

# Weighted graph

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# Weighted Graph

- We can add attributes to edges. We call the attributes weights.
  - For example if we are using the graph as a map where the vertices are the cities and the edges are highways between the cities.
  - Then if we want the shortest travel distance between cities an appropriate weight would be the road mileage.
  - If we are concerned with the dollar cost of a trip and want the cheapest trip then an appropriate weight for the edges would be the cost to travel between the cities.

# Shortest Path

- Digraph  $G = (V, E)$  with weight function  $W: E \rightarrow R$  (assigning real values to edges)
- Weight of path  $p = v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_k$  is

$$w(p) = \sum_{i=1}^{k-1} w(v_i, v_{i+1})$$

- Shortest path = a path of the minimum weight
- Applications
  - static/dynamic network routing
  - robot motion planning
  - map/route generation in traffic

# Shortest-Path Problems

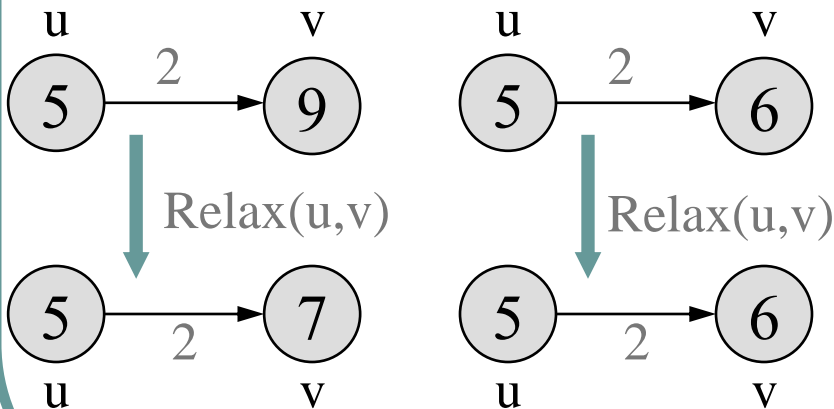
- Shortest-Path problems
  - **Single-source (single-destination).** Find a shortest path from a given source (vertex  $s$ ) to each of the vertices.
  - **Single-pair.** Given two vertices, find a shortest path between them. Solution to single-source problem solves this problem efficiently, too.
  - **All-pairs.** Find shortest-paths for every pair of vertices. Dynamic programming algorithm.

# Negative Weights and Cycles?

- Negative edges are OK, as long as there are no *negative weight cycles* (otherwise paths with arbitrary small “lengths” would be possible)
- Shortest-paths can have no cycles (otherwise we could improve them by removing cycles)
  - Any shortest-path in graph  $G$  can be no longer than  $n - 1$  edges, where  $n$  is the number of vertices

# Relaxation

- For each vertex  $v$  in the graph, we maintain  $v.d()$ , the estimate of the shortest path from  $s$ , initialized to  $\infty$  at the start
- Relaxing an edge  $(u,v)$  means testing whether we can improve the shortest path to  $v$  found so far by going through  $u$



```
Relax ( $u, v, G$ )  
if  $v.d() > u.d() + G.w(u, v)$   
  then  
     $v.setd(u.d() + G.w(u, v))$   
     $v.setparent(u)$ 
```

# Dijkstra's Algorithm

- Non-negative edge weights
- Like breadth-first search (if all weights = 1, one can simply use BFS)
- Use  $Q$ , a priority queue ADT keyed by  $v.d()$  (BFS used FIFO queue, here we use a PQ, which is re-organized whenever some  $d$  decreases)
- Basic idea
  - maintain a set  $S$  of solved vertices
  - at each step select "closest" vertex  $u$ , add it to  $S$ , and relax all edges from  $u$

# Demo

- [demo-dijkstra.ppt](#)



# Dijkstra's Pseudo Code

- Input: Graph  $G$ , start vertex  $s$

**Dijkstra** ( $G, s$ )

```
01 for each vertex  $u \in G.V()$ 
02      $u.setd(\infty)$ 
03      $u.setparent(NIL)$ 
04  $s.setd(0)$ 
05 // Set  $S$  is used to explain the algorithm
06  $Q.init(G.V())$  //  $Q$  is a priority queue ADT
07 while not  $Q.isEmpty()$ 
08      $u \leftarrow Q.extractMin()$ 
09
10     for each  $v \in u.adjacent()$  do
11         Relax ( $u, v, G$ )
12          $Q.modifyKey(v)$ 
```

relaxing  
edges

# Implementation

- Modify the graph API to support weighted edges as the following

```
#define INFINITIVE_VALUE 10000000
typedef struct {
    JRB edges;
    JRB vertices;
} Graph;
void addEdge(Graph graph, int v1, int v2, double weight);
double getEdgeValue(Graph graph, int v1, int v2); // return
    INFINITIVE_VALUE if no edge between v1 and v2
int indegree(Graph graph, int v, int* output);
int outdegree(Graph graph, int v, int* output);
double shortestPath(Graph graph, int s, int t, int* path,
    int*length); // return the total weight of the path and the path is
    given via path and its length. Return INFINITIVE_VALUE if no
    path is found
```

# Quiz

- Write the implementation of the weighted graph API. Test the API using the following example

```
Graph g = createGraph();
// add the vertices and the edges of the graph here
int s, t, length, path[1000];
double weight = shortestPath(g, s, t, path, &length);
if (weight == INFINITIVE_VALUE)
    printf("No path between %d and %d\n", s, t);
else {
    printf("Path between %d and %d:", s, t);
    for (i=0; i<length; i++) printf("%4d", path[i]);
    printf("Total weight: %f", weight);
}
```

# Solution

- dijkstra.c

# Mini Project II

- The objective of this project is to simulate a bus map in Hanoi.
- Firstly, you have to collect data about Hanoi's bus map in the form of a graph where
  - Each vertex is a bus station corresponding to a place in Hanoi
  - The edges connect the bus stations via the bus lines.
  - E.g., There are 16 stations connected by bus No 1A: “Yên Phụ - Hàng Đậu - Hàng Cót - Hàng Gà - Hàng Điều - Đường Thành - Phủ Doãn - Triệu Quốc Đạt - Hai Bà Trưng - Lê Duẩn - Khâm Thiên - Nguyễn Lương Bằng- Tây Sơn - Nguyễn Trãi - Trần Phú (Hà Đông) - Bến xe Hà Đông”
  - Cf.,  
<http://www.hanoibus.com.vn/InfobusVN/hanoibus/index.asp?pPage=lotrinh.htm>

## Mini project II (cont.)

- Each edge in the graph marked with the bus lines which traverse from one to the other. E.g., The edge “Yên Phụ - Trần Nhật Duật” is marked with 4A, 10A.
- Organize and store the data in a file to be loaded in the program when running
- Rewrite the graph API to be able to store the bus map in memory
- Develop a functionality to find the “shortest path” to move from a place to another. E.g., From “Yên Phụ” to “Ngô Quyền”.