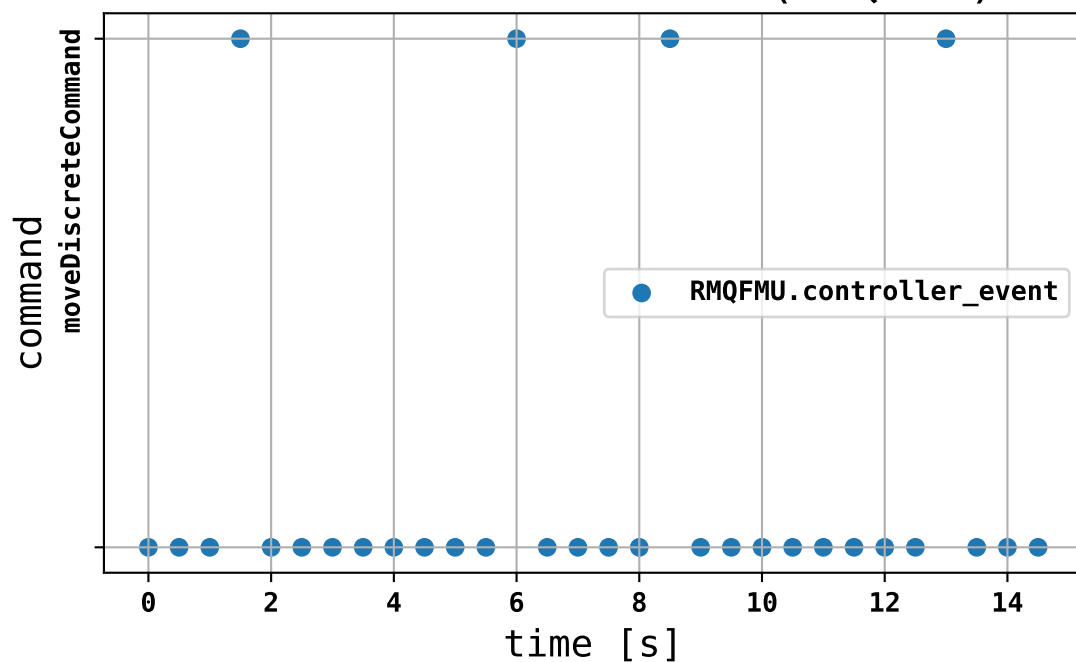
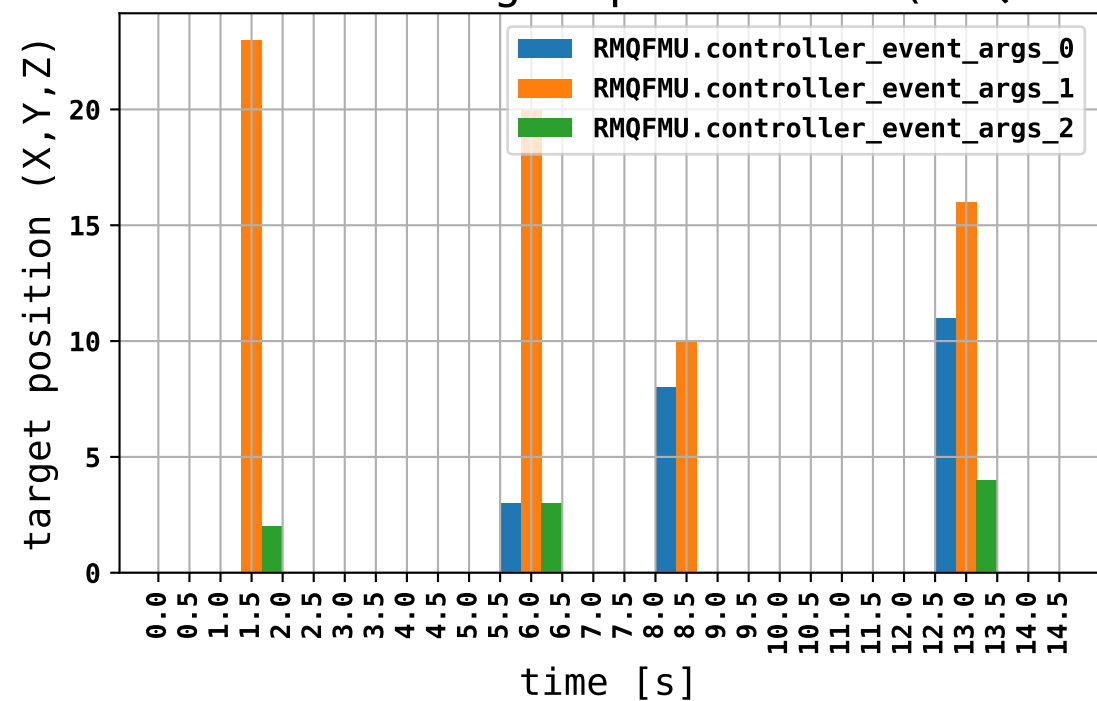


