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1 Introduction

The concept of remote monitoring and control (R&C), has its roots like many technological advancements in the arms race during World War II. Its first implementation sought to create unmanned aircraft capable of delivering greater payloads at longer distances. Fast forward to 1960's the first successful use of remote monitoring in a medical field was the need for medical testing and care in a remote location such as outer space. Kaiser Foundation International (KFI), tackled this problem and became a major (\$1.8 million in the 1970's adjusted for inflation this equals about \$11.5 million today) subcontractor to the Lockheed Missiles and Space Company (LMSC) to help design, develop and test a ground based remote health care delivery system. "The ground-based test unit will be installed at a sparsely populated site on earth to provide medical care to local residents. Trained physicians assistants will employ the unit to transmit medical information on residents of the area to physicians at an established facility many miles from the remote site. If the test program is successful, it may provide system technology to improve health care and medical services to remote areas on earth. Part of a four year NASA sponsored program, this concept, as applied to a remote area on earth, will be evaluated by NASA for possible use in advanced, long-duration, manned space missions." [3] . Figure 1.1 on page 5 shows the logo of the Space Technology Applied to Rural Papago Advanced Health Care (STARPAHC) logo.



Figure 1.1: Space Technology Applied to Rural Papago Advanced Health Care [3]

But there were still many barriers standing in the way of widespread adoption of M&C tools in healthcare. Some of the main challenges include: data transfer rates, lack of broadband infrastructure, financial and technological to name a few, that made it difficult to implement on a civilian scale. True civilian scale implementation began in the last decade (2010's), in America with the 'Connecting America: The National Broadband Plan' that aimed to "assist in the proliferation and improvement of broadband networks across the United States." [4]. With the technological advancements since then, it is now more financially feasible to adopt a telemedical technology due to a well developed, fast (data rate transfer) and cheap broadband infrastructure, as well as smaller, faster and more power efficient micro-controller-sensor integrated circuits.

1.1 Project aims

The aim of the project is to:

- 1 Design and program a wearable device for:
 - Collecting Electrocardiography (ECG) data,

- Sensing wearers physical activity (Pedometer).

The device must then be able to send the data to a remote database.

- 2 Design and program the database to store the ECG and Pedometer data.
- 3 Build a website that is able to display the data.

Figure 1.2 on page 6 shows a simplified flowchart of the possible data flow sequence. For the detailed flow chart see Figure 2.9 on page 15.

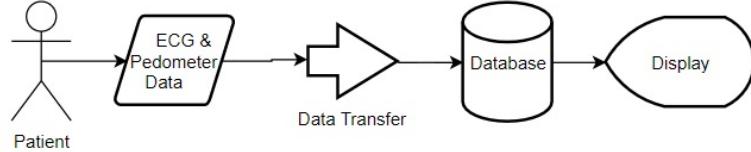


Figure 1.2: A simplified flow chart of the project aim

2 Analysis and design

In a lot of cases today, the need for patients to stay in hospital for long periods of time, is due to the need to monitor their biological signals as well as well-being. This is done to provide a safe environment for their recovery after treatment, or in case a diagnosis could not be made, to monitor them until the patient is deemed safe to discharge. This is especially true for older patients. The use of mobile sensors combined with remote monitoring would enable these patients to be discharged earlier compared to standard discharge time. This in turn would free up hospital space. Another benefit of this would be a substantial decrease in the cost of health care per a patient. Another advantage of remote monitoring in healthcare is the possibility of implementation and use of intelligent algorithms, which would continuously scan the data for anomalies in patients vital signs and identification of everyday routines and warning in case an out of ordinary event has been identified.

Recent advancements in technology facilitate the development of R&C even more. The use of smart sensors, which combine integrated circuits with sensing materials have already revolutionised many scientific, commercial and engineering fields. This is due to the fact that microprocessors have been getting smaller, faster and more power efficient with time, coupled with wireless connectivity where high data rates are available seemingly everywhere.

2.1 Existing implementations

As this concept is not new, there are a lot of companies that have already developed and created different solutions each with unique pros and cons. They find use both as private client based products as well as hospital provided services for better care and more efficient work flow. Some of the leading remote monitoring solution providers are:

- Biotronik Home Monitoring,
- Boston Scientific LATITUDE NXT,
- A&D Medical, Wellness Connected,
- GE Healthcare, Apex Pro CH.

2.1.1 Biotronik Home Monitoring

Biotronik Home Monitoring is a pioneering and first in class, remote cardiac monitoring system. Designed to maximise patient comfort while reducing patients effort, it sends data daily. Continuous cardiac device data is sent to the personal patient device, which in turn forwards the information to the Home Monitoring Service Center (HMSC). Furthermore HMSC allows physicians to safely review cardiac functions as well as sending alerts about relevant changes in patient health and the devices status. This allows for the continuous monitoring of both the patients condition and the device. Figure 2.1 on page 8 shows the company's logo, with their trademark slogan "excellence for life".



