

CMPT-439

Numerical Computation

Fall 2020

Solving Nonlinear Equations

Secant Method

Newton's Method

Nonlinear Equation Solvers

```
graph TD; A[Nonlinear Equation Solvers] --> B[Bracketing]; A --> C[Graphical]; A --> D[Open Methods]; B --> E[Bisection]; B --> F["False Position (Regula-Falsi)"]; D --> G[Newton Raphson]; D --> H[Secant]; I[All Methods are iterative]
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Bracketing

Bisection
False Position
(Regula-Falsi)

Graphical

Open Methods

Newton Raphson
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Bracketing

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Open Methods

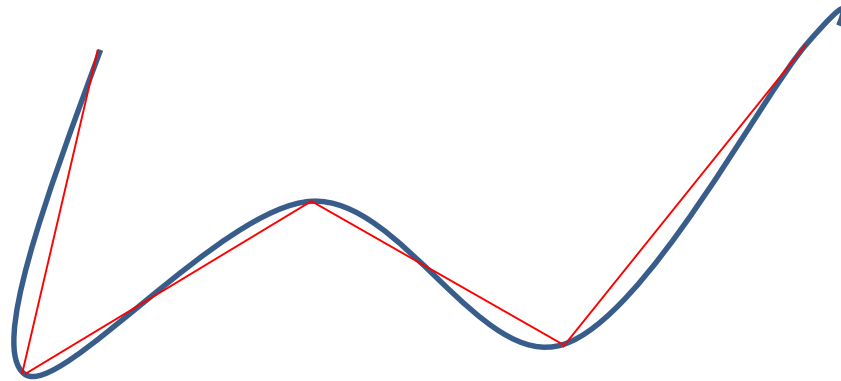
Newton Raphson

Secant

All Methods are iterative