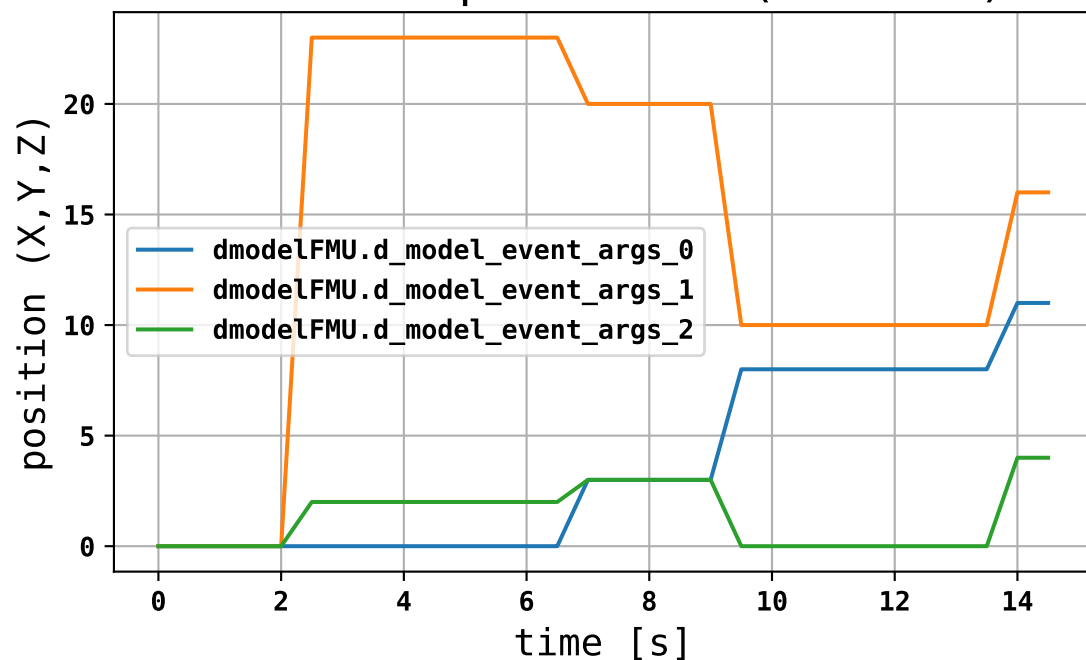
Controller commands (RMQFMU)



