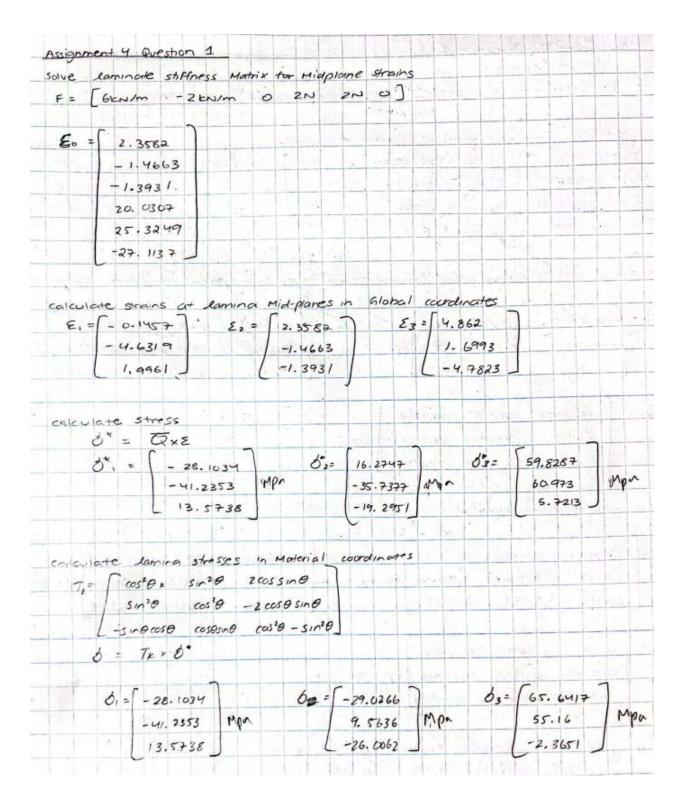
Assignment 4 Arjun Posarajah (1004881737) Oct 15, 2023



Question 1

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code:
  %%Ouestion 1%%
  %Ply Angles
  x1=0;
  x2=45;
  x3=60;
  t=0.125;%mm
  E1=125:
  E2=8.8:
  G12=6.8;
  v12=0.24;
  %%%Part 1 stiffness matrix in the material coordinate system
  S11=1/E1;
  S22=1/E2;
  S12=(-v12)/E1;
  S66=1/G12:
  Q11=S22/((S11*S22)-(S12.^2));
  Q22=S11/((S11*S22)-(S12.^2));
  Q12=(-S12)/((S11*S22)-(S12.^2));
  Q66=G12;
  Q= [Q11 Q12 0; Q12 Q22 0; 0 0 Q66];
 %%Part2 stiffness matrix for the same lamina rotated angles from the global coordinate system
 %%x1
 x10bar11=(Q11*((cosd(x1)).^4))+(Q22*((sind(x1).^4)))+(2*(Q12+(2*Q66)))*((sind(x1)).^2)*((cosd(x1)).^2);
  x10bar12 = (Q11 + Q22 - (4*Q66))*((cosd(x1)).^2)*((sind(x1)).^2) + (Q12)*(((cosd(x1)).^4) + ((sind(x1)).^4)); \\ x10bar12 = (Q11 + Q22 - (4*Q66))*((cosd(x1)).^2) + (Q12)*(((cosd(x1)).^4) + ((sind(x1)).^4)); \\ x10bar12 = (Q11 + Q22 - (4*Q66))*((cosd(x1)).^2) + (Q12)*(((cosd(x1)).^4) + ((sind(x1)).^4)); \\ x10bar12 = (Q11 + Q22 - (4*Q66)) + ((cosd(x1)).^2) + (Q12)*(((cosd(x1)).^4) + ((sind(x1)).^4)); \\ x10bar12 = (Q11 + Q22 - (4*Q66)) + ((cosd(x1)).^4) + ((co
 x1Qbar22=(Q11)*((sind(x1)).^4)+(Q22)*((cosd(x1)).^4)+(2*(Q12+(2*Q66)))*(((sind(x1)).^2)*((cosd(x1)).^2));
 x10bar16=(Q11-Q12-(2*Q66))*((cosd(x1)).^3)*(sind(x1))-((Q22-Q12-(2*Q66))*(cbsd(x1))*(((sind(x1)).^3)));
 x1Qbar26=(Q11-Q12-(2*Q66))*(cosd(x1))*((sind(x1)).^3)-(Q22-Q12-(2*Q66))*((cosd(x1)).^3)*(sind(x1));
 x1Qbar66 = ((Q11 + Q22 - (2*Q12) - (2*Q66))*((cosd(x1)).^2)*((sind(x1)).^2)) + ((Q66)*(((cosd(x1)).^4) + ((sind(x1)).^4)));
 x1Qbar= [x1Qbar11 x1Qbar12 x1Qbar16; x1Qbar12 x1Qbar22 x1Qbar26; x1Qbar16 x1Qbar26 x1Qbar66];
  x2Qbar11 = (Q11*((cosd(x2)).^4)) + (Q22*((sind(x2).^4))) + (2*(Q12+(2*Q66)))*((sind(x2)).^2)*((cosd(x2)).^2); \\
