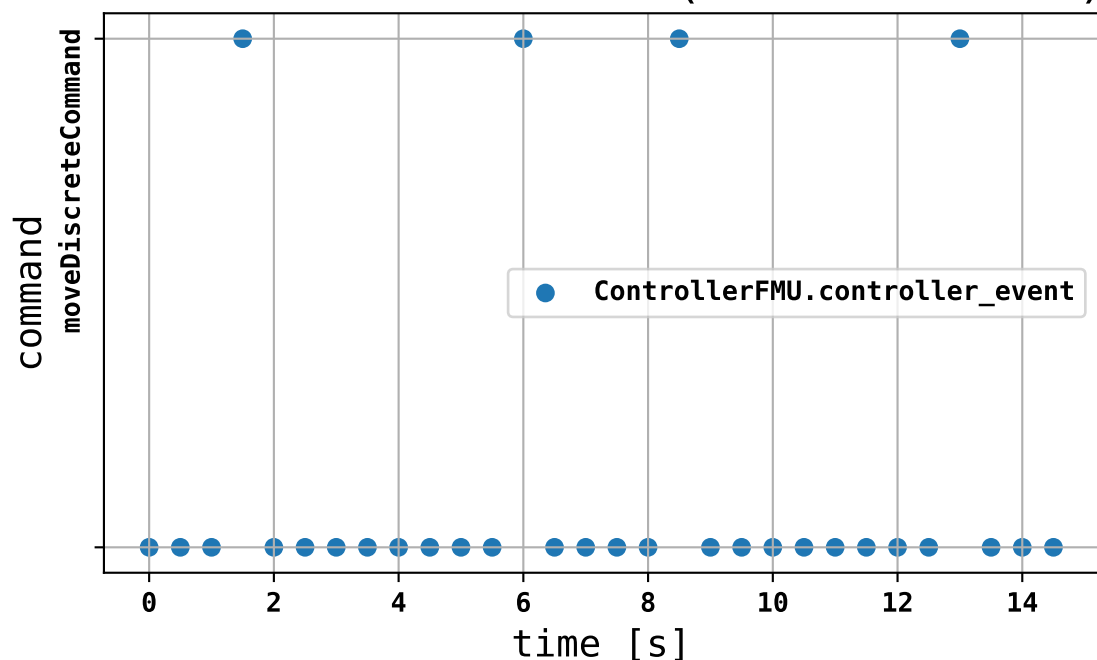
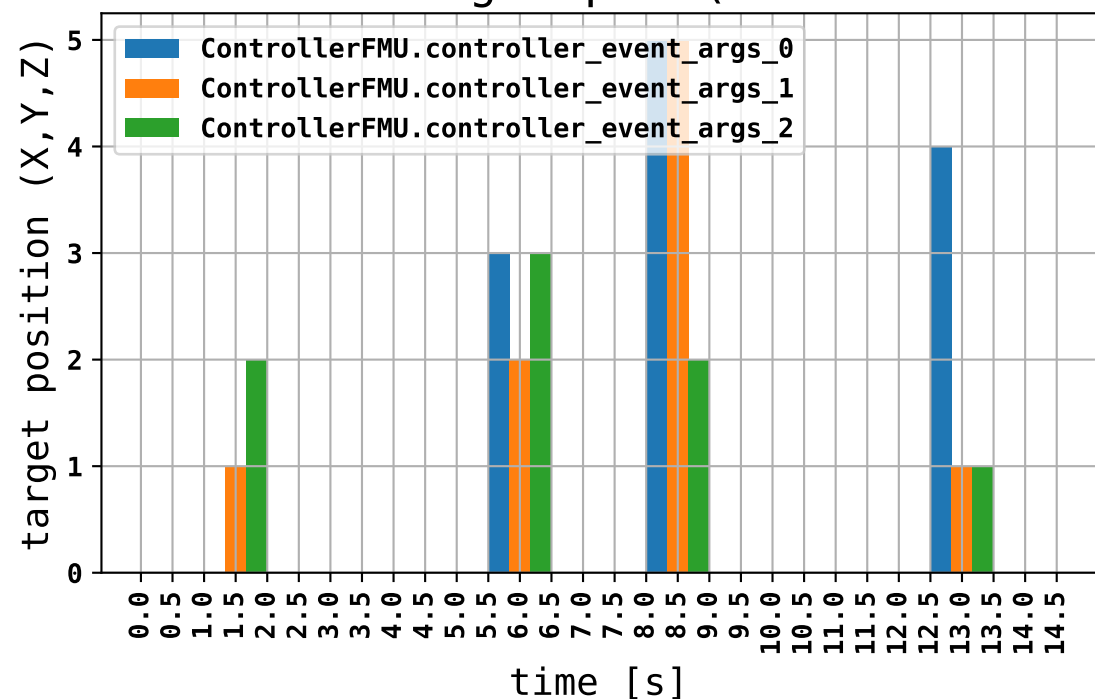


