

Efficient Auto-Tuning of Parallel Programs with Interdependent Tuning Parameters via Auto-Tuning Framework (ATF)

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
⚠ Please Note ⚠

This talk will be on a quite high level:

- focus of this talk are the “what” & “why” questions;
- we address the “how” question by illustrating our basic ideas only;
- details about our approach can be found in the paper.

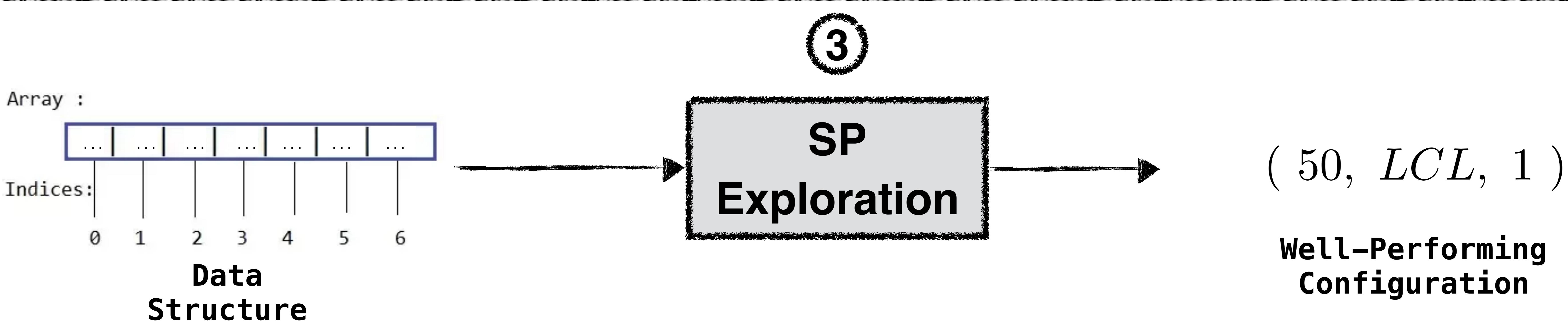
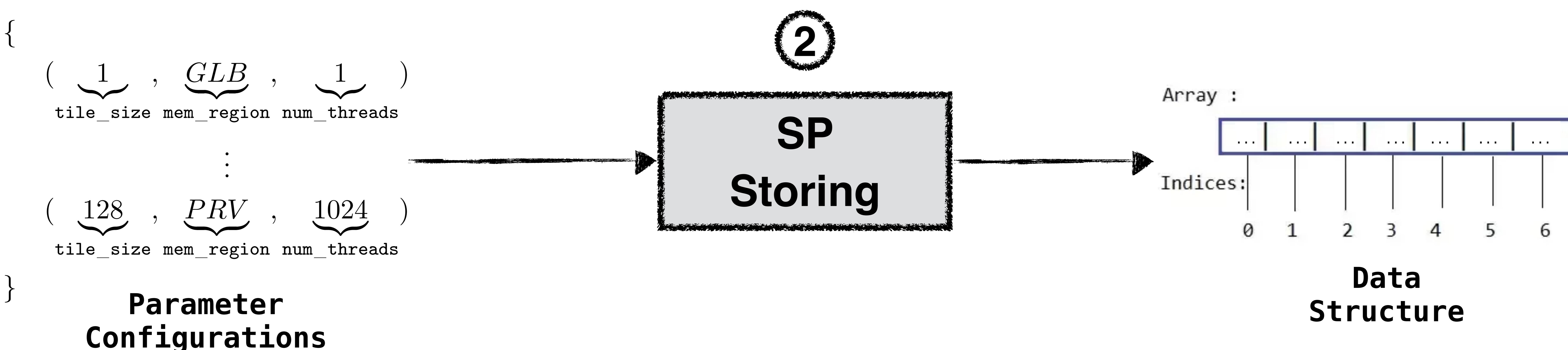
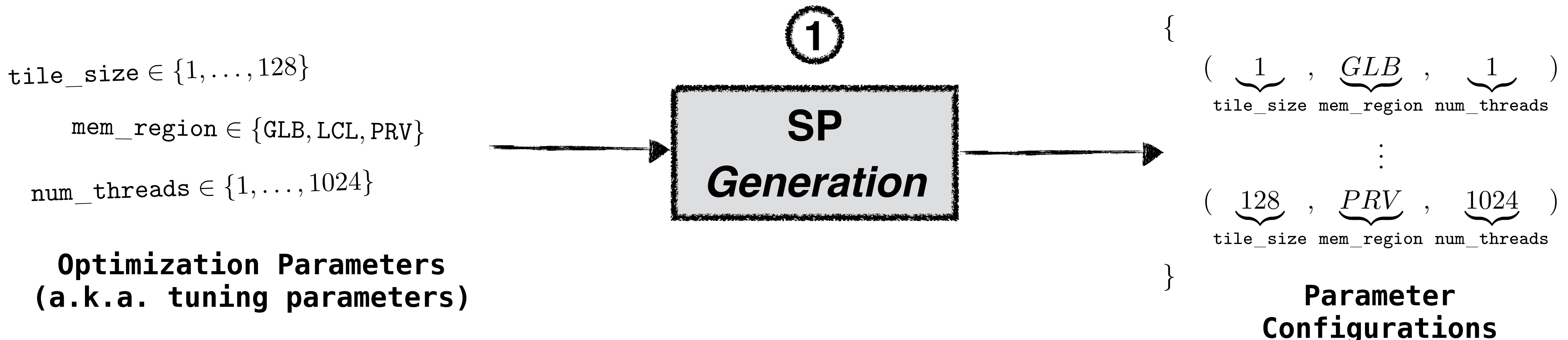
What is *Auto-Tuning*?

