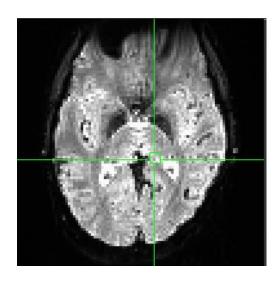
# **Submission for Final Project**

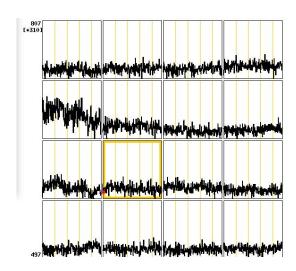
The aim of this project was to recreate the image as seen by the user using fMRI scans and BOLD signals. The submission of the project needed to include

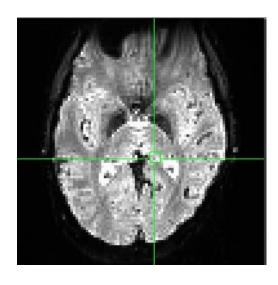
- a) BOLD run and the series obtained
- b) The model used
- c) The images obtained (5 each for each category) and
- d) The source code of the algorithm used.

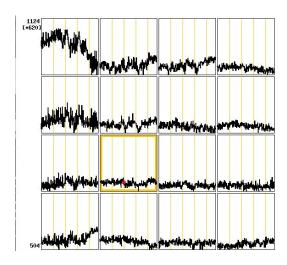
The submission is hereby divided in the aforementioned sections.

## **BOLD** runs



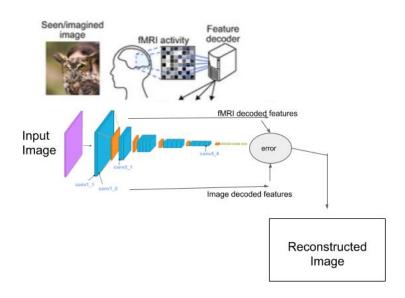






#### Model

We use a CNN model to replicate the visual cortex behavior. VGG 19 was used as our base CNN model upon which we further developed our algorithm. VGG 19 has been shown to have mimicked the activity of the visual cortex and for the same reason we choose this model. BOLD signal features were passed through the CNN to obtain a representation of the image. This was in turn compared with the feature maps obtained from the original stimulus image itself. Based on this, an error was calculated and the optimization was done on these features obtained from the CNN. These features were optimized using the scipy library's optimize function and an output was obtained. All outputs obtained were from the features obtained from the first convolution to the third convolution layer. This was done so because of the limitation of compute and data storage. The results obtained are shown in the subsequent sections.



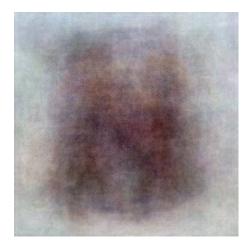
Model Used

# **Generated Images**

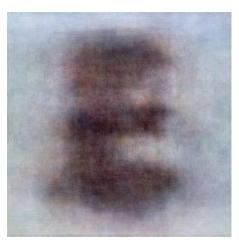
The different responses for the two subjects are shown in the following subsections for each of the three categories that exist i.e. Alphabets, Natural and Artificial responses.

### **Alphabets**

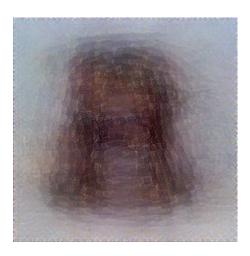
The responses for both the subjects for alphabet stimulus are compared side by side.



**Fig 1.A** Response From first subject



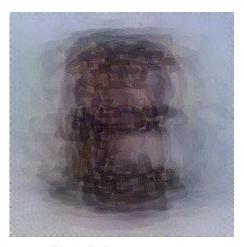
**Fig 2.A** Response From first subject



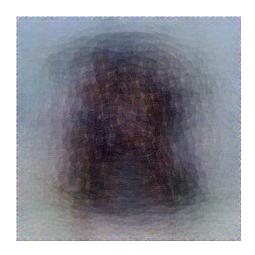
**Fig 3.A** Response From first subject



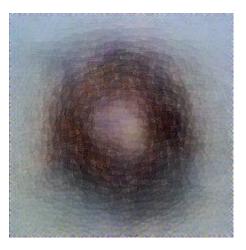
**Fig 1.B** Response from second subject



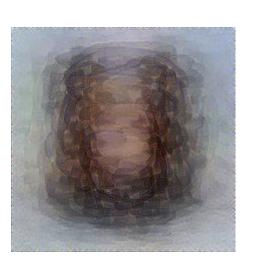
**Fig 2.B** Response from second subject



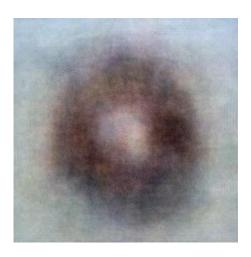
**Fig 3.B** Response from second subject



**Fig 4.A** Response From first subject



**Fig 5.A** Response From first subject



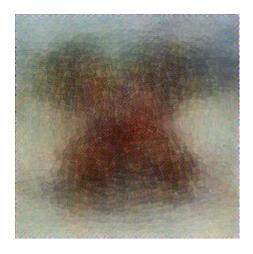
**Fig 4.B** Response from second subject



**Fig 5.B** Response from second subject

### **Artificial**

The responses for both the subjects for artificial stimulus are compared side by side.



