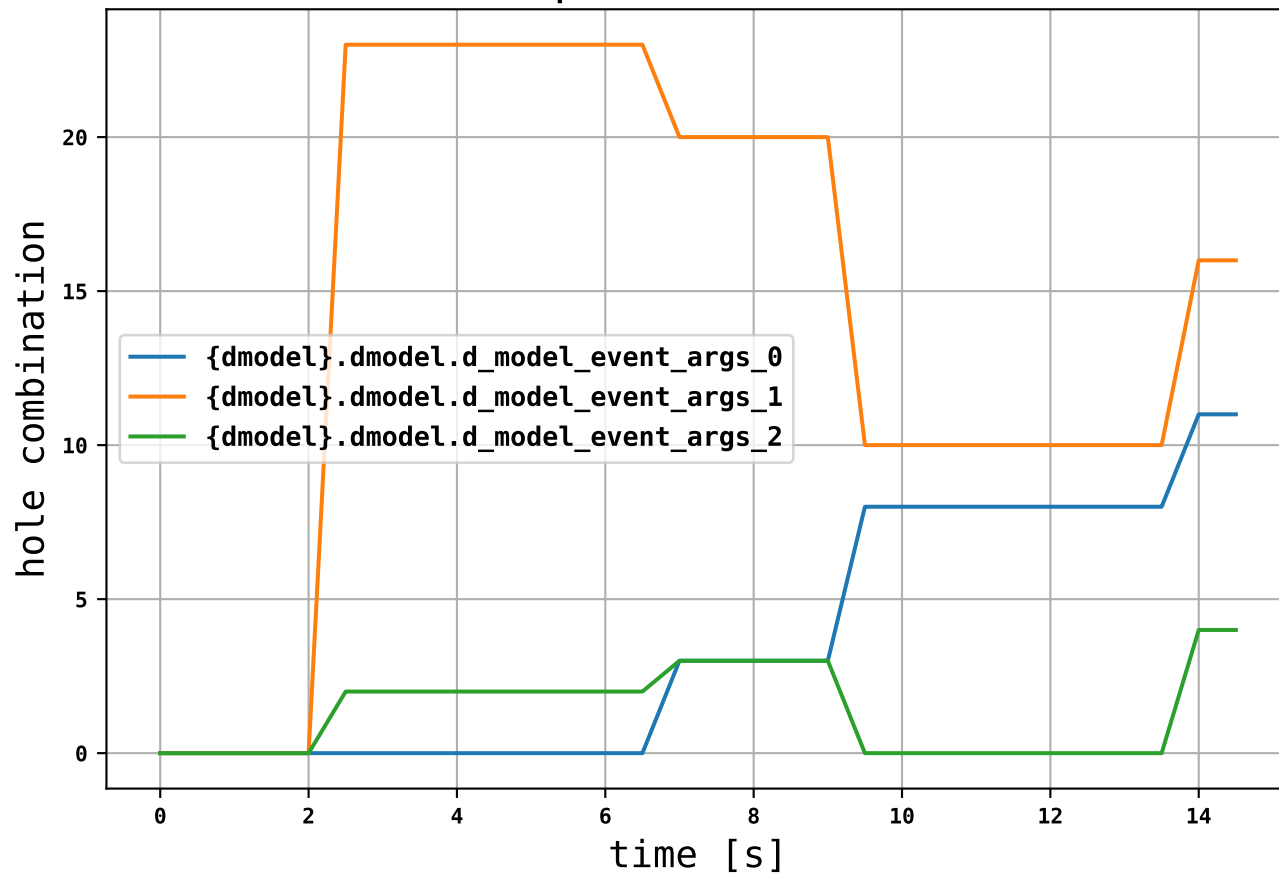
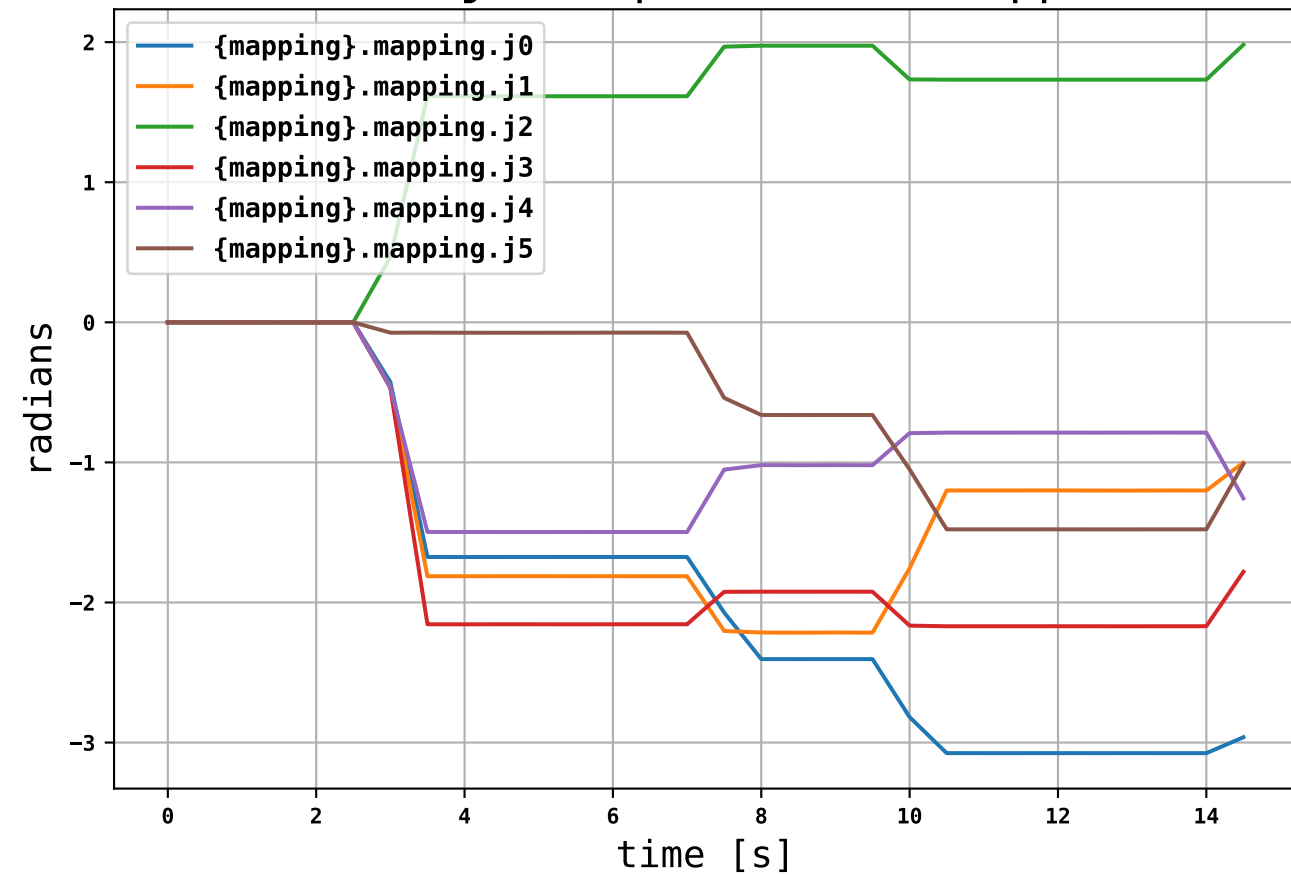