Auto-Tuning (AT) aims at automatizing the process of code optimization:



What is *Auto-Tuning*?

Auto-Tuning usually consists of three major phases:



What is *Auto-Tuning*?

Auto-Tuning (AT) can be categorized into two major categories:

Special-Purpose (SP) Auto-Tuning

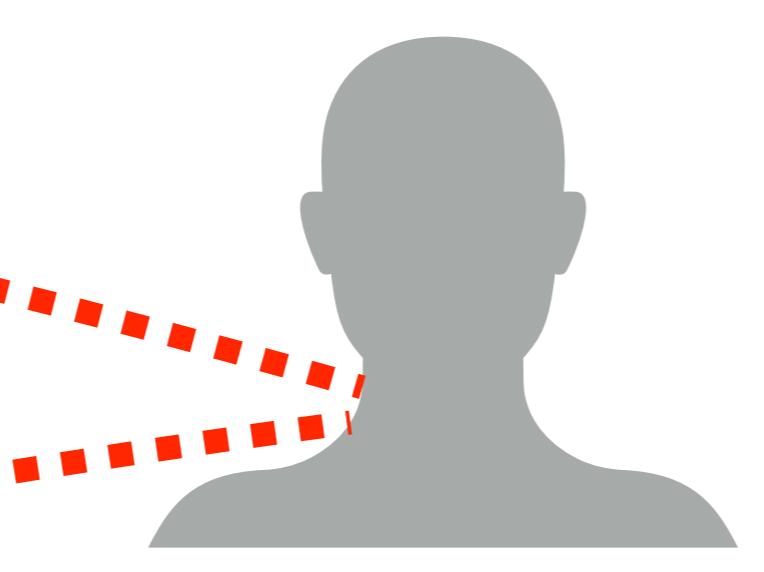
General-Purpose (GP) Auto-Tuning

Basic Idea:

Auto-Tunable Code

SP AT

complicated



Programmer

Auto-Tunable Code

SP AT

complicated

Basic Idea:

Auto-Tunable Code

SP AT

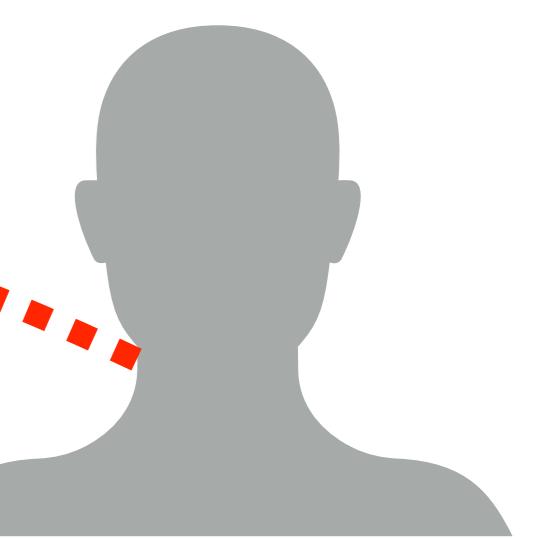
GP AT

simple

complicated,
but automatized

GP AT

simple



Programmer

Notable Examples:

ATLAS

FFTW

MilePost

PolyMage

CHiLL

Notable Examples:

OpenTuner

libTuning

Orio

PATUS

SPIRAL

Nitro

Apollo

KernelTuner

CLTune

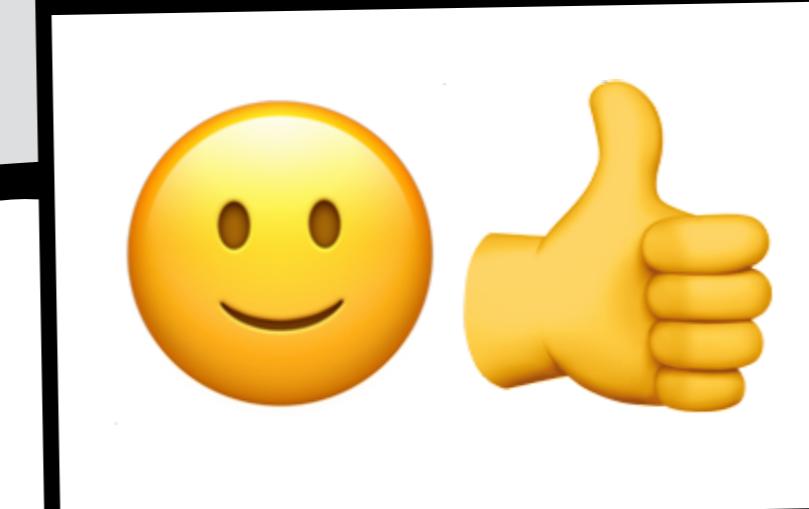
ActiveHarmony

What is *Auto-Tuning*?

Auto-Tuning (AT) can be categorized into two major categories:

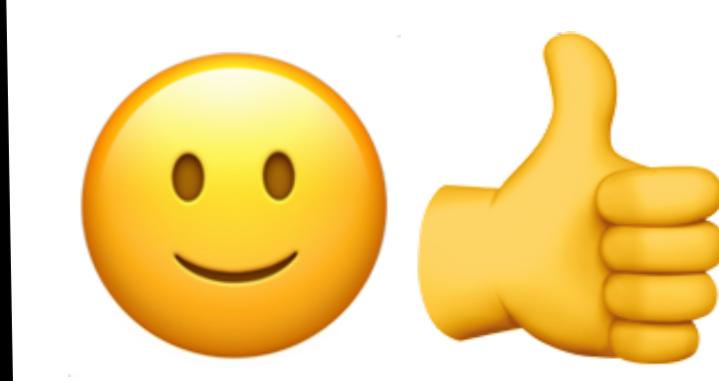
Special-Purpose Auto-Tuning

Special-Purpose Auto-Tuners
usually achieve good tuning results

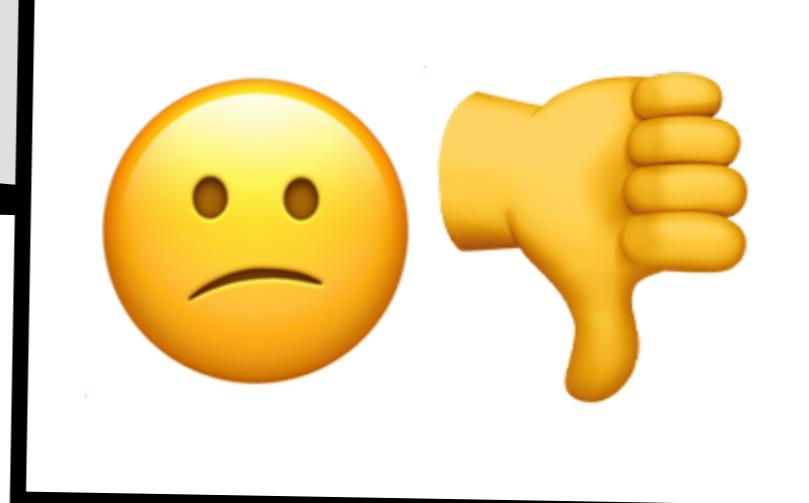


General-Purpose Auto-Tuning

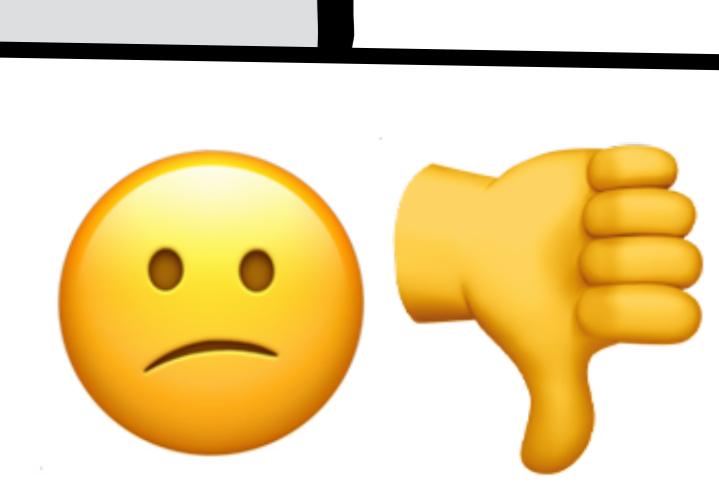
General-Purpose Auto-Tuners
automatically generate special-purpose tuners