Figure 2.1: Biotronik logo [6]

2.1.2 Boston Scientific LATITUDE NXT

Boston Scientific LATITUDE NXT is a in-home monitoring system allowing physicians to monitor connected devices between care visits. These devices send data at scheduled time, some of the devices that can connect to the LATITUDE NXT include: blood pressure monitors, cardiac monitors, weight scales, pacemakers and other healthcare devices. This products enables patients to plug-in the Communicator to the all ready existing analogue and digital phone lines, allowing the Communicator to connect to the LATITUDE system. In case the Communicator is not compatible with the phone line, additional equipment is required to connect via internet or cellular network. The connector is hands-free, meaning that it does not require patient intervention to send data and that it is done automatically. The LATITUDE NXT system is designed to improve clinic efficiency as well as provide a higher level of care for device patients. The company also developed an App that allows clinicians a read-only access to see LATITUDE

NXT system patient data from an iPhone. Figure 2.2 on page 9 shows the LATITUDE Communicator.



Figure 2.2: LATITUDE Wireless Communicator [7]

2.1.3 A&D Medical, Wellness Connected

Wellness Connected is an App that is simple and easy-to-use available for both Android and iOS users. It allows clients to manage their health and wellness by monitoring their key health metrics. From blood pressure, heart rate, weight to activity, calorie usage and sleep patterns. The App allows the client to better understand their current health state and allows for setting goals and charts the clients progress. The app also allows the user to share their current progress with family and even physicians. The App is free on

both AppStore and Google play but it requires the A&D Medical connected devices to gather data. The product range includes:

- a Deluxe Connected Weight Scale see figure 2.3 on page 10,
- b Deluxe Connected Blood Pressure Monitor see figure 2.4 on page 11,
- c Lifetrak Move Connected Activity Tracker see figure 2.5 on page 11,
- d Lifetrak Zone Connected Activity and Sleep Tracker see figure 2.6 on page 12.

This allows the user to tailor the data collected about them to their own preference and need but requires the user to interact with all the separate devices, which can be inconvenient.



Figure 2.3: Weight Scale [8]

2.1.4 GE Healthcare, Apex Pro CH

Apex Pro CH is a medical system offered by GE Healthcare. "ApexPro CH telemetry offers a highly flexible telemetry system to meet the current and future telemetry needs of growing hospitals" [5]. The ApexPro monitoring allows for centralised as well as decentralised use. Because the data



Figure 2.4: Blood Pressure Monitor [8]



Figure 2.5: Activity Tracker [8]



Figure 2.6: Activity and Sleep Tracker [8]

is accessible throughout the whole facility (Hospital), patients can migrate throughout the organisation while being monitored. Figure 2.7 on page 13 shows one of many GE Healthcare products compatible with their Apex Pro CH platform in this case the ApexPro FH.

2.2 User expectations

The final design should require as little interaction from the user as possible, and be simple to set up with regards to the wearable device see figure 2.8 on page 14. The device should also be capable of wireless communication. And with regards to the viewing data website, it should be intuitive for the user to interact.

2.3 Proposed design

Figure 2.9 on page 15 shows the detailed flow chart of the project. In total 4 programming languages were used:

- C,
- Hypertext Preprocessor (PHP),



Figure 2.7: ApexPro FH Telemetry System [5]

- Structured Query Language (SQL),
- C Sharp (C#).

And 3 different communication protocols:

- Inter-Integrated Circuit (I²C),
- Hypertext Transfer Protocol (HTTP),
- Secure Shell (SSH).

Due to the complexity of the project, and many stages of data transfer, each written in a different programming language, it will be easier to further sub categorise the project into:

- 1 The wearable device design,
- 2 Server design,
- 3 Displaying data.

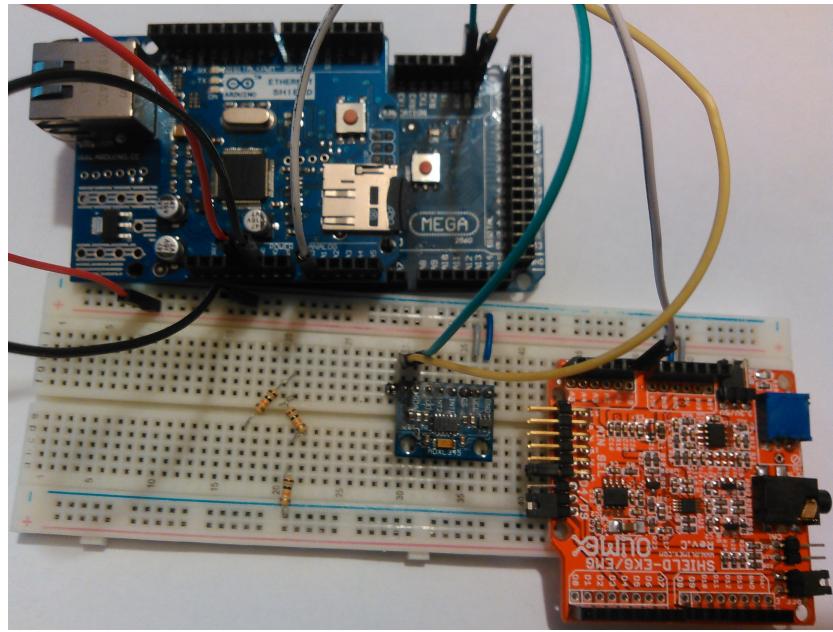


Figure 2.8: Wearable device design

2.3.1 Wearable device design

The wearable device consists of: a breadboard, two sensor modules, a micro-controller board and a Ethernet shield. The two sensor modules used were:

- a Olimex SHIELD-EKG-EMG see figure 2.10 on page 16,
- b Analog Devices ADXL 345 see figure 2.11 on page 16.

