

50
50

(3) definition of DPDA :-

DPDA is a M with 7 tuples set of final states

$$M = (\mathcal{Q}, \Sigma, \Gamma, S, q_0, \delta, F)$$

↓ ↓ ↓ ↓ ↓ ↓ ↓
 states inp alph stack alphabsl S starting state set of final states bottom

st $\delta(q, \epsilon, \gamma) \neq \emptyset \iff \forall a \in \Sigma \quad \delta(q, a, \gamma) = \emptyset$

$a \in \mathcal{Q}, \gamma \in \Gamma$

and No such $a \in \Sigma$ st

$\delta(a, a, \gamma)$ contain more than one element.

$$\begin{aligned} a &\in \Sigma \cup \{\epsilon\} \\ \gamma &\in \Gamma \end{aligned}$$

Yes.

det, $M = (\mathcal{Q}, \Sigma, \Gamma, S, q_0, \delta, F)$ be the DPDA for L

We will create M' following way:

Intuition, whenever w is accepted by L (st no proper prefix of w say $y \notin L$) run all the strings of the form ww' where $ww' \notin L$ will not belong to L'

$\therefore \{w \notin L \text{ st } \exists y \in \Sigma^*, y \text{ is proper pref of } w \text{ and } y \in L\}$

So, whenever we are in final state,
after reading input string of ~~we can~~ and some
alphabets are still to process we can reject them as they
should not be in L' .

So, $M' = (\emptyset, \Sigma, \delta', \alpha_0, z, F)$ st

$$\boxed{\delta'(\alpha_f, a, \cancel{x}) = \emptyset} \quad \textcircled{1}$$

st $\alpha_f \in F$

$x \in \Gamma^*$

Proof: Let, $ww' \in L$ st $w \in L$ and no ^{proper} pref of $w \in L$

Now $(\alpha_0, w, z_0) \xrightarrow{*} (\alpha_f, \epsilon, z)$

$z \in \Gamma^*$

But $(\alpha_0, ww', z_0) \xrightarrow{*} (\alpha_f, w', \cancel{z})$ so, ww'
will not
be accepted

and $\delta(\alpha_f, a, \cancel{x}z') = \emptyset$

SI($\cancel{x}z' = z$)

from the
construction $\textcircled{1}$

$x \in \Gamma$

$z' \in \Gamma^*$

Proved

(4) Subroutine for computing x_{i+1} from x_i

We will make a two way infinite TM for computing x_{i+1} from x_i .

At first we will have $\# \bullet \#$ as written on input tape of the subroutine and at each step it will be changed to

$\dots B \# 1 \# 0 \rightarrow B \# 1 0 \# B \rightarrow B \# 1 1 \# B \dots$

The transition diagram is as follows.

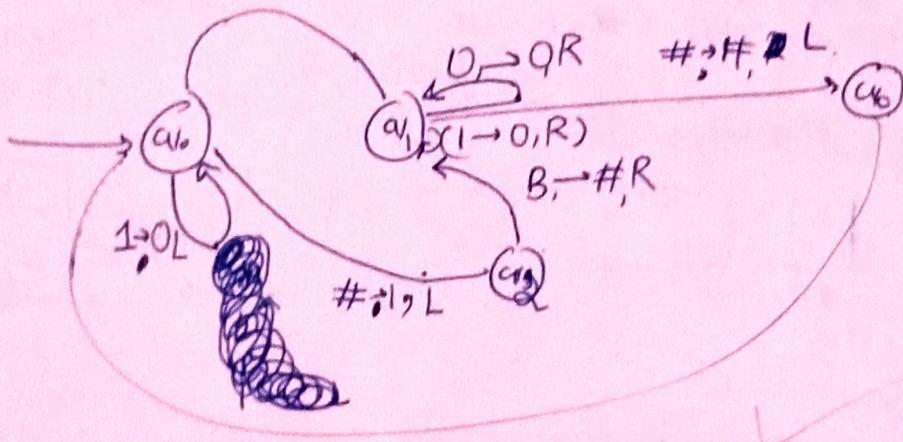
(15)