  x2Qbar12 = (Q11 + Q22 - (4*Q66))*((cosd(x2)).^2)*((sind(x2)).^2) + (Q12)*(((cosd(x2)).^4) + ((sind(x2)).^4)); 
  x20bar22 = (Q11)*((sind(x2)).^4) + (Q22)*((cosd(x2)).^4) + (2*(Q12 + (2*Q66)))*(((sind(x2)).^2)*((cosd(x2)).^2)); \\ x20bar22 = (Q11)*((sind(x2)).^4) + (Q22)*((cosd(x2)).^4) + (2*(Q12 + (2*Q66)))*(((sind(x2)).^2))*((cosd(x2)).^2); \\ x20bar22 = (Q11)*((sind(x2)).^4) + (Q22)*((cosd(x2)).^4) + (2*(Q12 + (2*Q66)))*(((sind(x2)).^2))*((cosd(x2)).^4) + (2*(Q12 + (2*Q66)))*(((sind(x2)).^4)) + (2*(Q12 + (2*Q66)))*(((sind(x2)).^4)) + (2*(Q12 + (2*Q66))))*(((sind(x2)).^4)) + (2*(Q12 + (2*Q66))))*(((sind(x2)).^4)) + (2*(Q12 + (2*Q66))))*(((sind(x2)).^4)) + (2*(Q12 + (2*Q66)))) + (2*(Q12 + (2*Q66))) + (2*(Q12 + (2*Q66)))) + (2*(Q12 + (2*Q66))) 
 x2Qbar16=(Q11-Q12-(2*Q66))*((cosd(x2)).^3)*(sind(x2))-((Q22-Q12-(2*Q66))*(cbsd(x2))*(((sind(x2)).^3)));
 x2Qbar26=(Q11-Q12-(2*Q66))*(cosd(x2))*((sind(x2)).^3)-(Q22-Q12-(2*Q66))*((cosd(x2)).^3)*(sind(x2));
 x2Qbar66 = ((Q11 + Q22 - (2*Q12) - (2*Q66))*((cosd(x2)).^2)*((sind(x2)).^2)) + ((Q66)*(((cosd(x2)).^4) + ((sind(x2)).^4)));
 x2Qbar= [x2Qbar11 x2Qbar12 x2Qbar16; x2Qbar12 x2Qbar22 x2Qbar26; x2Qbar16 x2Qbar26 x2Qbar66];
 x3Qbar11 = (Q11*((cosd(x3)).^4)) + (Q22*((sind(x3).^4))) + (2*(Q12+(2*Q66)))*((sind(x3)).^2)*((cosd(x3)).^2);
 x3Qbar12 = (Q11+Q22-(4*Q66))*((cosd(x3)).^2)*((sind(x3)).^2) + (Q12)*(((cosd(x3)).^4)+((sind(x3)).^4));
 x3Qbar22 = (Q11)*((sind(x3)).^4) + (Q22)*((cosd(x3)).^4) + (2*(Q12 + (2*Q66)))*(((sind(x3)).^2)*((cosd(x3)).^2));
 x3Qbar16=(Q11-Q12-(2*Q66))*((cosd(x3)).^3)*(sind(x3))-((Q22-Q12-(2*Q66))*(cbsd(x3))*(((sind(x3)).^3)));
 x30bar26 = (Q11 - Q12 - (2*Q66))*(cosd(x3))*((sind(x3)).^3) - (Q22 - Q12 - (2*Q66))*((cosd(x3)).^3)*(sind(x3));
 x3Qbar66 = ((Q11 + Q22 - (2*Q12) - (2*Q66))*((cosd(x3)).^2)*((sind(x3)).^2)) + ((Q66)*(((cosd(x3)).^4) + ((sind(x3)).^4)));