Arduino MEGA 2560 was used as the micro-controller board, the internet communication was done via Arduino Ethernet Shield, See figure 2.12, 2.13 on page 17 for the Arduino boards used.

2.3.2 Server design

Raspberry pi 3 was used as the server. First apache2 server had to be installed to host web pages, then php7 and MaridDB to handle the data. For detailed installation notes see the installation guide. Figure 2.14 on page 18 shows what Raspberry Pi 3 looks like.

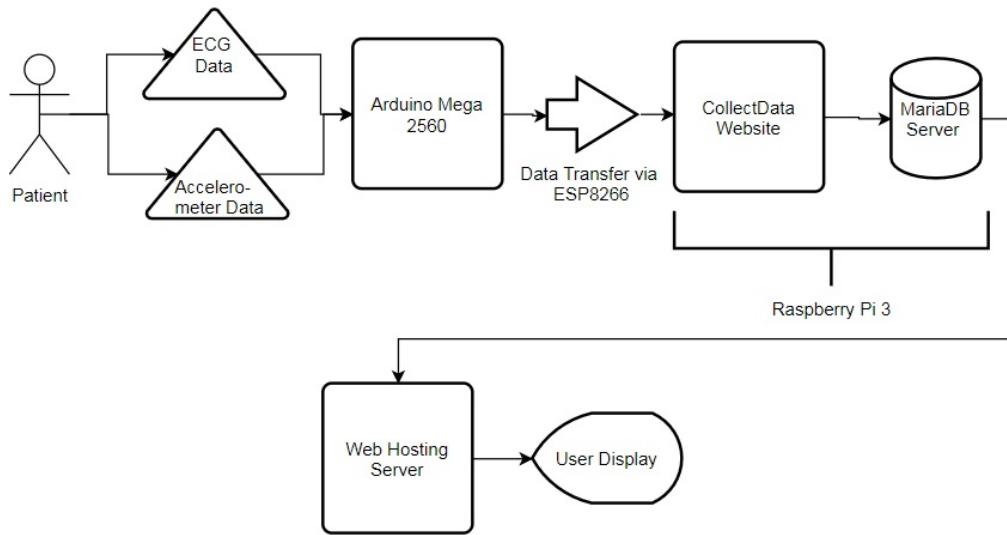


Figure 2.9: Project flowchart

2.3.3 Displaying the data

A Model-View-Controller (MVC) ASP.NET web application was used to display the data. Figure 2.15 on page 19 shows what the web application looks like.

