

GRADIENT, DIVERGENCE and CURL

The vector differential operator del, written $\vec{\nabla}$, is defined by

$$\vec{\nabla} \equiv \frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \equiv \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z}$$

Gradient of a scalar point function :

Let $\phi(x, y, z)$ be defined and differentiable at each point (x, y, z) in a certain region of space. Then the gradient of ϕ , written $\vec{\nabla}\phi$ or $\text{grad}\phi$, is defined by

$$\vec{\nabla}\phi = \left(\frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) \phi = \frac{\partial \phi}{\partial x} \vec{i} + \frac{\partial \phi}{\partial y} \vec{j} + \frac{\partial \phi}{\partial z} \vec{k}$$

Note that $\vec{\nabla}\phi$ defines a vector field.

Divergence of a vector point function :

Let $\vec{V} = V_1 \vec{i} + V_2 \vec{j} + V_3 \vec{k}$ be defined and differentiable at each point (x, y, z) in a certain region of space. Then the divergence of \vec{V} , written $\vec{\nabla} \cdot \vec{V}$ or $\text{div} \vec{V}$, is defined by

$$\begin{aligned} \vec{\nabla} \cdot \vec{V} &= \left(\frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) \cdot (V_1 \vec{i} + V_2 \vec{j} + V_3 \vec{k}) \\ &= \frac{\partial V_1}{\partial x} + \frac{\partial V_2}{\partial y} + \frac{\partial V_3}{\partial z} \end{aligned}$$

Note that $\vec{\nabla} \cdot \vec{V} \neq \vec{V} \cdot \vec{\nabla}$

Curl of a vector point function:

If $\vec{V} = V_1 \vec{i} + V_2 \vec{j} + V_3 \vec{k}$ is a differentiable vector field then the curl or rotation of \vec{V} , written $\vec{\nabla} \times \vec{V}$, $\text{curl} \vec{V}$ or $\text{rot} \vec{V}$, is defined by

$$\vec{\nabla} \times \vec{V} = \left(\frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) \times (V_1 \vec{i} + V_2 \vec{j} + V_3 \vec{k}) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_1 & V_2 & V_3 \end{vmatrix}$$

Directional derivative: Let f be a scalar point function of the cartesian co-ordinates (x, y, z) of a point. Then the partial derivatives

$\frac{\partial f}{\partial x}$ which gives the rate of increase of f along the x -axis, is called the directional derivative of f along the x -axis. Similar meaning are given to the partial derivatives $\frac{\partial f}{\partial y}$ and $\frac{\partial f}{\partial z}$.

We consider further two points P and P' , where a uniform point function f is continuous and has values f and $f + \delta f$. Let δs be

the distance PP' from P to P' . If $\lim_{\delta s \rightarrow 0} \frac{\delta f}{\delta s}$ be finite, then this limit is called the directional derivative of f at P in the direction from P to P' and is denoted by $\frac{df}{ds}$, which is a scalar.

Expressions for directional derivative :

Consider a scalar point function $f(\vec{r})$ or $f(x, y, z)$ in the neighbourhood of the point $P_0(x_0, y_0, z_0)$ of position vector \vec{r}_0 , where it is continuous and differentiable. A straight line through P_0 in the direction of the unit vector $\vec{e} = \cos \alpha \vec{i} + \cos \beta \vec{j} + \cos \gamma \vec{k}$ has the vector equation $\vec{r} = \vec{r}_0 + s\vec{e}$, where the scalar $s = |\overrightarrow{PP_0}| > 0$

The parametric equations of the straight line are

$$x = x_0 + s \cos \alpha, y = y_0 + s \cos \beta, z = z_0 + s \cos \gamma, \dots \dots \dots (1)$$

Along the line, $f(x, y, z)$ is a function of s alone and we have,

$$\frac{df}{ds} = \frac{\partial f}{\partial x} \frac{dx}{ds} + \frac{\partial f}{\partial y} \frac{dy}{ds} + \frac{\partial f}{\partial z} \frac{dz}{ds}$$

$$\text{or, by (1), } \frac{df}{ds} = \cos \alpha \frac{\partial f}{\partial x} + \cos \beta \frac{\partial f}{\partial y} + \cos \gamma \frac{\partial f}{\partial z} \dots \dots \dots (2)$$

If the partial derivatives be computed at P_0 , then (2) gives the directional derivative of $f(x, y, z)$ at P_0 in the direction of \vec{e} .

$$\begin{aligned} \text{Now, } \frac{df}{ds} &= \left(\frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) \cdot (\cos \alpha \vec{i} + \cos \beta \vec{j} + \cos \gamma \vec{k}) \\ &= \vec{\nabla} f \cdot \vec{e} \end{aligned}$$

= the directional derivative of f in the direction of \vec{e}

Solenoidal vector: A vector is said to be solenoidal if its divergence is zero.

