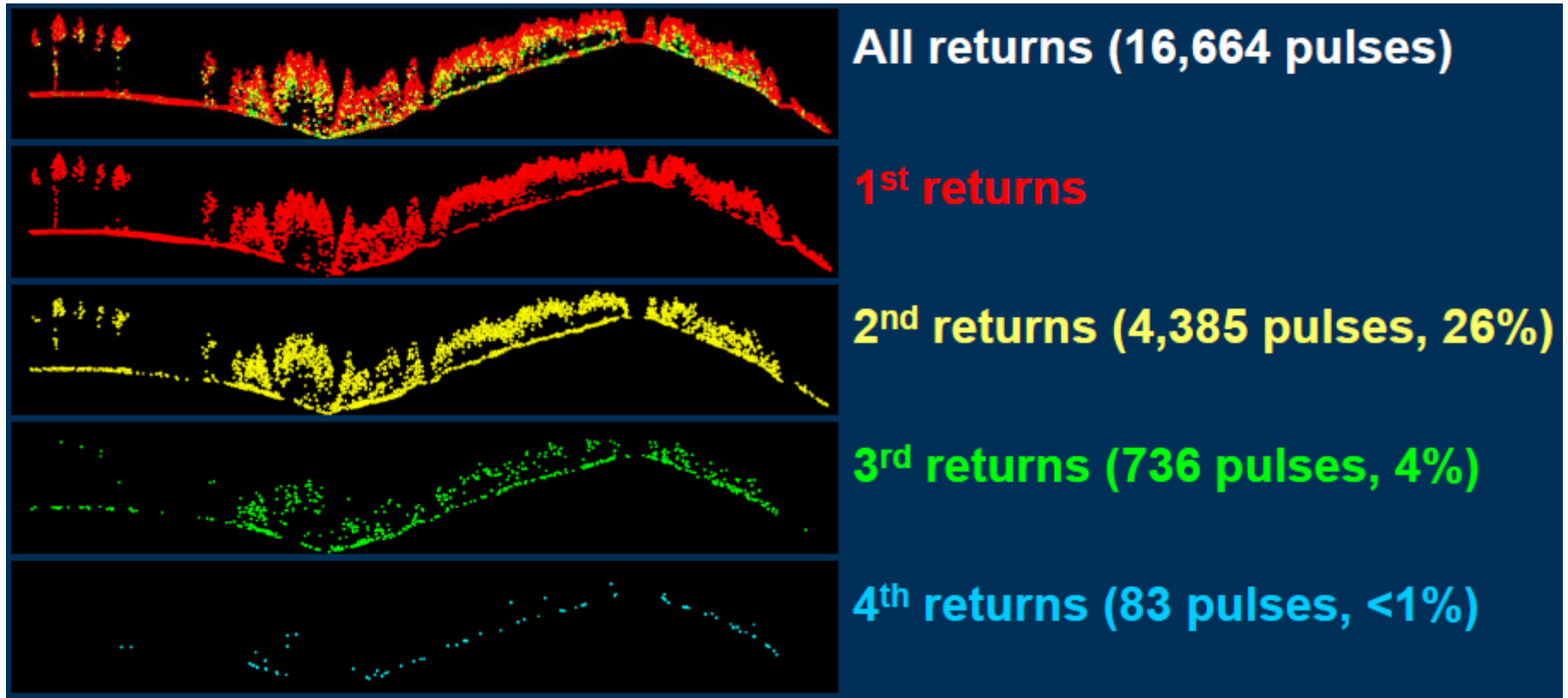
# Data Classification

- Discrete LiDAR Systems
  - Remember, each LiDAR pulse will have numerous returns / photons
  - However, discrete LiDAR records only a few of these returns
    - Typically this is 1 to 5 Returns
  - A LiDAR designed for five returns will not always record five
    - Depends on the topography which influences the amplitude of returns



# Data Classification

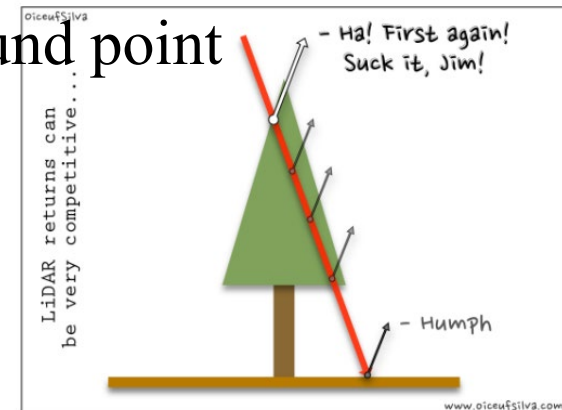
- Discrete LiDAR Systems



[http://LiDAR.cr.usgs.gov/downloadfile2.php?file=Nayegandhi\\_LiDAR\\_Technology\\_Overview](http://LiDAR.cr.usgs.gov/downloadfile2.php?file=Nayegandhi_LiDAR_Technology_Overview)