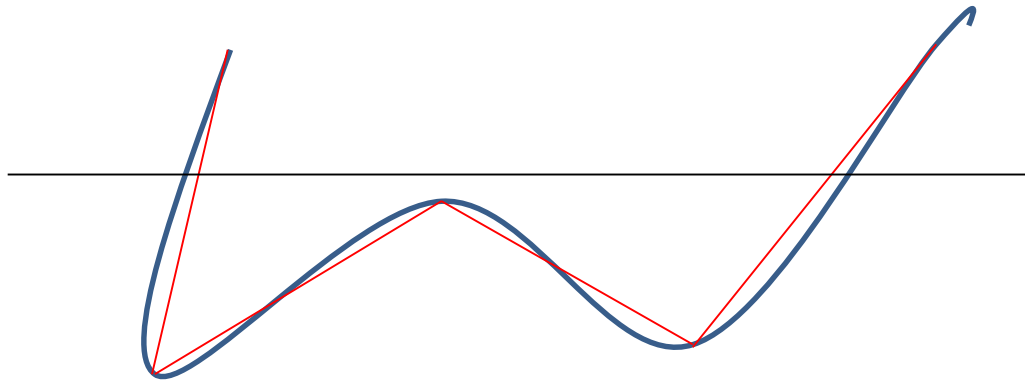
The Secant Method

- Basic idea: most nonlinear functions can be approximated by a set of straight lines over small intervals:



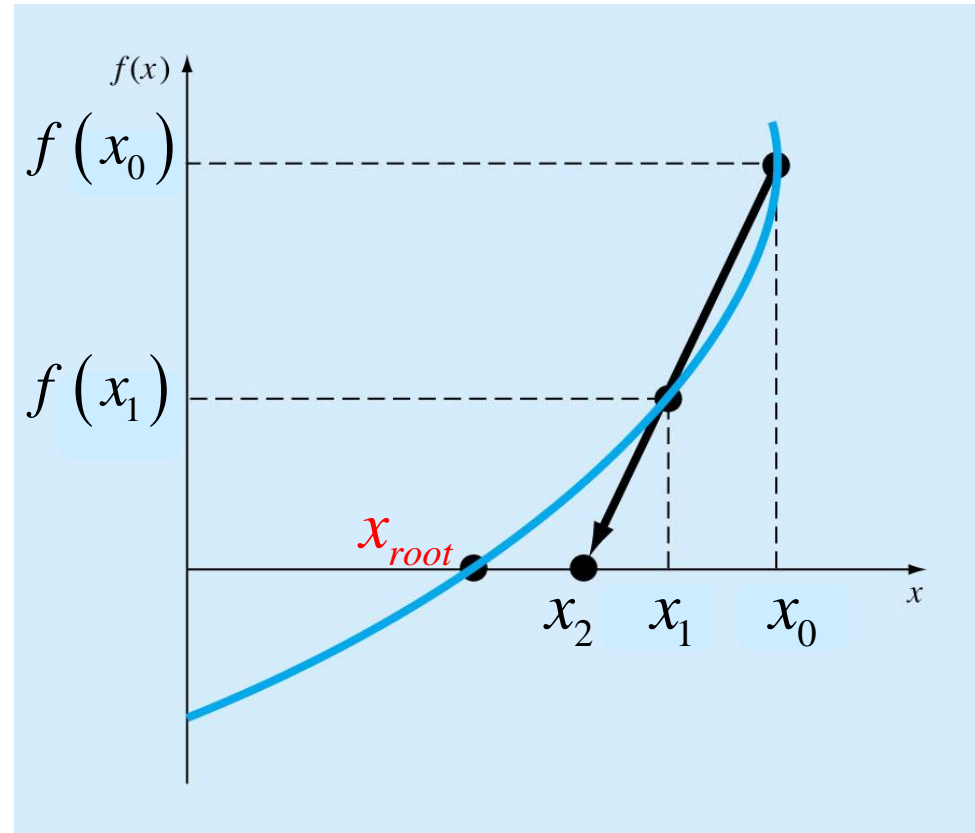
The Secant Method

- The secant method reduces finding a root of a nonlinear equation to finding a point where some linear equation determined by the approximating linear function has a root as close as possible to the root we are looking for



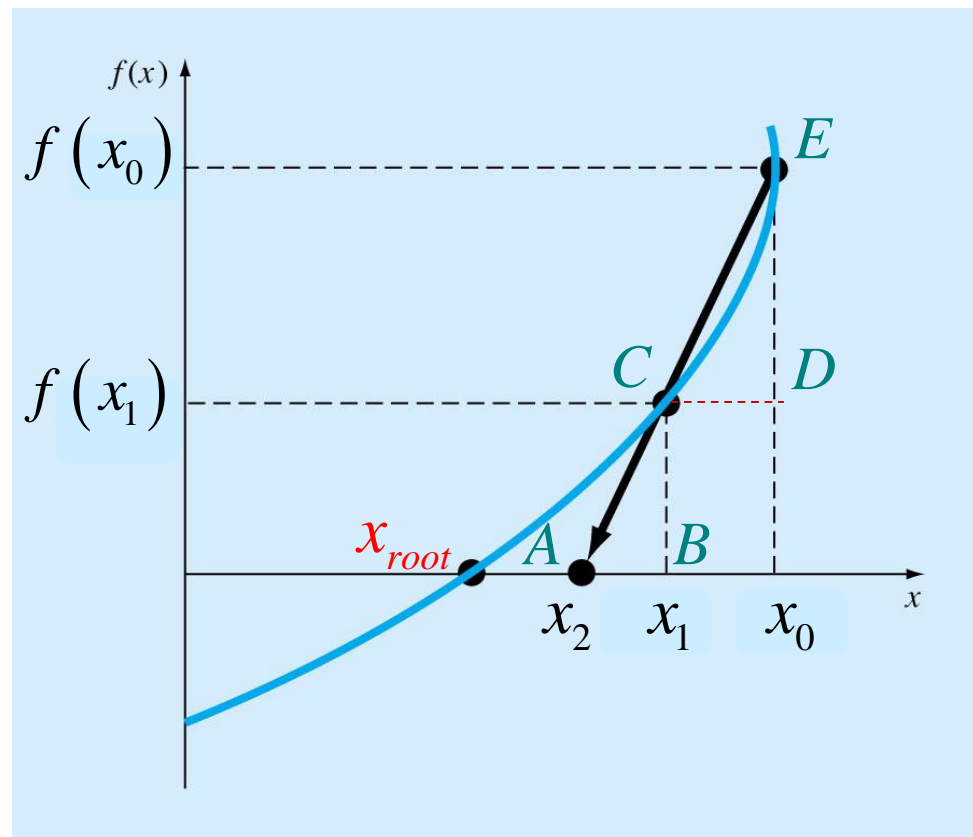
The Secant Method

- Requires two initial estimates of x : x_0, x_1 . However, because $f(x)$ is not required to change signs between estimates, it is not classified as a “bracketing” method
- Convergence is not guaranteed for an arbitrary chosen x_0 .