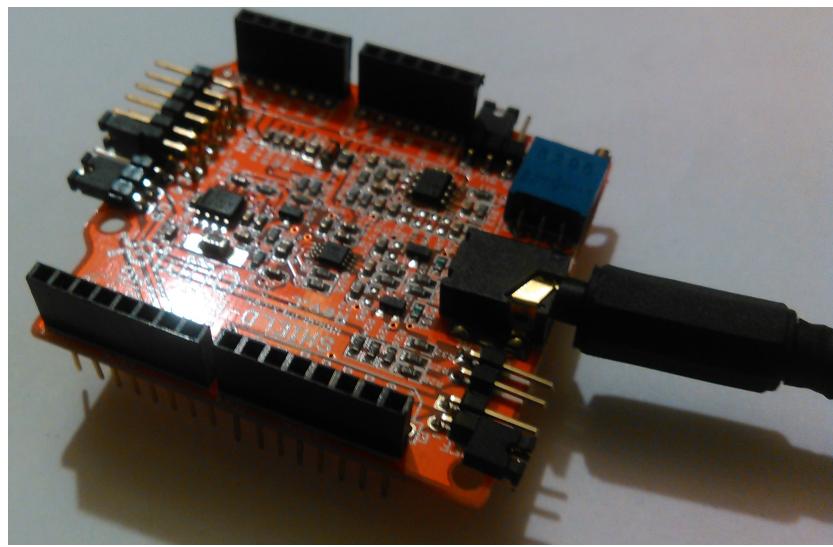


Figure 2.10: SHIELD-EKG-EMG

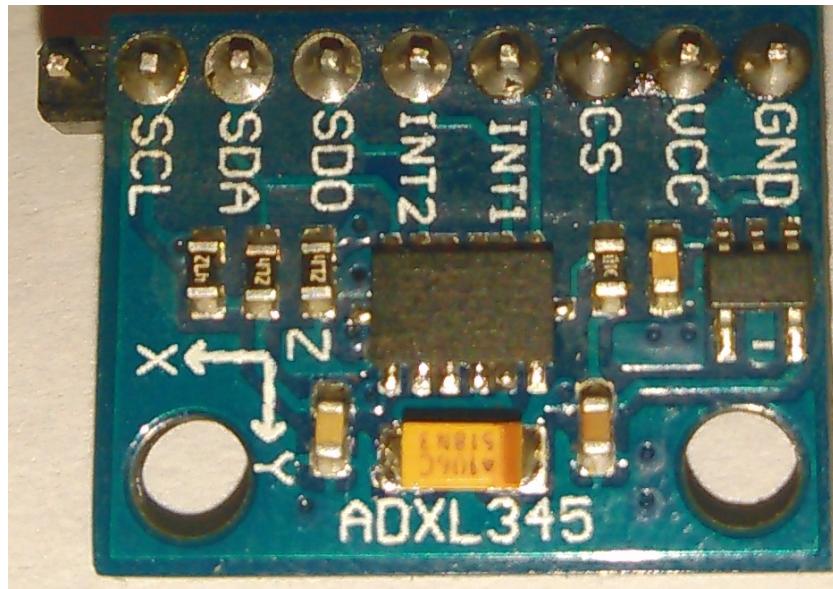


Figure 2.11: ADXL345

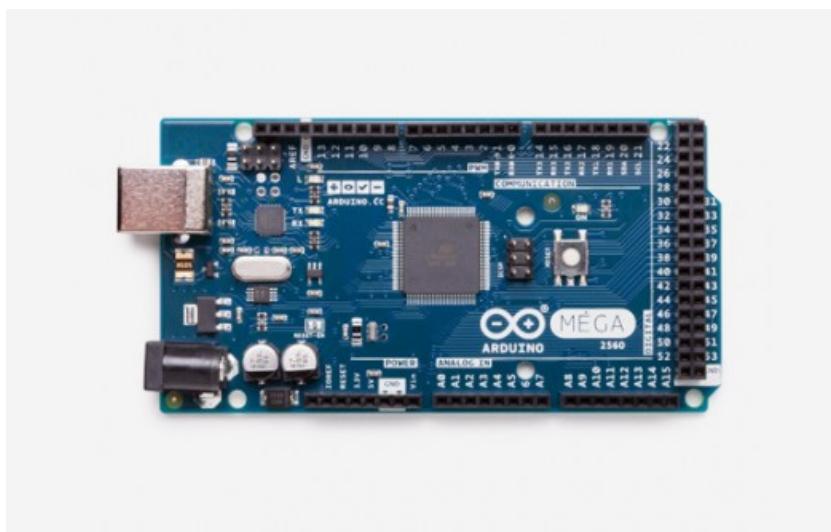


Figure 2.12: Arduino MEGA 2560 [1]

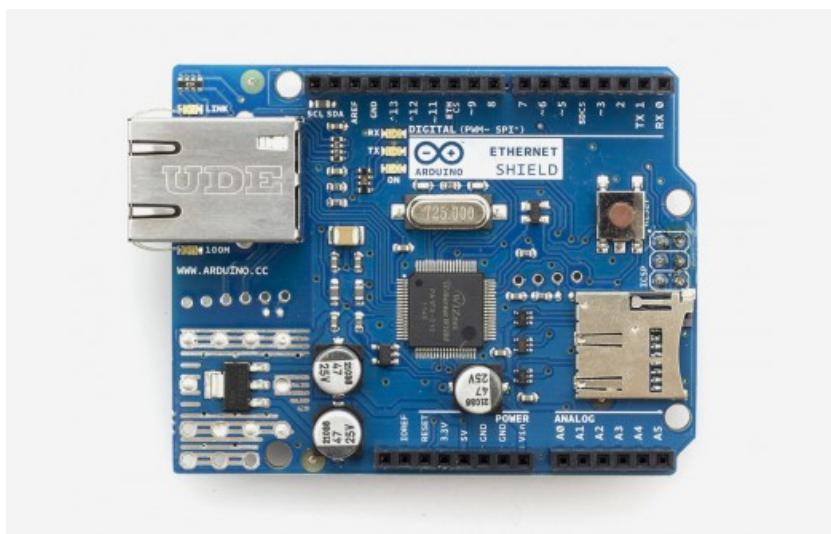


Figure 2.13: Arduino Ethernet Shield [1]



Figure 2.14: Raspberry Pi 3 [2]

3 Internal specification

The whole project can be categorised with respect to the programming language used. There for there will be 4 subsections: C, PHP, SQL and C# respectively. with the exception of SQL, all the files containing the discussed code can be found in the '/Code/' directory provided the root directory is the project CD/DVD drive, this will always be the case when directory navigation is mentioned unless specified otherwise.

3.1 C

C is the code that is executed by the Arduino MEGA 2560 micro-controller. It measures or requests measurements from the modules attached, then it processes the data and finally sends the data to the server via the Ethernet module. The `SendData.ino` located in the '/Code/Arduino/SendData/' directory contains all the code that will be discussed in this subsection. This part of the project also requires cable connections to be made between the micro-controller and modules. GND to GND and 5V to VCC have to be made on all boards with the exception of the ESP8266 module which can

Sample List		
Id	ECG	PEDO
1	200	1
2	230	3
3	230	0
4	250	2
5	0	2
6	36	2
7	250	2
8	36	2
9	0	0
10	10	0
11	10	2
12	20	2
13	1	2
14	10	2
15	20	2
16	1	2
17	10	2
18	20	2
19	1	2
20	10	2
21	20	2
22	1	2
23	10	2
24	20	2
25	1	2
26	329	0
27	328	0
28	330	0
29	330	0
30	330	0

Figure 2.15: Web application

only take 3.3V. Table 1 on page 20 shows how all other connections are to be made.

