

# Blur Test

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## Chapter 1

# Blur-Test

Testing out some blurs with opecv, OpenMP and CUDA



## Chapter 2

# File Index

### 2.1 File List

Here is a list of all documented files with brief descriptions:

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## Chapter 3

# File Documentation

### 3.1 blur.cu File Reference

convolution blurring in Nvidia CUDA

```
#include <cuda_runtime.h>
#include <iostream>
#include <opencv2/core/core.hpp>
#include <opencv2/core/cuda.hpp>
#include <opencv2/core/cuda/common.hpp>
#include <opencv2/core/matx.hpp>
#include <opencv2/cudaimgproc.hpp>
#include <opencv2/highgui.hpp>
#include <opencv2/opencv.hpp>
#include <stdio.h>
```

#### Macros

- `#define SAFE\_CALL(call, msg) _safe_cuda_call((call), (msg), __FILE__, __LINE__)`  
*a macro for safe calling CUDA functions*

#### Functions

- `__host__ void generate\_gaussian\_kernel\_2d(float *kernel, const int n, const float sigma=1)`  
*generate the gaussian kernel with given kernel size and standard deviation*
- `__host__ void generate\_gaussian\_kernel\_1d(float *kernel, const int n, const float sigma=1)`  
*generate a 1D gaussian kernel*
- `__device__ __forceinline__ void set\_value(const int &val, uchar &out)`  
*Sets the value of a uchar type.*
- `__device__ __forceinline__ void set\_value(const float &val, float &out)`  
*set the value for a floating point type.*
- `__device__ __forceinline__ void set\_value(const float &val, float3 &out)`  
*set the value for a float3 tupe. All the 3 fields will have the value val*
- `__device__ __forceinline__ void set\_value(const float3 &val, uchar3 &out)`  
*set the value for a unsigned char3 type with a flot3 type*

- `__device__ __forceinline__ void set\_value (const int &val, uchar3 &out)`  
*Sets the value of a uchar3 type.*
- `__device__ __forceinline__ uchar3 subtract\_value (uchar3 in1, uchar3 in2)`  
*Subtraction for uchar3 types.*
- `__device__ __forceinline__ float3 add\_value (float3 in1, float3 in2)`  
*add two values and return it*
- `__device__ __forceinline__ float add\_value (float in1, float in2)`  
*add two floating point values*
- `__device__ __forceinline__ uchar subtract\_value (uchar in1, uchar in2)`  
*Subtraction for uchar types.*
- `__device__ __forceinline__ float3 multiply\_value (const float &x, const uchar3 &y)`  
*multiplication for float and uchar3 types. Multiply each filed in uchar3 with the float value and return a float3*
- `__device__ __forceinline__ float3 multiply\_value (const float &x, const float3 &y)`  
*multiplication for float and float3 types. Multiply each filed in uchar3 with the float value and return a float3*
- `__device__ __forceinline__ float multiply\_value (const float &x, const uchar &y)`  
*multiplication for float and uchar4 types*
- `template<typename T_in , typename T_out , typename F_cal >`  
`__global__ void gaussian\_blur (const float *kernel, int n, const cv::cuda::PtrStepSz< T_in > input, cv::cuda::PtrStepSz< T_out > output)`  
*applies the gaussian blur convolution to the input image*
- `template<typename T_in , typename T_out , typename F_cal >`  
`__global__ void gaussian\_blur\_x (float *kernel, int kernel_size, const cv::cuda::PtrStepSz< T_in > input, cv::cuda::PtrStepSz< T_out > output)`
- `template<typename T_in , typename T_out , typename F_cal >`  
`__global__ void gaussian\_blur\_y (float *kernel, int kernel_size, const cv::cuda::PtrStepSz< T_in > input, cv::cuda::PtrStepSz< T_out > output)`
- `template<class... Ts>`  
`void gaussian\_blur\_exit (Ts &&...inputs)`  
*free all the GPU resources*
- `void call\_gaussian\_blur\_2d (float *d_kernel, const int &n, const cv::cuda::GpuMat &input, cv::cuda::GpuMat &output)`  
*calls the gaussian\_blur function appropriately based on the type of image*
- `void call\_gaussian\_blur\_1d (float *d_kernel, const int &n, const cv::cuda::GpuMat &input, cv::cuda::GpuMat &output)`  
*calls the separable gaussian\_blur function appropriately based on the type of image*
- `__host__ void gaussian\_blur (const cv::Mat &input, cv::Mat &output, const int n=3, const float sigma=1.0, bool two_d=true)`  
*the gaussian blur function which runs on the HOST CPU. It calls the `call_gaussian_blur` function after initialization of the appropriate values and kernel.*
- `void gaussian\_blur\_init (const cv::Mat &input, cv::Mat &output)`  
*initialization for gaussian blurring operation*
- `int main (int argc, char **argv)`