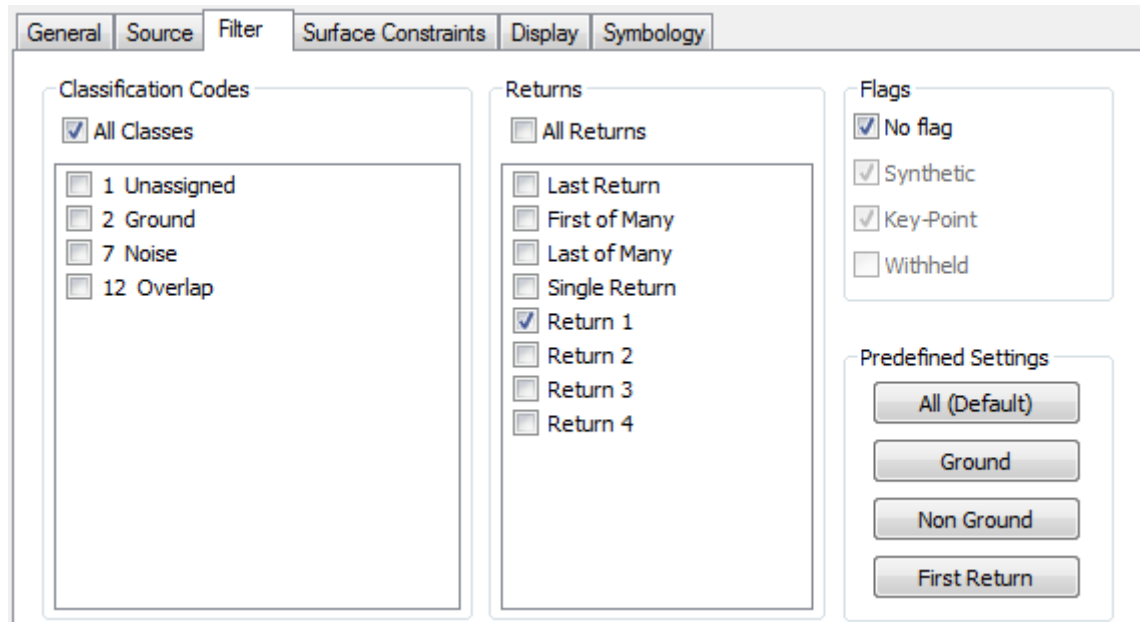
# Data Classification

- Return Classes
  - Provide more info than the Return Number
  - Can be determined by simple algorithms
  - Example Classes:
    - Single Return → Possible ground or solid surface point
    - First Return of Many → Possible tree top point
    - Last Return of Many → Possible ground point
  - Why bother?
    - Aids with filtering LiDAR data
    - Aids with creating surface models



# Data Classification

- Filtering LiDAR Data in ArcGIS
  - Right click the dataset in the Table of Contents
  - Filtering effects both display and analysis



# Data Rasterization

- Converting 3-D data to 2.5-D data
  - 3-D = Multiple z values for any x,y coordinate
  - 2.5-D = Single z value for each x,y coordinate
  - Binning
    - Selecting a Cell Size and putting LiDAR data in each cell
  - Filtering
    - Removing points of particular class, height, etc...
  - Interpolation
    - Implementing a method for filling in "No Data" gaps
  - More on this next Lecture...



# Data Rasterization

- Elevation Raster → Digital Elevation Model
  - More next Lecture...
- Intensity Raster → Intensity Map / Image
  - LAS Dataset to Raster tool
    - The average return strength of the pulse at each point
    - ESRI recommends filtering by first returns



<http://desktop.arcgis.com/en/arcmap/latest/manage-data/las-dataset/LiDAR-solutions-creating-intensity-images-from-LiDAR.htm>

# Data Rasterization

- Example – Baltimore, MD
  - Intensity returns can be highly inconsistent!
  - Dependent on the reflectivity of the object hit
  - Dependent on return number, scan angle, etc..

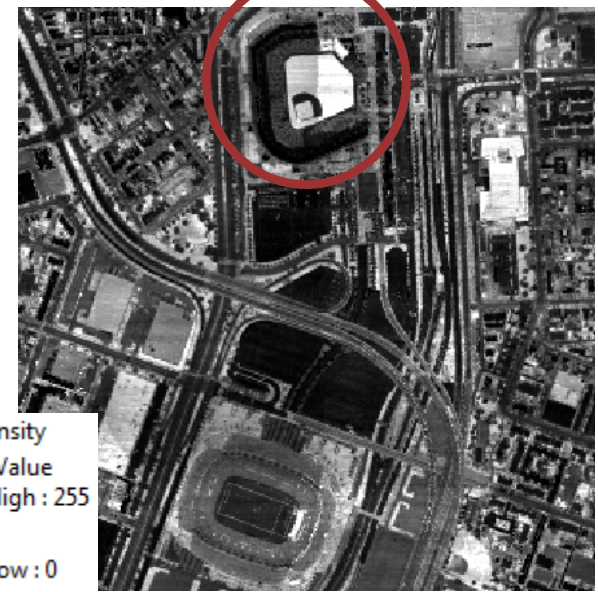
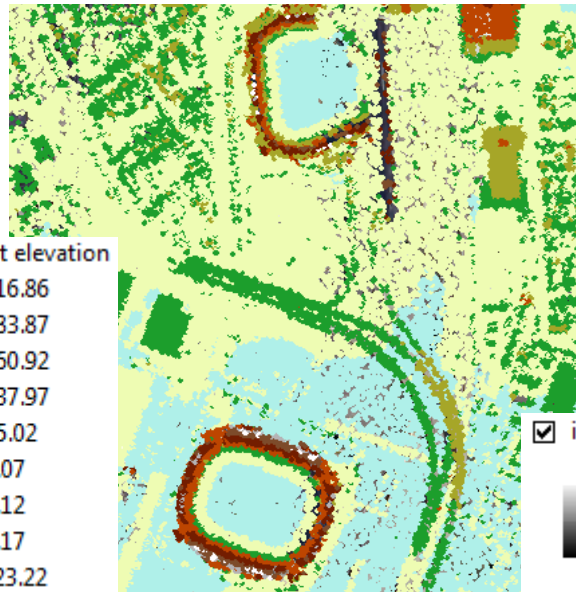
Intensity