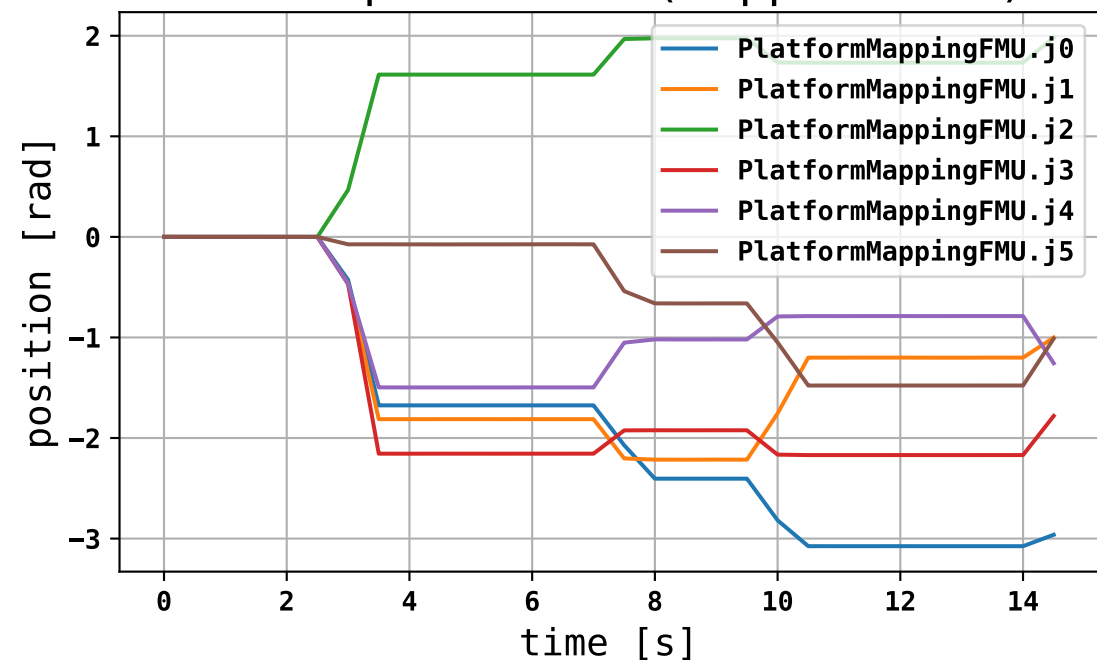
Controller target positions (RMQFMU)



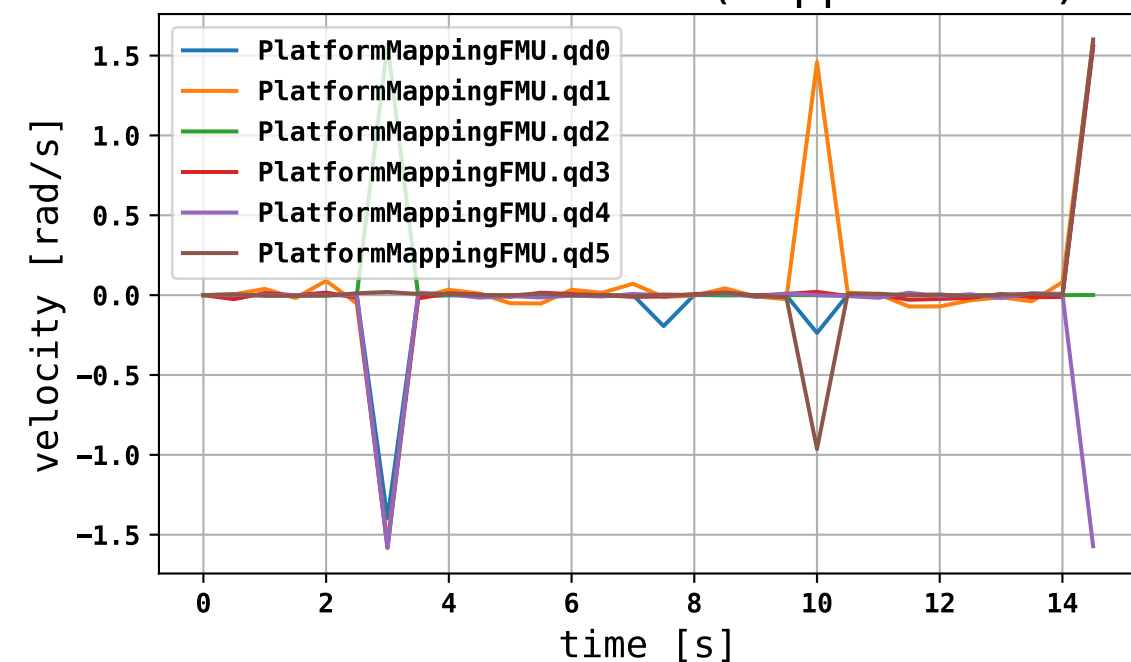
Discrete positions (D-Model)



Joint positions (CoppeliaSim)



Joint velocities (CoppeliaSim)



Joint forces (CoppeliaSim)