$\delta(a, a) = (P, b, \bullet P)$ $0 \rightarrow 1, R$

is shown as

$a \rightarrow b, D$ P

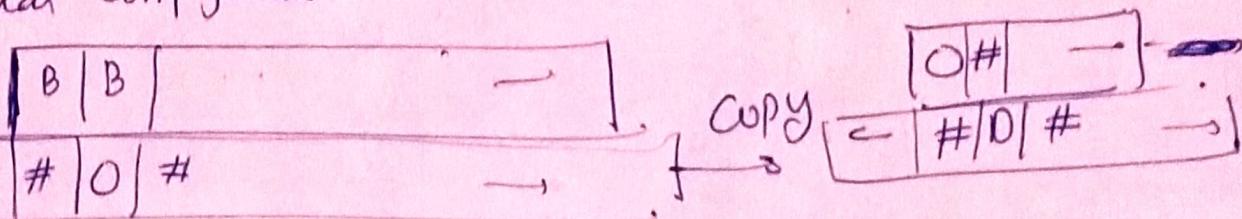
Dir the direction
enum of $\{L, R\}$



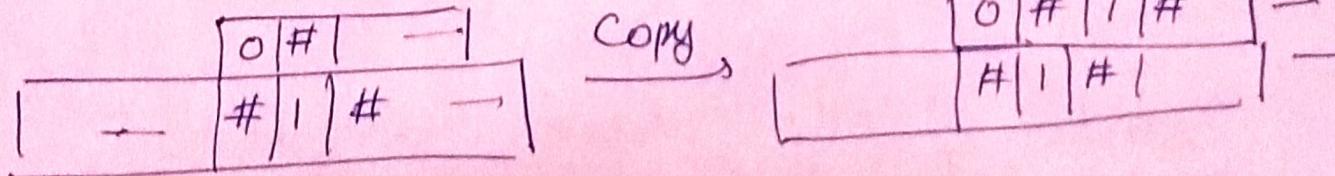
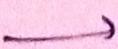
Description of M' : whenever it sees 0, it will replace it by 1 and return to the marker, 1 whenever it gets 1 it converts it to 0 and carry 1 to the next bit

for the input. $\# 1 1 1 1 \#$ it carry 1 to the $\#$ marker and then replace $\bullet \#$ with 1 and replace the ~~blank~~ blank with $\#$ marker.

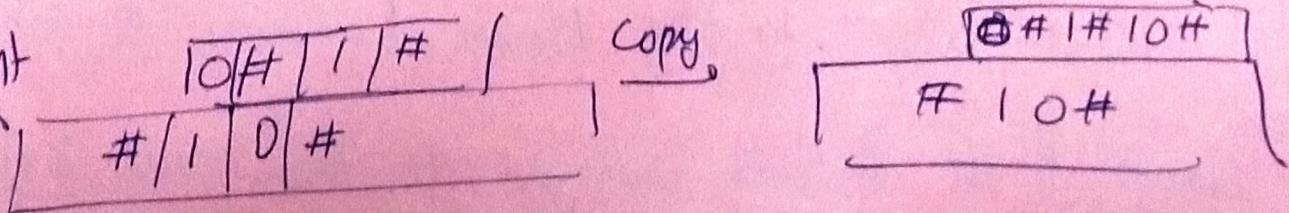
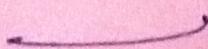
We will use the previous subroutine in this description.
 we will be creating a TM with one finite and one infinite
 tape (Both sides). The first tape will contain the required
 output and the second tape we will use to call the subroutine
 that increments by x_i . 1. we will be assuming that there is a
 (copy) subroutine that allows to copy the
 initial configuration



Increment



Increment



* ①

Claim: At any moment stack can be represented as γw where $\gamma \in \Gamma^*$ and $w \in \Sigma^*$ on ~~no~~ number of steps

Proof By induction:

start symbol of the grammar

Base case.

$$(aI, \overset{w}{\gamma}, S) \xrightarrow{0} (P, S)$$

(true)

Induction (axi):

$$(aI, \overset{w\alpha w'}{\gamma}, S) \xrightarrow{*} (P, \overset{\alpha w'}{\gamma}, AP) \quad P \in \Sigma^*$$

Now $A \rightarrow \alpha B, B$

$$\text{So, } (aI, \overset{w}{\gamma}, S) \xrightarrow{*} (P, \overset{w}{\gamma}, AP) \xrightarrow{*} (P, \overset{w}{\gamma}, BP)$$

$$\text{and } A \rightarrow \alpha \quad (aI, \overset{w\alpha}{\gamma}, S) \xrightarrow{*} (P, \overset{w\alpha}{\gamma}, AP) \xrightarrow{*} (P, \overset{w}{\gamma}, P)$$