Inconsistency



LAS point elevation

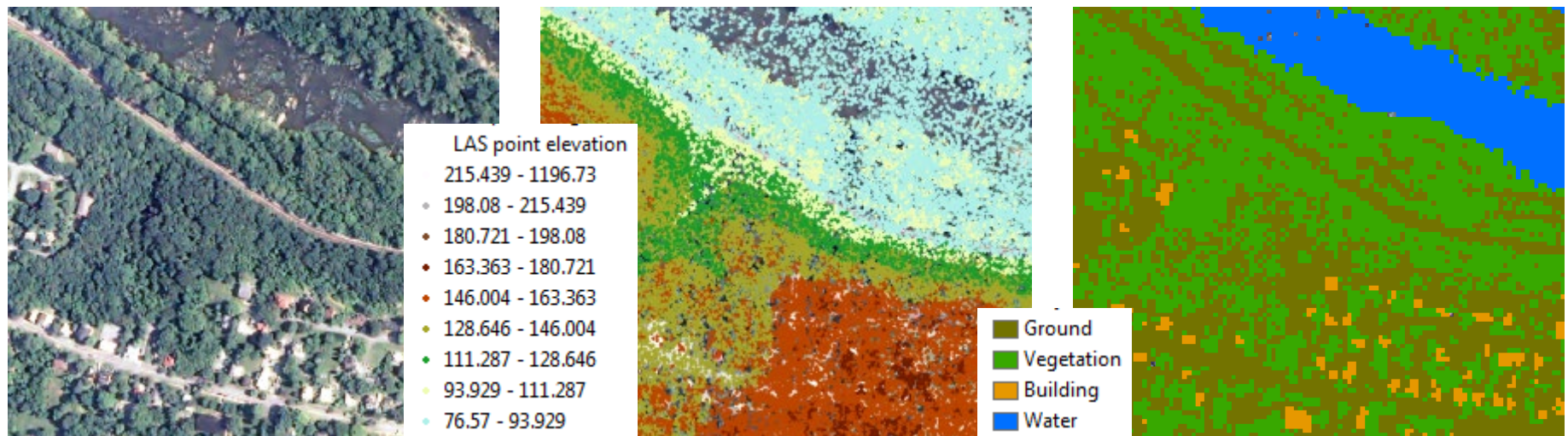
183.87 - 416.86  
• 160.92 - 183.87  
• 137.97 - 160.92  
• 115.02 - 137.97  
• 92.07 - 115.02  
• 69.12 - 92.07  
• 46.17 - 69.12  
• 23.22 - 46.17  
• -228.87 - 23.22



☒ intensity  
Value  
High : 255  
Low : 0

# Data Rasterization

- Classification Raster → Feature Class Map
  - LAS Point Statistics As Raster tool
    - Convert LiDAR to a land use land class raster
- Example – Harper's Ferry, WV



<http://desktop.arcgis.com/en/arcmap/latest/tools/data-management-toolbox/las-point-statistics-as-raster.htm>



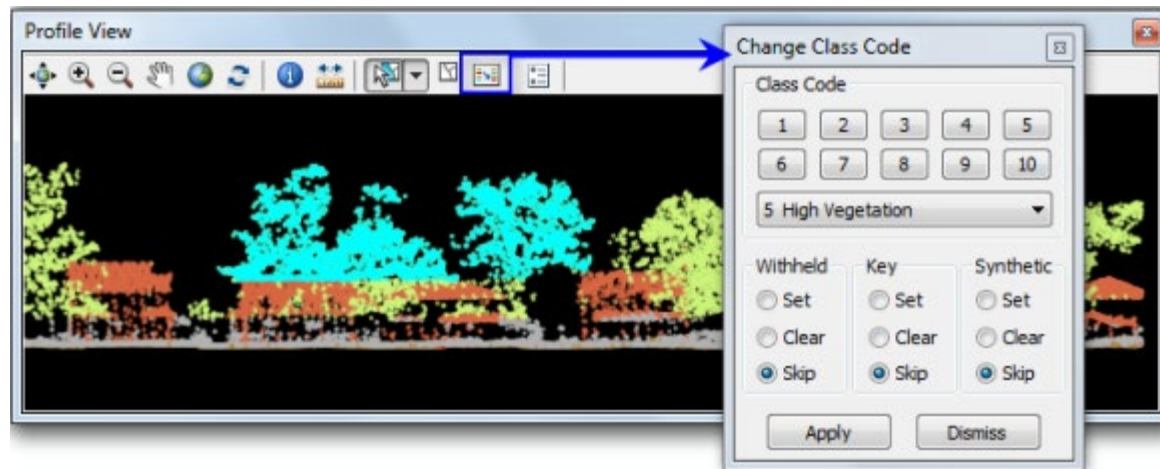
# ArcGIS LiDAR Tools

- LiDAR Classification
  - Manual classification of LiDAR data
  - Change LAS Class Codes tool
    - Reclassify one set of classification codes into another
    - Works globally on the entire LAS file
    - Useful for updating the classification of LAS files generated prior to LAS 1.1 specification
  - Set LAS Class Codes Using Features tool
    - Uses a reference feature class (line, polygon)
    - Ex: Classifying water using a polygon breakline

