

# Group quiz

EE24BTECH11038 - M.B.S Aravind

**Forward Euler method:-** Given an ODE and an initial value  $y(x_0) = y_0$ , Euler's method yield's approximate solution values at equidistant x-values  $x_0, x_1 = x_0 + h, x_2 = x_0 + 2h, \dots$  namely

$$y_1 = y_0 + hf(x_0, y_0) \quad (0.1)$$

$$y_2 = y_1 + hf(x_1, y_1) \quad (0.2)$$

In general

$$y_n = y_{n-1} + hf(x_{n-1}, y_{n-1}) \quad (0.3)$$

where the step  $h$  equals, e.g., 0.1 or 0.2 or a smaller value for greater accuracy

## Analysis of parameter variations

Given differential equation is

$$\frac{di}{dt} = \frac{v(t) - Ri}{L} \quad (0.4)$$

$$i_{n+1} = i_n + h \frac{v(t) - Ri}{L} \quad (0.5)$$

### • Varying R

- Let the values of  $L, T, \alpha$  be 1H, 1 sec, 0.5 respectively.
- The plot of  $i$  vs. time (for different values of  $R$  is given by)

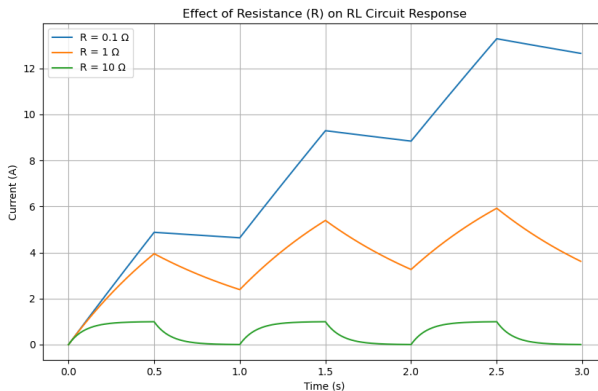


Fig. 0.1: Caption

–  **$R=0.1\Omega$**

- 1) The current reaches a high peak value as a result of minimal resistance restricting the flow.
- 2) The decay phase is slow because the inductor dominates, storing energy and releasing it gradually.

–  **$R=1\Omega$**

- 1) Slower current buildup than in the low resistance case.
- 2) The peak current is lower, as more energy is dissipated in the resistor.

–  **$R=10\Omega$**

- 1) The peak current is significantly lower because the resistor limits current flow.
- 2) The response stabilizes much faster, as energy is quickly dissipated.

**Varying L**

- Let the values of  $R, T, \alpha$  be  $1\Omega, 1 \text{ sec}, 0.5$  respectively.

–  **$L=0.1H$**

- 1) Faster current response.
- 2) Smaller time constant ( $\tau = L/R$ ), leading to a quicker rise and fall.

–  **$L=1H$**

- 1) Balanced response between resistive and inductive behavior.
- 2) Current change is neither too abrupt nor too slow.

–  **$L=10H$**

- 1) Smoother transitions as the inductor resists rapid current changes.
- 2) Larger time constant, leading to slow response and gradual decay.
- 3) The inductor stores more energy, resulting in a lagged response.

- The plot of  $i$  vs. time (for different values of  $L$  is given by)