The Secant Method

$$\triangle ABC \sim \triangle CDE \rightarrow \frac{|AB|}{|BC|} = \frac{|CD|}{|DE|}$$



$$|AB| = x_1 - x_2 \quad |BC| = f(x_1)$$

$$|CD| = x_0 - x_1 \quad |DE| = f(x_0) - f(x_1)$$

The Secant Method

$$\triangle ABC \sim \triangle CDE \rightarrow \frac{|AB|}{|BC|} = \frac{|CD|}{|DE|}$$

$$\frac{(x_1 - x_2)}{f(x_1)} = \frac{(x_0 - x_1)}{f(x_0) - f(x_1)}$$



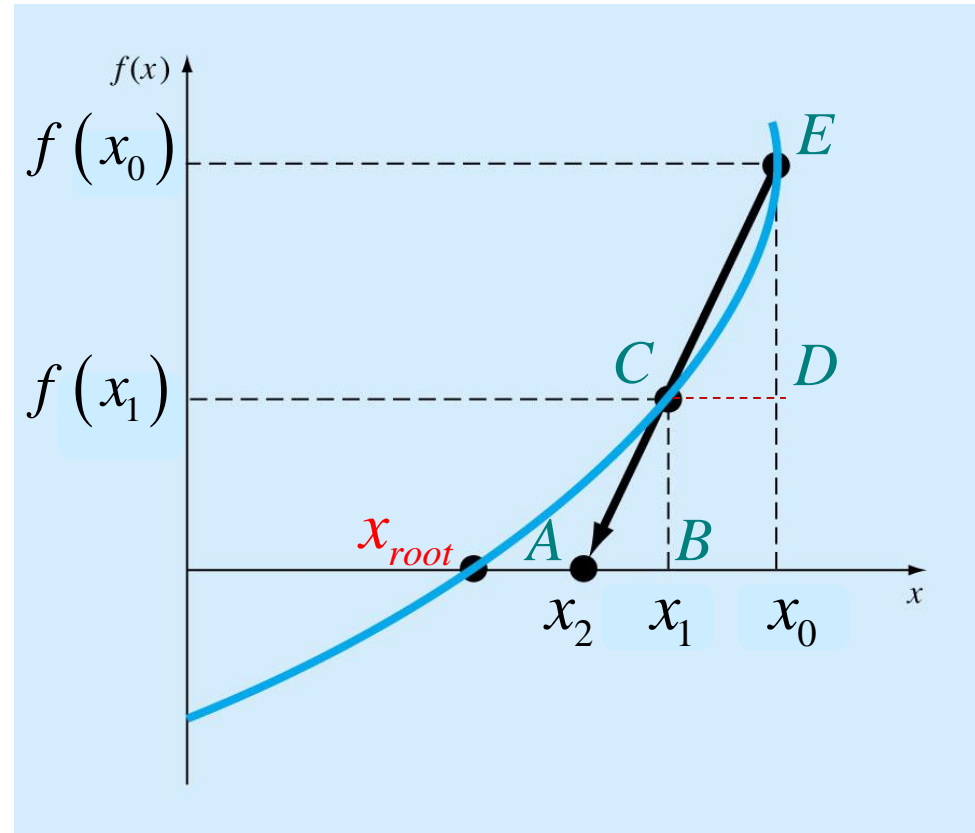
$$x_2 = x_1 - f(x_1) \frac{(x_0 - x_1)}{f(x_0) - f(x_1)}$$



.....



$$x_{n+1} = x_n - f(x_n) \frac{(x_{n-1} - x_n)}{f(x_{n-1}) - f(x_n)}$$



$$|AB| = x_1 - x_2 \quad |BC| = f(x_1)$$

$$|CD| = x_0 - x_1 \quad |DE| = f(x_0) - f(x_1)$$

The Secant Method: Preliminaries

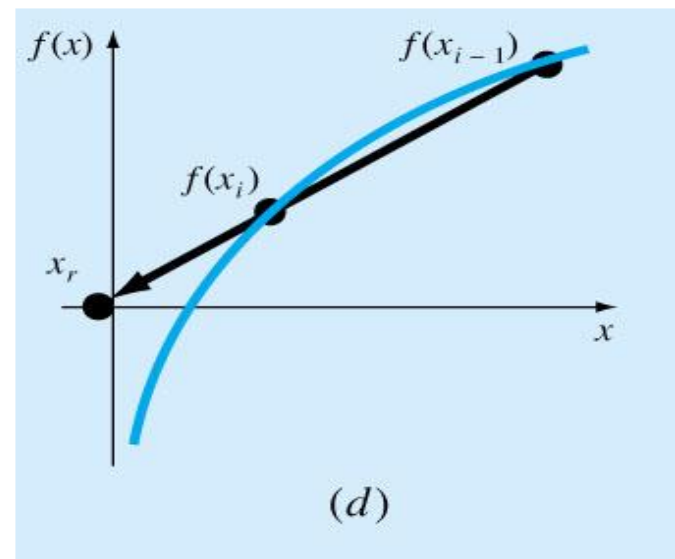
- The secant method should be used to find a root of $f(x)=0$
- A root should be estimated first. It can be done by plotting a graph of $f(x)$ and choosing an initial interval close to a point where $f(x)=0$

The Secant Method: Algorithm

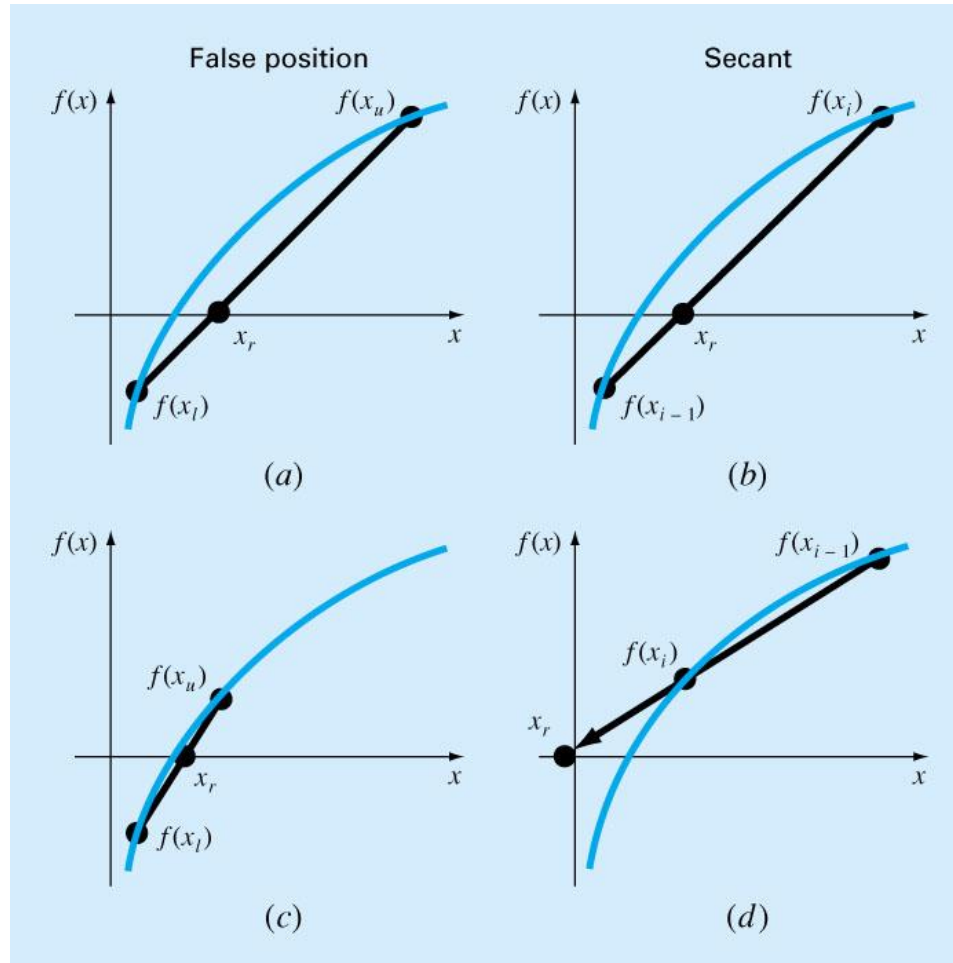
- Determine δ - the tolerance value to ensure the appropriate true or approximate accuracy of a solution
- Determine x_0 and x_1 close enough to the projected root
- If $|f(x_0)| < |f(x_1)|$ then swap x_0 and x_1
- **Step 1.** Set $x_2 = x_1 - f(x_1) \frac{(x_0 - x_1)}{f(x_0) - f(x_1)}$; $x_0 = x_1$; $x_1 = x_2$
- **Step 2 (true error).** If $|f(x_2)| \leq \delta$, then stop and x_2 is a root, (estimation) else go to Step 1
- **Alternative Step 2.** If $|x_0 - x_1| \leq \delta$, then stop and x_2 is a root, (absolute approximate error*) else go to Step 1
- *A relative approximate error should also be used here

The Secant Method: Analysis

- The secant method converges faster than the bisection method
- However, if the function is far from linear near the root, the successive iterations can fly off to points far from the root:



Secant and False Position: Comparison



Which method is better?

- There is no best method. All of them have advantages and disadvantages.
