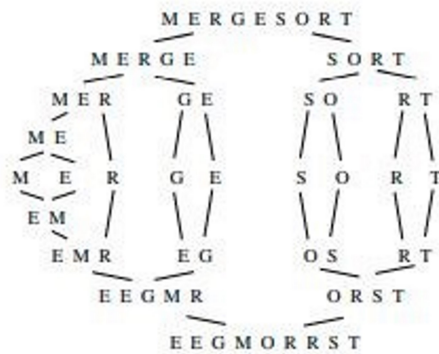


Sorting

15 July 2021 22:22

➤ MERGE SORT:

- Recursive algorithm
- Divide and Conquer
- Using Queues to merge



Code:

```
mergesort(item_type s[], int low, int high) {
    int i; /* counter */
    int middle; /* index of middle element */
    if (low < high) {
        middle = (low+high)/2;
        mergesort(s,low,middle);
        mergesort(s,middle+1,high);
        merge(s, low, middle, high);
    }
}

merge(item_type s[], int low, int middle, int high){
    int i; /* counter */
    queue buffer1, buffer2;
    /* buffers to hold elements for merging */

    init_queue(&buffer1);
    init_queue(&buffer2);
```

```

for (i=low; i<=middle; i++) enqueue(&buffer1,s[i]);
for (i=middle+1; i<=high; i++) enqueue(&buffer2,s[i]);

```

```

i = low;
while (!(empty_queue(&buffer1) ||
empty_queue(&buffer2))) {
    if (headq(&buffer1) <= headq(&buffer2))
        s[i++] = dequeue(&buffer1);
    else
        s[i++] = dequeue(&buffer2);
}

```

/* If the queue sizes are different then there are elements that don't require comparing and rest elements are required to fill in the merge */

```

while (!empty_queue(&buffer1))
    s[i++] = dequeue(&buffer1);
while (!empty_queue(&buffer2))
    s[i++] = dequeue(&buffer2);
}

```

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➤ **HEAP SORT:**

- Priority queue requirement
- Tree structure in heap
- Methods include heapify, bubble_up, bubble_down, extract_minimum

Code:

```

pq_insert(priority_queue *q, item_type x){
    if (q->n >= PQ_SIZE)
        printf("Warning: priority queue overflow insert
x=%d\n",x);
}

```

```

        else {
            q->n = (q->n) + 1;
            q->q[ q->n ] = x;
            bubble_up(q, q->n);
        }
    }
}

```

/* This subroutine trickles the inserted node at the end of the heap up to it's right position in the heap */

```

bubble_up(priority_queue *q, int p){
    if (pq_parent(p) == -1) return; /* at root of heap, no
    parent */
    if (q->q[pq_parent(p)] > q->q[p]) {
        pq_swap(q,p,pq_parent(p));
        bubble_up(q, pq_parent(p));
    }
}

```

```

make_heap(priority_queue *q, item_type s[], int n){
    int i; /* counter */
    pq_init(q);
    for (i=0; i<n; i++)
        pq_insert(q, s[i]);
}

```

```

item_type extract_min(priority_queue *q){
    int min = -1; /* minimum value */
    if (q->n <= 0)
        printf("Warning: empty priority queue.\n");
    else {
        min = q->q[1];
        q->q[1] = q->q[ q->n ];
        q->n = q->n - 1;
        bubble_down(q,1);
    }
    return(min);
}

```

```

bubble_down(priority_queue *q, int p){
    int c; /* child index */
    int i; /* counter */
    int min_index; /* index of lightest child */

    c = pq_young_child(p);
    min_index = p;

    /* This checks each child of a node in heap if they are
    more dominant than them and record the index */
    for (i=0; i<=1; i++)
        if ((c+i) <= q->n) {
            if (q->q[min_index] > q->q[c+i])
                min_index = c+i;
        }

    if (min_index != p) {
        pq_swap(q,p,min_index);
        bubble_down(q, min_index);
    }
}

heapsort(item_type s[], int n){
    int i; /* counters */
    priority_queue q; /* heap for heapsort */
    make_heap(&q,s,n);
    for (i=0; i<n; i++)
        s[i] = extract_min(&q);
}

```

➤ **QUICK SORT:**

- Recursive algorithm
- Divide and Conquer
- Partitioning using a pivot index
- Randomization algorithm

- Pivot element would be in the correct position, elements less than pivot would be before it and greater after it.