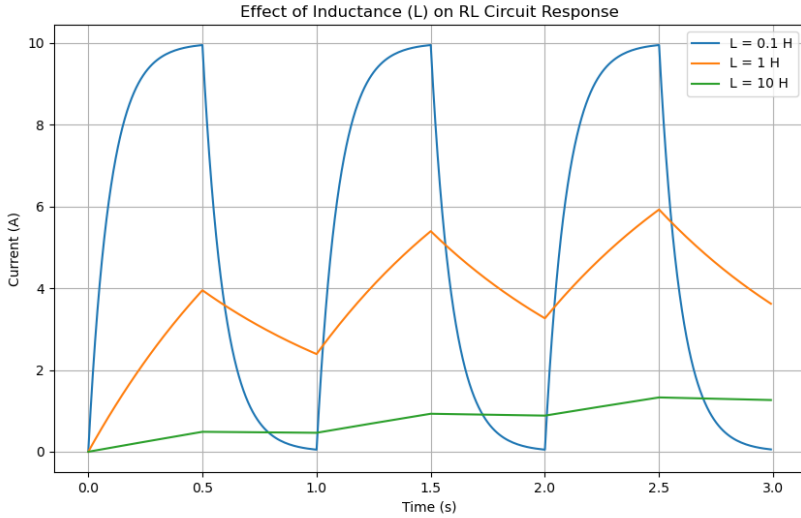


Fig. 3.1: Caption

### Error analysis

The error in the forward Euler method can be analyzed using a Taylor series expansion. Given a general differential equation:

$$\frac{dy}{dt} = f(t, y) \quad (3.1)$$

with an exact solution  $y(t)$ , we expand it around  $t_n$  using the Taylor series:

$$y(t_{n+1}) = y(t_n) + h \frac{dy}{dt} + h^2 \frac{d^2y}{dt^2} + O(h^3) \quad (3.2)$$

Substituting the differential equation  $\frac{dy}{dt} = f(t, y)$  and using the Euler approximation:

$$y_{n+1} = y_n + hf(t_n, y_n) \quad (3.3)$$

The local truncation error is given by the omitted higher-order terms:

$$E_n = \frac{h^2}{2} \frac{d^2y}{dt^2} + O(h^3) \quad (3.4)$$

Plotting the response using the Euler method for different values of  $h$  where  $R, L, T, \alpha$  are  $1\Omega, 1H, 1 \text{ sec}, 0.5$  respectively

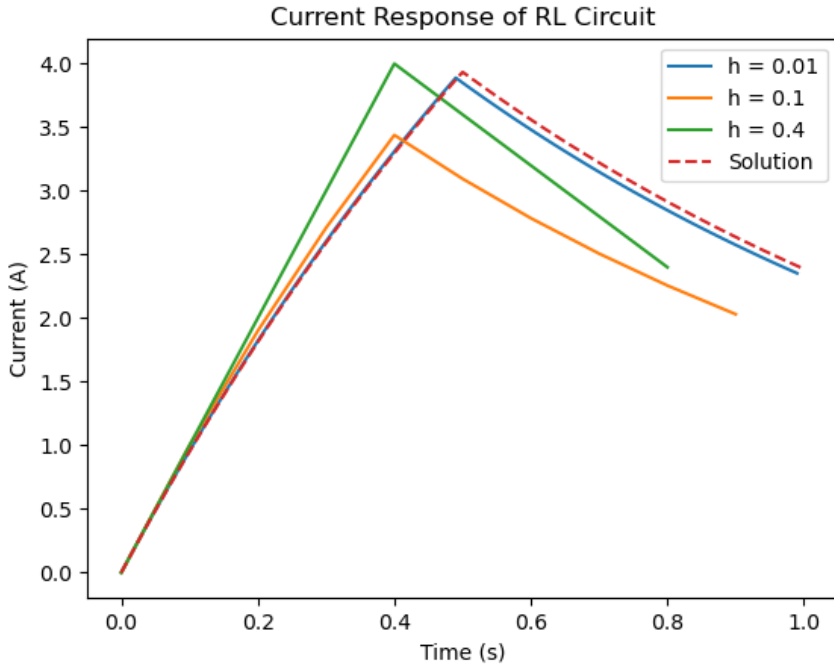


Fig. 3.2: Caption

h value	Deviation in 1st step	Deviation in 2nd step
0.01	0.000498	0.000986
0.1	0.048	0.087
0.4	0.7032	-0.5149

TABLE 3: Caption

There is a noticeable deviation for every value of  $h$ , and as  $h$  increases, the deviation also increases. This indicates that the Euler method is not stable for larger values of  $h$