

CMPT-439

Numerical Computation

Fall 2020

Solving Nonlinear Equations
Bisection Method

The problem

- It is not a problem to find the exact solution of a quadratic equation

$$ax^2 + bx + c = 0 \Rightarrow x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

- But what should we do with

$$ax^5 + bx^4 + cx^3 + dx^2 + ex + r = 0 \Rightarrow x = ?$$

$$\sin x + x = 0 \Rightarrow x = ?$$

$$f(x) = 0 \Rightarrow x = ?$$

The problem

- It is very difficult (and usually impossible) to find the exact roots of nonlinear equations
- Numerical methods should be applied to solve this problem

Nonlinear Equation Solvers

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graph TD; A[Nonlinear Equation Solvers] --> B[Bracketing]; A --> C[Graphical]; A --> D[Open Methods]; B --> E[Bisection]; B --> F["False Position (Regula-Falsi)"]; D --> G[Newton Raphson]; D --> H[Secant];
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Bracketing

Bisection
False Position
(Regula-Falsi)

Graphical

Open Methods

Newton Raphson
Secant

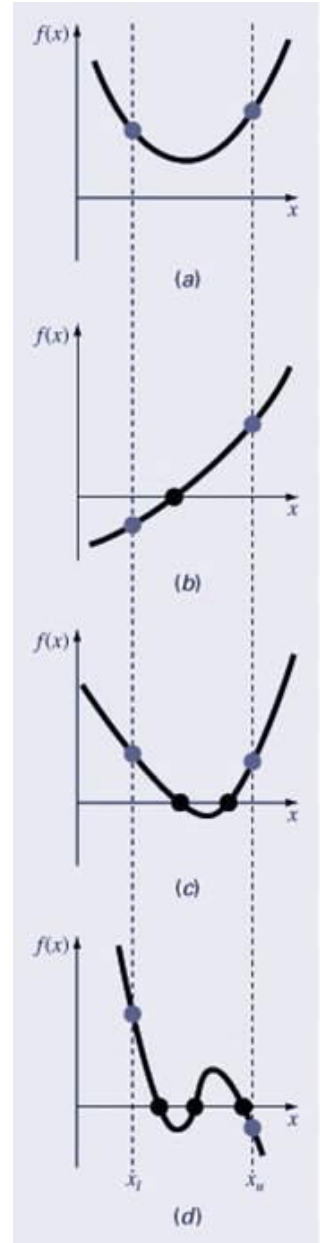
All Methods are iterative

Graphical Methods

A simple method for obtaining the estimate of the root of the equation $f(x)=0$ is to make a plot of the function and observe where it crosses the x -axis.

Graphing the function can also indicate where roots may be and where some root-finding methods may fail:

- a) Same sign, no roots
- b) Different sign, one root
- c) Same sign, two roots
- d) Different sign, three roots



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Bracketing Methods

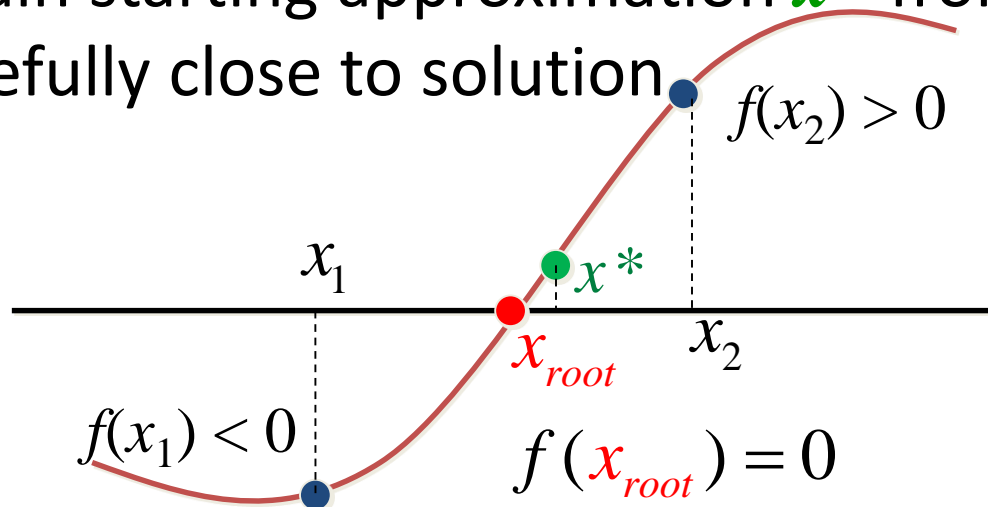
Bracketing methods are based on making two initial guesses that “bracket” the root - that is, are on either side of the root.

Brackets are formed by finding two guesses x_l and x_u where the sign of the function changes; that is, where $f(x_l) f(x_u) < 0$

The ***incremental search*** method tests the value of the function at evenly spaced intervals and finds brackets by identifying function sign changes between neighboring points.