However: they have to be designed &
implemented from scratch for each new
target application, which requires
expert knowledge and is cumbersome



However: current approaches struggle
with programs that have
interdependent tuning parameters



What are *Interdependent Tuning-Parameters*?

Independent Parameters

Parameters:

`tile_size` $\in \{1, \dots, 128\}$

`mem_region` $\in \{\text{GLB}, \text{LCL}, \text{PRV}\}$

`num_threads` $\in \{1, \dots, 1024\}$

Constraints:

`<none>`

Configurations:

$\{ (1, \text{GLB}, 1), \dots, (128, \text{PRV}, 1024) \}$

Each combination of parameters' values represents a valid parameter configuration

Interdependent Parameters

Parameters:

`tile_size_1` $\in \{1, \dots, 128\}$

`tile_size_2` $\in \{1, \dots, 128\}$

`tile_size_3` $\in \{1, \dots, 128\}$

Constraints:

`tile_size_3 | tile_size_2 | tile_size_1`

Configurations:

$\{ (1, 1, 1), (1, \cancel{1}, 2), \dots, (128, 128, 128) \}$

*tile_size_2
not multiple of
tile_size_3*

Only combinations that satisfy the constraints represent valid configurations

Interdependent Tuning-Parameters in General-Purpose Auto-Tuning

Current approach have either ***no support*** or only ***limited efficiency*** for programs with interdependent tuning parameters:

OpenTuner

Orio

libTuning

no support: invalid configurations are kept in the search space, which severely hinders the tuners from finding well-performing configurations

ActiveHarmony

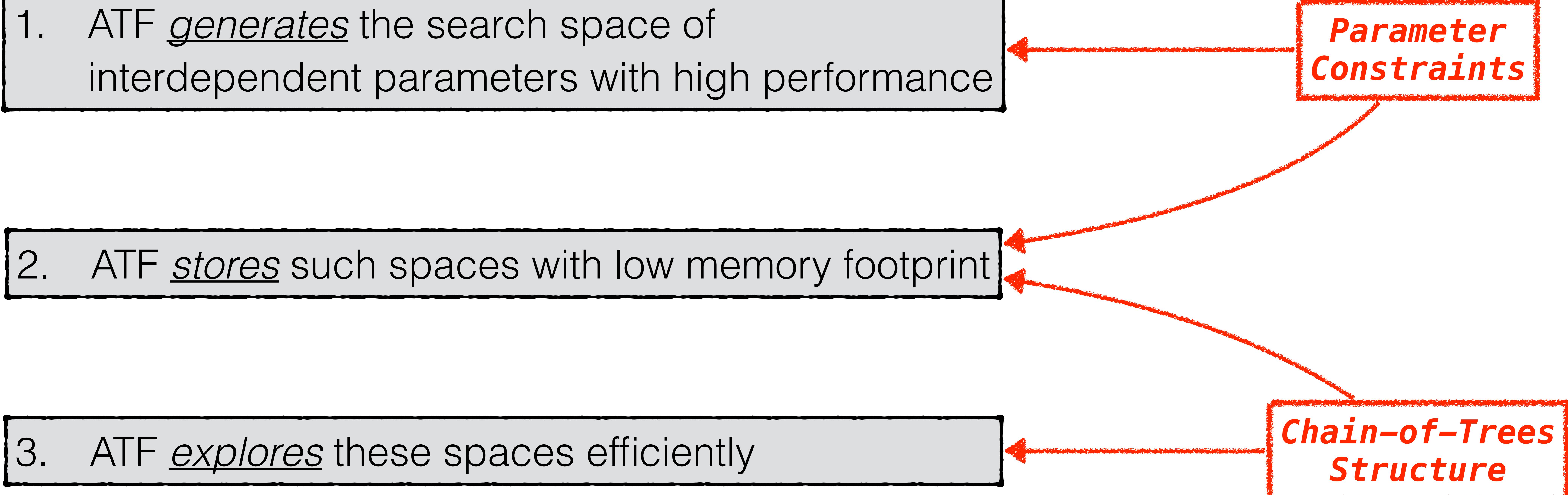
CLTune

KernelTuner

limited efficiency: the approaches are efficient for small search spaces only, because of sub-optimal process to generating, storing, and exploring the search spaces of interdependent parameters