Hence true

$$P = 8$$

$\gamma = \epsilon$ and $P \in \Sigma^*$

So, our PDA will be such a ~~long~~ st

~~$(Q, \Sigma, F, \delta, Q_0)$~~

$$N(M) = \{w \mid w \in L(G) \text{ and } (aI, w, S, \cdot) \xrightarrow{*} (aI, \epsilon, \epsilon)\}$$

and let $G = (V, T, P, S)$

so, ~~$(Q, \Sigma, F, \delta, Q_0)$~~

$$M = (\{aI\}, T, (VUT), \delta, aI, S, \phi)$$

① High level intuition :-

for every production of the form

$$A \rightarrow \alpha B \beta$$

we will add following transition to our PDA

$$\delta(\alpha, \alpha, A) \rightarrow (P, B\beta)$$

e.g., $\alpha \in \Sigma, A \in \Gamma$

So,

$\boxed{\alpha | w}$

\boxed{A}

\Rightarrow

Push operation

\boxed{w}

\boxed{B}

$\boxed{\beta}$

and, every production of the form

$$A \rightarrow \alpha$$

$$\delta(\alpha, \alpha, A) \rightarrow (\cancel{P}, \cancel{\epsilon})$$

$\boxed{\alpha | w}$

$\cancel{P} \boxed{w}$

\boxed{A}

\Rightarrow

\boxed{m}

\boxed{n}

S will be,

for every production

$$A \rightarrow \alpha B \beta$$

$$\delta(a, \alpha, A)$$

~~stack~~

$$\delta(a, \alpha, A) \ni (v, B\beta)$$

and, for all $A \rightarrow \alpha$

$$\delta(a, \alpha, A) \ni (v, A)$$

and, for all $t \in T$

$$\delta(a, z, t) \ni (a, \epsilon)$$



Proof: The PDA will be one-torn.

We will use claim (1) to prove this

According to the claim, stack can only one variable of the grammar at the top or no ~~variables~~ variable at all and once no variable is at the top, no way ^w can introduce a variable

So, whenever there is a variable. lets say

A and $A \rightarrow \alpha \beta$

stack top will be replaced by B and β will be squeezed in between
so, push operation.

Now, $A \rightarrow \alpha$

will remove the only variable from top and
push nothing (start of pop operation)

and ^{so}, no variable is in the stack
only transition is of form

$t \in T$.

(15) $S(a, r, t) \rightarrow (a, \epsilon)$

So, all pop operations till the stack being emptied
(if $w \in L(G)$)

Hence proved

(2) Let L be a linear context free language and so we have a one-turn PDA M for it.

~~$\leftarrow \text{NFA}$~~
 R is a regular language and \exists DFA M' for it

$$M = (Q, \Sigma, \Gamma, \delta, a_0, Z, \{w\})$$

$Q = \{q\}$

$$M' = (Q', \Sigma, \delta', a_0', F')$$

We will create an one-turn PDA for it.

$$\delta(a, a, \gamma) \rightarrow (a, \gamma)$$

$a \in Q$

$\gamma \in (\Sigma \cup \Gamma) \cup \{\epsilon\}$

~~10~~

$$\delta([a, a^i], a, \gamma) \rightarrow ([a, a^i], \gamma)$$

$\gamma \in F$

$$\delta'(a, a) = (P')$$

$$\text{So, } M_f = (Q \times Q', \Sigma, \Gamma, \delta, a_0, \{a, a_0\}, Z, F)$$

st. $\forall w \in L(M_f)$

$$([a, a_0], w, Z) \xrightarrow{*} ([a, a_f], \epsilon, F)$$

st. $(a_f \in F)$

So, it will both be $L(M)$ and $N(M)$

Intuition: while simulating the one turn PDA, we will also simulate the DFA with it

for every $\delta(a, a, s) \rightarrow (q_1, s')$

if $\delta'(a', a) = p'$

the following transition in new one turn PDA will

be $\delta([a, a'], a) \rightarrow ([q_1, s'], \cancel{s})$

$([a, p'], s')$

It will only accept if for some work both stack goes empty and the DFA enters the final state.

Moreover, if we are not using ϵ moves in PDA

there is no case of non-determinism handling in the DFA part

So, each step, PDA will non-deterministically choose next step and DFA will be simulating deterministically and accepts iff stack goes empty and reaches final