

PHYSICAL COMPUTING

(Basics of electronics, Arduino, Processing)

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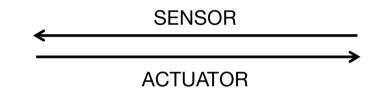
DISCLAIMER:

Not a computer scientist or an electrical engineer



PHYSICAL COMPUTING



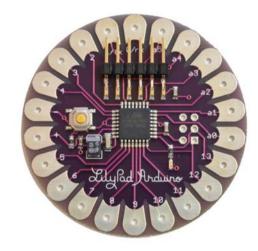




AN INTERACTIVE SYSTEM

THE REAL WORLD









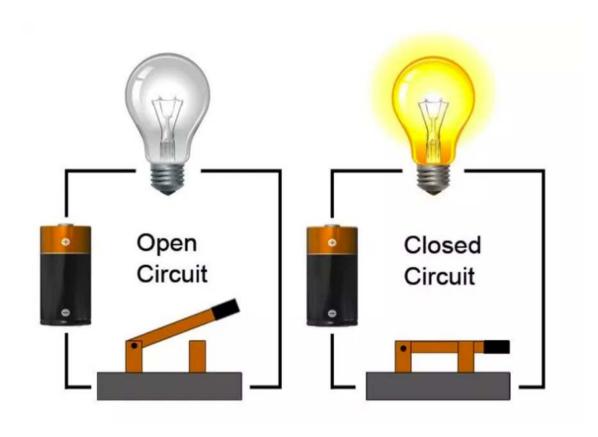








ELECTRICAL CIRCUIT

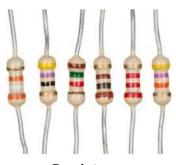


Center for Human-Computer Interaction University of Salzburg

ELECTRONIC COMPONENTS







Resistor



Variable Resistor (Potentiometer)



Light-Dependent Resistor (LDR)



Relay



Servo Motor



Capacitor



Diode



Light-Emitting Diode (LED)



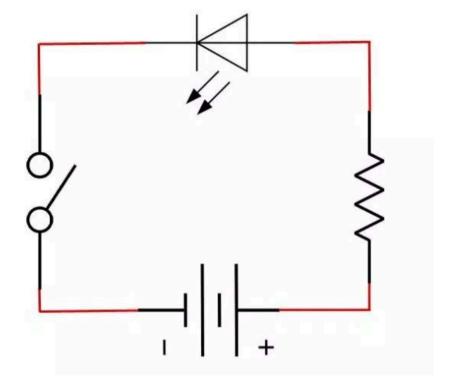
Transistor



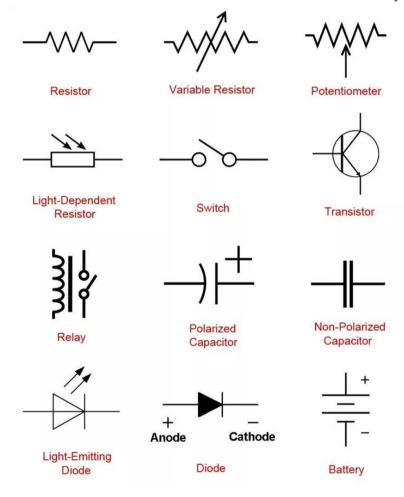
Integrated Circuit (IC)



DC Motor



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RESISTANCE (A.K.A. HOW NOT TO BURN THINGS)



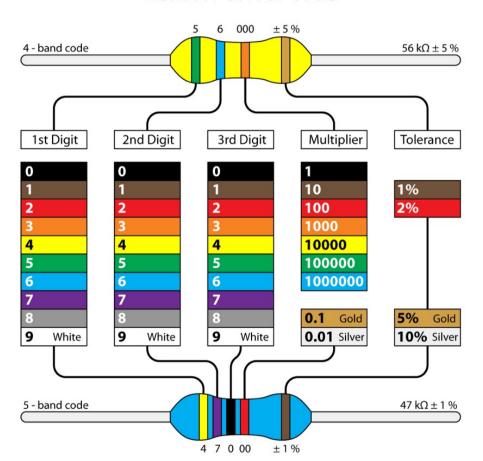
- Ohm's Law Resistance (R) = Voltage (V) / Current (I)
 - Resistance is measured in Ohms (Ω)
 - Voltage is measured in volts (V)
 - Current is measured in amps (A)

$$R = \frac{V_{Bat} - V_{LED}}{I_{LED}}$$

- Battery has 9V
- LED needs 2V
- LED has current rating of .02A (20mA)