 x3Qbar= [x3Qbar11 x3Qbar12 x3Qbar16; x3Qbar12 x3Qbar22 x3Qbar26; x3Qbar16 x3Qbar26 x3Qbar66];
```

```
%%%Part3: Calculating A,B,D
 %Need to input z manually for spacing changes/ply changes
 A11=x10bar11*(t)+ x20bar11*(t)+x30bar11*(t):
 A12=x1Qbar12*(t)+ x2Qbar12*(t)+x3Qbar12*(t);
  A22=x1Qbar22*(t)+ x2Qbar22*(t)+x3Qbar22*(t);
 A16=x1Qbar16*(t)+ x2Qbar16*(t)+x3Qbar16*(t);
A26=x1Qbar26*(t)+ x2Qbar26*(t)+x3Qbar26*(t);
 A66=x1Qbar66*(t)+ x2Qbar66*(t)+x3Qbar66*(t);
 B11= 0.5*((x1Qbar11*(-1/32))+(x2Qbar11*(0))+(x3Qbar11*(1/32)));
 B12= 0.5*((x1Qbar12*(-1/32))+(x2Qbar12*(0))+(x3Qbar12*(1/32)));
B22= 0.5*((x1Qbar22*(-1/32))+(x2Qbar22*(0))+(x3Qbar22*(1/32)));
B16= 0.5*((x1Qbar16*(-1/32))+(x2Qbar16*(0))+(x3Qbar16*(1/32)));
B26= 0.5*((x1Qbar26*(-1/32))+(x2Qbar26*(0))+(x3Qbar26*(1/32)));
 B66= 0.5*((x1Qbar66*(-1/32))+(x2Qbar66*(0))+(x3Qbar66*(1/32)));
 D11=(1/3)*((x1Qbar11*(13/2048))+(x2Qbar11*(1/2048))+(x3Qbar11*(13/2048)));
D12=(1/3)*((x1Qbar12*(13/2048))+(x2Qbar12*(1/2048))+(x3Qbar12*(13/2048)));
D22=(1/3)*((x1Qbar22*(13/2048))+(x2Qbar22*(1/2048))+(x3Qbar22*(13/2048)));
 D16=(1/3)*((x1Qbar16*(13/2048))+(x2Qbar16*(1/2048))+(x3Qbar16*(13/2048)));
 D26=(1/3)*((x1Qbar26*(13/2048))+(x2Qbar26*(1/2048))+(x3Qbar26*(13/2048)));
\label{eq:decomposition} D66 = (1/3)*((x1Qbar66*(13/2048)) + (x2Qbar66*(1/2048)) + (x3Qbar66*(13/2048)));
 %%%Part4 Laminate Stiffness Matrix
A= [A11 A12 A16; A12 A22 A26; A16 A26 A66];
B= [B11 B12 B16; B12 B22 B26; B16 B26 B66];
 D= [D11 D12 D16; D12 D22 D26; D16 D26 D66];
Oij=[A11 A12 A16 B11 B12 B16: A12 A22 A26 B12 B22 B26:A16 A26 A66 B16 B26 B66: B11 B12 B16 D11 D12 D16: B12 B22 B26 D12 D22 D26: B16 B26 B66 D16 D26 D66]:
 %Part5 Solve Laminate Stiffness Matrix for Midplane Strains
 F=[6;-2; 0;2; 2;0];
 Eo=linsolve(Qij,F);
  %Part6 Calculate Strains at Lamina Mid-Planes in Global Coordinates