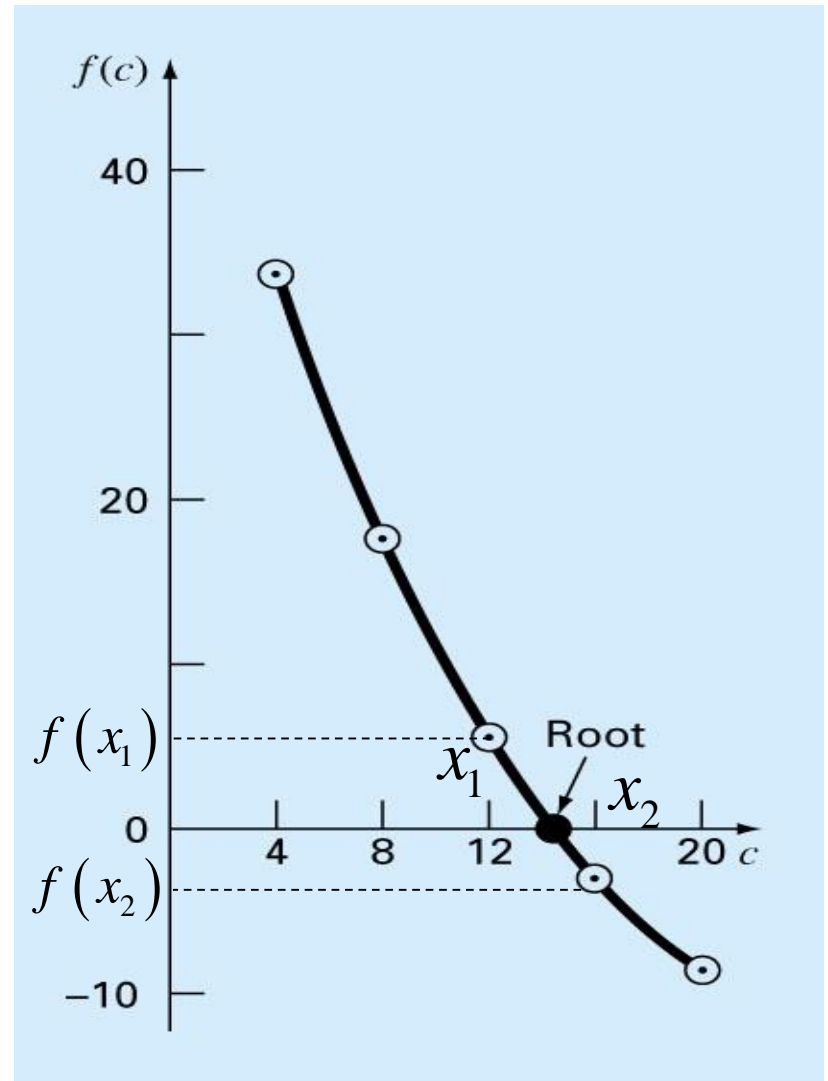
Root Finding using Bracketing

- Given some function, find location where $f(x)=0$
- Need:
 - Starting points x_1, x_2 that **bracket** the root
 - Obtain starting approximation x^* from x_1, x_2 , hopefully close to solution

