Mining Time Series: Forecasting

Mining Massive Datasets

Prof. Carlos Castillo

Topic 29



Sources

- Data Mining, The Textbook (2015) by Charu Aggarwal (chapter 14)
- Introduction to Time Series Mining (2006) tutorial by Keogh Eamonn [alt. link]
- Time Series Data Mining (2006) slides by Hung Son Nguyen

Forecasting (AR, MA, ARMA, ARIMA, ...)

Stationary vs Non-Stationary processes

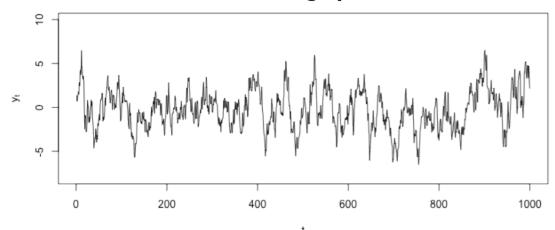
Stationary process

- Parameters do not change over time
- E.g., White noise has zero mean, fixed variance, and zero covariance between y_t and y_{t+L} for any lag L

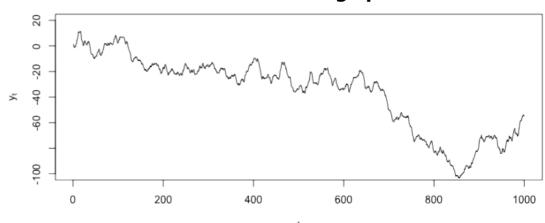
Non-stationary process

- Parameters change over time
- E.g., price of oil, height of a child, glucose level of a patient, ...

Stationary process



Non-stationary process



Strictly stationary time series

A strictly stationary time series is one in which the distribution of values in any time interval [a,b]is identical to that in [a+L, b+L] for any value of time shift (lag) L

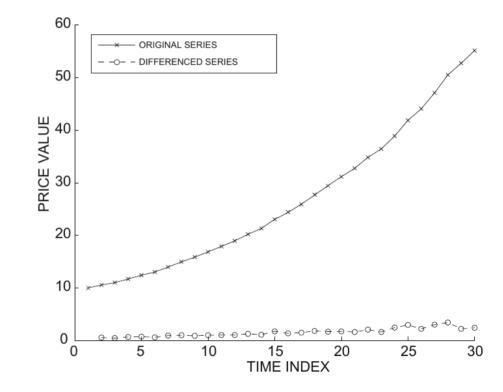
• In this case, current parameters (e.g., mean) are good predictors of future parameters

Differencing

First order differencing

$$y_i' = y_i - y_{i-1}$$

In this first example, if the original series is superlinear, the differenced series is stationary or non-stationary?

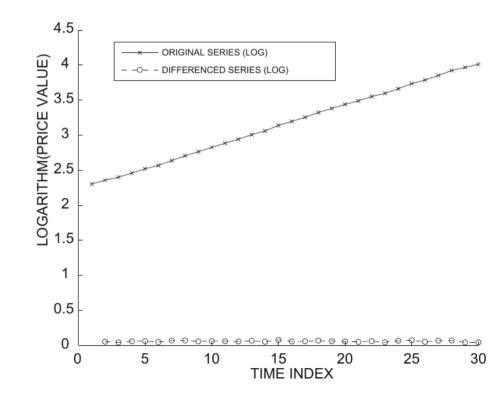


Differencing (cont.)

First order differencing

$$y_i' = y_i - y_{i-1}$$

In this second example, where the series is linear, the differenced series is stationary or non-stationary?



Other differencing operations

Second-order differencing

$$y_i'' = y_i' - y_{i-1}'$$

= $y_i - 2 \cdot y_{i-1} + y_{i-2}$

• Seasonal differencing (m = 24 hours, 7 days, ...) $y'_i = y_i - y_{i-m}$

If you find a differencing that yields a stationary series, the forecasting problem is basically solved.

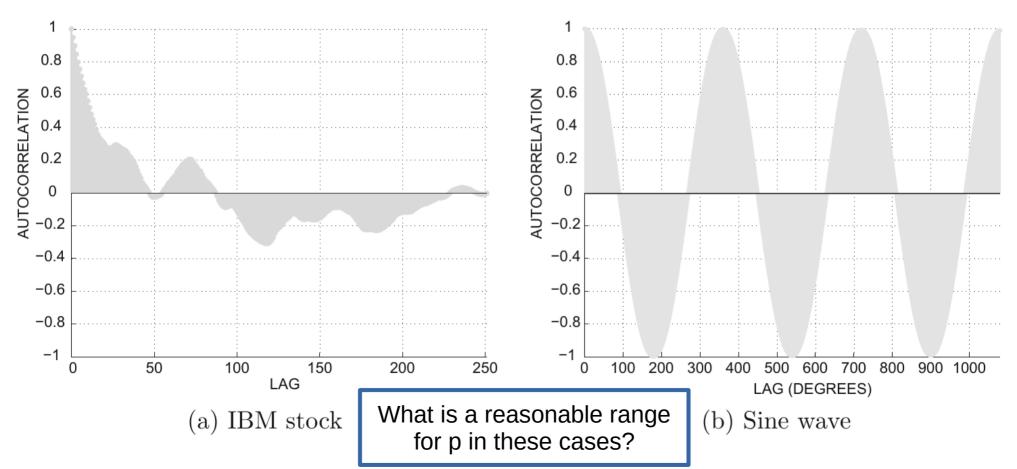
Autoregressive model AR(p)