- **Bisection** → the number of iterations can be exactly predicted from a desired accuracy, but it yields to the secant and false positions methods in speed of convergence
- **Secant** → the fastest method in general, but may fly off a root
- **False position** → faster than bisection, but does not work (as well as the bisection) when a root can't be bracketed

Nonlinear Equation Solvers

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graph TD; A[Nonlinear Equation Solvers] --> B[Bracketing]; A --> C[Graphical]; A --> D[Open Methods]; B --> E["Bisection<br/>False Position<br/>(Regula-Falsi)"]; D --> F["Newton-Raphson<br/>Secant"];
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Bracketing

Bisection
False Position
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Graphical

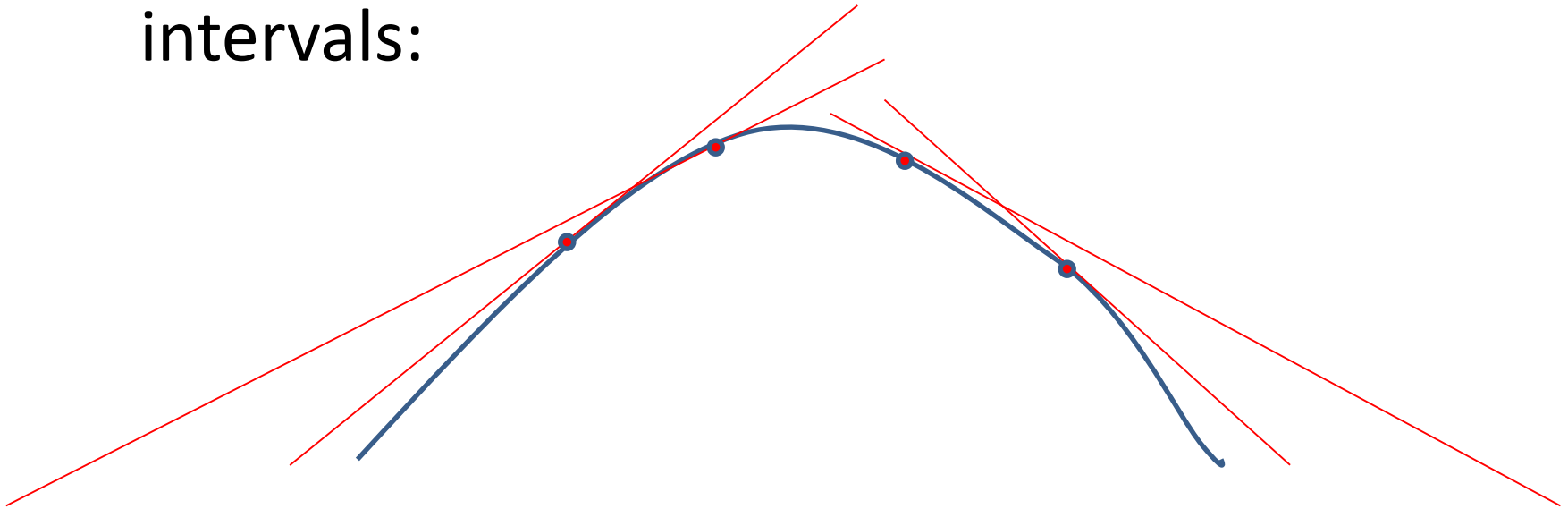
Open Methods

Newton-Raphson
Secant

All Methods are iterative

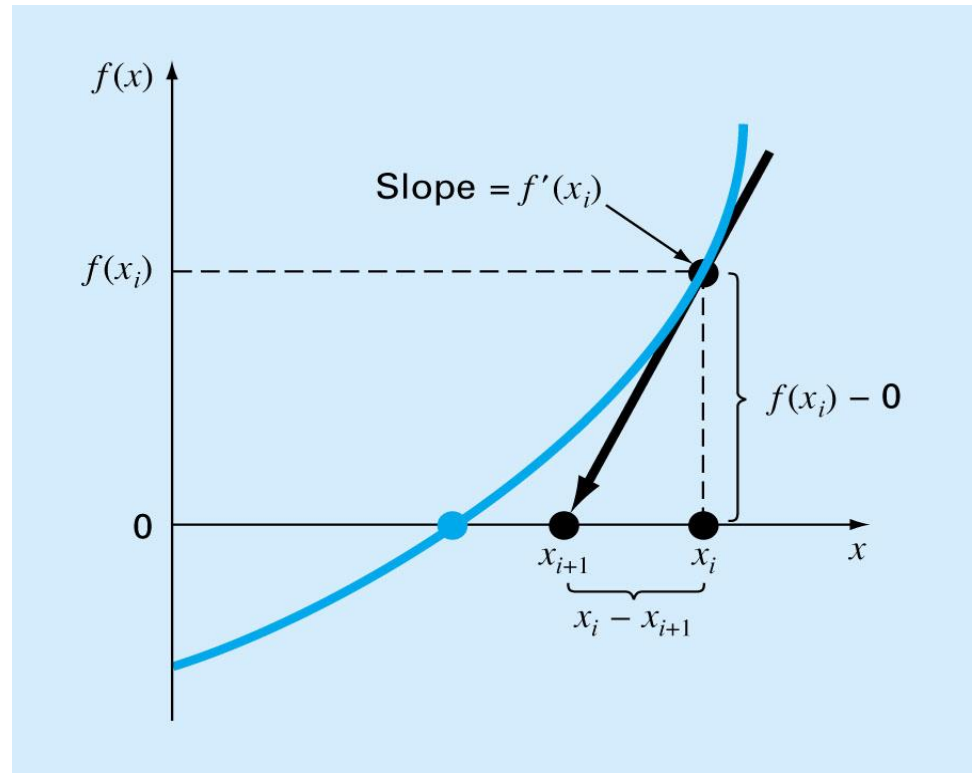
The Newton's Method

- Basic idea: most nonlinear functions can be approximated by a set of tangents over small intervals:



The Newton's Method

- A convenient method for functions whose derivatives can be evaluated analytically. It may not be convenient for functions whose derivatives cannot be evaluated analytically.