<http://desktop.arcgis.com/en/arcmap/latest/tools/3d-analyst-toolbox/change-las-class-codes.htm>

# ArcGIS LiDAR Tools

- LiDAR Classification
  - Manual classification of LiDAR data
  - Using the LAS Dataset Profile View tool
    - Select points manually and then change code

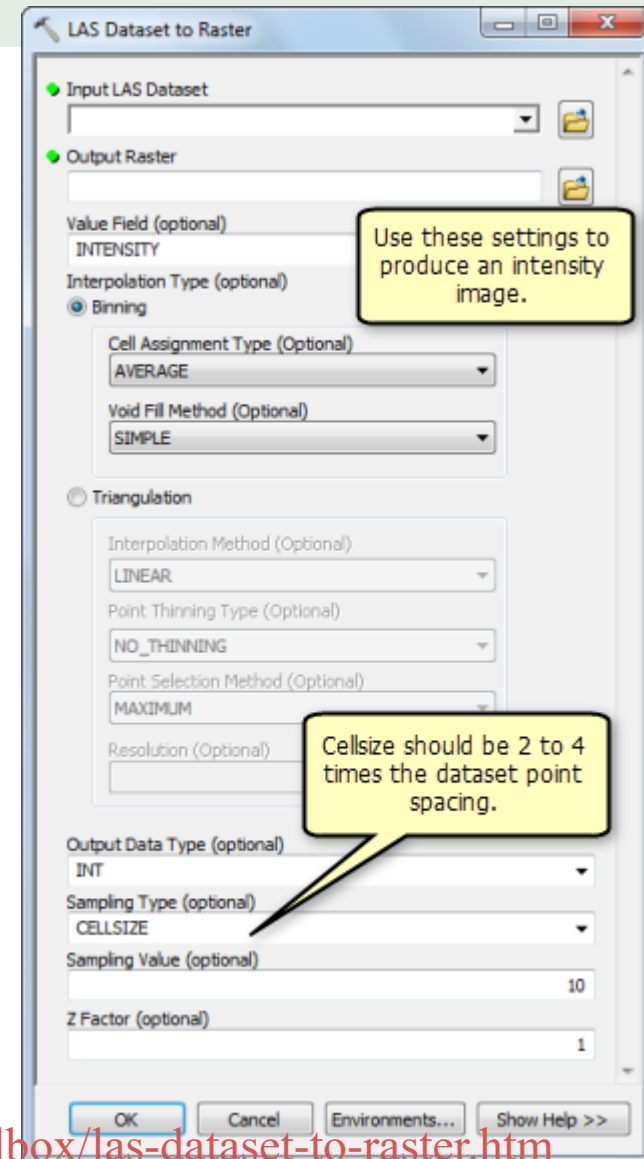


- Automated classification methods in Lecture 6...

<http://desktop.arcgis.com/en/arcmap/latest/manage-data/las-dataset/editing-las-dataset-points.htm>

# ArcGIS LiDAR Tools

- LiDAR Rasterization
  - LAS Dataset to Raster tool
    - Need to filter before running tool
  - For Intensity (This Lecture)
    - Use Average Value, First Returns
  - For Elevation (Lecture 3)
    - DTM = Min Value, Ground Points
    - DSM = Max Value, Non-ground
  - ESRI recommends a Cell Size ~4 times the "Point Spacing"



<http://desktop.arcgis.com/en/arcmap/latest/tools/conversion-toolbox/las-dataset-to-raster.htm>



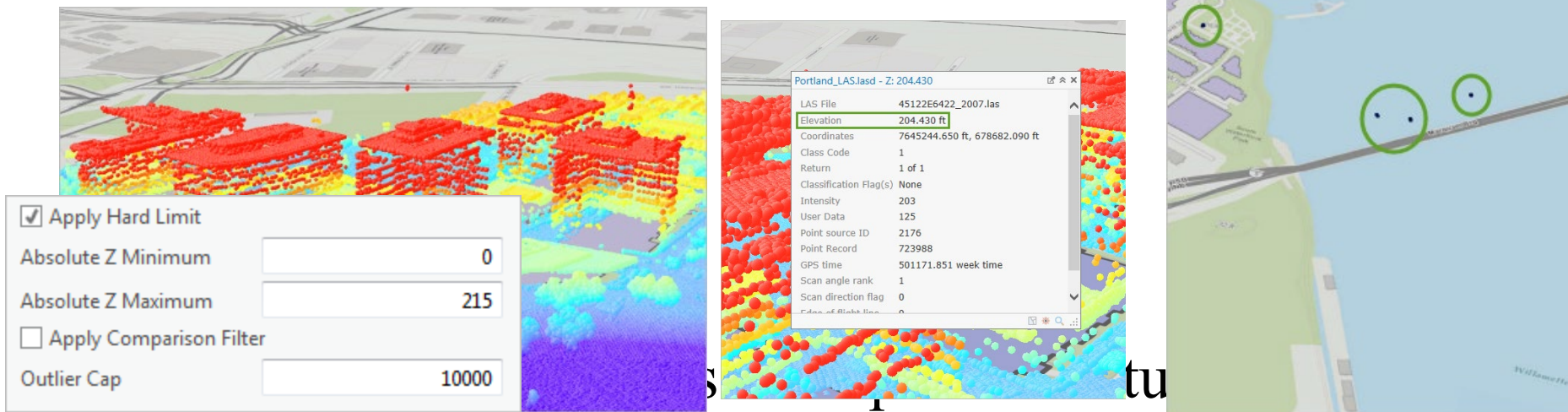
# ArcGIS LiDAR Tools

- Noise Detection
  - Locate Outliers tool
  - Identifies possible erroneous LiDAR points
  - Tool Parameters:
    - Hard Limit
      - Finds outliers based on max and min Z values
    - Comparison Filter
      - Finds outliers based on height difference relative to neighbors
      - Calculates local changes in elevation and slope
    - Outlier Cap
      - Maximum number of outliers to be identified