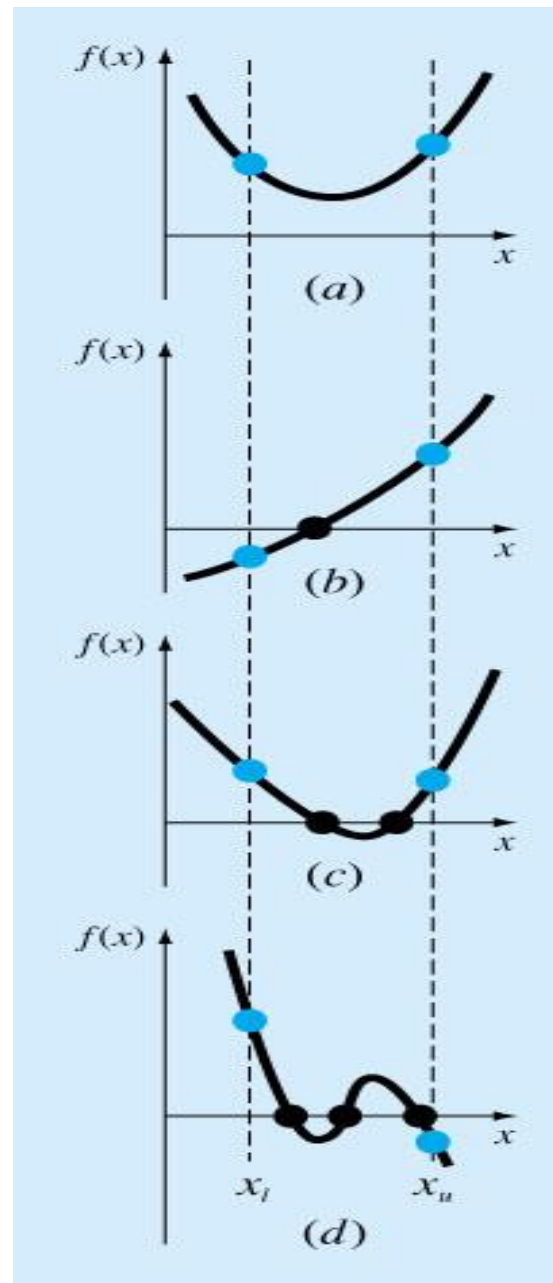


Basis of Bisection Method

- **Theorem.** An equation $f(x)=0$, where $f(x)$ is a real continuous function, has at least one root between x_1 and x_2 if $f(x_1)f(x_2) < 0$ (the function changes sign on opposite sides of the root)
- **So** at least one root of the equation $f(x)=0$ exists between the two points if the function $f(x)$ is real, continuous, and changes sign on the interval $[x_1, x_2]$



Some Examples:



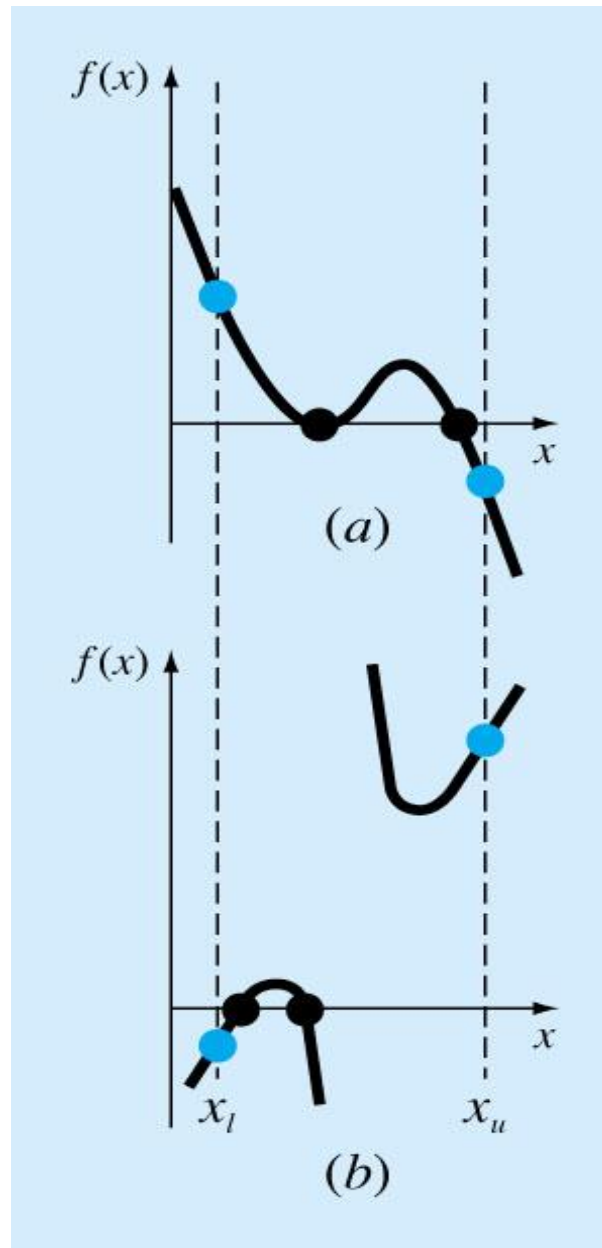
No root

Nice case (one root)

Oops!! (two roots!!)

Three roots(Might work for a while!!)

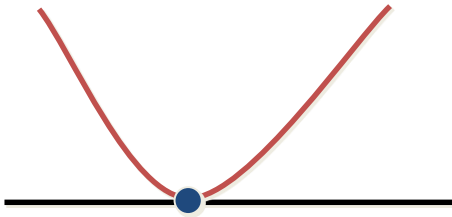
Some Examples:



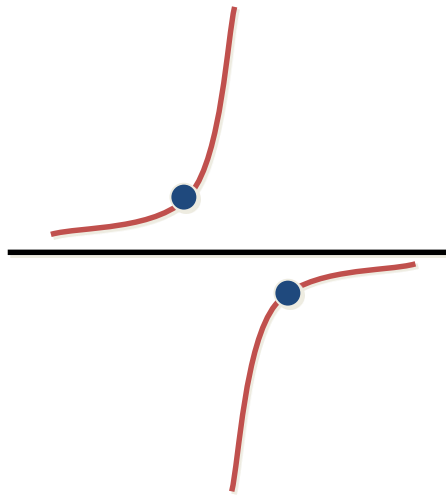
Two roots(Might work for a while!!)