## Variables

- `cv::cuda::GpuMat ginput`
- `cv::cuda::GpuMat goutput`

### 3.1.1 Detailed Description

convolution blurring in Nvidia CUDA

Author

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## 3.1.2 Macro Definition Documentation

### 3.1.2.1 SAFE\_CALL

```
#define SAFE_CALL(  
    call,  
    msg ) _safe_cuda_call((call), (msg), __FILE__, __LINE__)
```

a macro for sage calling CUDA functions

#### Parameters

<i>call</i>	the CUDA function call
<i>msg</i>	user specified message

## 3.1.3 Function Documentation

### 3.1.3.1 add\_value() [1/2]

```
__device__ __forceinline__ float add_value (  
    float in1,  
    float in2 )
```

add two floating point values

#### Parameters

<i>in1</i>	value 1
<i>in2</i>	value 2

#### Returns

the sum

### 3.1.3.2 add\_value() [2/2]

```
__device__ __forceinline__ float3 add_value (  
    float3 in1,  
    float3 in2 )
```

add two values and return it

**Parameters**

<i>in1</i>	input 1
<i>in2</i>	input 2

**Returns**

returns the added value

**3.1.3.3 call\_gaussian\_blur\_1d()**

```
void call_gaussian_blur_1d (
    float * d_kernel,
    const int & n,
    const cv::cuda::GpuMat & input,
    cv::cuda::GpuMat & output )
```

calls the separable gaussian\_blur function appropriately based on the type of image

**Parameters**

<i>d_kernel</i>	the kernel, stored on GPU device memory
<i>n</i>	the size of the kernel
<i>input</i>	the input image stored on the GPU
<i>output</i>	the output image stored on the GPU

**3.1.3.4 call\_gaussian\_blur\_2d()**

```
void call_gaussian_blur_2d (
    float * d_kernel,
    const int & n,
    const cv::cuda::GpuMat & input,
    cv::cuda::GpuMat & output )
```

calls the gaussian\_blur function appropriately based on the type of image

**Parameters**

<i>d_kernel</i>	the kernel, stored on GPU device memory
<i>n</i>	the size of the kernel
<i>input</i>	the input image stored on the GPU
<i>output</i>	the output image stored on the GPU

## 3.1.3.5 gaussian\_blur() [1/2]

```
__host__ void gaussian_blur (
    const cv::Mat & input,
    cv::Mat & output,
    const int n = 3,
    const float sigma = 1.0,
    bool two_d = true )
```

the gaussian blur function which runs on the HOST CPU. It calls the `call_gaussian_blur` function after initialization of the appropriate values and kernel.

## Parameters

<i>input</i>	the input image stored on the CPU memory
<i>output</i>	the output image stored on the CPU memory
<i>n</i>	the size of the Gaussian kernel, defaults to 3
<i>sigma</i>	the standard deviation of the Gaussian kernel, defaults to 1.
<i>two↔ _d</i>	whether to use the 2D gaussian blur kernel or two separable 1D gaussian blur kernels, defaults to true

## 3.1.3.6 gaussian\_blur() [2/2]

```
template<typename T_in , typename T_out , typename F_cal >
__global__ void gaussian_blur (
    const float * kernel,
    int n,
    const cv::cuda::PtrStepSz< T_in > input,
    cv::cuda::PtrStepSz< T_out > output )
```

applies the gaussian blur convolution to the input image

## Template Parameters

<i>t_in</i>	the type of input image, i.e uchar for black and white, uchar3 for rgb, float3 etc
<i>t_out</i>	the type of output image
<i>f_cal</i>	the type for calculating intermediate sums and products

## Parameters

<i>kernel</i>	the kernel to apply the convolution
<i>n</i>	the dimension of the kernel (n x n)
<i>input</i>	the input image
<i>output</i>	the output image