3.1.1 Collecting ECG data

Collecting ECG data is very straightforward because all that is needed is a analogue to digital conversion of the A0 pin on the Olimex shield. But the sampling rate has to be consistent there for a timer interrupt has to be used to achieve this. Arduino MEGA 2560 has 6 built in timers, timer0 to timer5. Timer5 has been configured as this timer is not used by the delay() function and the Wire library as well as the PWM outputs are located at pins 44, 45 and 46. A sampling rate of 200Hz will be used as it is the smallest sampling rate at witch the ECG signal can still analysed. Using the function:

$$\text{Timerspeed}(Hz) = \frac{\text{Arduinoclockspeed}(16MHz)}{\text{prescaler} * (\text{compareregister} + 1)} \quad (1)$$

Pin number on Arduino MEGA board	Pin number on module
A0	A0 on the Olimex EKG-SHIELD
SDA 20	SDA 7 on ADXL 345
SCL 21	SCL 8 on ADXL 345
If connecting the Arduino Ethernet module	
RX0	RX0
IOREF	IOREF
If connecting the ESP8266 module	
RX0	RX
TX0	TX
GND	GND
3.3V	3.3V
GND	IO0
3.3V	EN

Table 1: Table of connections

By rearranging the equation and using a 64 prescaler, compare match register value can be found as it is needed to set the correct frequency:

$$\text{comparematchregister} = \left(\frac{16000000}{64 * 200} \right) - 1 \quad (2)$$

The compare match register value is 1249, it is possible to set this value as greater than 256 because timer5 is a 16bit timer therefore the maximum register value is 65536.

3.1.2 Collecting Pedometer data

The Pedometer data first has to be collected. First the ADXL345 accelerometer data has to be pulled up. This is done using I²C serial communication. Serial Peripheral Interface (SPI) could also be used, but it requires a greater number of connections (4 in case of SPI and only 2 in case of I²C). For this protocol the sensor address and the data registers address have to be known. In this case the sensor address is 0x53 and the data registers addresses are

0x32 to 0x37, where 0x32 (DATA_X0) and 0x33 (DATA_X1) are the data registers addresses for the X-Axis. Both registers contain 8 bits of data that have to be combined for a 16 bit X-Axis measurement. The DATA_X1 register contains the most significant bits (MSB) of the 16 bit number. The same operation needs to be done to the Y and Z axis, 0x34 (DATA_Y0) and 0x35 (DATA_Y1) are both are the Y-Axis register addresses with the DATA_Y1 containing the MSB, 0x36 (DATA_Z0) and 0x37 (DATA_Z1) are both are the Z-Axis register addresses with the DATA_Z1 containing the MSB. These values are then squared and summed. The sum is later compared to a threshold value and if the sum is greater than the threshold value then a step-counter is incremented and returned.

3.1.3 Sending data

Originally the wearable device was intended to be wireless. But due to electrical problems the ESP8266 Wi-Fi module could not be used. This was because Arduino MEGA 2560 can supply a maximum current of 50mA on the 3.3V pin and the ESP8266 wifi module at peak power consumption when transferring data over Wi-Fi network, requires 400mA. And therefore the module reset when insufficient power to the module was provided. Also the breadboard used to power all the devices with an inbuilt, 3.3V stabilizer could not be used to power the ESP8266 Wi-Fi module as the 3.3V ground and the 5V ground of the breadboard power supply had a voltage difference of 1.5V. This would make it impossible for the ESP8266 Wi-Fi module to communicate with Arduino MEGA 2560 as they would not share a common ground. And due to time constraint buying and waiting for voltage stabiliser was not an option. Nevertheless both the Ethernet shield and the ESP8266 Wi-Fi shield code files are included in the '/Code/Arduino/Transferring Data/' directory. But ultimately the Ethernet shield code was used in the Send-Data.ino file. To send the data first the IP address of the Raspberry Pi 3 server has to be known. In this case it is 192.168.0.38. After a successfully connection to the server as a client the POST request can be sent.

```
POST /collectdata.php HTTP/1.1
Host: 192.168.0.38
Accept: */*
Content-Length: 32
Content-Type: application/x-www-form-urlencoded
```

```
ecg=ecgString&pedo=NumberOfSteps
```

First the request method is specified in this case POST, then the file is specified and the HTTP protocol version. Another key part of the POST request is the Content-Type specifier as well as Content-Length. And finally the parameter name and values are specified, in case of more than one parameter each successive parameter is added after the & sign. The post method was used as it has no data length restraint compared to a GET request.

3.2 PHP

The *collectdata.php* file contains the PHP code that is executed every time it is requested, the file can be found in the '/Code/' directory. First two values *ecgString* and *pedo* are created and inherit values from their POST equivalent. Because ECG data is sent as a long string where each value is separated with a "," from the next one the built in *explode()* function is used to separate the values and inserts the into *aecgArray*. Next a *mysqli_connect* link is created that will grant access to the database. If link execution is successfully, data is inserted into an existing table "patient1". After the data has been inserted into the table the connection is closed.