Discontinuous function. Need special method

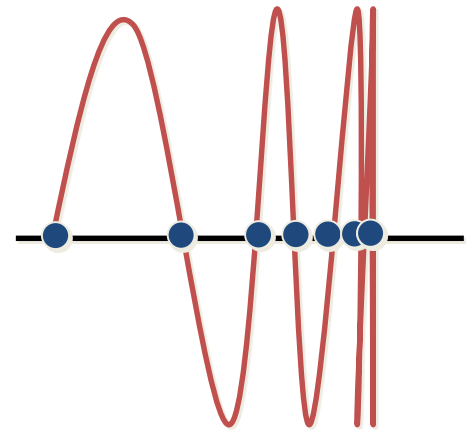
Complicated cases



Tangent point:
very difficult
to find



Singularity:
brackets don't
surround root



Pathological case:
infinite number of
roots – e.g. $\sin(1/x)$

Bisection Method (Interval Halving)

- Suppose $f(x_1) < 0$ and $f(x_2) > 0$
- Thus points x_1 and x_2 bracket a root. Find
$$x_{half} = (x_1 + x_2)/2$$
and evaluate $f(x_{half})$
- If $f(x_{half}) > 0$, set $x_2 = x_{half}$ else set $x_1 = x_{half}$
- Stop when x_1 and x_2 are close enough or when $f((x_1 + x_2)/2)$ is close to 0.
- If the function f is continuous, this **will definitely** succeed in finding **some** root

Bisection Method: Algorithm

For the arbitrary equation of one variable, $f(x)=0$

1. Pick x_1 and x_2 such that they bound the root of interest, check if $f(x_1)f(x_2) < 0$
2. Estimate the root by evaluating $f\left[(x_1 + x_2)/2\right]$
3. Narrow the interval:
 - If $f(x_1)f\left[(x_1 + x_2)/2\right] < 0$, then root lies in the lower subinterval, then $x_2 = (x_1 + x_2)/2$

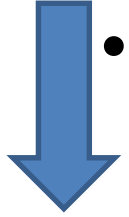




- If $f(x_1)f((x_1 + x_2)/2) > 0$, root lies in the upper subinterval, then $x_1 = (x_1 + x_2)/2$
 - If $f(x_1)f((x_1 + x_2)/2) = 0$, then root is $(x_1 + x_2)/2$ and terminate.
4. Compare the **absolute approximate error** ϵ_a or **absolute relative approximate error** ϵ_r with the pre-determined threshold δ
5. If $\epsilon < \delta$, then root is $(x_1 + x_2)/2$ and terminate; Otherwise go to step 2 and repeat the process.

$$\left\{ \begin{array}{l} \left| x_1 - \frac{x_1 + x_2}{2} \right| \\ \text{or} \\ \left| x_2 - \frac{x_1 + x_2}{2} \right| \end{array} \right\} \epsilon_a$$
$$\left\{ \begin{array}{l} \frac{\left| x_1 - \frac{x_1 + x_2}{2} \right|}{\left| \frac{x_1 + x_2}{2} \right|} \\ \text{or} \\ \frac{\left| x_2 - \frac{x_1 + x_2}{2} \right|}{\left| \frac{x_1 + x_2}{2} \right|} \end{array} \right\} \epsilon_r$$

Variation for steps 4 and 5



- If $f(x_1)f((x_1 + x_2)/2) > 0$, root lies in the uppersubinterval, then $(x_1 + x_2)/2$
- If $f(x_1)f((x_1 + x_2)/2) = 0$, then root is $(x_1 + x_2)/2$ and terminate.

4. Estimate the **true absolute error** ε_t and compare it with the pre-determined threshold δ
5. If $\varepsilon_t < \delta$, then root is $(x_1 + x_2)/2$ and terminate; Otherwise go to step 2 and repeat the process.

$$f((x_1 + x_2)/2) < \delta \quad \varepsilon_t$$

Programming Bisection

```
function [root,ea,iter]=bisect(func,xl,xu,es,maxit,varargin)
% bisect: root location zeroes
% [root,ea,iter]=bisect(func,xl,xu,es,maxit,p1,p2,...):
%     uses bisection method to find the root of func
% input:
%   func = function handle
%   xl, xu = lower and upper guesses
%   es = desired relative error (default = 0.0001%)
%   maxit = maximum allowable iterations (default = 50)
%   p1,p2,... = additional parameters used by func
% output:
%   root = real root
%   ea = approximate relative error (%)
%   iter = number of iterations

if nargin<3,error('at least 3 input arguments required'),end
test = func(xl,varargin{:})*func(xu,varargin{:});
if test>0,error('no sign change'),end
if nargin<4||isempty(es), es=0.0001;end
if nargin<5||isempty(maxit), maxit=50;end
iter = 0; xr = xl;
while (1)
    xrold = xr;
    xr = (xl + xu)/2;
    iter = iter + 1;
    if xr ~= 0,ea = abs((xr - xrold)/xr) * 100;end
    test = func(xl,varargin{:})*func(xr,varargin{:});
    if test < 0
        xu = xr;
    elseif test > 0
        xl = xr;
    else
        ea = 0;
    end
    if ea <= es || iter >= maxit,break,end
end
root = xr;
```

Bisection: Analysis

- Very robust method
- Convergence rate:
 - Error bounded by the size of $[x_1, x_2]$ interval
 - Interval shrinks in half at each iteration!
 - Therefore, error cut in half at each iteration:
$$|\varepsilon_{n+1}| = \frac{1}{2} |\varepsilon_n|$$
 - This is called “linear convergence”

Convergence of an iterative algorithm

- **Convergence** of an iterative algorithm means that the algorithm stops in some natural way: a solution can be found with some accuracy (usually the accuracy of the solution is determined by a tolerable error)
- Thus **the algorithm converges when the error drops below some reasonable pre-determined threshold value (tolerance)**

Bisection: how many iterations it takes?