Goal of this Work

We present three new contributions of our general-purpose Auto-Tuning Framework (ATF):



1. Generation

Basic Idea

ATF relies on *parameter constraints*, rather than traditional *search space constraints*:

```
for ( v1 : r1 )  
...  
    Search Space Constraint (SC)  
    ...  
    for ( vk : rk )  
        if( sc(v1,...,vk) )  
            add_config( v1,...,vk );
```

Classical Approach

PCs enable generating groups of interdependent parameters independently & in parallel

```
parallel_for ( G : {G1,...,Gn} )
```

```
{
```

```
    parallel_for ( v1G : r1G )
```

```
        if( pc1G(v1G) )
```

Parameter Constraint (PC)

```
        parallel_for ( vtgG : rtgG )
```

```
            if( pctgG(vtgG) )  
                ...
```

```
                for ( vtg+1G : rtg+1G )
```

```
                    if( pc(vtg+1G) )  
                        ...
```

```
                    for( vkG : rkG )
```

```
                        if( pc(vkG) )
```

```
                            add_config( v1G,...,vkG );
```

ATF's parameter constraints enable:

1. Checking Constraints Early

2. Generating groups of interdependent parameters independently & in parallel

3. Generating individual groups in parallel

ATF's Approach

2. Storing

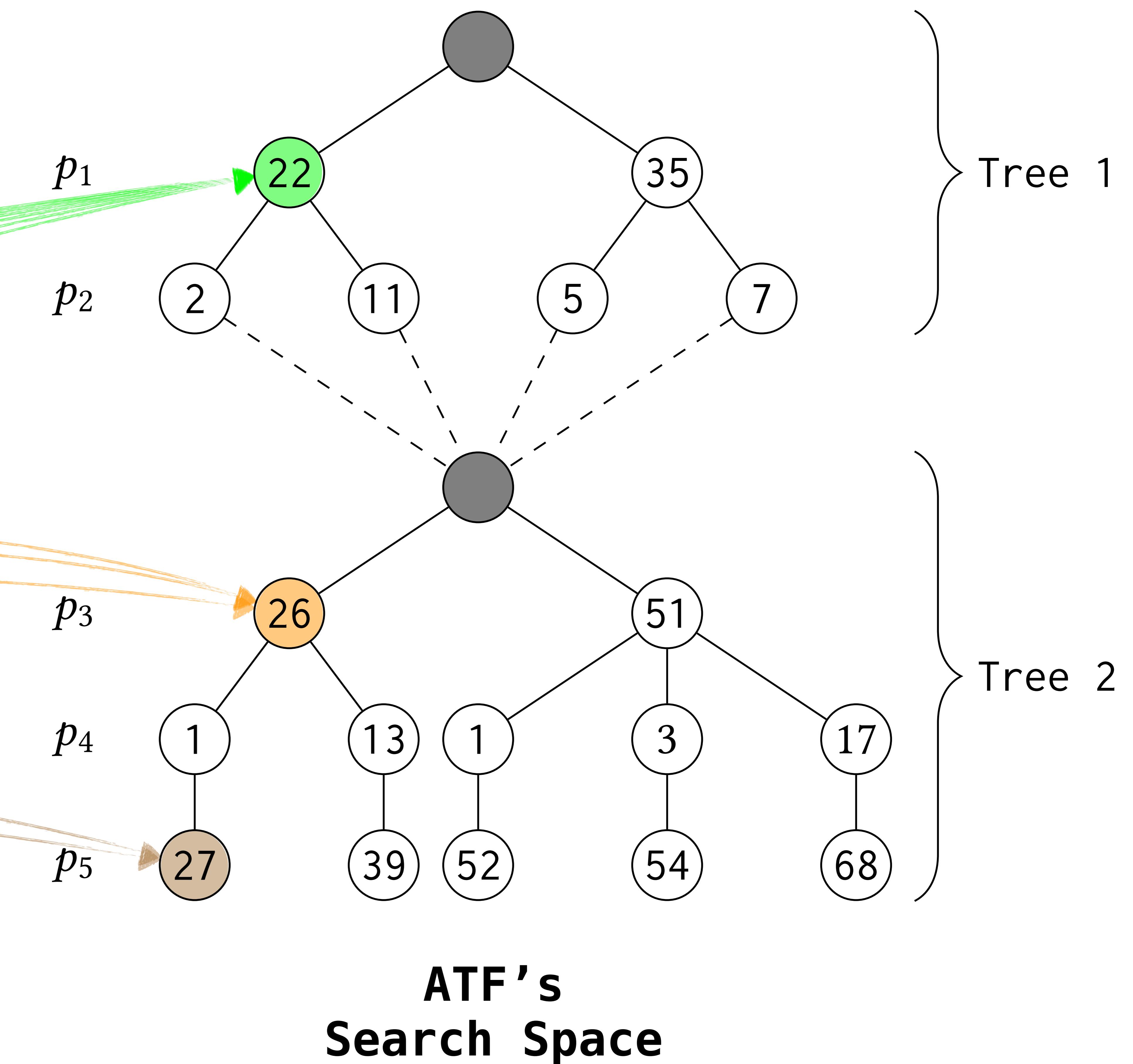
ATF relies on a new *chain-of-trees* search space structure & parameter constraints:

$p_1 := (n_1,$	$\{22, 35\},$	$-$	$)$
$p_2 := (n_2,$	$\{2, 5, 7, 11\},$	$\text{divides}(n_1)$	$)$
$p_3 := (n_3,$	$\{26, 51\},$	$-$	$)$
$p_4 := (n_4,$	$\{1, 3, 13, 17\},$	$\text{divides}(n_3)$	$)$
$p_5 := (n_5,$	$\{27, 39, 52, 54, 68\},$	$\text{equals}(n_3 + n_4)$	$)$

Example Parameters

22	22	22	22	22	22
2	2	2	2	2	11
26	26	51	51	51	26
1	13	1	3	17	1
27	39	52	54	68	27

Traditional
Search Space

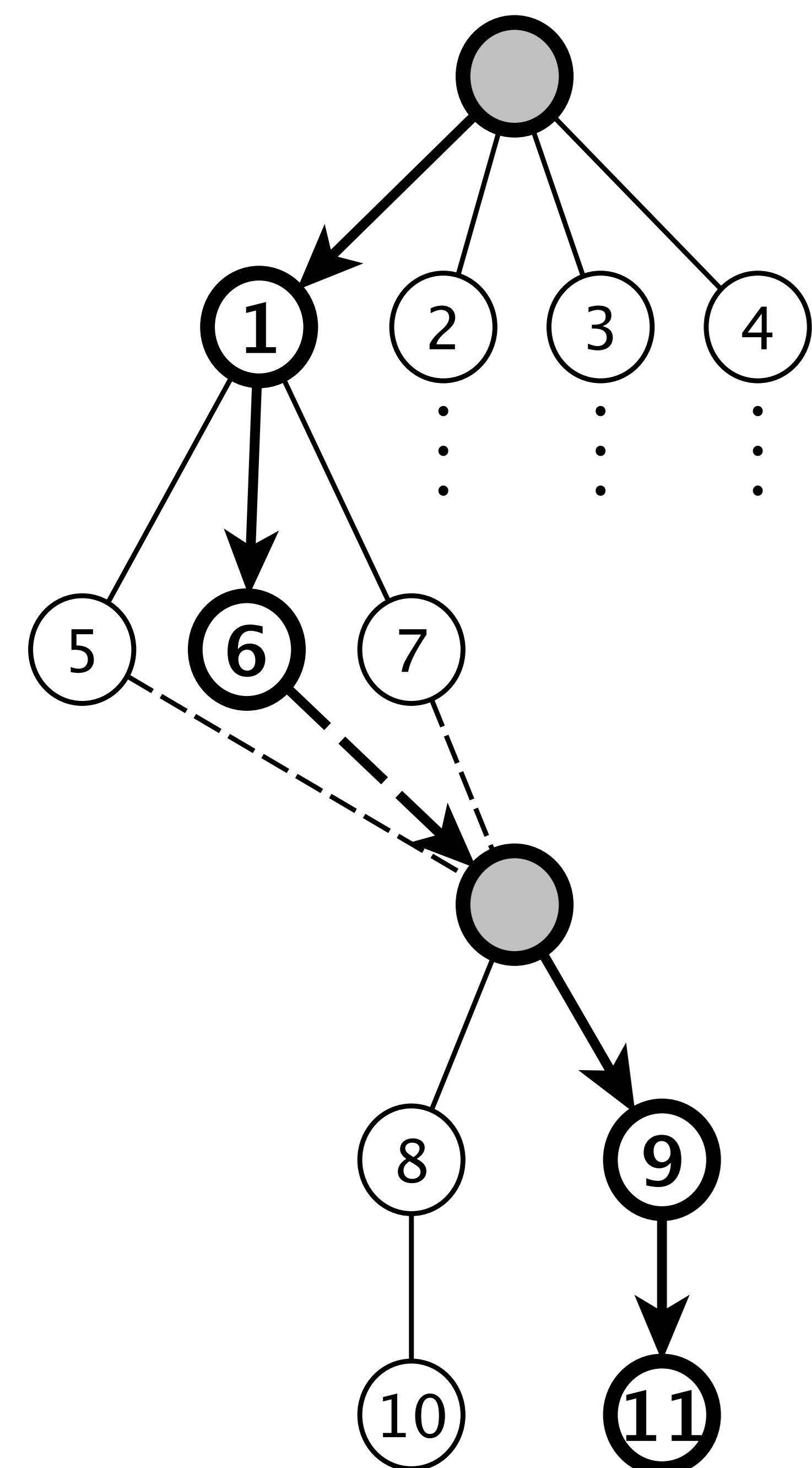