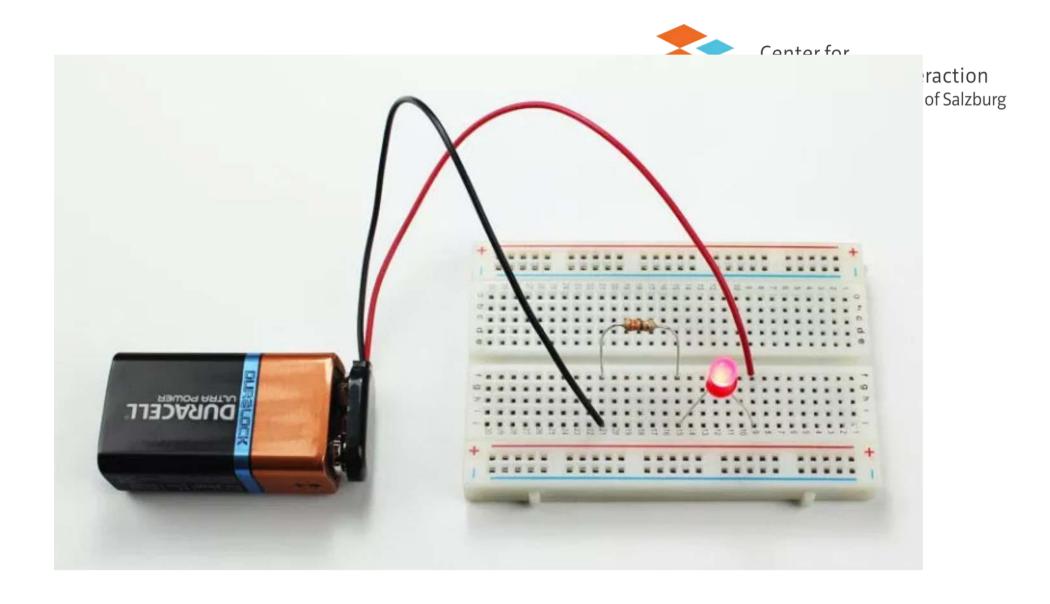
$$350 = \frac{9V - 2V}{.02A}$$

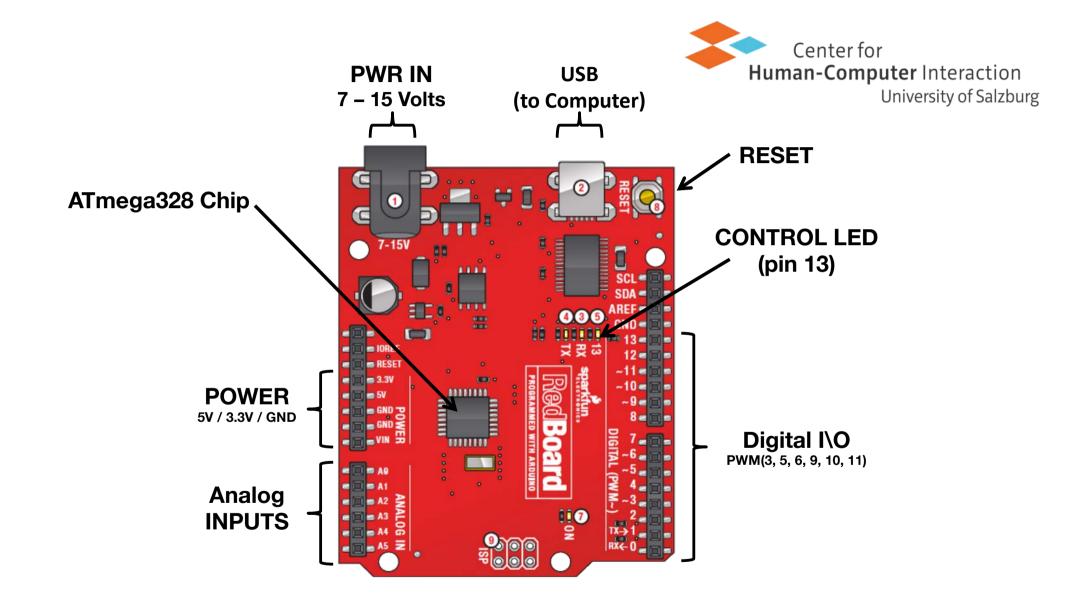
Resistor colour code



















www.arduino.cc/en/Main/Software



ARDUINO 1.8.5

The open-source Arduino Software (IDE) makes it easy to write code and upload it to the board. It runs on Windows, Mac OS X, and Linux. The environment is written in Java and based on Processing and other open-source software.

This software can be used with any Arduino board. Refer to the **Getting Started** page for Installation instructions.

Windows Installer, for Windows XP and up **Windows** ZIP file for non admin install

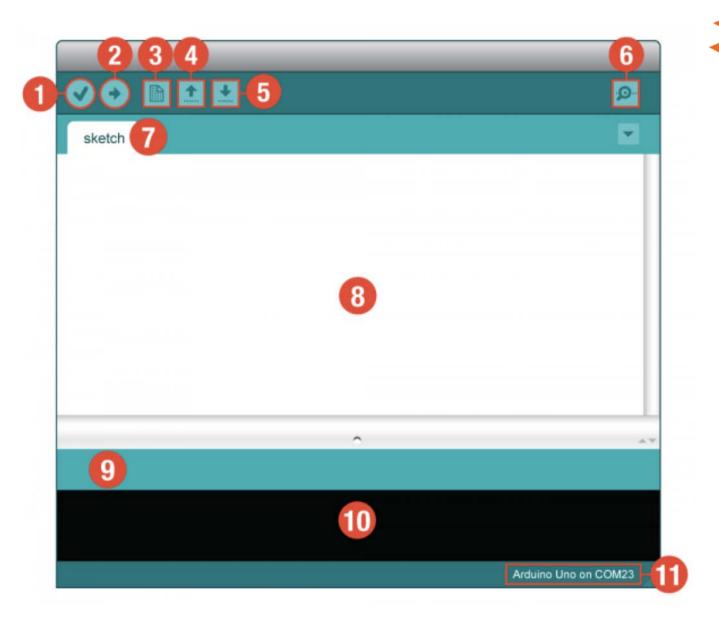
Windows app Requires Win 8.1 or 10



Mac OS X 10.7 Lion or newer

Linux 32 bits Linux 64 bits Linux ARM

Release Notes Source Code Checksums (sha512)





THE ARDUINO IDE

- 1. Verify
- 2. Upload
- 3. New
- 4. Open
- 5. Save
- 6. Serial Monitor
- 7. Sketch Name
- 8. Code Area
- 9. Message Area
- 10. Text Console
- 11. Board and Serial Port



```
void setup() {
   // put your setup code here, to run once:
}

void loop() {
   // put your main code here, to run repeatedly:
}
```

```
New
  sketch_may04a §
int buttonPin = 3;
void setup()
  Serial.begin(9600);
 pinMode(buttonPin, INPUT);
void loop()
  if (digitalRead(buttonPin) == HIGH)
    Serial.write('H');
  else
    Serial.write('L');
  delay(1000);
```

Arduino/Genuino Uno on COM1



BLINK





- 1. Plug in your RedBoard
- Make sure you're connected to the right COM port tools > port
 and that you have the right board selected tools > board > Arduino Uno
- 3. Type in the code on the left. Skip things after // and between /* and */
- 4. Verify your code
- 5. If no error, hit 'upload'
- 6. See what happens to the control LED on your board