- Length of the first interval $L_0 = |x_1 - x_2|$
- After 1 iteration $L_1 = L_0/2$
- After 2 iterations $L_2 = L_0/4$
- ...
- After n iterations $L_n = L_0/2^n$

Bisection: how many iterations it takes?

- After n iterations $L_n = L_0 / 2^n$
- Since the pre-determined threshold δ for the ***absolute approximate error*** cannot be larger than the length of the interval, then, knowing δ , it is always easy to predict the number of iterations n if absolute approximate error is used to estimate accuracy of our solution:

$$\delta = \frac{L_0}{2^n} \Rightarrow 2^n = \frac{L_0}{\delta} \Rightarrow n = \log_2 \frac{L_0}{\delta}$$

Bisection: Advantages

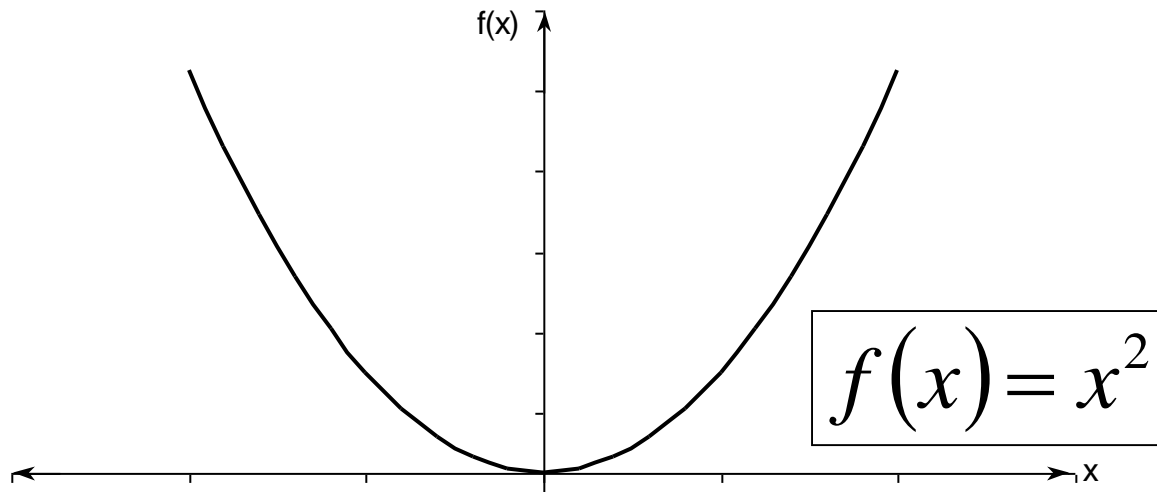
- Always converges regardless of the pre-determined threshold value if a root was initially bracketed correctly
- The root bracket gets halved with each iteration - guaranteed

Bisection: Drawbacks

- Slow convergence (usually more iterations are needed than for other methods to be considered)
- If one of the initial guesses is too close to the root, the convergence is slower

