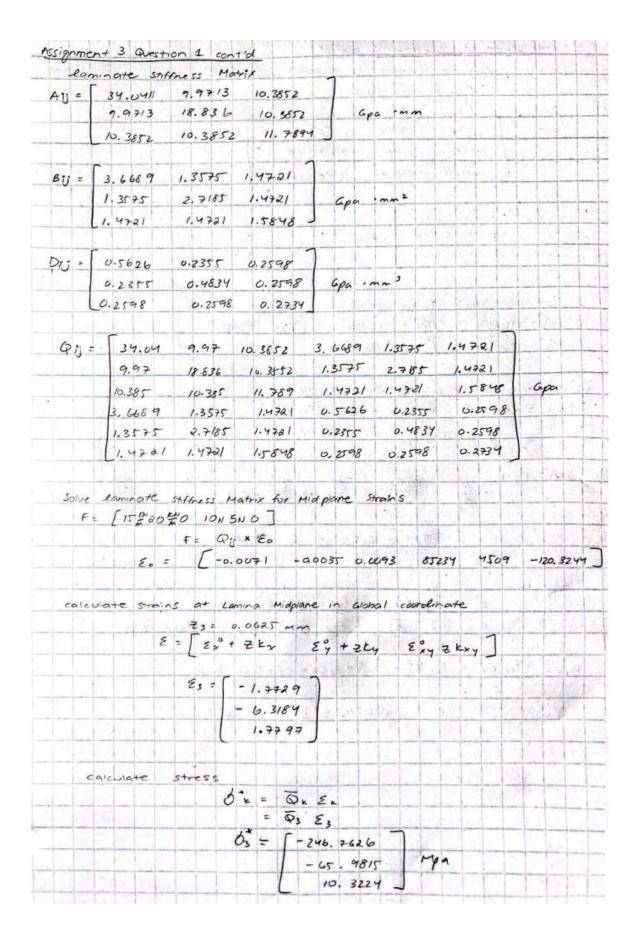
Assignment 3 Arjun Posarajah (1004881737) Oct 8, 2023



Question 1

uestion 1	10/20	,7	132 3		18	176	1/12	100	13/1	7 0
0.045	125~~	(D	N W			13			10	
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	2,8	. 6534	4	14.0	VEU		27.1345		1	1



calculate	lamina stresses in Material coordinates
	0 = 0° for ply 3
	$\partial_{x} = T_{k} \partial_{x}^{\dagger}$
Tx -	COS 20 SIN'S 200505100
12	5/n20 cos20 -2cos051m0
	-SINDICOSO COSOSINO COSTO -SINTO
b3 =	-246.76
	-65. 98 Mpa
	-10.322
	m stress failure criterion
d+ s-	SOMPA OT = 40 MPA ZLT = 75MPA
OL = 030	эссмра 07 = 160мра
OL = 71	
1 -	CHECK CHECK OL = ESUMPA V
07 = -16	
	TYA
Tsai - Hi	511 12 6,62 52 Ziz
	$\frac{\partial z}{\partial \hat{z}} - \frac{\partial z}{\partial \hat{z}} + \frac{\partial z}{\partial \hat{z}} + \frac{\partial z}{\partial \hat{z}} + \frac{\partial z}{\partial \hat{z}} \ge 1$
	TTH = 0.516 < 1
Carried Service of the service of th	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Heat.	
Tsai - w	
Tsai - w	Fu = 07 07 Fax = 07 07
Tsai - w	Fu = 07 07 Fax = 07 07
Tsai - w	F. = 07 07 F22 = 07 07
	$F_{11} = \frac{07}{07} \frac{07}{07}$ $F_{22} = \frac{07}{07} \frac{07}{07}$ $F_{66} = \frac{1}{7}$ $F_{66} = \frac{1}{7}$
	Fu = 07 07 Fax = 07 07
	$F_{11} = \frac{07}{07} \frac{07}{07}$ $F_{22} = \frac{07}{07} \frac{07}{07}$ $F_{66} = \frac{1}{7}$ $F_{66} = \frac{1}{7}$

Code:

```
%%Question 1%%
%Ply Angles
x1=0;
x2=30;
x3=60;
x4=90;
t=0.125;%mm
E1=132;
E2=8.4;
G12=6;
v12=0.25;
%%%Part 1 stiffness matrix in the material coordinate system
S11=1/E1;
S22=1/E2;
S12=(-v12)/E1;
S66=1/G12;
Q11=S22/((S11*S22)-(S12.^2));
Q22=S11/((S11*S22)-(S12.^2));
Q12=(-S12)/((S11*S22)-(S12.^2));
Q66=G12;
Q= [Q11 Q12 0; Q12 Q22 0; 0 0 Q66];
```

```
%%%Part2 stiffness matrix for the same lamina rotated angles from the global coordinate system
%%x1
x1Qbar11=(Q11*((cosd(x1)).^4))+(Q22*((sind(x1).^4)))+(2*(Q12+(2*Q66)))*((sind(x1)).^2)*((cosd(x1)).^2);
 \texttt{xlQbarl2=} \ (Q11+Q22-(4*Q66))*((cosd(x1)).^2)*((sind(x1)).^2) \ + \ (Q12)*(((cosd(x1)).^4)+((sind(x1)).^4)); \\
 x | Q bar 22 = (Q11) * ((sind(x1)) .^4) + (Q22) * ((cosd(x1)) .^4) + (2*(Q12 + (2*Q66))) * (((sind(x1)) .^2) * ((cosd(x1)) .^2)); 
x1Qbar16 = (Q11 - Q12 - (2*Q66))*((cosd(x1)).^3)*(sind(x1)) - ((Q22 - Q12 - (2*Q66))*(cosd(x1))*(((sind(x1)).^3)));