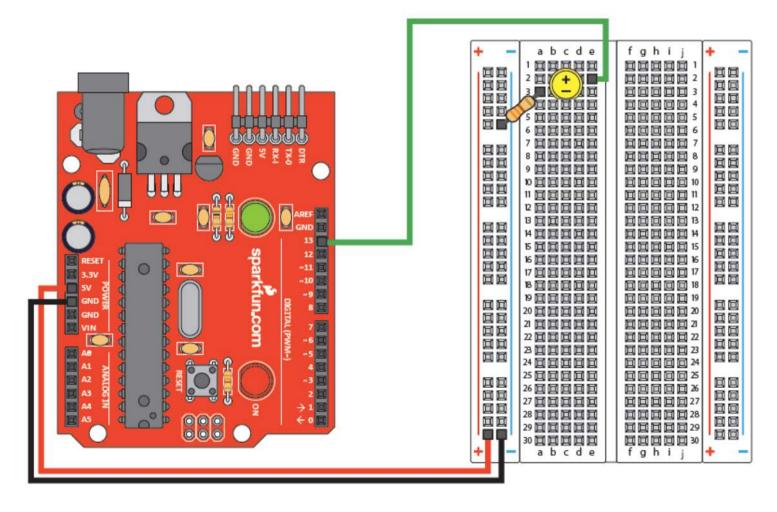


Needed:

1 LED

1 330 Ω Resistor

Jumper cables





```
void setup() {
    pinMode(13, OUTPUT);
    }

void loop() {
    digitalWrite(13, HIGH);
    delay(1000);
    digitalWrite(13, LOW);
    delay(1000);
}
```



SIK EXAMPLES

Download the zip:

https://www.sparkfun.com/sikcode (direct download)

- 1. Unzip >
- 2. Find the Arduino Folder on your PC > Go to 'Examples' >
- 3. Drop the unzipped folder in the Examples

(Restart Arduino)



PHOTO RESISTOR

Open:

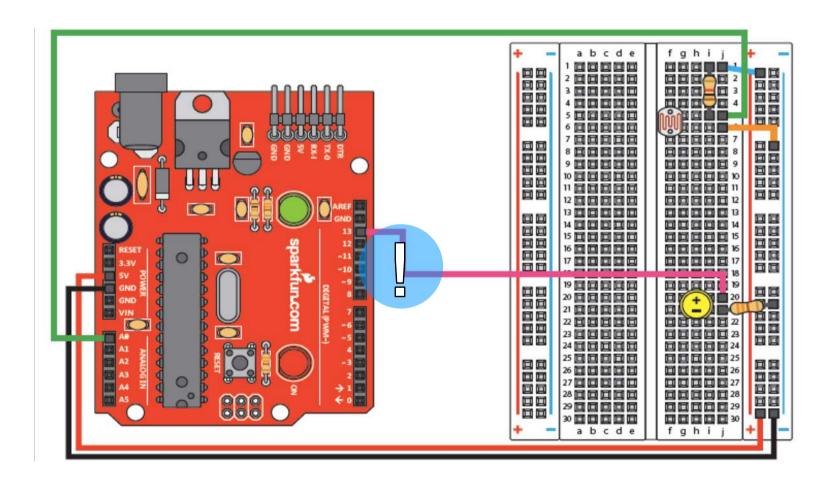
file > examples > SIK Guide > Circuit 6: Photoresistor



Needed:

- Previous Blink setup (to Pin9!)
- Photo resistor
- 10k resistor
- Jumper cables

The voltage is divided over two resistors (the photo resistor and the 10k resistor)

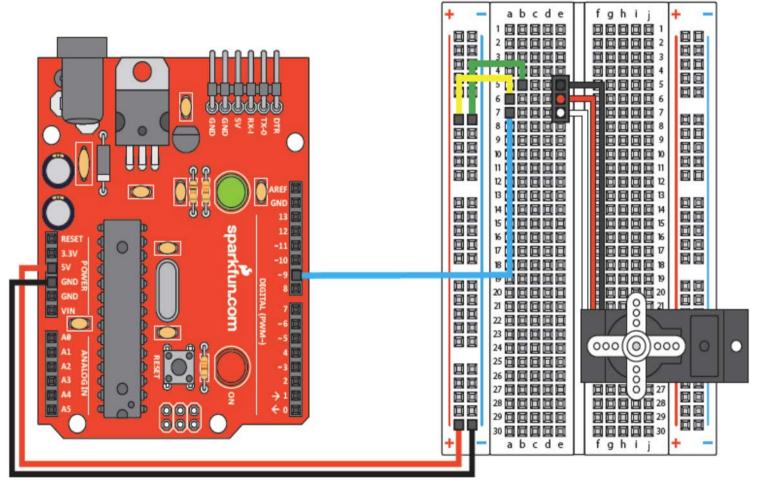




```
void loop() {
    lightLevel = analogRead(sensorPin);
    Serial.print(lightLevel);

calibratedlightLevel = map(lightLevel, 0, 1023, 0, 255);
    Serial.print("\t");
    Serial.print(calibratedlightLevel);
}
```





