Neural temporal point processes for earthquake catalogs

Ariane Ducellier

University of Washington

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What is a point process?

A point process is a random collection of points falling in some space.

For a temporal point process, the space is a portion of the real line.

 \rightarrow Ex: A collection of timings of earthquake events.

For a marked point process, there is also some information associated with the timing of the events.

 \rightarrow Ex: A collection of timings and magnitudes of earthquake events.



Conditional intensity function (CIF)

 $N_{\delta}(t)$: Number of events between t and $t + \delta$.

 $\mathcal{H}_t = \{((t_i, m_i) \forall i : t_i < t\}: \text{ Event history up to time } t.$

Conditional intensity function (\sim event rate):

$$\lambda\left(t\mid\mathcal{H}_{t}\right)=\lim_{\delta\to0}\Pr\left\{N_{\delta}\left(t\right)>0\mid\mathcal{H}_{t}\right\}$$

Our objective: Computing the value of $\lambda(t)$ knowing the event sequence $\{(t_1, m_1), \cdots, (t_n, m_n)\}$ between T_1 and T_2 .

Epidemic-Type Aftershock Sequence (ETAS) model

- Magnitude-frequency distribution law of Gutenberg and Richter: $Pr(m_i > m) = e^{-\beta(m-m_C)}$ for $m > m_C$.
- Omori-Utsu law of aftershock decay: Number of aftershocks decays as $1/t^p$.
- Each event, irrespective of whether it is a small or a big event, can trigger its own offspring.

$$\lambda\left(t\mid\mathcal{H}_{t}\right) = \mu + \sum_{i:t_{i} < t} Ae^{\alpha\left(m_{i} - m_{C}\right)} \left(1 + \frac{t - t_{i}}{c}\right)^{-p}$$

Fitting an ETAS model

Find the parameters (μ, A, α, c, p) that maximizes the likelihood:

L = Pr {The first event occurs between t_1 and $t_1 + dt$ |

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\mathcal{H}_{\mathcal{T}_1} and the first event does not occur between \mathcal{T}_1 and t_1\}* Pr {The second event occurs between t_2 and t_2+dt | \mathcal{H}_{t_1} and the second event does not occur between t_1 and t_2\}* ... Pr {The last event occurs between t_n and t_n+dt | \mathcal{H}_{t_{n-1}} and the last event does not occur between t_{n-1} and t_n\}
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Fitting an ETAS model

Find the parameters (μ, A, α, c, p) that maximizes the log-likelihood:

$$I = \sum_{i: T_1 \leq t_i \leq T_2} \log \lambda \left(t \mid \mathcal{H}_{t_i} \right) - \int_{T_1}^{T_2} \lambda \left(t \mid \mathcal{H}_t \right) dt$$

Goodness of fit of ETAS model

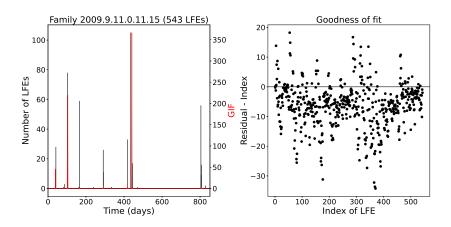
Residual process:

Transform times $\tau_i = \int_{T_1}^{t_i} \hat{\lambda}(t \mid \mathcal{H}_t) dt$ where $\hat{\lambda}$ is the fitted conditional intensity function.

Plot τ_i as a function of i. There is a good fit if the points follow the straight line y = x.

Plot $\tau_i - i$ as a function of i. There is a good fit if the points are horizontally aligned.

Example on an LFE family using R package PtProcess



First step: Encoding the timings of the events

Timing t_j of earthquake event is transformed into a vector y_j :

- Inter-event times: $y_j = t_j t_{j-1}$ or $y_j = \log(t_j t_{j-1})$.
- Decomposition into a sum of M cosine and sine functions: y_j is the vector of the M weights associated.

Second step: Encode the history of the process

The hidden state h_i contains all the history of the process until time t_i .

- Update at each time step $h_{i+1} = f(h_i, y_i)$.
- Encode the history of all events together: $H = f(y_1, y_2, \dots, y_n)$

Third step: Use the hidden states to get the conditional intensity function

- Parametric density function: $\lambda(\tau_i) = f(\tau_i, \theta_i)$ and $\theta_i = \sigma(Wh_i + b)$.
- Non parametric: $\lambda(\tau_i) = f(Wh_i + b)$.

Compute the loss function $I = -\sum_{i=1}^{n} \log \lambda(t_i) + \int_{0}^{T} \lambda(t) dt$ and minimize it using a gradient method.



More about ETAS and NTPP

- CORSSA website: http://www.corssa.org/en/home/
- Technical session at SSA meeting: New Developments in Physics- and Statistics-based Earthquake Forecasting oral session (Friday 10am to 11:15 am)
- Oleksandr Shchur blog: https://shchur.github.io/blog/

Questions?