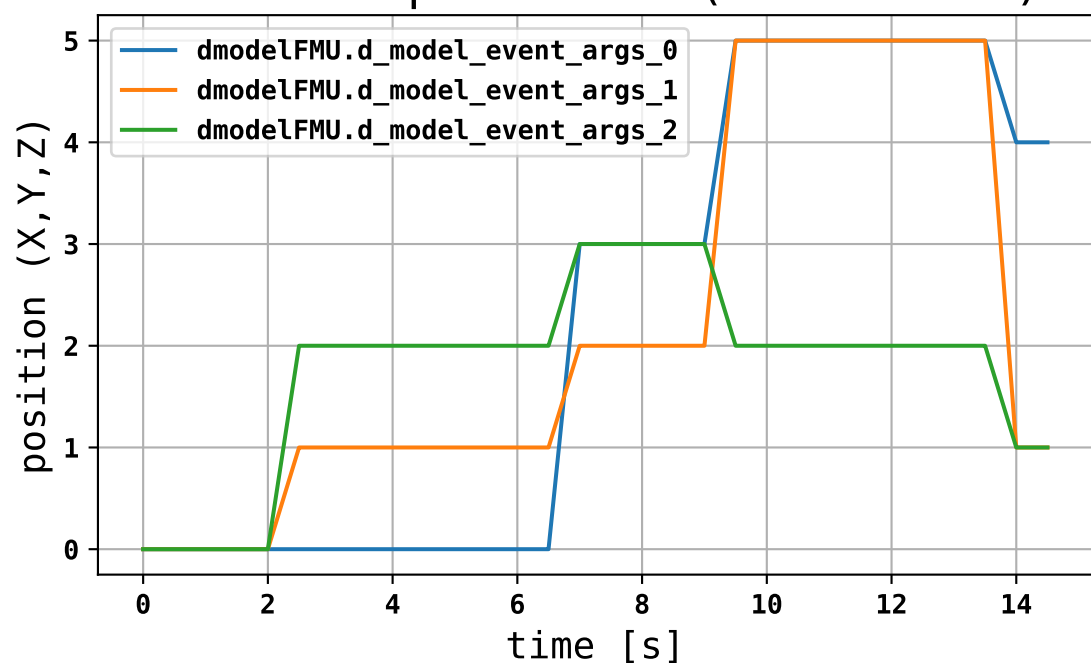
Controller commands (ControllerFMU)