3.3 SQL

First, two new users have to be created. One that will have access to the database from the php file and the other that will have external access from the MVC web application. This is done using:

```
create user 'collect'@'localhost' identified by 'data';
create user 'proj'@'localhost' identified by 'mnp';
```

Next the database that will store the ECG and Pedometer data is created, this is done using the querry:

```
create database ecgpedodata;
```

After the database has been created a table has to be created to store data:

```
USE ecgpedodata;
CREATE TABLE patient1 (id MEDIUMINT NOT NULL AUTO_INCREMENT, ecg SMALLINT
NOT NULL, pedo TINYINT NOT NULL);
```

All that is left is to grant access to the created users to ecgpedadata database.

```
GRANT ALL PRIVILEGES ON ecgpedodata.* TO 'collect'  
@'localhost' IDENTIFIED BY 'data';  
GRANT ALL PRIVILEGES ON ecgpedodata.* TO 'proj'  
@'192.168.0.%' IDENTIFIED BY 'mnp';
```

The first user only needs to access the database on local host , but the website needs to be able to access the database remotely therefore a "%" which will allow the proj user to log into the database from any Internet Protocol (IP) dress on the local network.

3.4 C#

Because the Raspberry Pi 3 server is a MySQL server and not a SQL server a MySQL.Data NuGet package has to be installed for the server to recognise the queries as show by figure 3.1, 3.2 on page 24, 25.

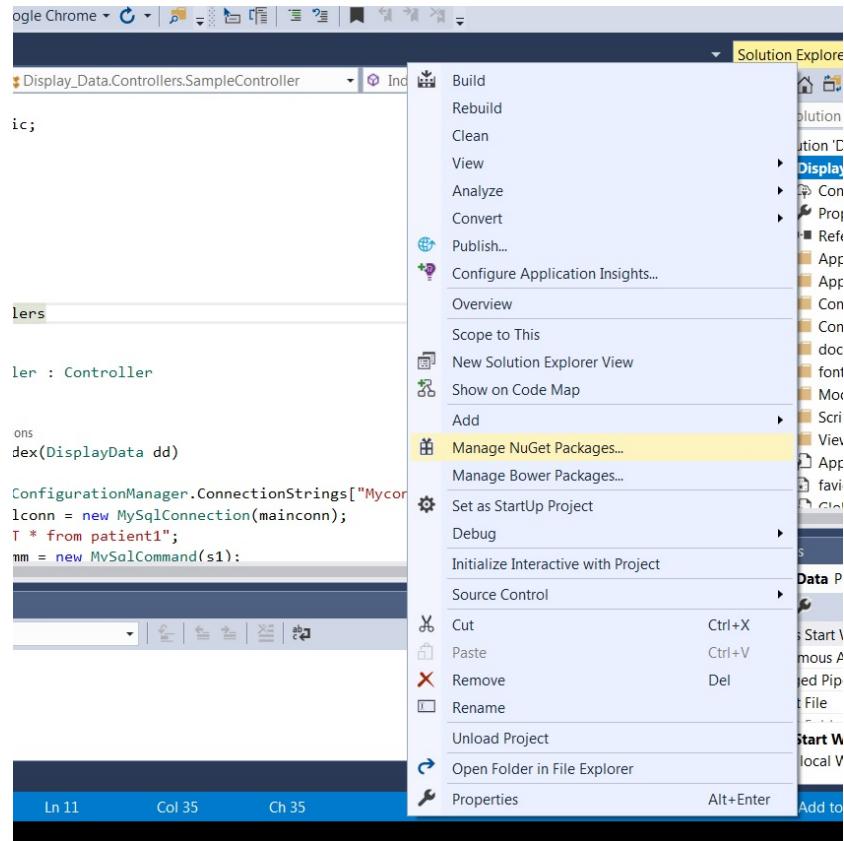


Figure 3.1: Manage NuGet packages option

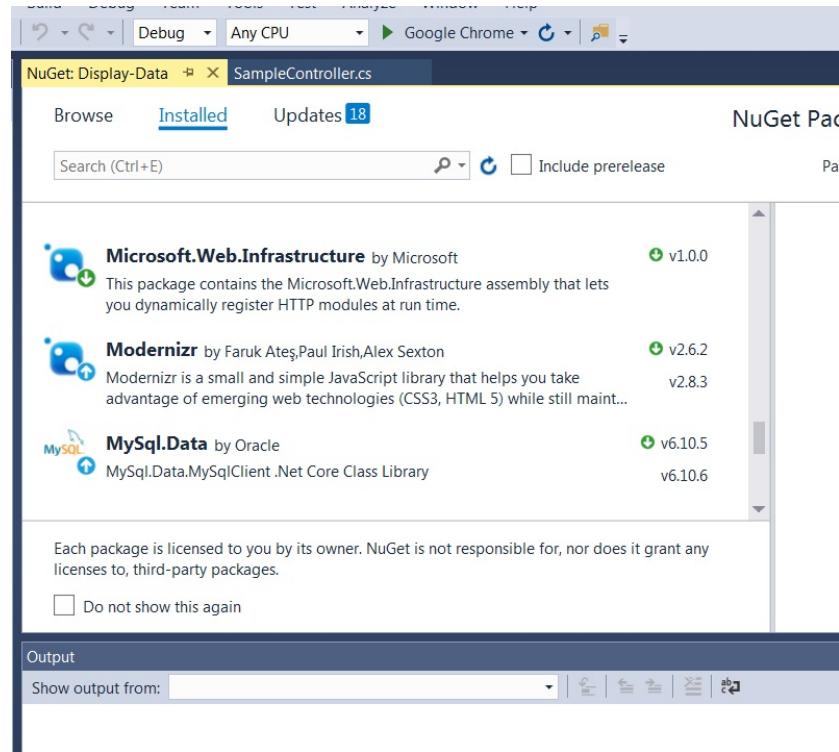


Figure 3.2: NuGet packages manager

A connection string has to be added to Web.config file that specifies the servers IP address the database and the user details.

```
<add name="Myconn" connectionString="Data Source=192.168.0.38;  
port=3306; Initial Catalog=ecgpedodata;User Id=proj;password=mnp" />
```

In the SampleController.cs using the directive MySql.Data.MySqlClient a connection to the Raspberry Pi server is established and data from ecgpedodata database, table patient1 is accessed. Which is then displayed as a table by Index.cshtml.