<http://desktop.arcgis.com/en/arcmap/latest/tools/3d-analyst-toolbox/locate-outliers.htm>

# ArcGIS LiDAR Tools

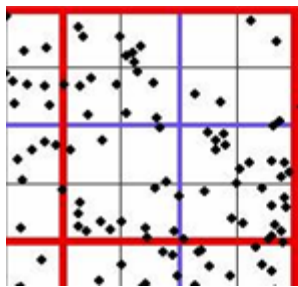
- Locate Outliers
  - Example – Extracting Roof Forms from LiDAR
    - Goal is to create realistic 3-D Building Models
    - Locate Outliers tool is used to limit the maximum and minimum point elevations in the dataset



<https://learn.arcgis.com/en/projects/extract-roof-forms-for-municipal-development/lessons/create-elevation-layers.htm>

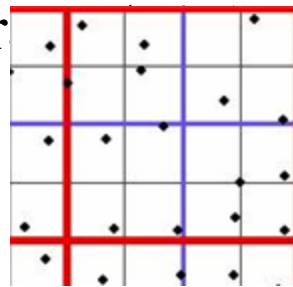
# ArcGIS LiDAR Tools

- Noise Minimization
  - Problem – LiDAR data can make messy slope maps
  - One Possible Solution
    - Convert LiDAR to terrain dataset
    - Use pyramiding to thin the data
    - Use a window size equal to the



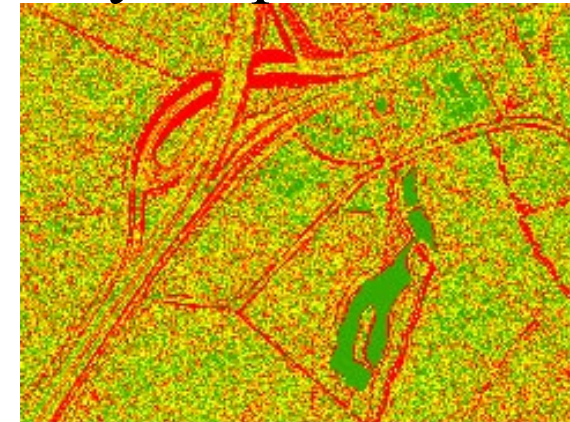
Full Resolution Point Data

No window size pyramid level has been applied to the points.



Window Size  
Pyramid Level 1

One point is selected in each black window to represent the terrain at the present scale range.



<http://desktop.arcgis.com/en/arcmap/latest/manage-data/las-dataset/LiDAR-solutions-minimizing-noise-from-LiDAR-for-contouring-and-slope-analysis.htm>

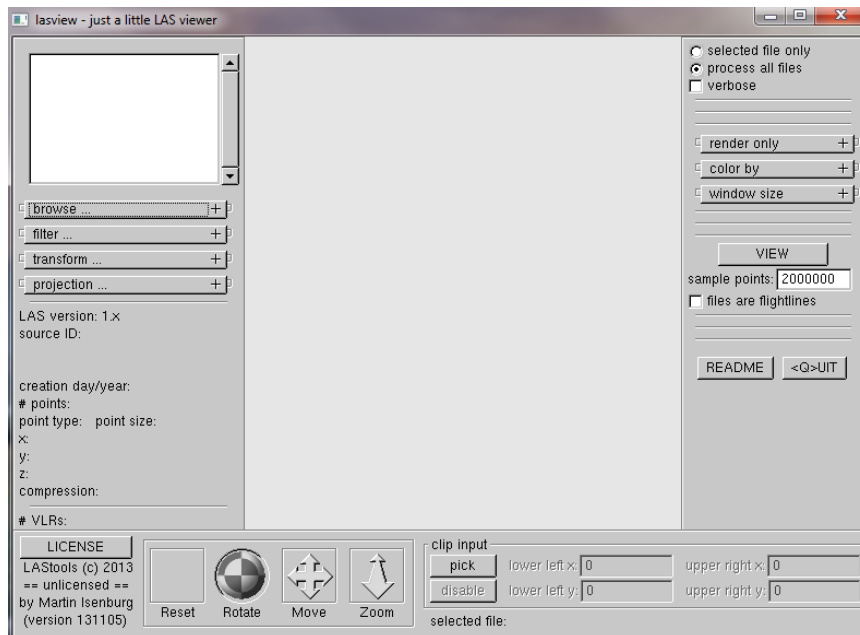
# LAStools

- LAStools
  - <http://rapidlasso.com/lastools/>
  - Suite of LiDAR processing tools
  - Free for personal use
  - License required for personal use
  - Run as executable or through ArcGIS or QGIS
  - Includes blogs, workshops, and tutorials
  - Low memory overhead and can run on multicores
  - Before using any tool, see the README file
  - We'll expand on these tools throughout the course