ATF's search space structure
avoids memory-intensive redundancies

3. Exploration

Basic Idea

ATF exploits its new *chain-of-trees* search space structure for a multi-dimensional search:



$I_1 \in (0, 0.25]$, $\text{NUM_CHILD}_0 = 4$
 $\Rightarrow k_1 = 1, s_1 = ①$

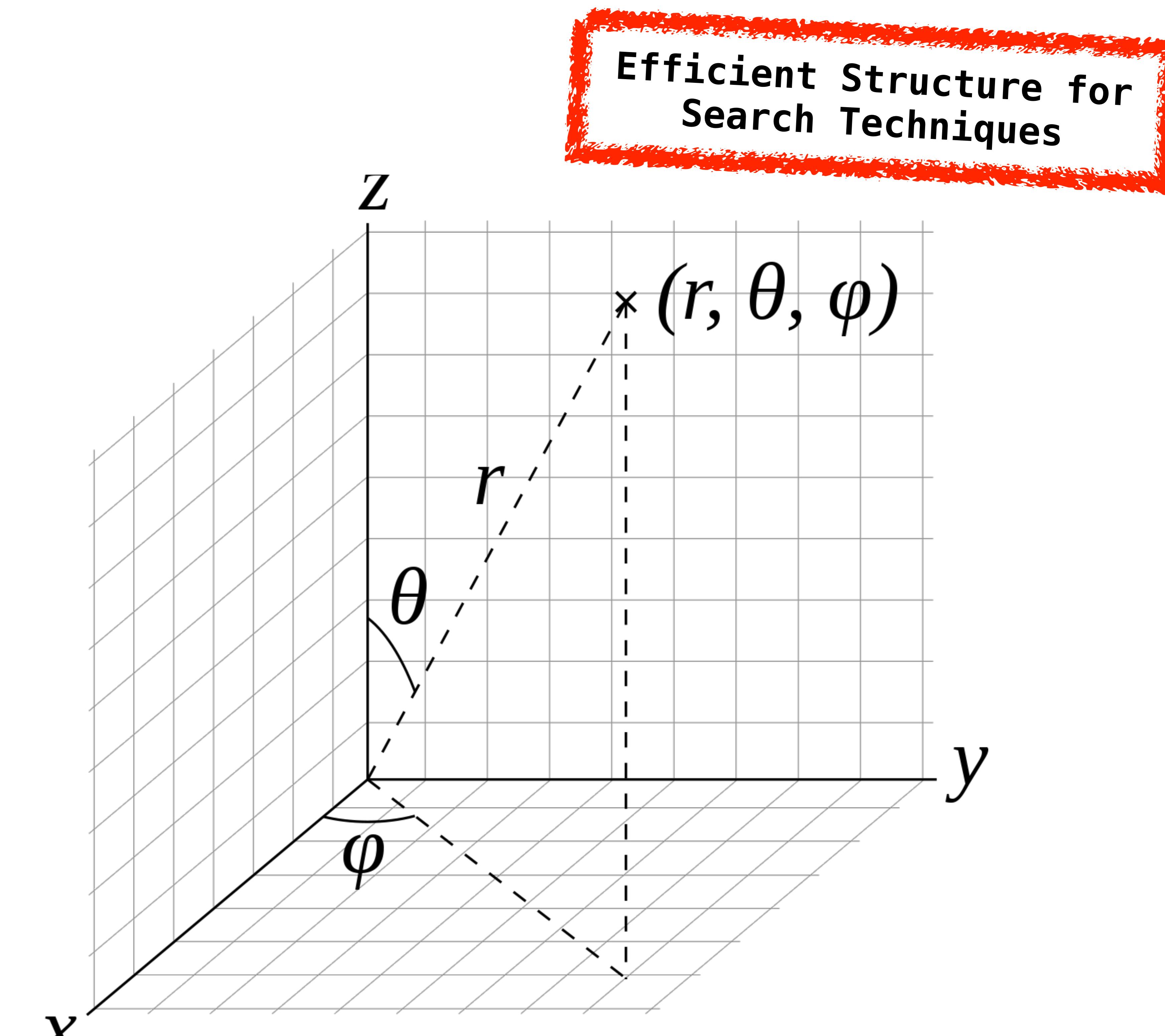
$I_2 \in (0.33, 0.66]$, $\text{NUM_CHILD}_{(1)} = 3$
 $\Rightarrow k_2 = 2, s_2 = ⑥$