### 3.1.3.7 gaussian\_blur\_exit()

```
template<class... Ts>
void gaussian_blur_exit (
    Ts &&... inputs )
```

free all the GPU resources

#### Template Parameters

<i>Ts</i>	
-----------	--

#### Parameters

<i>inputs</i>	varidaic list of resources
---------------	----------------------------

### 3.1.3.8 gaussian\_blur\_init()

```
void gaussian_blur_init (
    const cv::Mat & input,
    cv::Mat & output )
```

initialization for gaussian blurring operation

#### Parameters

<i>input</i>	input image stored on the CPU
<i>output</i>	output image stored on the CPU

### 3.1.3.9 generate\_gaussian\_kernel\_1d()

```
__host__ void generate_gaussian_kernel_1d (
    float * kernel,
    const int n,
    const float sigma = 1 )
```

generate a 1D gaussian kernel

#### Parameters

<i>kernel</i>	the array in which the weights are stored
<i>n</i>	the size of the kernel. a 1D kernel of length n is needed
<i>sigma</i>	the standard deviation of the kernel

## Returns

**3.1.3.10 generate\_gaussian\_kernel\_2d()**

```
__host__ void generate_gaussian_kernel_2d (
    float * kernel,
    const int n,
    const float sigma = 1 )
```

generate the gaussian kernel with given kernel size and standard deviation

## Parameters

<i>kernel</i>	the array in which the weights are stored
<i>n</i>	the size of the kernel, t.e. n x n kernel is needed
<i>sigma</i>	the standard deviation

**3.1.3.11 multiply\_value() [1/3]**

```
__device__ __forceinline__ float3 multiply_value (
    const float & x,
    const float3 & y )
```

multiplication for float and float3 types. Multiply each filed in uchar3 with the float value and return a float3

## Parameters

<i>x</i>	Input 1
<i>y</i>	Input 2

## Returns

value after multiplication

**3.1.3.12 multiply\_value() [2/3]**

```
__device__ __forceinline__ float multiply_value (
    const float & x,
    const uchar & y )
```

multiplication for float and uchar4 types

**Parameters**

<i>x</i>	Input 1
<i>y</i>	Input 2

**Returns**

$x*y$

**3.1.3.13 multiply\_value() [3/3]**

```
__device__ __forceinline__ float3 multiply_value (
    const float & x,
    const uchar3 & y )
```

multiplication for float and uchar3 types. Multiply each filed in uchar3 with the float value and return a float3

**Parameters**

<i>x</i>	Input 1
<i>y</i>	Input 2

**Returns**

value after multiplication

**3.1.3.14 set\_value() [1/5]**

```
__device__ __forceinline__ void set_value (
    const float & val,
    float & out )
```

set the value for a floating point type.

**Parameters**

<i>val</i>	the value
<i>out</i>	the output

**3.1.3.15 set\_value() [2/5]**

```
__device__ __forceinline__ void set_value (
```



```
const float & val,  
float3 & out )
```

set the value for a float3 tupe. All the 3 fields will have the value `val`

#### Parameters

<i>val</i>	the value
<i>out</i>	the output

#### 3.1.3.16 `set_value()` [3/5]

```
__device__ __forceinline__ void set_value (  
    const float3 & val,  
    uchar3 & out )
```

set the value for a unsigned char3 type with a flot3 type

#### Parameters

<i>val</i>	the value to set
<i>out</i>	the ouput

#### 3.1.3.17 `set_value()` [4/5]

```
__device__ __forceinline__ void set_value (  
    const int & val,  
    uchar & out )
```

Sets the value of a uchar type.

#### Parameters

<i>val</i>	The value
<i>out</i>	The output

#### 3.1.3.18 `set_value()` [5/5]

```
__device__ __forceinline__ void set_value (  
    const int & val,  
    uchar3 & out )
```

Sets the value of a uchar3 type.

**Parameters**

<i>in</i>	<i>val</i>	The value
	<i>out</i>	The output

**3.1.3.19 subtract\_value() [1/2]**

```
__device__ __forceinline__ uchar subtract_value (
    uchar in1,
    uchar in2 )
```

Subtraction for uchar types.