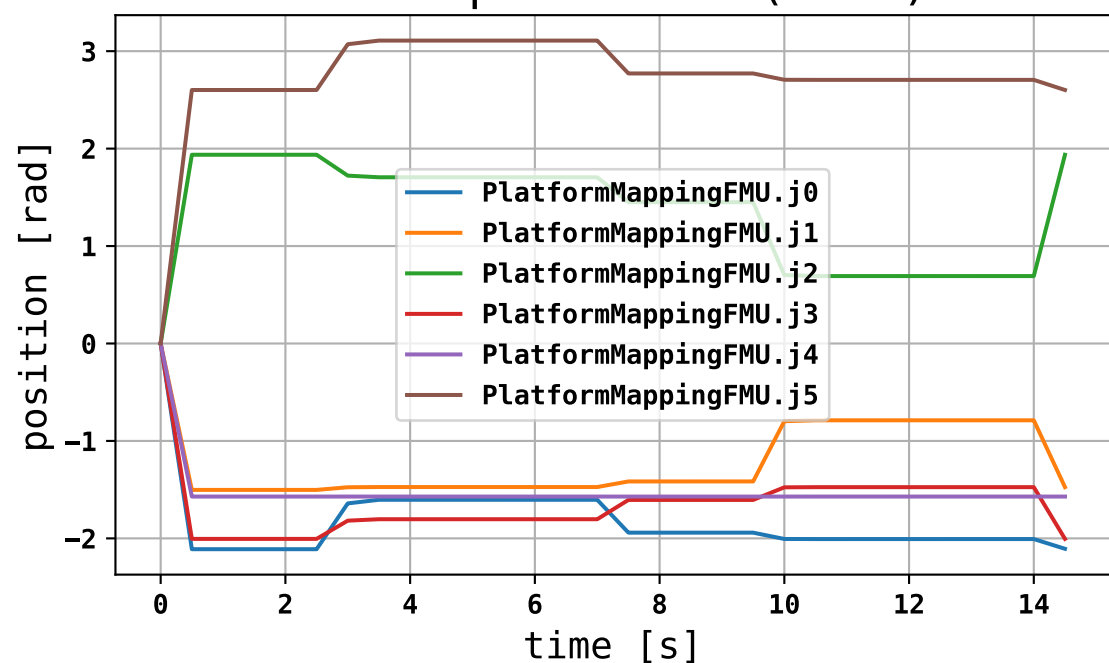
Controller target pos.(ControllerFMU)



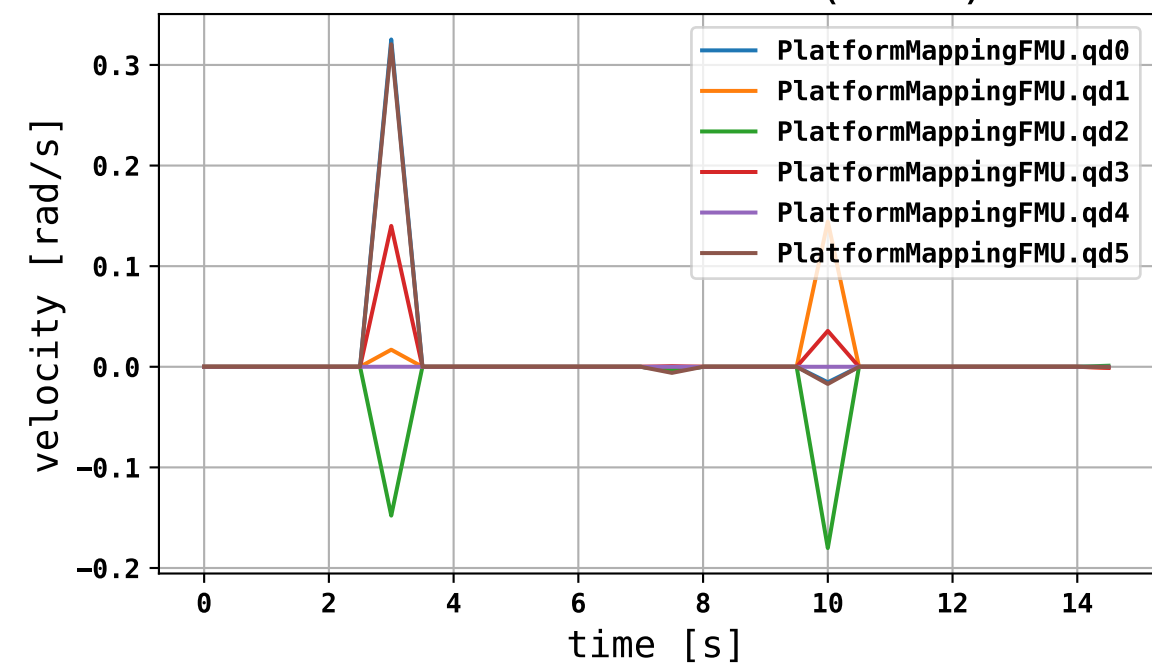
Discrete positions (d-modelFMU)



Joint positions (UR3e)



Joint velocities (UR3e)



Joint forces (UR3e)