Needed:

- Servo
- Jumper cables



```
#include <Servo.h>
Servo servo1;

void setup() {
    servo1.attach(9, 900, 2100);
}
```



```
void loop() {
   int position;

   servol.write(90);
   delay(1000);
   servol.write(180);
   delay(1000);
   servol.write(0);
   delay(1000);
```

• • •



```
for(position = 0; position < 180; position += 2) {</pre>
     servol.write(position);
     delay(20);
for (position = 180; position >= 0; position -= 1) {
     servol.write(position);
     delay(20);
```



PROCESSING



WHAT IS PROCESSING?

Very basic programming language with a focus on visually oriented applications.

Based on Java.

Very similar to the Arduino IDE, with additional libraries for Arduino/Pi integration (Serial.library / Firmata)

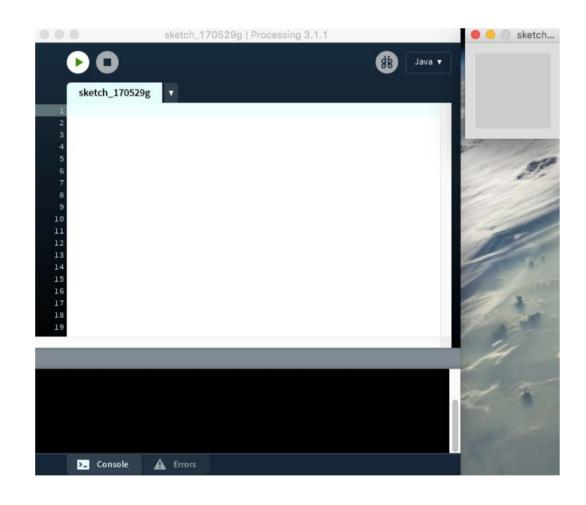




- Easy to get into
- Runs of most OS's
- Super-supportive community
- Lots of options to expand
- Able to connect via serial
- Can be exported as an executable



LET'S SKETCH



A LINE

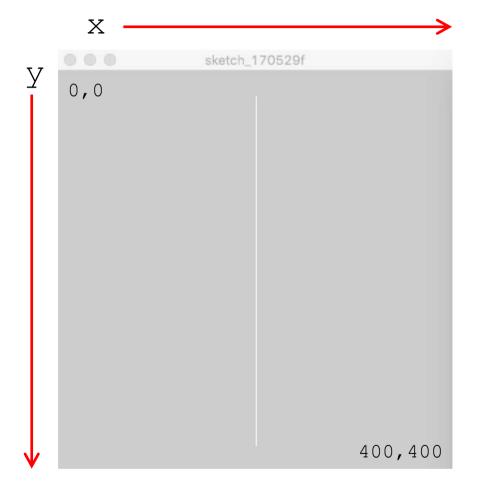
```
sketch_170529f | Processing 3.1.1
                                                                Java ▼
 sketch_170529f V
void setup() {
  size(400, 400);
  stroke(255);
void draw() {
  line(200, 25, 200, 375);
 >_ Console
               A Errors
```



```
void setup() {
    size(400, 400);
    stroke(255);
}

void draw() {
    line(200, 25, 200, 375);
}
```