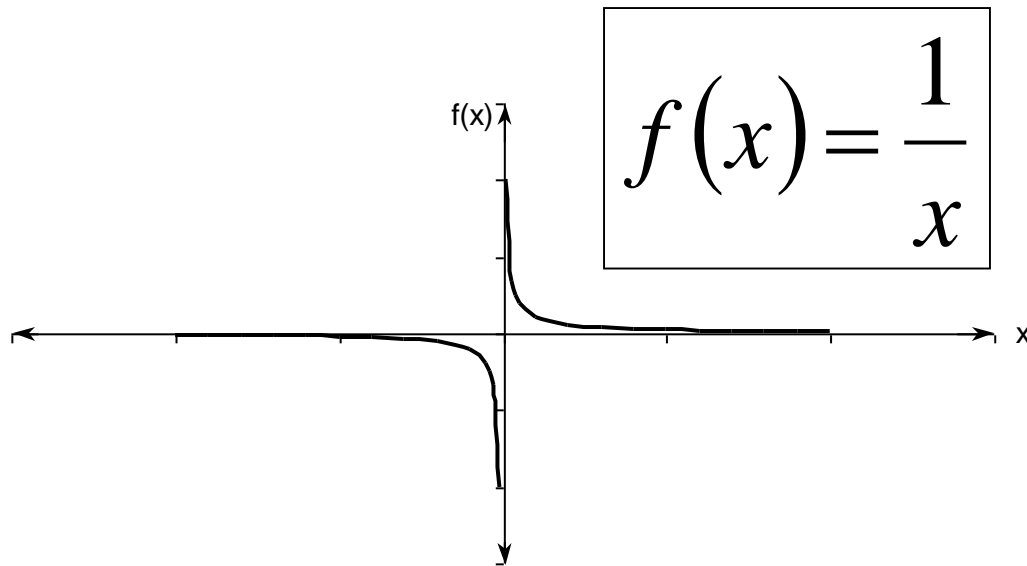
Bisection: Drawbacks

- If a function $f(x)$ is such that it just touches the x -axis, it will not be possible to find the lower and upper guesses.



Bisection: Drawbacks

- Function changes sign but no root exists



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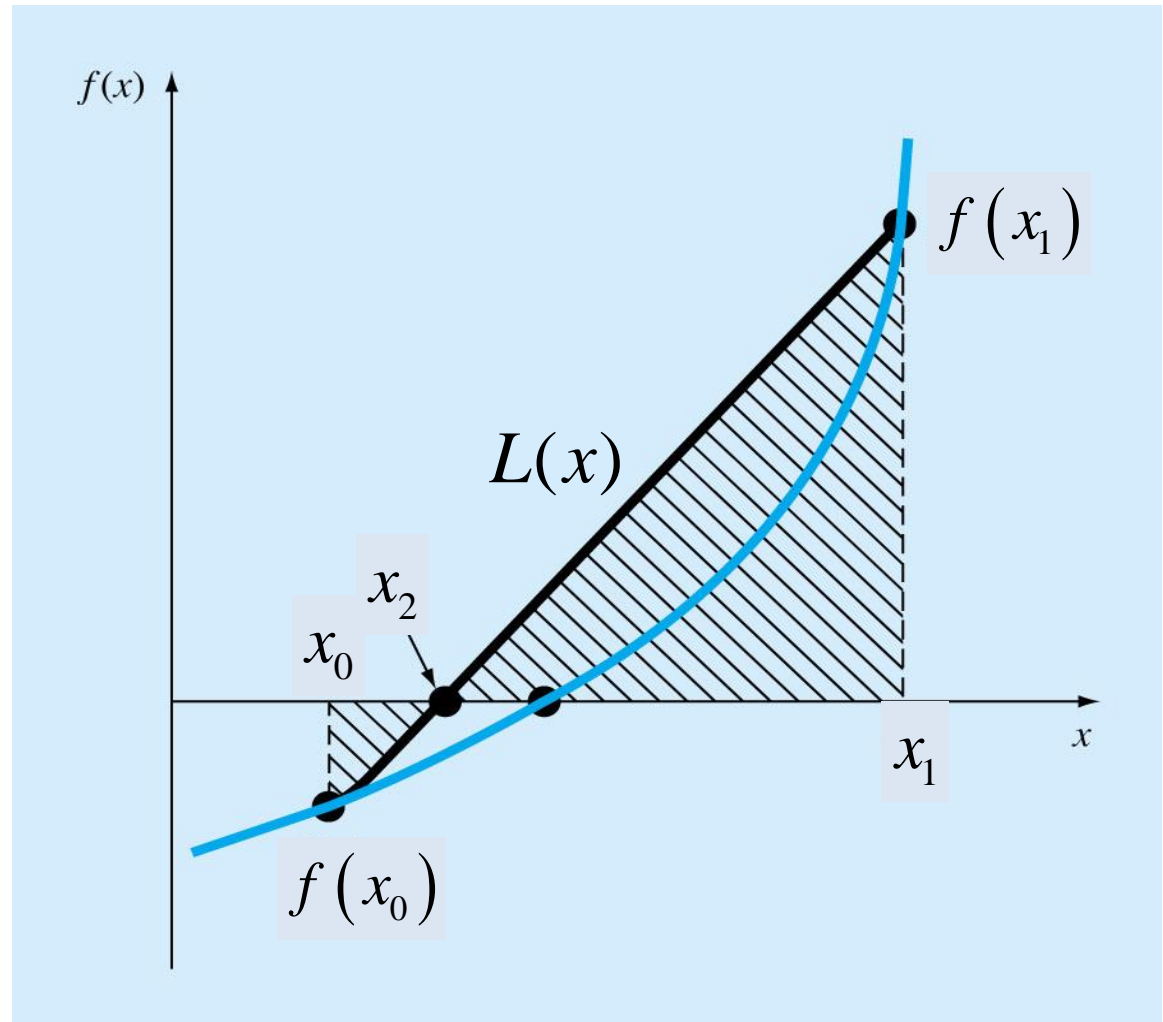
All Methods are iterative