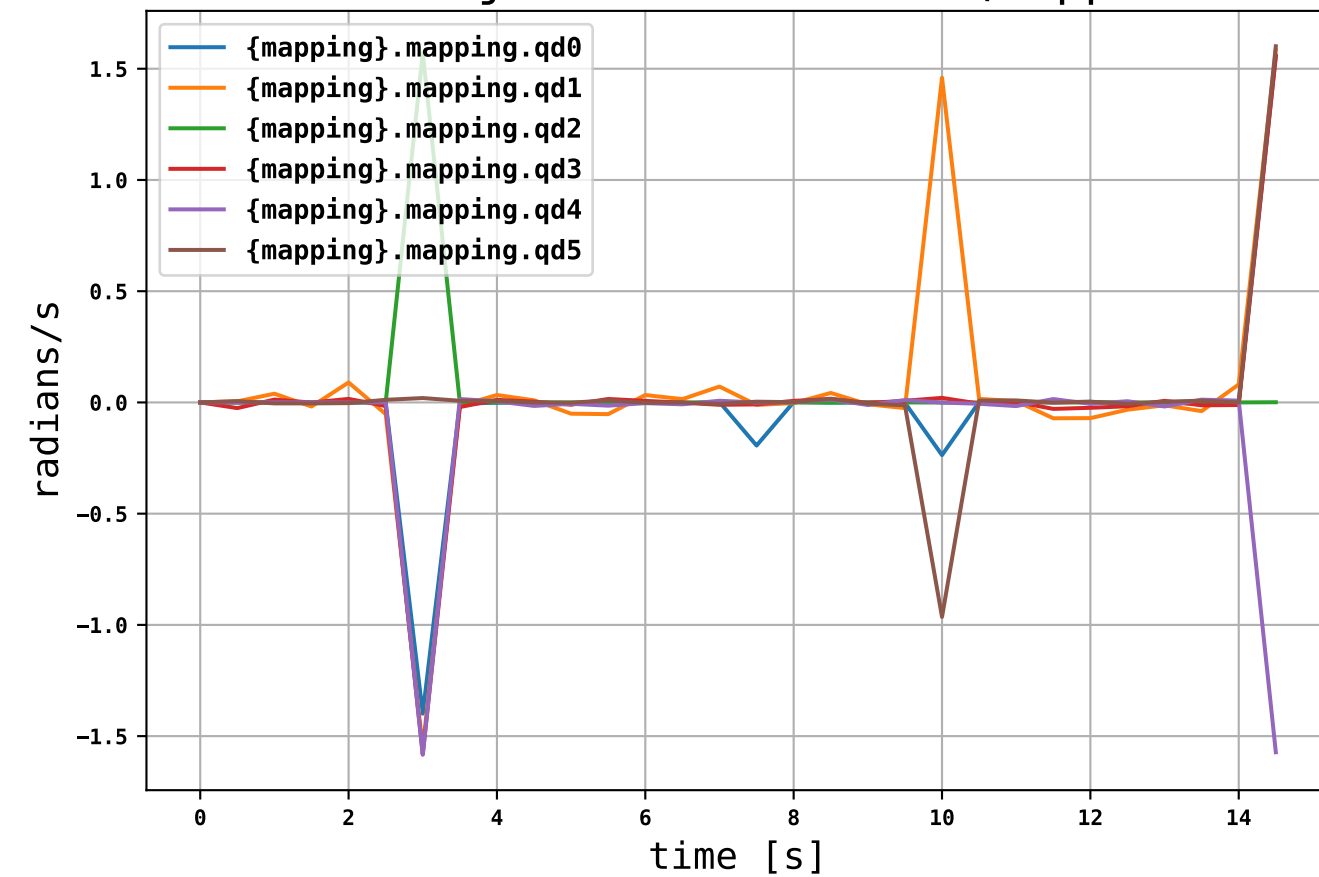
Discrete positions (D-Model)



Co-sim UR5e joint positions (CoppeliaSim)



Co-sim UR5e joint velocities (CoppeliaSim)



Co-sim UR5e joint force (CoppeliaSim)