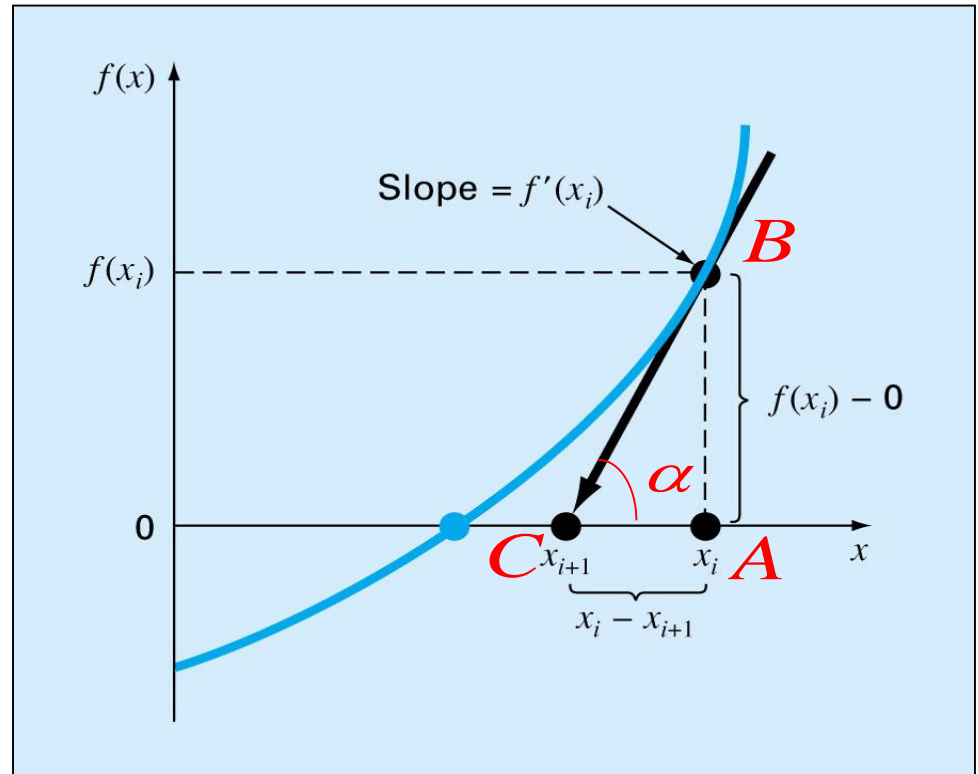


The Newton's Method

$$\tan(\alpha) = \frac{AB}{AC}$$

$$f'(x_i) = \tan(\alpha) = \frac{f(x_i)}{x_i - x_{i+1}}$$

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$



The Newton-Raphson Formula

➤ Based on Taylor series expansion:

$$f(x_{i+1}) = f(x_i) + f'(x_i)\Delta x + f''(x_i)\frac{\Delta x^2}{2!} + O\Delta x^3$$

The root is the value of x_{i+1} when $f(x_{i+1}) = 0$

Rearranging,

$$0 = f(x_i) + f'(x_i)(x_{i+1} - x_i)$$

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

Newton vs. Secant

Newton-Raphson:

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

Secant:

$$x_{i+1} = x_i - f(x_i) \frac{(x_{i-1} - x_i)}{f(x_{i-1}) - f(x_i)} = x_i - \frac{f(x_i)}{\frac{f(x_{i-1}) - f(x_i)}{(x_{i-1} - x_i)}}$$

$$\lim_{(x_{i-1} - x_i) \rightarrow 0} \frac{f(x_{i-1}) - f(x_i)}{(x_{i-1} - x_i)} = f'(x_i)$$

- The secant method transforms to the Newton method when a secant transforms into a tangent

The Newton Method: Preliminaries

- The Newton's method should be used to find a root of $f(x)=0$
- A root should be estimated first. This can be done by plotting a graph of $f(x)$ and estimating x_0 close to the projected x where $f(x)=0$
- The derivative $f'(x)$ of $f(x)$ must be evaluated

Evaluation of the derivative in MATLAB

- In MATLAB, the derivative of any function (if it exists) can be evaluated symbolically as follows:
- Define x as a symbolic variable using `syms x`, then define $f(x)$ as a symbolic function, e.g. `f=sin(x)+3*x^2`
- Then apply the command `diff(f)`, which returns a symbolic expression containing the derivative of f
- For example, `fprime=diff(f)` for the f determined above returns `cos(x)+6*x`
- Then you may use the `eval` command to find the value of `fprime`, e.g. `x=1; eval(fprime)` returns `fprime(1)`

The Newton Method: Algorithm