4 External specification

For full Raspberry Pi installation and set-up see the Instalation.pdf file located in the '/Raport/' directory. To set up the wearable device, first the electrodes 4.1 on page 26, have to be placed on the body of the patient, see figure 4.2 on page 27. It is good practice to shave the hair under the electrode prior to application.

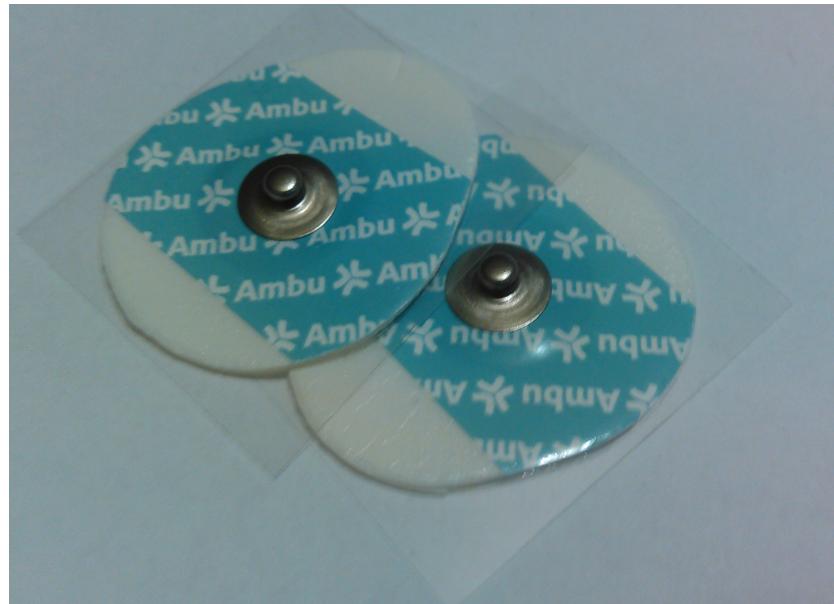


Figure 4.1: Electrodes



Figure 4.2: Electrode on the patient

Next attach the leads to the electrode and plug in the jack end of the cable to into Olimex SHIELD-EKG-EMG, it should be noted that red lead attaches to the right arm electrode, white lead attaches to the left arm electrode and the black lead attaches to the left ankle, see figure 4.3, 4.4, 4.5. Figure 2.10 on page 16 shows how the jack end of the leads plugs in to the Olimex SHIELD-EKG-EMG.

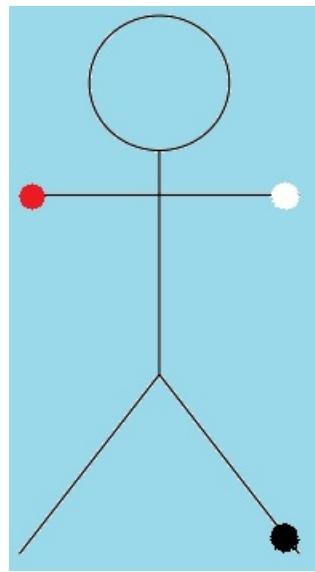


Figure 4.3: Lead colour placement



Figure 4.4: Lead



Figure 4.5: Electrode attached to the lead

Connect the Ethernet shield via a Ethernet cable to a router. Next turning the power button on the bread board power supply to power on the wearable device. This concludes the wearable device set-up.

To display the gathered data open the solution and run the program, see figure 2.15 on page 19 what the data display looks like.

5 Testing and Results

Figures 5.1, 5.2 show the A0 Olimex SHIELD-EKG-EMG value against time graph. Figure 5.1 with the highest possible sampling rate and figure 5.2 with the sampling rate of 200Hz. This shows that the sampling rate has been chosen correctly and as no crucial data has been lost. The noise could be caused by high frequency muscle contraction or power line interference (50Hz). Olimex SHIELD-EKG-EMG has a 3rd order "Besselworth" filter with the cut-off frequency set to 40Hz.