Autocorrelation(L) =
$$\frac{\text{Covariance}_t(y_t, y_{t+L})}{\text{Variance}_t(y_t)}$$

- Autocorrelation lines in [-1,1]
- High absolute values ⇒ predictability
- Autoregressive model of order p, AR(p):

$$y_t^{AR} = \sum_{i=1}^{p} a_i \cdot y_{t-i} + c + \epsilon_t$$

How to decide p? Autocorrelation plots



Finding coefficients and evaluating

training element

• Each data point is a
$$y_t^{AR} = \sum_{i=1}^P a_i \cdot y_{t-i} + c + \epsilon_t$$
 training element

- Coefficients found by least-squares regression
- Best models have $R^2 \rightarrow 1$

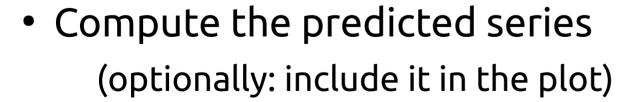
$$R^{2} = 1 - \frac{\text{Mean}_{t}(\epsilon_{t}^{2})}{\text{Variance}_{t}(y_{t})}$$

Exercise

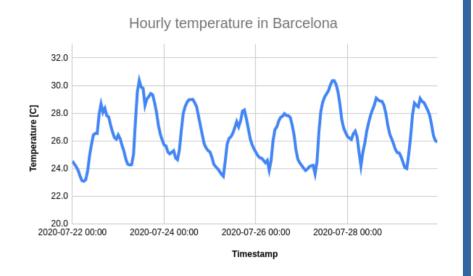
- Create a simple auto-regressive model
- Use two lags:

1 hour

24 hours



Compute the maximum error



Answer in Google Spreadsheet

Moving average model MA(q)

Focus on the variations (shocks) of the model,
i.e., places where change was unexpected

• AR(p) model:
$$y_t^{AR} = \sum_{i=1}^{r} a_i \cdot y_{t-i} + c + \epsilon_t$$

• MA(q) model:
$$y_t^{\text{MA}} = \sum_{i=1}^q b_i \cdot \epsilon_{t-i} + c + \epsilon_t$$

Autoregressive moving average model ARMA(p,q)

 Combines both the autoregressive and the moving average model

$$y_t^{\text{ARMA}} = \sum_{i=1}^p a_i \cdot y_{t-i} + \sum_{i=1}^q b_i \cdot \epsilon_{t-i} + c + \epsilon_t$$

Select small p, q, to avoid overfitting

Autoregressive integrated moving average model ARIMA(p,q)

 Combines both the autoregressive and the moving average model on differenced series

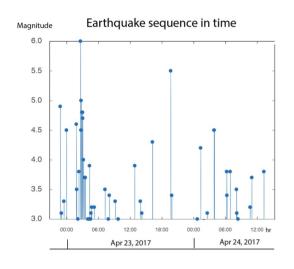
$$y_t^{\text{ARIMA}} = \sum_{i=1}^p a_i \cdot (y_{t-i} - y_{t-i-1}) + \sum_{i=1}^q b_i \cdot \epsilon_{t-i} + c + \epsilon_t$$

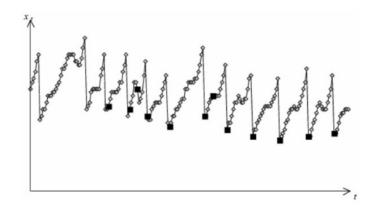
Note: this is an ARIMA(p,1,q) model as we're using first order differencing

See also: ARIMA end-to-end project in Python by Susan Li (2018)

Event detection (a simple framework)