**Parameters**

<i>in</i>	<i>in1</i>	Input 1
<i>in</i>	<i>in2</i>	Input 2

**Returns**

Output

**3.1.3.20 subtract\_value() [2/2]**

```
__device__ __forceinline__ uchar3 subtract_value (
    uchar3 in1,
    uchar3 in2 )
```

Subtraction for uchar3 types.

**Parameters**

<i>in</i>	<i>in1</i>	Input 1
<i>in</i>	<i>in2</i>	Input 2

**Returns**

Output

**3.2 main.cpp File Reference**

gaussian blurring using CPU

```
#include <cmath>
#include <iostream>
#include <opencv2/core.hpp>
#include <opencv2/highgui.hpp>
#include <opencv2/imgcodecs.hpp>
#include <opencv2/opencv.hpp>
#include <vector>
```

## Functions

- void [generate\\_gaussian\\_kernel](#) (std::vector< std::vector< float > > &kernel, const int n, const float sigma=1)  
*Generate a 2D gaussian kernel.*
- void [apply\\_convolution](#) (const std::vector< std::vector< float > > &kernel, const Mat &original\_img, Mat &new\_img, const int &r, const int &c)  
*apply a convolution kernel to a pixel*
- void [apply\\_convolution\\_multi\\_threaded](#) (const std::vector< std::vector< float > > &kernel, const Mat &original\_img, Mat &new\_img, const int &r, const int &c)  
*apply a convolution kernel to a pixel using multiple threads (OMP)*
- void [apply\\_kernel](#) (const std::vector< std::vector< float > > &kernel, const Mat &original\_img, Mat &new\_img)  
*apply a convolution kernel to the entire image*
- void [apply\\_kernel\\_multithreaded](#) (const std::vector< std::vector< float > > &kernel, const Mat &original\_img, Mat &new\_img)  
*apply a convolution kernel to the entire image using multiple threads (OMP)*
- int **main** (int argc, char \*\*argv)

### 3.2.1 Detailed Description

gaussian blurring using CPU

Author

Arjun31415

### 3.2.2 Function Documentation

#### 3.2.2.1 [apply\\_convolution\(\)](#)

```
void apply_convolution (
    const std::vector< std::vector< float > > & kernel,
    const Mat & original_img,
    Mat & new_img,
    const int & r,
    const int & c )
```

apply a convolution kernel to a pixel

**Parameters**

<i>kernel</i>	the convolution kernel
<i>original_img</i>	the original image
<i>new_img</i>	the output image
<i>r</i>	the row number of the current pixel
<i>c</i>	the column number of the current pixel

**3.2.2.2 apply\_convolution\_multi\_threaded()**

```
void apply_convolution_multi_threaded (
    const std::vector< std::vector< float > > & kernel,
    const Mat & original_img,
    Mat & new_img,
    const int & r,
    const int & c )
```

apply a convolution kernel to a pixel using multiple threads (OMP)

**Parameters**

<i>kernel</i>	the convolution kernel
<i>original_img</i>	the original image
<i>new_img</i>	the output image
<i>r</i>	the row number of the current pixel
<i>c</i>	the column number of the current pixel

**3.2.2.3 apply\_kernel()**

```
void apply_kernel (
    const std::vector< std::vector< float > > & kernel,
    const Mat & original_img,
    Mat & new_img )
```

apply a convolution kernel to the entire image

**Parameters**

<i>kernel</i>	the convolution kernel
<i>original_img</i>	the original image
<i>new_img</i>	the output image

### 3.2.2.4 apply\_kernel\_multithreaded()

```
void apply_kernel_multithreaded (
    const std::vector< std::vector< float > > & kernel,
    const Mat & original_img,
    Mat & new_img )
```

apply a convolution kernel to the entire image using multiple threads (OMP)

#### Parameters

<i>kernel</i>	the convolution kernel
<i>original_img</i>	the original_img
<i>new_img</i>	the output image

### 3.2.2.5 generate\_gaussian\_kernel()

```
void generate_gaussian_kernel (
    std::vector< std::vector< float > > & kernel,
    const int n,
    const float sigma = 1 )
```

Generate a 2D gaussian kernel.

#### Parameters

<i>kernel</i>	the kernel to be populated
<i>n</i>	the size of the kernel, the <i>kernel</i> must be of size $n * n$
<i>sigma</i>	the standard deviation of the gaussian kernel



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