Code:

```
quicksort(item_type s[], int l, int h){
    int p; /* index of partition */

    if ((h-l)>0) {
        p = partition(s,l,h);
        quicksort(s,l,p-1);
        quicksort(s,p+1,h);
    }
}

int partition(item_type s[], int l, int h){
    int i; /* counter */
    int p; /* pivot element index */
    int firsthigh; /* divider position for pivot element */

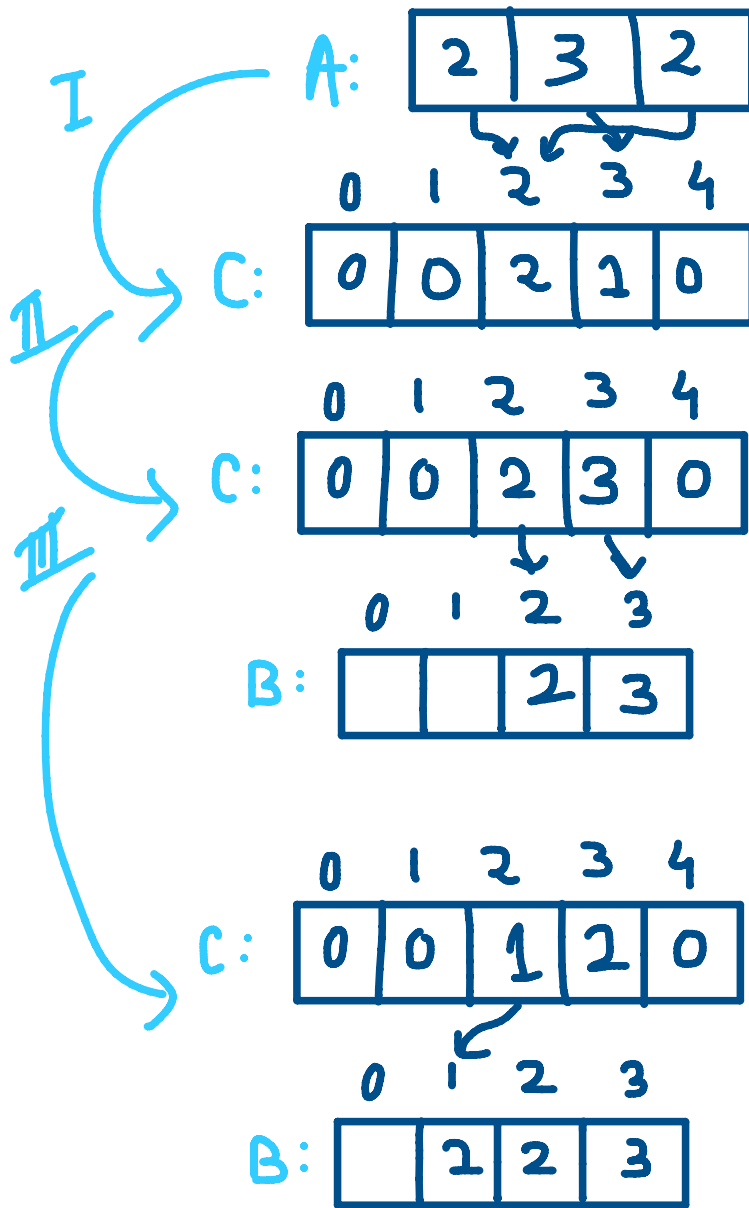
    p = h;
    firsthigh = l;

    for (i=l; i<h; i++)
        if (s[i] < s[p]) {
            swap(&s[i],&s[firsthigh]);
            firsthigh ++;
        }
    swap(&s[p],&s[firsthigh]);
    return(firsthigh);
}
```

➤ COUNTING SORT:

- Sort assumes elements are in set of 0 to K
- Requires an array index 0 to K as a mediatory array as well as an extra final array to store the final answer.