The False Position Method

- The **method of false position** takes care of bracketing a root using x_0, x_1 chosen such that $f(x_0), f(x_1)$ are of opposite sign (in the same way as for the bisection method)
- Unlike the bisection method, this method determines its step taking not the midpoint between the two x-values, but taking the intersection point of a line between the pair of x-values and the x-axis

The False-Position Method (Regula-Falsi)

- If a real root is bounded by x_0 and x_1 of $f(x)=0$, then we can approximate the solution by doing a linear interpolation between the points $[x_0, f(x_0)]$ and $[x_1, f(x_1)]$ to find the x_2 value such that $L(x_2)=0$, where $L(x)$ is the linear approximation of $f(x)$

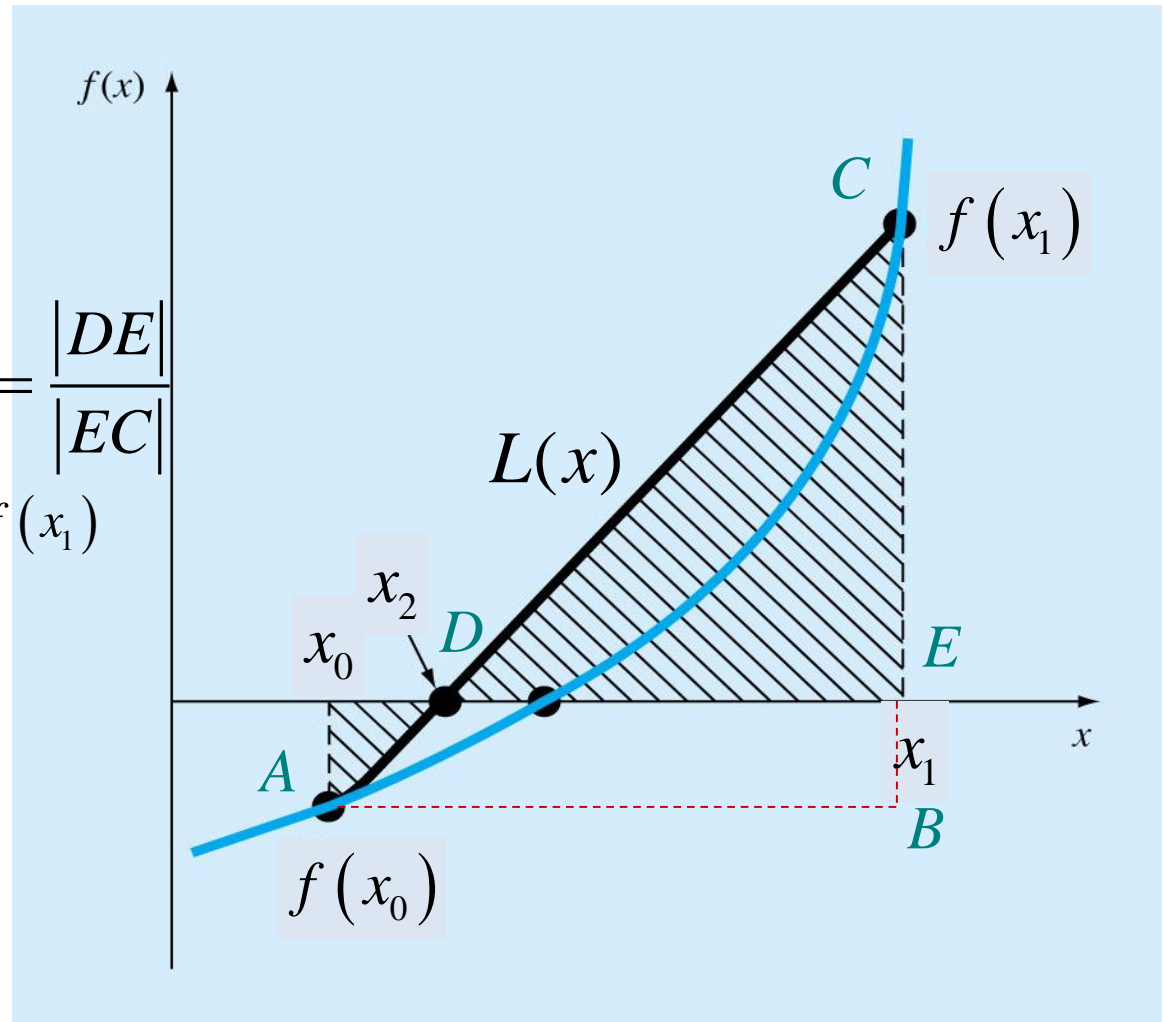


The False-Position Method (Regula-Falsi)

$$\sphericalangle ABC \sim \sphericalangle DEC \rightarrow \frac{|AB|}{|BC|} = \frac{|DE|}{|EC|}$$

$$|AB| = x_0 - x_1 \quad |BC| = f(x_0) - f(x_1)$$

$$|DE| = x_1 - x_2 \quad |EC| = f(x_1)$$



The False-Position Method (Regula-Falsi)