**Fig 6.A** Response From first subject

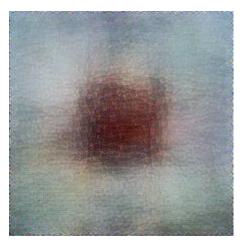


Fig 7.A Response From first subject

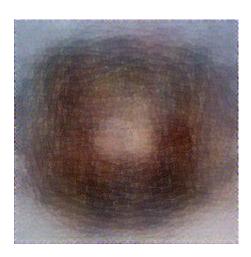
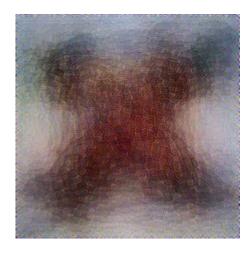
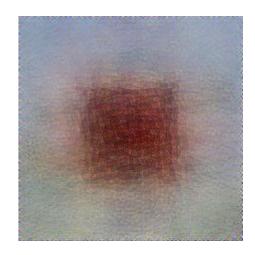


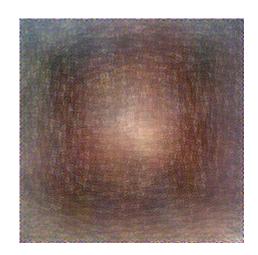
Fig 8.A Response From first subject



**Fig 6.B** Response from second subject



**Fig 7.B** Response from second subject



**Fig 8.B** Response from second subject

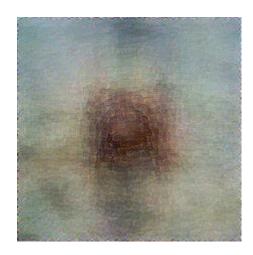
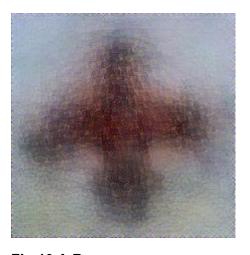


Fig 9.A Response From first subject



Flg 10.A Response From first subject

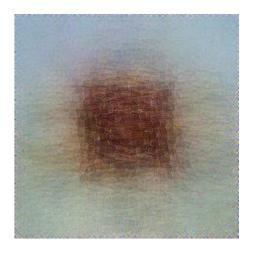


Fig 9.B Response from second subject

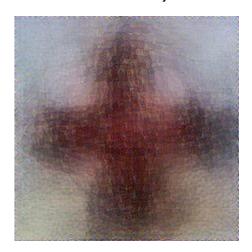
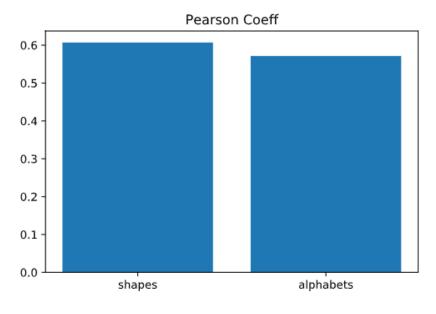


Fig 10.B Response from second subject



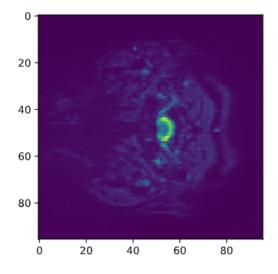
Pearson Coefficients for alphabets and shapes

## **Natural**

The responses for both the subjects for natural stimulus are compared side by side.



Fig 11.A Response From first subject



**Fig 11.B** BOLD info for given response



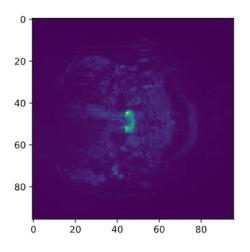
Fig 12.A Response from second subject



Fig 13.A Response From first subject



Fig 14.A Response From first subject



**Fig 12.B** BOLD info for given response



Fig 13.B Response from second subject



**Fig 14.B** Response from second subject



Fig 15.A Response

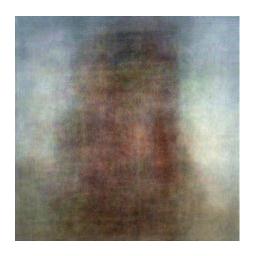
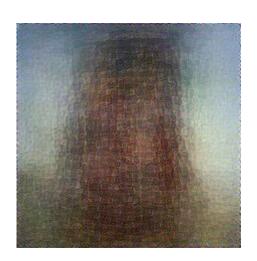