- No requirement for comparison for sorting



Code:

```
counting_sort(item_type A[], int k){
    item_type C[k+2];
    int i;
    for(i=0;i<=k;i++){
        C[i]=0;
    }
    for(i=0;i<k;i++){
        C[A[i]] = C[A[i]] + 1;
    }
}
```

```

    }
    for(i=0; i<k; i++){
        C[i] = C[i] + C[i-1];
    }
    for(i=k; i>0; i--){
        B[C[A[i]]] = C[A[i]];
        C[A[i]] = C[A[i]] - 1;
    }
}

```

➤ **RADIX SORT:**

- Sorts each digits sequentially

Code:

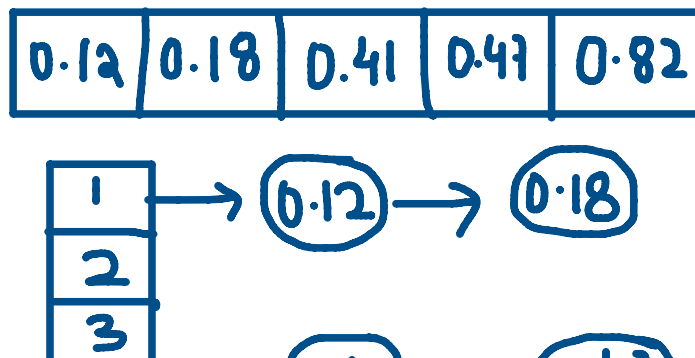
```

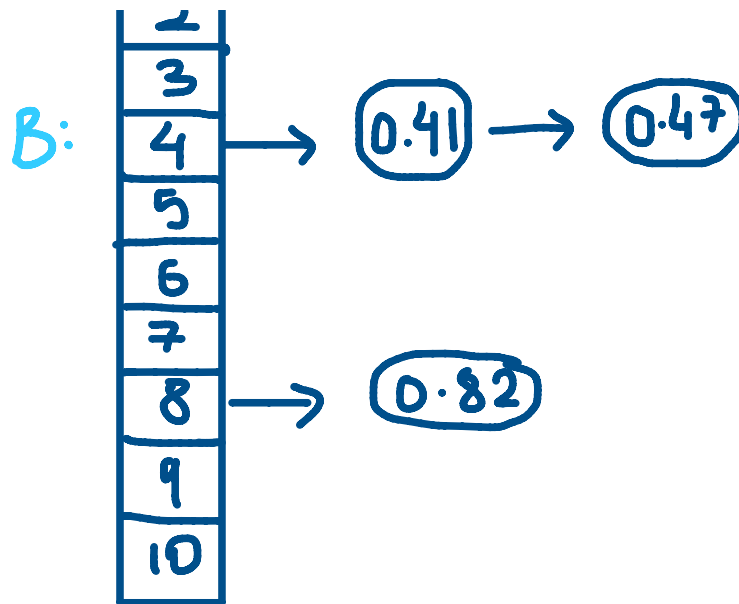
radixsort(item_type A[], int l, int h){
    For all 1 to digits:
        Sort A on each digits
}

```

➤ **BUCKET SORT:**

- Sorting algorithm appropriate for continuous values in range [0,1)
- Uses array of linked lists as buckets in order to group elements in the same range and sort each bucket individually then combine





Code:

```

bucketsort(item_type A[], int n){
    Declare B[n] as new array
    For 0 to n-1:
        B[i] = empty list
    For 0 to n-1:
        insert A[i] to list B[floor(A[i])]
    For 0 to n-1:
        Sort list B[i]
    Concatenate all lists in B[0 to n-1]
}

```