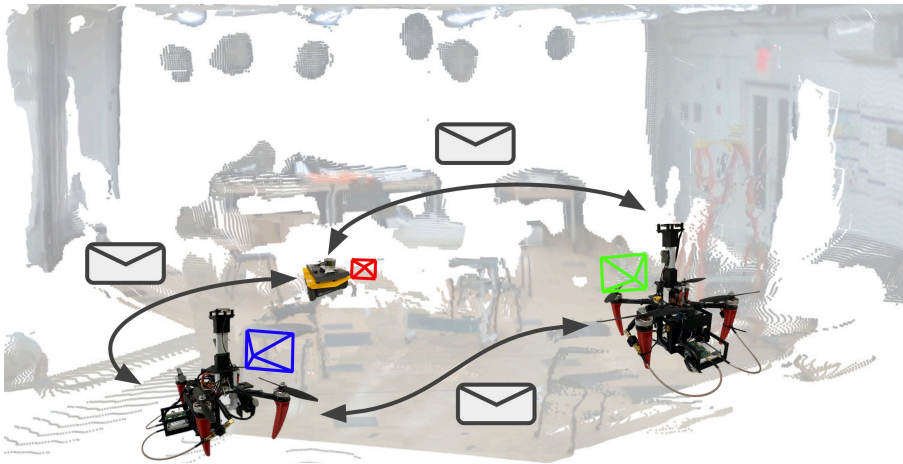




RGB Input



Reconstructed consistent 3D Pointcloud output by ARGOS framework



Depth Output