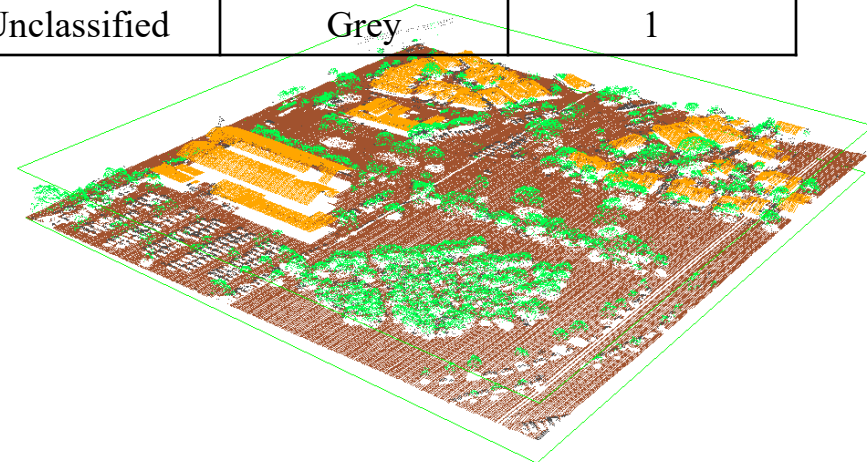


# LAStools

- LASview – A simple LiDAR data viewer
  - A bit bare bones, but very fast
  - Allows multiple classification schemes



Description	Color	Class
Ground	Brown	2
Building	Yellow	6
High Vegetation	Green	5
Unclassified	Grey	1



<http://rapidlasso.com/lasview/>

# LAStools

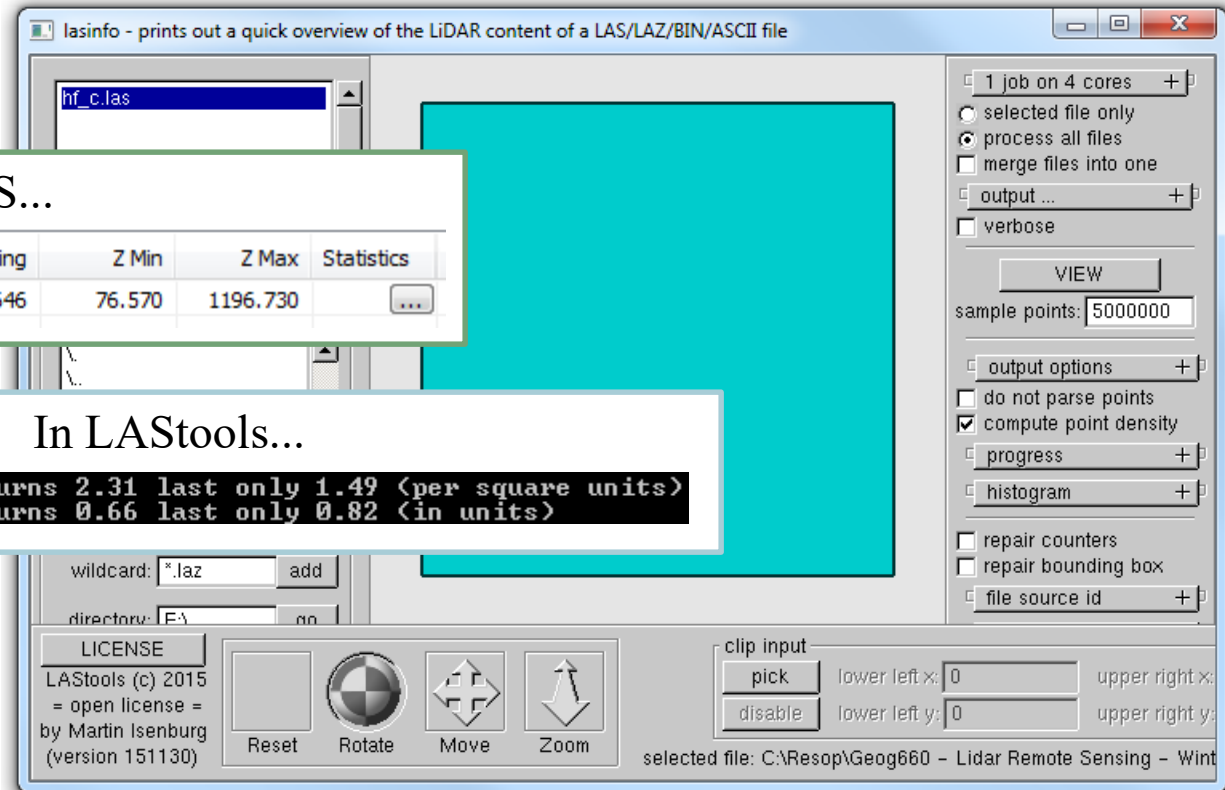
- LASinfo – Calculates Simple Data Statistics

In ArcGIS...

LAS File	Version	Point Count	Point Spacing	Z Min	Z Max	Statistics
hf_c.las	1.2	5,075,278	0.646	76.570	1196.730	...