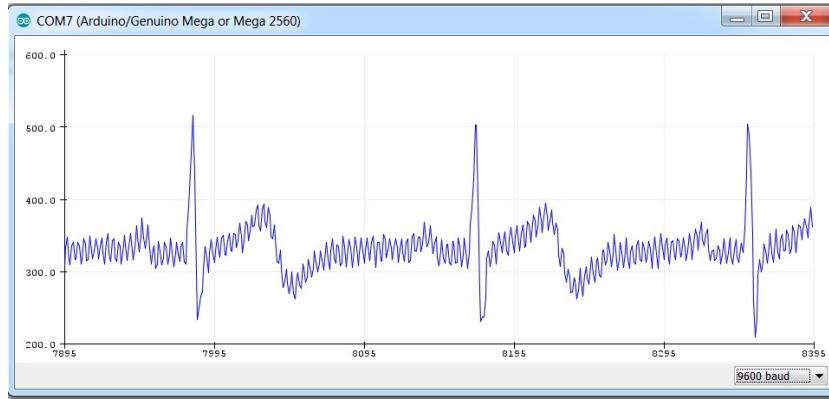


Figure 5.1: ECG with the highest possible sampling rate

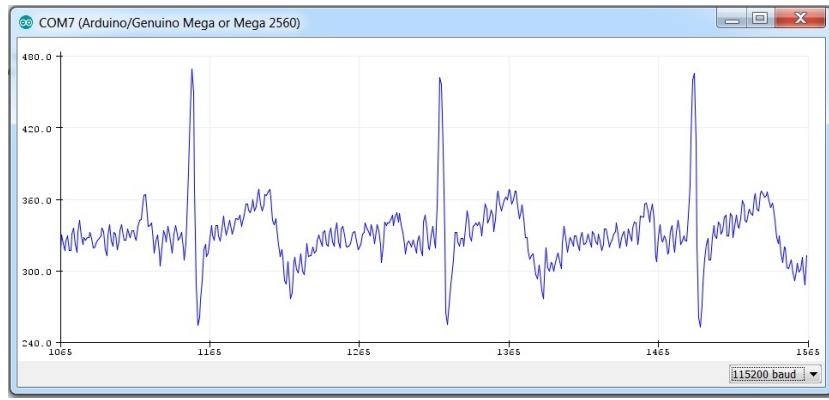


Figure 5.2: ECG with 200Hz sampling rate

Next the ECG signal of a stationary person (figure 5.1), is compared to a physically active one (figure 5.3), a conclusion can be drawn that collecting ECG data while the patient is walking results in the signal being very distorted. This limits the use of this very much as only one variable can be collected at a time. Either pedometer data is collected and the ECG data is too distorted, or the patient is forced to stay stationary.

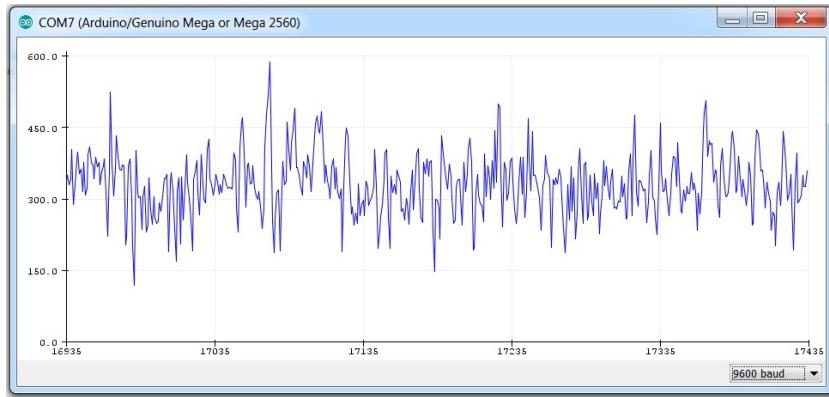


Figure 5.3: Active

All other data processing and data transferring steps work well as can be seen by figure 2.15 on page 19.

6 Summary and Conclusion

To summarise

- 1 A wearable device capable of collecting ECG data and counting the patients steps (pedometer) has been successfully implemented.
- 2 The device is also capable of sending this data to a remote database.
- 3 A system of collecting the data and writing it to the database has been implemented successfully.
- 4 A database to store the patients data has been designed.
- 5 A web application having access to the database and capable of displaying the data has been built.

Therefore all project aims have been met. But some key design specifications have not. These are:

- 1 The wearable device is not a mobile device because it requires constant Ethernet cable connection for the data to be sent to the database,
- 2 The wearable device is not capable of sustaining long pedometer readings as the cables used for communication between the micro-controller and ADXL345 tend to come out and this stops the algorithm from functioning properly,
- 3 The web application displays the data in a very raw manner, and is not intuitive.

To improve the project a voltage stabiliser should be used to provide sufficient power to the ESP8266 Wi-Fi module to work without rebooting. Another solution would be to use a Wi-Fi shield capable of running of 5V input. This will allow the patient to move freely with the device anywhere. Data saving to a SD card should be implemented. This will allow for data storage in case there is no internet available or the server is off-line for maintenance. A crucial improvement to the project is the permanent soldering of cable connections, used for supplying power and communication. This will result in more resilient wearable device. Another key feature of the project is the web application. Improving the application by displaying data as graphs, implementing user authentication that would allow several users to access their data would drastically improve project quality.

References

- [1] *Arduino MEGA 2560 and Ethernet Shield* product page:
<https://store.arduino.cc/arduino-mega-2560-rev3>
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List of used software:

- Arduino,

- Win32DiskImager,
- PuTTY,
- Raspberrian Jessie,
- MariaDB,
- Apache,
- MySQL,
- Visual Studio,
- LaTeX.

The licences for the software can be found in the '/Raport/License/' directory.