- Determine δ - the tolerance value to ensure the appropriate accuracy of a solution
- Determine x_0 close enough to the projected root and evaluate the derivative $f'(x)$
- If $f(x_0) = 0$ then stop; If $f'(x_0) = 0$ then choose another x_0
- **Step 1.** Set
$$x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$
- **Step 2 (true error).** If $|f(x_1)| \leq \delta$, then stop and x_1 is a root, (estimation) else set $x_0 = x_1$ and go to Step 1
- **Alternative Step 2.** If $|x_0 - x_1| \leq \delta$, then stop and x_1 is a root, (absolute approximate error*) else set $x_0 = x_1$ and go to Step 1
- *A relative approximate error should also be used here

The Newton Method: Advantages

- Converges faster than other methods (quadratic convergence – the error of each step approaches a constant K times the square of the error of the previous step), if it converges at all
- Requires only one guess
- Allows for finding complex roots of an equation

The Newton Method: Drawbacks

1. Divergence at inflection points

Selection of the initial guess or an iteration value of the root that is close to the **inflection (concavity change)** point of the function $f(x)$ may start diverging away from the root in the Newton-Raphson method.

For example, to find the root of the equation $f(x) = (x-1)^3 + 0.512 = 0$.

The Newton-Raphson method reduces to
$$x_{i+1} = x_i - \frac{(x_i^3 - 1)^3 + 0.512}{3(x_i - 1)^2}.$$

Table 1 shows the iterated values of the root of the equation.

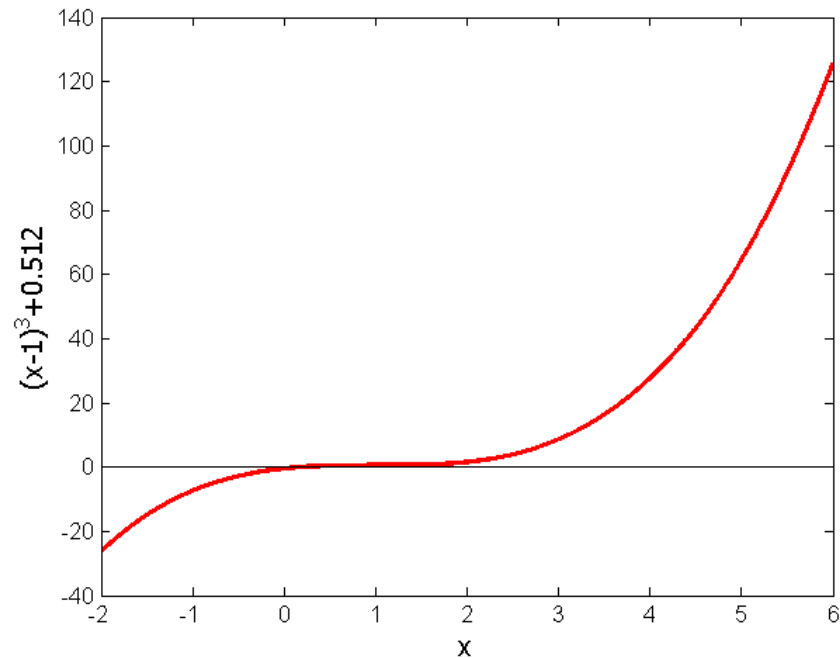
The root starts to diverge at Iteration 6 because the previous estimate of 0.92589 is close to the inflection point of $x = 1$.

Eventually after 12 more iterations the root converges to the exact value of $x = 0.2$.

Drawbacks – Inflection Points

Table 1 Divergence near inflection point.