  y1=-0.125;
 E1= [Eo(1,1)+(y1*(Eo(4,1)));Eo(2,1)+(y1*(Eo(5,1)));Eo(3,1)+(y1*(Eo(6,1)))]
 E3= [Eo(1,1)+(y2*(Eo(4,1)));Eo(2,1)+(y2*(Eo(5,1))); Eo(3,1)+(y2*(Eu(5,1)));
E3= [Eo(1,1)+(y3*(Eo(4,1)));Eo(2,1)+(y3*(Eo(5,1))); Eo(3,1)+(y3*(Eo(6,1)))];
  %Part7 Calculate Stress
  Ss1=x10bar*E1
 Ss2=x2Qbar*E2
Ss3=x3Qbar*E3
  %Part8 Calculate Lamina Stresses in Material Coordinates
 TRI= [(cosd(x1))*2 (sind(x1))*2 (cosd(x1))*(sind(x1)); (sind(x1))*2 (cosd(x1))*(sind(x1))*2 (cosd(x1))*(sind(x1))*2 (cosd(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind(x1))*(sind
 S1=Tk1*Ss1
 S2=Tk2*Ss2
S3= Tk3*Ss3
   %Part9 Tsai Hill
  sigmaLplus=900;
 sigmaLminus=750;
sigmaTplus=50;
sigmaTminus=180;
TLT= 80;
 plyITsaihill=((S1(1,1).^2)/(sigmaLminus .^2))-(((S1(1,1))*(S1(2,1)))/(sigmaLminus .^2))+(((S1(2,1)).^2)/(sigmaTminus .^2))+(((S1(3,1)).^2)/(TLT.^2)) ply2Tsaihill=((S2(1,1).^2)/(sigmaLminus .^2))-(((S2(1,1))*(S2(2,1)))/(sigmaLminus .^2))+(((S2(2,1)).^2)/(sigmaTplus .^2))+(((S2(3,1)).^2)/(TLT.^2)) ply3Tsaihill=((S3(1,1).^2)/(sigmaLplus .^2))-(((S3(1,1))*(S3(2,1)))/(sigmaLplus .^2))+(((S3(2,1)).^2)/(sigmaTplus .^2))+(((S3(3,1)).^2)/(TLT.^2))
 F11 1/((sigmaLplus)*(sigmaLminus))
  F22 1/((sigmaTplus)*(sigmaTminus))
 F1= (1/(sigmaLplus))-(1/(sigmaLminus))
 F2 (1/(sigmaTplus))-(1/(sigmaTminus))
 F66= 1/(TLT.^2)
 F12= (-1/2)*(sqrt(F11*F22))
 ply1TsaiWu_{\overline{z}} \ (F11*(S1(1,1).^2)) + (F22*(S1(2,1).^2)) + (F66*(S1(3,1).^2)) + (F1*S1(1,1)) + (F2*S1(2,1)) + 2*(F12*S1(1,1)*S1(2,1)) + (F12*S1(1,1)) + (
 ply2TsaiWu= (F11*(S2(1,1).^2))+(F22*(S2(2,1).^2))+(F66*(S2(3,1).^2))+(F1*S2(1,1))+(F2*S2(2,1))+2*(F12*S2(1,1)*S2(2,1))
 p1y3TsaiWu_{\overline{z}} (F11*(S3(1,1).^2)) + (F22*(S3(2,1).^2)) + (F66*(S3(3,1).^2)) + (F1*S3(1,1)) + (F2*S3(2,1)) + 2*(F12*S3(1,1)*S3(2,1)) + (F12*S3(1,1).^2)) + (F12*S3(1,1).^2) + (F12*S
```