 xlQbar26 = (Q11 - Q12 - (2*Q66))*(cosd(x1))*((sind(x1)).^3) - (Q22 - Q12 - (2*Q66))*((cosd(x1)).^3)*(sind(x1)); \\
 xlQbar66 = ((Q11+Q22-(2*Q12)-(2*Q66))*((cosd(x1)).^2)*((sind(x1)).^2))+((Q66)*(((cosd(x1)).^4)+((sind(x1)).^4))); \\
xlQbar= [xlQbar11 xlQbar12 xlQbar16; xlQbar12 xlQbar22 xlQbar26; xlQbar26 xlQbar26 xlQbar66];
 x2Qbar11 = (Q11*((cosd(x2)).^4)) + (Q22*((sind(x2).^4))) + (2*(Q12+(2*Q66)))*((sind(x2)).^2)*((cosd(x2)).^2); \\
x2Qbar12 = (Q11+Q22-(4*Q66))*((cosd(x2)).^2)*((sind(x2)).^2) + (Q12)*(((cosd(x2)).^4)+((sind(x2)).^4));
 x2Qbar22 = (Q11)*((sind(x2)).^4) + (Q22)*((cosd(x2)).^4) + (2*(Q12+(2*Q66)))*(((sind(x2)).^2)*((cosd(x2)).^2)); \\
x2Qbar16=(Q11-Q12-(2*Q66))*((cosd(x2)).^3)*(sind(x2))-((Q22-Q12-(2*Q66))*(cosd(x2))*(((sind(x2)).^3)));
 x20bar26 = (Q11 - Q12 - (2*Q66))*(cosd(x2))*((sind(x2)).^3) - (Q22 - Q12 - (2*Q66))*((cosd(x2)).^3)*(sind(x2)); \\
x2Qbar66 = ((Q11+Q22-(2*Q12)-(2*Q66))*((cosd(x2)).^2)*((sind(x2)).^2))+((Q66)*(((cosd(x2)).^4)+((sind(x2)).^4)));
x20bar= [x20bar11 x20bar12 x20bar16; x20bar12 x20bar22 x20bar26; x20bar26 x20bar26 x20bar26];
 x3Qbar11 = (Q11*((cosd(x3)).^4)) + (Q22*((sind(x3).^4))) + (2*(Q12+(2*Q66)))*((sind(x3)).^2)*((cosd(x3)).^2); \\ x3Qbar11 = (Q11*((cosd(x3)).^4)) + (Q22*((sind(x3)).^4))) + (Q22*((sind(x3)).^4))) + (Q22*((sind(x3)).^4)) + (Q22*((sind(x3)).^4))) + (Q22*((sind(x3)).^4)) + (Q22*((sind(x3)).^4))) + (Q22*((sind(x3)).^4))) + (Q22*((sind(x3)).^4)) + (Q
x3Qbar12 = (Q11+Q22-(4*Q66))*((cosd(x3)).^2)*((sind(x3)).^2) + (Q12)*(((cosd(x3)).^4)+((sind(x3)).^4));
 x3Qbar22 = (Q11)*((sind(x3)).^4) + (Q22)*((cosd(x3)).^4) + (2*(Q12+(2*Q66)))*(((sind(x3)).^2)*((cosd(x3)).^2)); \\
x3Qbar16=(Q11-Q12-(2*Q66))*((cosd(x3)).^3)*(sind(x3))-((Q22-Q12-(2*Q66))*(cosd(x3))*(((sind(x3)).^3)));
 x3Qbar26 = (Q11 - Q12 - (2*Q66))*(cosd(x3))*((sind(x3)).^3) - (Q22 - Q12 - (2*Q66))*((cosd(x3)).^3)*(sind(x3)); \\
x3Qbar66 = ((Q11+Q22-(2*Q12)-(2*Q66))*((cosd(x3)).^2)*((sind(x3)).^2))+((Q66)*(((cosd(x3)).^4)+((sind(x3)).^4)));
x30bar= [x30bar11 x30bar12 x30bar16; x30bar12 x30bar22 x30bar26; x30bar26 x30bar26 x30bar66];
88x4
 x4Qbar11 = (Q11*((cosd(x4)).^4)) + (Q22*((sind(x4).^4))) + (2*(Q12+(2*Q66)))*((sind(x4)).^2)*((cosd(x4)).^2); \\
x40bar12 = (011+022-(4*066))*((cosd(x4)).^2)*((sind(x4)).^2) + (012)*(((cosd(x4)).^4)+((sind(x4)).^4));
