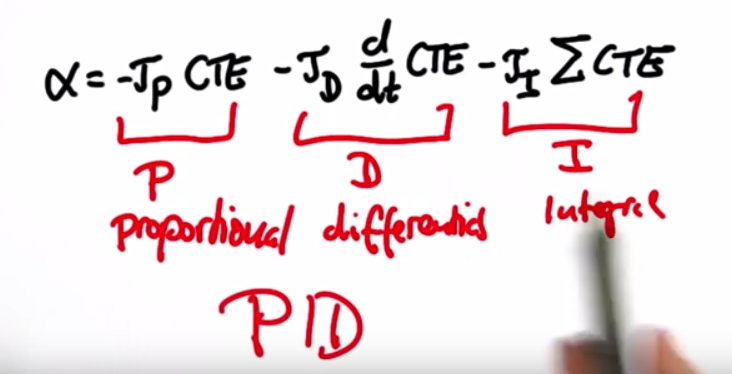
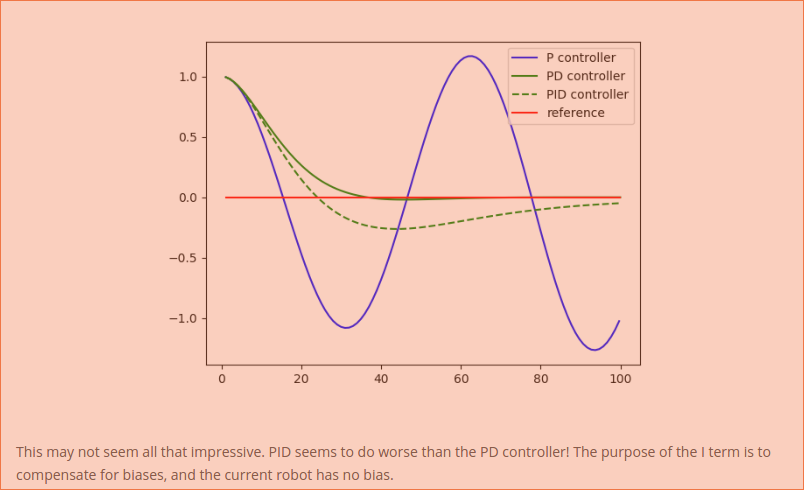
**LESSON 16.11 PID Control - Implementation**



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**Lesson 16.12: values of Control Gains?**

