

Education

Southeast University Nanjing, China

B.E. IN ELECTRONIC SCIENCE AND ENGINEERING

Sep. 2015 - Jun. 2019

• GPA: 3.95/4.0, Score: 92.03/100, Ranking: 1/126

· Related Courses: Advanced Mathematics(98), College Physics(96), Signals & Systems(95), Fundamentals of Semiconductor Physics(96), Fundamentals of Semico damentals of Circuit(98), Microcomputer Systems & Interfaces(96)

Technical University of Munich

Munich, Germany

EXCHANGE STUDENT IN ELECTRICAL AND COMPUTER ENGINEERING

Oct. 2018 - Mar. 2019

 Related Courses: Advanced Topics in IC Design, Memory technologies for data storage, System-on-Chip Technologies, Superconducting Quantum Chip, Machine Learning for Computer Vision

Skills_

Programming C/C++, Python, Java, Matlab, Verilog HDL, LaTeX

Multisim, Altium Designer, Proteus, OpenCV, Git, Android, MySQL Tools

Chinese(Native), English(GRE 330+4.0) Languages

Lab Experience

Lab of Media Technology Munich, Germany

GRADUATION DESIGN, SUPERVISED BY PROF. DR.-ING. ECKEHARD STEINBACH

Nov. 2018 - Present

- Develop a neural-network-based **teleoperation** control scheme and combine haptic code into the control scheme.
- · Compare it with the state-of-the-art methods, such as wave-based time domain passivity approach (TDPA).

Display Research Center

Nanjing, China

MEMBER, INSTRUCTED BY PROF. JUN XIA

Jul. 2018 - Oct. 2018

- Conducted research about non-invasive imaging through opaque scattering layers.
- Employed Matlab to optimize transmission matrix to improve the performance.

Nanjing, China

Laboratory of MEMS

TEAM LEADER Sep. 2017 - Jun. 2018

- Designed PDMS chips and implemented EIS(Electrochemical Impedance Spectroscopy) to detect C. elegans.
- Established optical path system to detect the information of green fluorescent protein stimulated by the incident laser, based on PMT.

Projects

RobocupRescue Qingdao, China

CORE MEMBER

CORE MEMBER

TEAM LEADER

Jun. 2016 - Jun. 2018

- Operated the **mechanical arm** in the robot, the total cost of which was nearly RMB 100,000.
- Participated in Robocup China Competition and gained the third prize(3/5) in 2017 and promoted to get the second prize(2/6) in 2018.

IoT Design Nanjing, China

Adopted LAN to realize wireless communication among several nodes and applied voice module to realize interaction..

• Designed an **Android** App to display the information of sensors, such as temperature.

Embedded Intelligence Vehicle

Nanjing, China

Nov. 2016 - May. 2017

Apr. 2017 - Dec.2017

- Programmed with Python to establish the navigation system based on Raspberry Pi to realize auto-driving.
- Built the database(MySQL) to store the data gathered from GPS module and other sensors.
- Used PID control algorithm to adjust the DC motor, Veyron, to drive the four-wheeled vehicle.

Robotics Competition Nanjing, China

Sep. 2016 - Jul. 2017 CORE MEMBER

- Upgraded the circuits of Hero Robot, exploited OpenCV to recognize digits and won the first Prize in the East Division of China.
- · Held the Robot Opening Day to introduce basic knowledge about robots, visitors up to 1k+.

Honors & Awards

2016 National Scholarship, RMB 8000, top 1% in Southeast University Nanjing, China

Competitions, RoboMaster, Electronic Design, Embedded Program, FPGA Design, Advanced Mathematics All

DECEMBER 9, 2018 Yu Zhu · RESUME