Iteration Number	x_i
0	5.0000
1	3.6560
2	2.7465
3	2.1084
4	1.6000
5	0.92589
6	-30.119
7	-19.746
18	0.2000



Divergence at inflection point for
$$f(x) = (x-1)^3 + 0.512 = 0$$

Drawbacks – Division by Zero

2. Division by zero

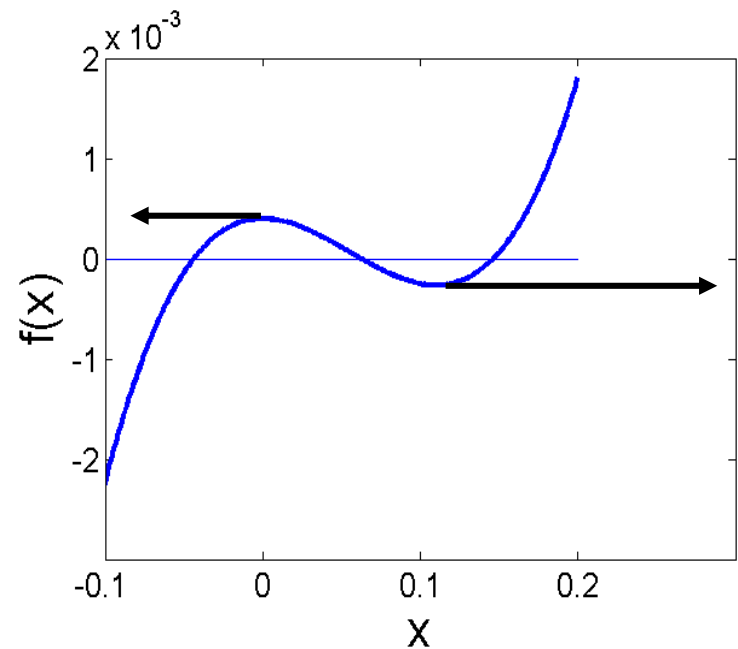
For the equation

$$f(x) = x^3 - 0.03x^2 + 2.4 \times 10^{-6} = 0$$

the Newton-Raphson method reduces to

$$x_{i+1} = x_i - \frac{x_i^3 - 0.03x_i^2 + 2.4 \times 10^{-6}}{3x_i^2 - 0.06x_i}$$

For $x_0 = 0$ or $x_0 = 0.02$, the denominator will equal zero.



Pitfall of division by zero or near a zero number

Drawbacks – Oscillations near local maximum and minimum

3. Oscillations near local maximum and minimum

Results obtained from the Newton-Raphson method may oscillate about the local maximum or minimum without converging on a root but converging on the local maximum or minimum.

Eventually, it may lead to division by a number close to zero and may diverge.

For example, the equation $f(x) = x^2 + 2 = 0$ has no real roots.

Drawbacks – Root Jumping

4. Root Jumping

In some cases where the function $f(x)$ is oscillating and has a number of roots, one may choose an initial guess close to a root. However, the guesses may jump and converge to some other root.

For example

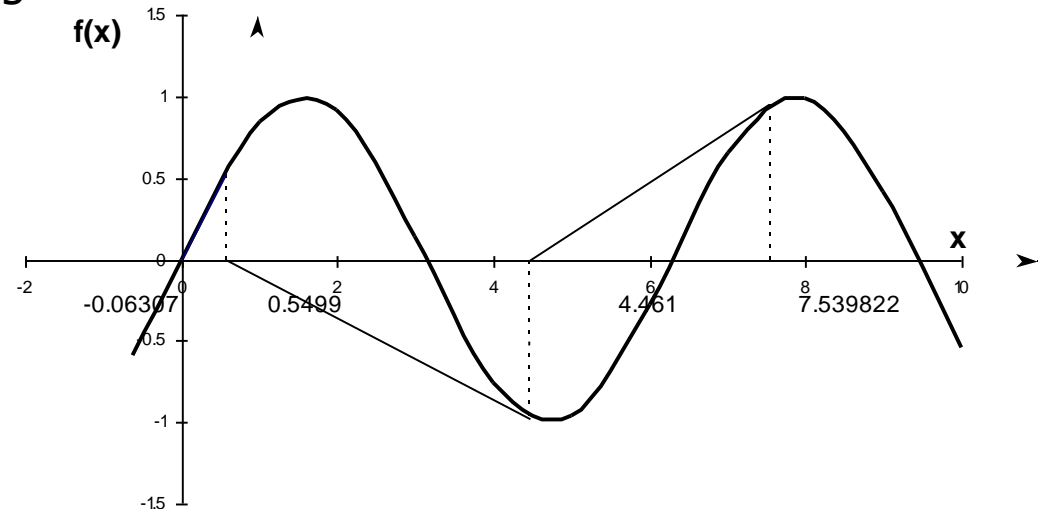
$$f(x) = \sin x = 0$$

Choose

$$x_0 = 2.4\pi = 7.539822$$

It will converge to $x = 0$

instead of $x = 2\pi = 6.2831853$



Root jumping from intended location of root for $f(x) = \sin x = 0$.

Drawbacks – may not converge on some occasions:

when $f'(x_i)=0$
or when it may get stuck in the endless loop when x_i equals on of x_0, x_1, \dots, x_{i-1}