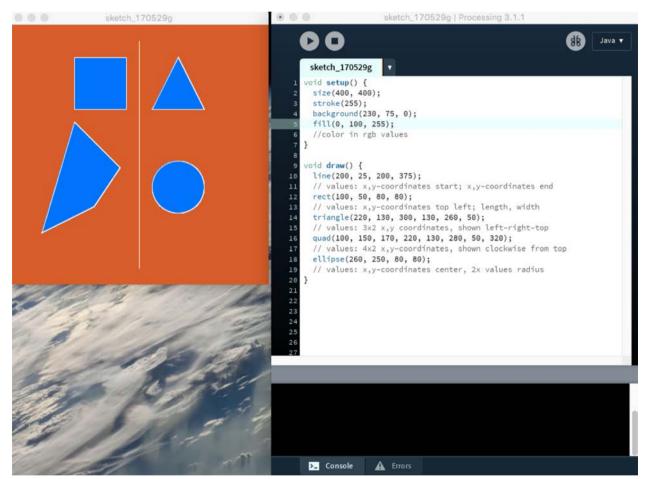




```
void setup() {
    size(400, 400);
    stroke(255);
}

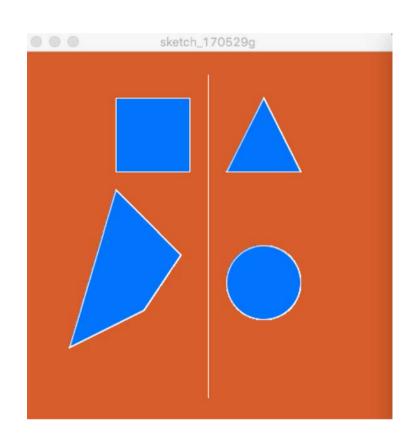
void draw() {
    line(200, 25, 200, 375);
}
```







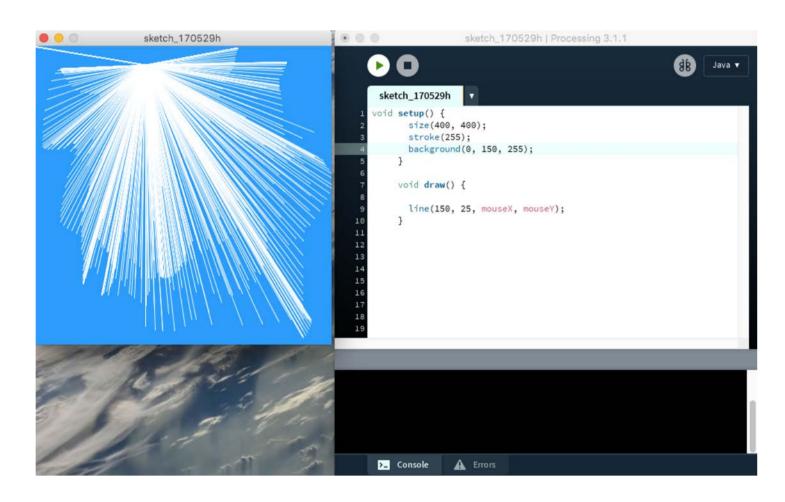




```
void setup() {
  size(400, 400);
  stroke (255);
  background(230, 75, 0);
  fill(0, 100, 255);
void draw() {
  line(200, 25, 200, 375);
  rect(100, 50, 80, 80);
  triangle(220, 130, 300, 130, 260, 50);
  quad(100, 150, 170, 220, 130, 280, 50, 320);
  ellipse(260, 250, 80, 80);
```



MOVING THE LINE







```
void setup() {
    size(400, 400);
    stroke(255);
    background(0, 150, 255);
}
void draw() {
    line(150, 25, mouseX, mouseY);
}
```



ASSIGNMENT (15-20 MIN)

Draw a stick figure that waves when you move the mouse

Bonus: make it wave automatically



POSSIBLE SOLUTION:



```
void setup() {
   size(400, 400);
   stroke (255);
   fill(0, 100, 255);
void draw() {
   background(100, 0, 100);
   triangle(150, 260, 250, 260, 200, 140);
   ellipse(200, 100, 80, 80);
   line(175, 260, 175, 320);
   line(225, 260, 225, 320);
   line (mouseX, mouseY, 180, 180);
```

<u>https://processing.org/reference/</u> (or *help > find in reference*)
for the basics of Processing

https://forum.processing.org/two/ (new forum)

https://forum.processing.org/one/ (previous forum)

And most importantly: file > examples > basics



ADDING AN ARDUINO

If you have the board with you, open up your Arduino IDE and add the following code*:

```
void setup() {
Serial.begin(9600);
}

void loop() {
Serial.println("Hello, world!");
delay(1000);
}
```

Add your board and upload.