Fig 16.A Response From first subject



Fig 15.B Response



**Fig 16.B** Response from second subject

#### Code

The algorithm used for implementation is explained below.

```
def reconstruct_img(features, net,
             layer_weight=None, channel=None, mask=None, initial_image=None,
maxiter=500, disp=True, save_intermediate_every=1, save_intermediate=False,
loss_type='gram',
save_intermediate_path=None,save_intermediate_ext='jpg',save_intermediate_postpr
ocess=normalise_img):
      # loss function
      loss_fun = switch_loss_fun(loss_type)
      # make dir for saving intermediate
      if save_intermediate:
      if save_intermediate_path is None:
      save_intermediate_path = os.path.join('./recon_img_lbfgs_snapshots' +
datetime.now().strftime('%Y%m%dT%H%M%S'))
      if not os.path.exists(save_intermediate_path):
      os.makedirs(save_intermediate_path)
      # get img size, #of pixel and mean of img
      img_size = net.blobs['data'].data.shape[-3:]
      num_of_pix = np.prod(img_size)
      img_mean = net.transformer.mean['data']
      # initial image
      if initial_image is None:
      initial_image = np.random.randint(0, 256, (img_size[1], img_size[2], img_size[0]))
      if save_intermediate:
      save_name = 'initial_img.png'
PIL.Image.fromarray(np.uint8(initial_image)).save(os.path.join(save_intermediate_pat
h, save_name))
      # preprocess initial img
      initial_image = img_preprocess(initial_image, img_mean)
      initial_image = initial_image.flatten()
      # layer_list
      layer_list = list(features.keys())
```

```
print("layer list : "+ str(layer_list))
      layer_list = sort_layer(net, layer_list)
       print("layer list sorted : "+ str(layer_list))
       # number of layers
      num_of_layer = len(layer_list)
      # layer weight
      if layer_weight is None:
      weights = np.ones(num_of_layer)
      weights = np.float32(weights)
      weights = weights / weights.sum()
      layer_weight = {}
      for i, lyr in enumerate(layer_list):
      layer_weight[lyr] = weights[i]
      # feature mask
      feature_masks = create_feature_masks(features, masks=mask,
channels=channel)
      # optimization
      loss_list = []
      res = minimize(obj_fun, initial_image, args = (net, features, feature_masks,
layer_weight, loss_fun, save_intermediate, save_intermediate_every,
save_intermediate_path, save_intermediate_ext,
                           save_intermediate_postprocess, loss_list),
             method='L-BFGS-B', jac=True, options= {'maxiter': maxiter})
      # recon img
      img = res.x
      img = img.reshape(img_size)
      # return img
      return img_caffe_deproc(img, img_mean), loss_list
def obj_fun(img, net, features, feature_masks, layer_weight, loss_fun,
save_intermediate, save_intermediate_every, save_intermediate_path,
save_intermediate_ext, save_intermediate_postprocess, loss_list=[]):
      # reshape img
      img_size = net.blobs['data'].data.shape[-3:]
      img = img.reshape(img_size)
      # save intermediate image
      t = len(loss_list)
      if save_intermediate and (t % save_intermediate_every == 0):
      img_mean = net.transformer.mean['data']
```

```
save_path = os.path.join(save_intermediate_path, '%05d.%s' % (t,
save_intermediate_ext))
       if save_intermediate_postprocess is None:
       snapshot_img = img_caffe_deproc(img, img_mean)
       snapshot_img = save_intermediate_postprocess(img_caffe_deproc(img,
img_mean))
       PIL.Image.fromarray(snapshot_img).save(save_path)
       # layer_list
       layer_list = features.keys()
       layer_list = sort_layer(net, layer_list)
       # num_of_layer
       num_of_layer = len(layer_list)
       # cnn forward
       net.blobs['data'].data[0] = img.copy()
       net.forward(end=layer_list[-1])
       # cnn backward
       loss = 0.
       layer_start = layer_list[-1]
       net.blobs[layer_start].diff.fill(0.)
       for j in range(num_of_layer):
       layer_start_index = num_of_layer - 1 - j
       layer_end_index = num_of_layer - 1 - j - 1
       layer_start = layer_list[layer_start_index]
       if layer_end_index >= 0:
       layer_end = layer_list[layer_end_index]
       else:
       layer_end = 'data'
       feat_j = net.blobs[layer_start].data[0].copy()
       feat0_j = features[layer_start]
       mask_j = feature_masks[layer_start]
       layer_weight_j = layer_weight[layer_start]
       loss_j, grad_j = loss_fun(feat_j, feat0_j, mask_j)
       loss_j = layer_weight_j * loss_j
       grad_j = layer_weight_j * grad_j
       loss = loss + loss_j
       g = net.blobs[layer_start].diff[0].copy()
       g = g + grad_j
       net.blobs[layer_start].diff[0] = g.copy()
       if layer_end == 'data':
       net.backward(start=layer_start)
       else:
       net.backward(start=layer_start, end=layer_end)
       net.blobs[layer_start].diff.fill(0.)
```

grad = net.blobs['data'].diff[0].copy()

grad = grad.flatten().astype(np.float64)
loss\_list.append(loss)

return loss, grad