$$\sphericalangle ABC \sim \sphericalangle DEC \rightarrow \frac{|AB|}{|BC|} = \frac{|DE|}{|EC|}$$

$$|AB| = x_0 - x_1 \quad |BC| = f(x_0) - f(x_1)$$

$$|DE| = x_1 - x_2 \quad |EC| = f(x_1)$$

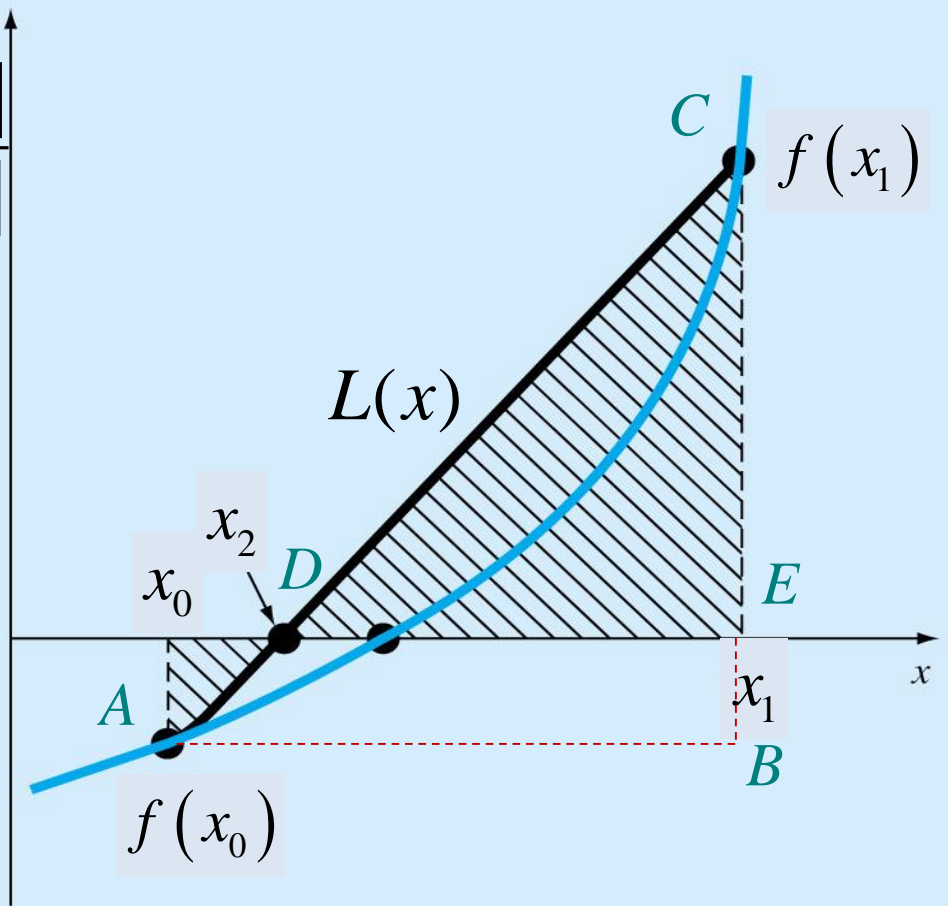
$$\frac{(x_1 - x_2)}{f(x_1)} = \frac{(x_0 - x_1)}{f(x_0) - f(x_1)}$$



■ ■ ■ ■ ■ ■ ■ ■ ■



$$x_{n+1} = x_n - f(x_n) \frac{(x_{n-1} - x_n)}{f(x_{n-1}) - f(x_n)}$$



The False Position Method :

Preliminaries

- The false position method should be used to find a root of $f(x)=0$
- A root should be estimated first. It can be done by plotting a graph of $f(x)$ and narrowing an interval around a point where $f(x)=0$.
- Then the initial values x_0, x_1 should be chosen such that $f(x_0), f(x_1)$ are of opposite sign

The False Position Method: Algorithm

- Determine δ - the tolerance value to ensure the appropriate true or approximate accuracy of a solution
- Determine x_0 and x_1 close enough to the projected root such that $f(x_0)f(x_1) < 0$ and set $x = x_1$
- **Step 1.** Set
$$x_2 = x_1 - f(x_1) \frac{(x_0 - x_1)}{f(x_0) - f(x_1)}$$
- **Step 2.** If $f(x_0)f(x_2) < 0$, then set $x_1 = x_2$ else set $x_0 = x_2$
- **Step 2 (true error).** If $|f(x_2)| \leq \delta$, then stop and x_2 is a root, (estimation) else go to Step 1
- **Alternative Step 2.** If $|x - x_2| \leq \delta$, then stop and x_2 is a root, (absolute approximate error*) else $x = x_2$ and go to Step 1
- *A relative approximate error should also be used here

Bisection vs False Position

- The false position method converges faster than the bisection method
- As well as the bisection method, the false position method cannot work if a root cannot be bracketed
- Bisection does not take into account the shape of the function; this can be good or bad depending on the function!

Example: $f(x) = x^{10} - 1$