Switch to Processing.

Sketch > Import Library > Serial

import processing.serial.*; should appear



Add the following code after your import statement:

```
Serial myPort;
String val;

void setup() {
   String portName = Serial.list()[0];
   //change the 0 to the COM port you're actually using
   myPort = new Serial(this, portName, 9600);
}
```



For mac:

import processing.serial.*;
Serial myPort;
printArray(Serial.list());



Add the following code as your void draw:

```
void draw() {
    if ( myPort.available() > 0) {
       val = myPort.readStringUntil('\n');
    }
    println(val);
}
```



FROM PROCESSING TO ARDUINO

Start a new Processing sketch, and **import the serial library**. Add the following code:

```
Serial myPort;

void setup() {
    size(200,200);
    String portName = Serial.list()[0];
    //change to fit COM port
    myPort = new Serial(this, portName, 9600);
}
```





```
void draw() {
    if (mousePressed == true) {
        myPort.write('1');
    }
    else {
        myPort.write('0');
    }
}
```

Hit 'Run' and see what happens when you click your mouse in the grey area.



Now, open your Arduino IDE (and, if you want to, stick an LED in pin13 and GND of your board).

Declare the following global variables before your setup:

```
char val;
int ledPin = 13;
```



Add the following setup:

```
void setup() {
  pinMode(ledPin, OUTPUT);
  Serial.begin(9600);
}
```



Add this loop, run the code and click your mouse:

```
void loop() {
     if (Serial.available()) {
          val = Serial.read();
     if (val == '1') {
          digitalWrite(ledPin, HIGH);
     else {
          digitalWrite(ledPin, LOW);
     delay(10);
```



FIRMATA FIRMWARE

Lets you communicate directly to Arduino via the Processing IDE

Advantage: some examples are included (*Processing > File > Examples*)



Upload *Examples > Firmata > StandardFirmata* to your board Quit the Arduino IDE

Include the Firmata library in Processing

Sketch > Import Library > Add Library ... > Arduino (Firmata)

Open & Run

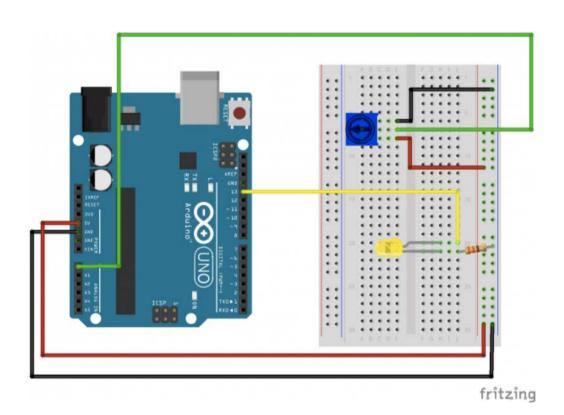
Examples > Topics > Fractals and L-Systems > Tree



No need to understand the code, but take a look at this line:

How can we change that variable to take an input from our Arduino?





Build the top part of this circuit (forget about the LED, we don't need it)

Potentiometer

- + to 5V
- to GNDoutput pin to A0



Back to processing. Before setup, add the lines:

```
import processing.serial.*; // reference the serial library
import cc.arduino.*; // reference the arduino library
Arduino arduino; // create a variable of the Arduino data type
```



Then, in your setup, add:

arduino = new Arduino(this, Arduino.list()[0], 57600);

Take care to choose the right COM port!



Finally, replace:

```
float a = (mouseX / (float) width) * 90f;
```

with:

```
float a = (arduino.analogRead(0) / (float) width) * 90f;
```

Run the Processing sketch, and see what happens when you turn the pot meter.



YOUR ASSIGNMENT

- Minimum make an illustration by hand (code shapes and colours) with simple interaction (input mouse, keyboard)
- Add complex interaction (input camera, microphone, microcontroller, ...)
- Add automation/math/gravity/physics
- For inspiration
- https://www.openprocessing.org/browse/#
- https://processing.org/examples/
- https://www.youtube.com/user/shiffman
- PS on 16th June 2020



For intermediate questions:

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