$I_3 \in (0.5, 1]$, $\text{NUM_CHILD}_{(1, 6)} = 2$
 $\Rightarrow k_3 = 2, s_3 = ⑨$

$I_4 \in (0, 1]$, $\text{NUM_CHILD}_{(1, 6, 9)} = 1$
 $\Rightarrow k_4 = 1, s_4 = ⑪$

ATF's
Search Space

mapping



Coordinate Space

ATF's search space structure enables
reducing the complexity of exploration to exploring a Coordinate Spaces

Experimental Evaluation

ATF is able to auto-tune important applications for **CPU & GPU** on **real-world data sets** to high performance:

Stencil

ATF is able to auto-tune the **CONV** implementation in [1] to:

>40x higher performance
than CONV+CLTune
on CPU

>10⁴x higher performance
than CONV+CLTune
on GPU

>3x higher performance
than Intel MKL-DNN
on CPU 

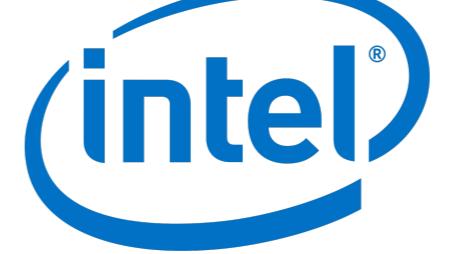
>15x higher performance
than NVIDIA cuDNN
on GPU 

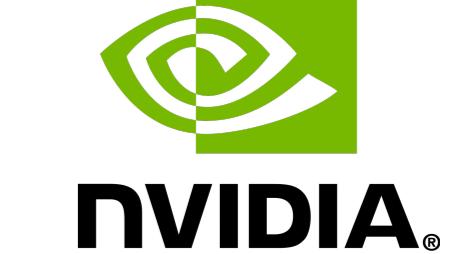
Linear Algebra

ATF is able to auto-tune the **GEMM** implementation in [1] to:

>2x higher performance
than GEMM+CLTune
on CPU

>120x higher performance
than GEMM+CLTune
on GPU

>2x higher performance
than Intel MKL
on CPU 

>2x higher performance
than NVIDIA cuBLAS
on GPU 

Quantum Chemistry

ATF is able to auto-tune the **CCSD(T)** implementation in [1] to:

>2x higher performance
than TensorComprehensions
on GPU

CLTune **fails!**

(too high search space generation time)

Data Mining

ATF is able to auto-tune the **PRL** implementation in [1] to:

>1.66x higher performance
than PRL+CLTune
on CPU

>1.07x higher performance
than PRL+CLTune
on GPU

**OpenTuner fails for all applications because of a
too high amount of invalid configurations within its search space**

ATF – User Interface

ATF's user interface is focus of our previous work [1]:

```
#atf::tp name      NUM_WG_1
range          interval<int>( 1, N_1 )

#atf::tp name      NUM_WI_1
range          interval<int>( 1, N_1 )

// ...

#atf::tp name      LM_SIZE_1
range          interval<int>( 1, N_1 )
constraint    LM_SIZE_1 <= N_1

#atf::tp name      PM_SIZE_1
range          interval<int>( 1, N_1 )
constraint    PM_SIZE_1 <= LM_SIZE_1

// ...

// OpenCL kernel code
```

Auto-Tuning in ATF via
easy-to-use Tuning Directives [1]

(ATF is also available as programming library in C++ [2] / Python (WIP) – for online auto-tuning)

[1] Rasch, Gorlatch. "ATF: A Generic, Directive-Based Auto-Tuning Framework", Concurrency and Computation: Practice and Experience, 2019

[2] Rasch, Haidl, Gorlatch. "ATF: A Generic Auto-Tuning Framework", HPCC, 2017

Questions?



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