x40bar22 = (Q11)*((sind(x4)).^4) + (Q22)*((cosd(x4)).^4) + (2*(Q12+(2*Q66)))*(((sind(x4)).^2)*((cosd(x4)).^2));
 x4Qbar16 = (Q11 - Q12 - (2*Q66))*((cosd(x4)).^3)*(sind(x4)) - ((Q22 - Q12 - (2*Q66))*(cosd(x4))*(((sind(x4)).^3))); \\
x4Qbar26 = (Q11 - Q12 - (2*Q66))*(cosd(x4))*((sind(x4)).^3) - (Q22 - Q12 - (2*Q66))*((cosd(x4)).^3)*(sind(x4));
x4Qbar66 = ((Q11+Q22-(2*Q12)-(2*Q66))*((cosd(x4)).^2)*((sind(x4)).^2))+((Q66)*(((cosd(x4)).^4)+((sind(x4)).^4));
%%%Part3: Calculating A,B,D
All=xlObarl1*(t)+ x2Obarl1*(t)+x3Obarl1*(t)+ x4Obarl1*(t);
A12=x1Qbar12*(t) + x2Qbar12*(t)+x3Qbar12*(t) + x4Qbar12*(t);
A22=x1Qbar22*(t)+ x2Qbar22*(t)+x3Qbar22*(t)+ x4Qbar22*(t);
A16=x1Qbar16*(t) + x2Qbar16*(t) +x3Qbar16*(t) + x4Qbar16*(t);
A26=x1Qbar26*(t)+ x2Qbar26*(t)+x3Qbar26*(t)+ x4Qbar26*(t);
A66=x1Qbar66*(t)+ x2Qbar66*(t)+x3Qbar66*(t)+ x4Qbar66*(t);
Bll= 0.5*((xlQbarll*(-3/64))+(x2Qbarll*(-1/64))+(x3Qbarll*(1/64))+(x4Qbarll*(3/64)));
B12= 0.5*((x1Qbar12*(-3/64))+(x2Qbar12*(-1/64))+(x3Qbar12*(1/64))+(x4Qbar12*(3/64)));
B22= 0.5*((x1Qbar22*(-3/64))+(x2Qbar22*(-1/64))+(x3Qbar22*(1/64))+(x4Qbar22*(3/64)));
B16= 0.5*((xlQbar16*(-3/64))+(x2Qbar16*(-1/64))+(x3Qbar16*(1/64))+(x4Qbar16*(3/64)));
B26= 0.5*((x1Qbar26*(-3/64))+(x2Qbar26*(-1/64))+(x3Qbar26*(1/64))+(x4Qbar26*(3/64)));
B66= 0.5*((xlQbar66*(-3/64))+(x2Qbar66*(-1/64))+(x3Qbar66*(1/64))+(x4Qbar66*(3/64)));
D11=(1/3)*((x1Qbar11*(7/512))+(x2Qbar11*(1/512))+(x3Qbar11*(1/512))+(x4Qbar11*(7/512)));
D12=(1/3)*((x1Qbar12*(7/512))+(x2Qbar12*(1/512))+(x3Qbar12*(1/512))+(x4Qbar12*(7/512)));
D22=(1/3)*((x1Qbar22*(7/512))+(x2Qbar22*(1/512))+(x3Qbar22*(1/512))+(x4Qbar22*(7/512)));
D16=(1/3)*((xlQbar16*(7/512))+(x2Qbar16*(1/512))+(x3Qbar16*(1/512))+(x4Qbar16*(7/512)));
D26=(1/3)*((x10bar26*(7/512))+(x20bar26*(1/512))+(x30bar26*(1/512))+(x40bar26*(7/512)));
D66=(1/3)*((x1Qbar66*(7/512))+(x2Qbar66*(1/512))+(x3Qbar66*(1/512))+(x4Qbar66*(7/512)));
%%%Part4 Laminate Stiffness Matrix
A= [All Al2 Al6; Al2 A22 A26; Al6 A26 A66];
B= [B11 B12 B16; B12 B22 B26; B16 B26 B66];
D= [D11 D12 D16; D12 D22 D26; D16 D26 D66];
Oi1=(All Al2 Al6 Bl1 Bl2 Bl6: Al2 A22 A26 Bl2 B22 B26:Al6 A26 A66 Bl6 B26 B66; Bl1 Bl2 Bl6 Dl1 Dl2 Dl6 :Bl2 B22 B26 Dl2 D22 D26: Bl6 B26 B66 Dl6 D26 D66)
%Part5 Solve Laminate Stiffness Matrix for Midplane Strains
F=[10 ;5; 0 ;10; 0 ;0];
Eol=linsolve(Qij,F);
Eo= [.001; .001; 0.001; 1; 1; 1].* Eol %convert the KN/m to N/m
```