In LAStools...

```
point density: all returns 2.31 last only 1.49 <per square units>
spacing: all returns 0.66 last only 0.82 <in units>
```



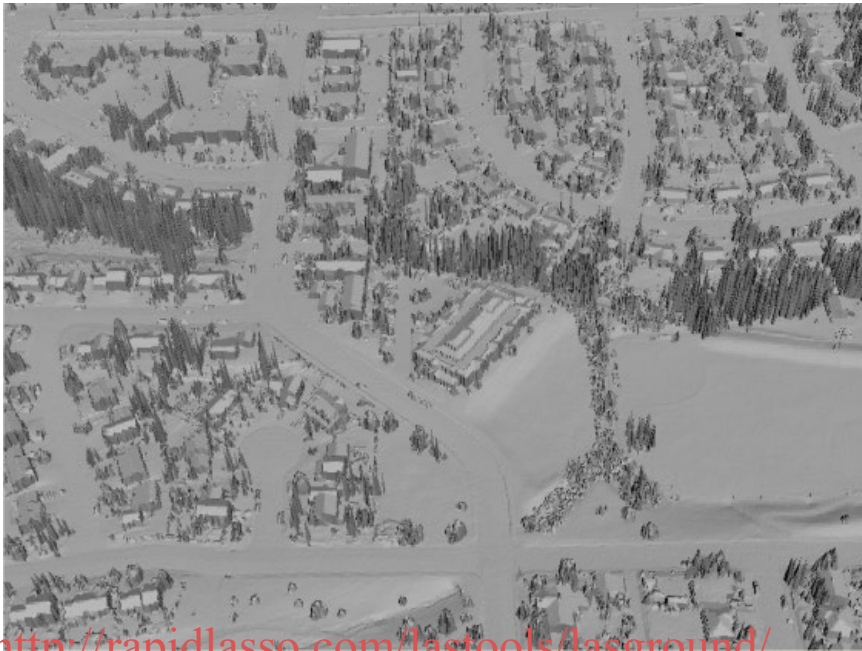
<http://rapidlasso.com/2014/03/20/density-and-spacing-of-LiDAR/>



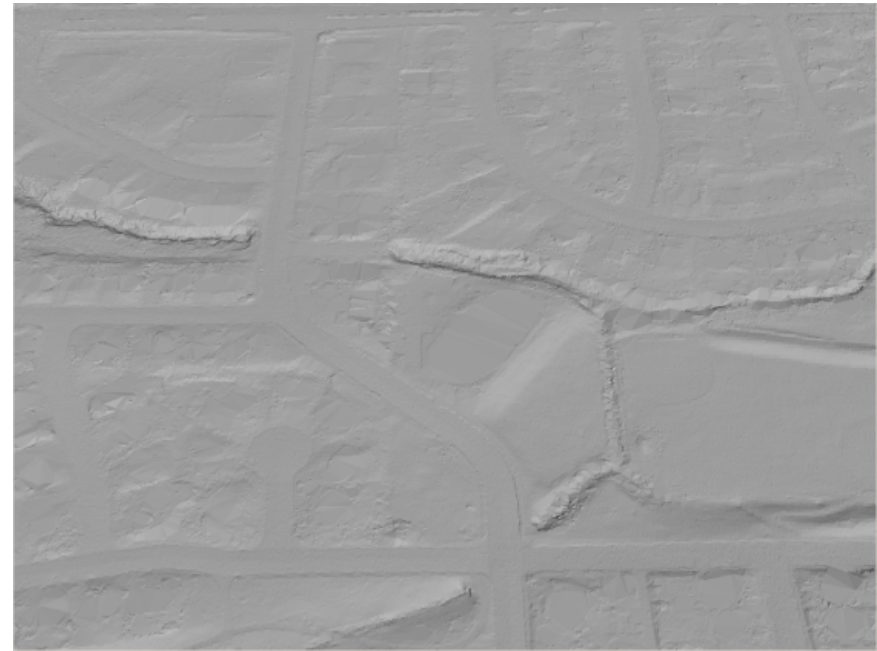
# LAStools

- LASground – Bare Earth Extraction
  - Classifies LiDAR data points as either ground (class = 2) or non-ground (class = 1)