Event: an important occurrence





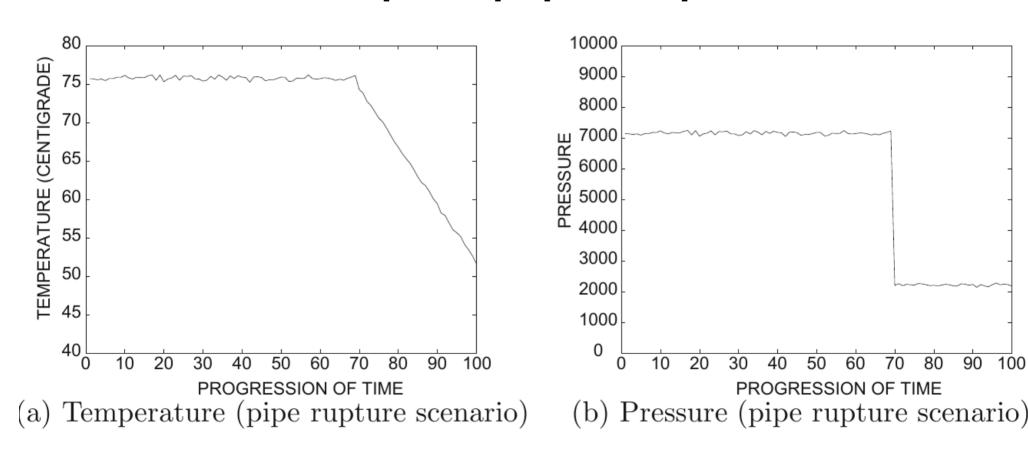


Earthquake or aftershock

Droplet release

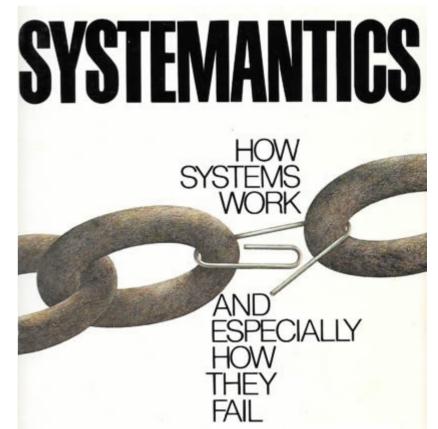
Sudden price change

Example: pipe rupture

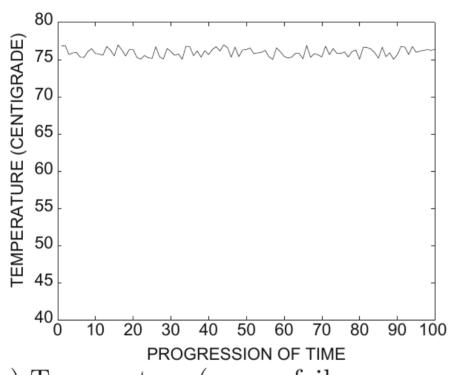


(... but what if sensors fail? ...

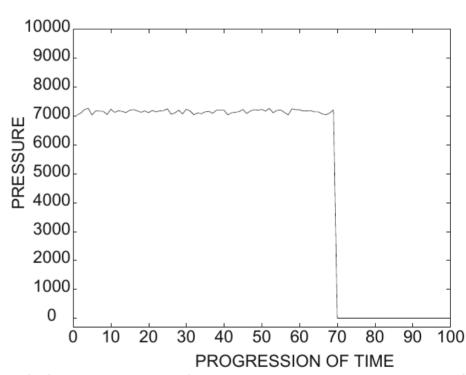
- "Systems in general work poorly or not at all"
- "In complex systems, malfunction and even total non-function may not be detectable for long periods, if ever"



... can we detect failure? ...)



(c) Temperature (sensor failure scenario)



(d) Pressure (sensor failure scenario)

A general scheme for event detection in multivariate time series

- Let $T_1, T_2, ..., T_r$ be times at which an event has been observed in the past
- (Offline) Learn coefficients α_1 , α_2 , ..., α_d to distinguish between event times and non-event times
- (Online) Observe series and determine deviation of every stream i at timestamp t as z_t^i
- (Online) Compute composite alarm level $Z_t = \sum_{i=1}^{n} \alpha_i \cdot z_t^i$

Learning discrimination coefficients

$$\alpha_1$$
, α_2 , ..., α_d

• Average alarm level for events

$$Q^{\mathrm{event}}(\alpha_1, \dots, \alpha_d) = \frac{1}{r} \sum_{T}^{r} Z_{T^i}$$

$$Z_t = \sum_{i=1}^d \alpha_i \cdot z_t^i$$

 Average alarm level for non-events (we assume most points are non-events)

$$Q^{\text{normal}}(\alpha_1, \dots, \alpha_d) = \frac{1}{N} \sum_{i=1}^{N} Z_t$$

Learning discrimination coefficients α_1 , α_2 , ..., α_d (cont.)

• For events $Q^{ ext{event}}(lpha_1,\ldots,lpha_d)=rac{1}{r}\sum^r Z_{T^i}$

• For non-events $Q^{\mathrm{normal}}(\alpha_1, \dots, \alpha_d) = \frac{1}{N} \sum_{i=1}^N Z_i$

Maximize
$$Q^{\mathrm{event}}(\alpha_1, \dots, \alpha_d) - Q^{\mathrm{normal}}(\alpha_1, \dots, \alpha_d)$$

subject to $\sum_{i=1}^d \alpha_i^2 = 1$ Use any off-the-shelf iterative optimization solver

Summary

Things to remember

- Time series forecasting
- Event detection

Exercises for TT27-TT29

- Data Mining, The Textbook (2015) by Charu Aggarwal
 - Exercises 14.10 → 1-6