Before, Raw Data



After, Ground Points



<http://rapidlasso.com/lastools/lasground/>

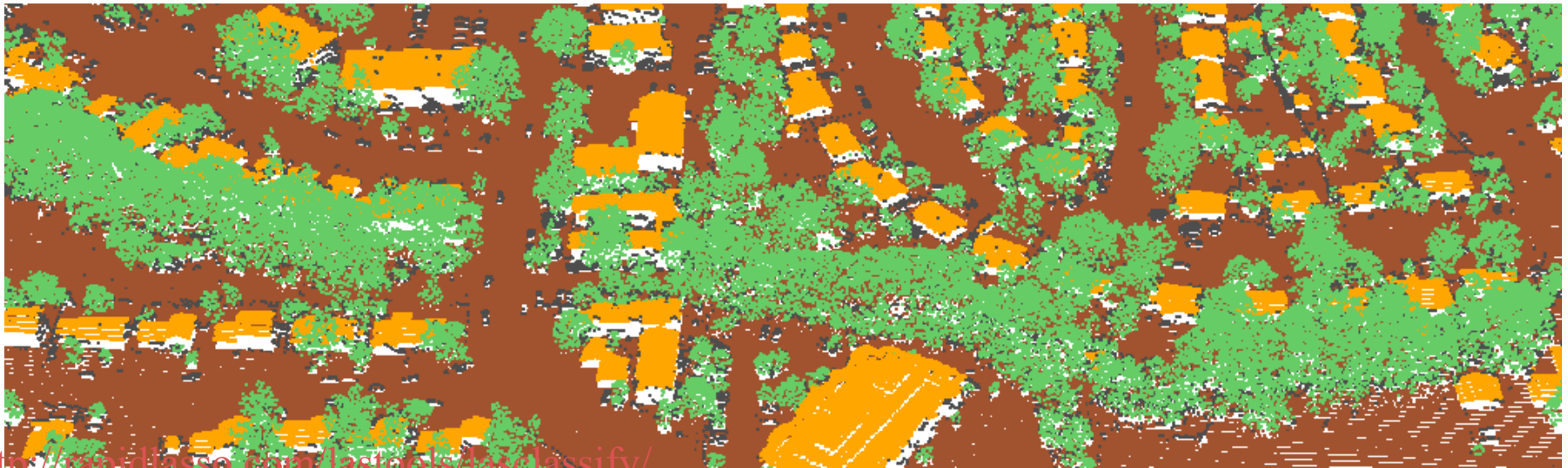
# LAStools

- LASheight – Calculates height above ground
  - Assumes ground classified as (class = 2)
    - First run LASground
  - Creates a temporary bare earth model TIN
  - Stores height in the "user data" field of LAS file
  - Allows the user to overwrite the Z values with height values (if they desire)
  - A possible method to develop canopy height models; we'll go more into this next Lecture
  - Can also use to filter out outliers and artifacts

<http://rapidlasso.com/lastools/lasheight/>

# LAStools

- LASclassify – Automated classification script
  - Classifies buildings (class = 6), vegetation (class = 5)
  - Requires that ground points are already classified AND that height above ground is calculated
    - First run LASground and LASheight

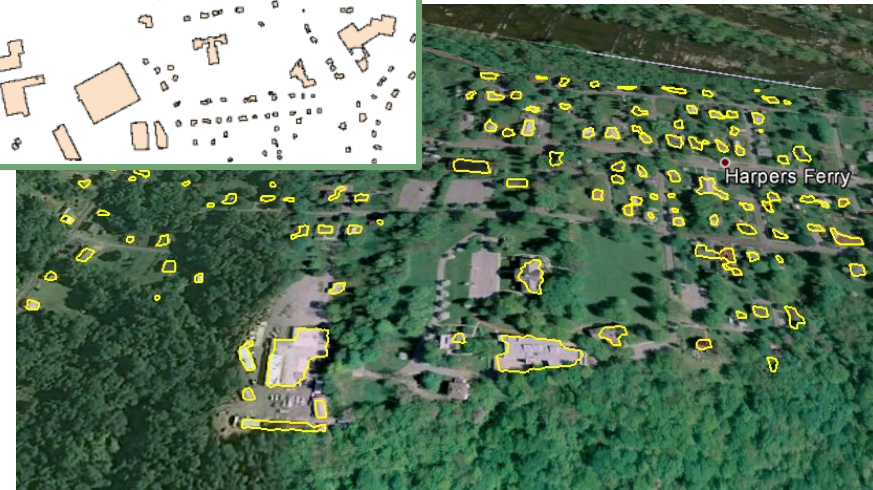
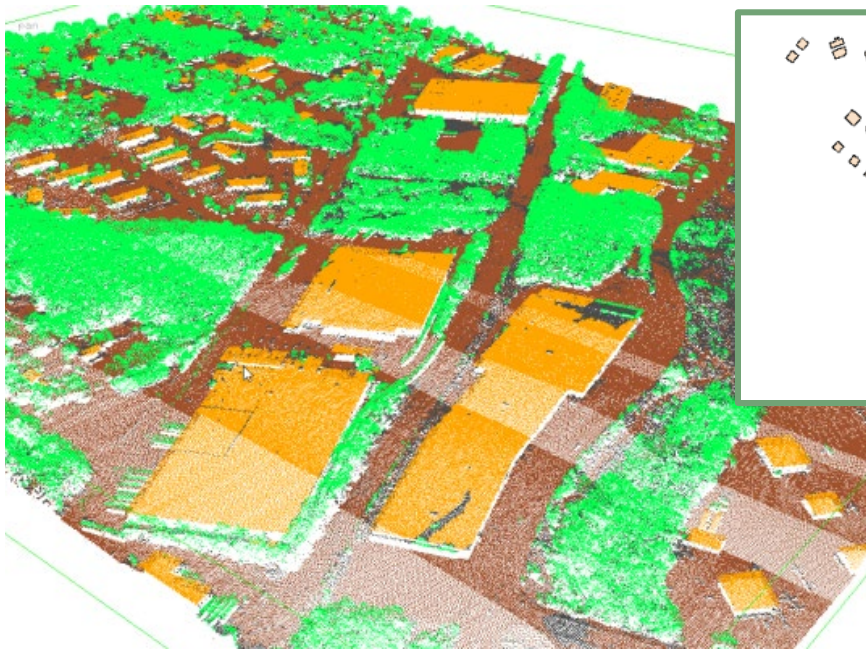


<http://rapidlasso.com/lastools/lasclassify/>



# LAStools

- LASboundary – Create boundary polygons
  - Heavily parameterized, pay attention to the lab
  - Validate results in Google Earth or with imagery



<http://rapidlasso.com/lastools/lasboundary/>

# LAStools

- Other Useful LAStools
  - LAS2txt
    - Converts from binary LAS/LAZ to an ASCII text format
  - LASoverlap
    - Computes and displays the area of flight line overlap
  - LASoverage
    - Removes overlap that is not in the flight line "sweet spot"
  - LASclip
    - Removes points outside of a polygon feature shapefile
  - LASnoise
    - Removes isolated noise points from a LiDAR dataset
  - Too many to list!