Irrotational vector: A vector \vec{A} is said to be irrotational if $\vec{\nabla} \times \vec{A} = \vec{0}$ i.e., if $\text{curl } \vec{A} = \vec{0}$.

Formulae involving $\vec{\nabla}$: If \vec{A} and \vec{B} are differentiable vector functions, and ϕ and ψ are differentiable scalar function of position (x, y, z) , then

1. $\vec{\nabla}(\phi + \psi) = \vec{\nabla}\phi + \vec{\nabla}\psi$ or $\text{grad}(\phi + \psi) = \text{grad } \phi + \text{grad } \psi$.
2. $\vec{\nabla} \cdot (\vec{A} + \vec{B}) = \vec{\nabla} \cdot \vec{A} + \vec{\nabla} \cdot \vec{B}$ or $\text{div}(\vec{A} + \vec{B}) = \text{div } \vec{A} + \text{div } \vec{B}$
3. $\vec{\nabla} \times (\vec{A} + \vec{B}) = \vec{\nabla} \times \vec{A} + \vec{\nabla} \times \vec{B}$ or $\text{curl}(\vec{A} + \vec{B}) = \text{curl } \vec{A} + \text{curl } \vec{B}$
4. $\vec{\nabla} \cdot (\phi \vec{A}) = (\vec{\nabla} \phi) \cdot \vec{A} + \phi (\vec{\nabla} \cdot \vec{A})$
5. $\vec{\nabla} \times (\phi \vec{A}) = (\vec{\nabla} \phi) \times \vec{A} + \phi (\vec{\nabla} \times \vec{A})$
6. $\vec{\nabla} \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\vec{\nabla} \times \vec{A}) - \vec{A} \cdot (\vec{\nabla} \times \vec{B})$

$$7. \nabla \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \nabla) \vec{A} - \vec{B} (\nabla \cdot \vec{A}) - (\vec{A} \cdot \nabla) \vec{B} + \vec{A} (\nabla \cdot \vec{B})$$

$$8. \nabla (\vec{A} \cdot \vec{B}) = (\vec{B} \cdot \nabla) \vec{A} + (\vec{A} \cdot \nabla) \vec{B} + \vec{B} \times (\nabla \times \vec{A}) + \vec{A} \times (\nabla \times \vec{B})$$

$$9. \nabla \cdot (\nabla \phi) = \nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} \quad \text{where} \quad \nabla^2 \equiv \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \quad \text{is called}$$

the Laplacian operator.

$$10. \nabla \times (\nabla \phi) = \vec{0}. \text{ The curl of the gradient of } \phi \text{ is zero.}$$

$$11. \nabla \cdot (\nabla \times \vec{A}) = 0. \text{ The divergence of the curl of } \vec{A} \text{ is zero.}$$

$$12. \nabla \times (\nabla \times \vec{A}) = \nabla (\nabla \cdot \vec{A}) - \nabla^2 \vec{A}$$

Worked out exercises:

Exercise1: Find $\nabla \phi$ if (a) $\phi = \ln |\vec{r}|$, (b) $\phi = \frac{1}{r}$, where $r = |\vec{r}|$.

$$\odot. (a) \vec{r} = x\vec{i} + y\vec{j} + z\vec{k}. \text{ Then } |\vec{r}| = \sqrt{x^2 + y^2 + z^2}, \phi = \ln |\vec{r}| = \frac{1}{2} (x^2 + y^2 + z^2)$$

$$\begin{aligned} \nabla \phi &= \frac{1}{2} \nabla \{ \ln(x^2 + y^2 + z^2) \} \\ &= \frac{1}{2} \left[\vec{i} \frac{\partial}{\partial x} \{ \ln(x^2 + y^2 + z^2) \} + \vec{j} \frac{\partial}{\partial y} \{ \ln(x^2 + y^2 + z^2) \} + \vec{k} \frac{\partial}{\partial z} \{ \ln(x^2 + y^2 + z^2) \} \right] \\ &= \frac{1}{2} \left\{ \vec{i} \frac{2x}{x^2 + y^2 + z^2} + \vec{j} \frac{2y}{x^2 + y^2 + z^2} + \vec{k} \frac{2z}{x^2 + y^2 + z^2} \right\} \\ &= \frac{x\vec{i} + y\vec{j} + z\vec{k}}{x^2 + y^2 + z^2} = \frac{\vec{r}}{r^2} \quad \text{where } r = |\vec{r}|. \end{aligned}$$

$$\begin{aligned} (b) \nabla \phi &= \nabla \left(\frac{1}{r} \right) = \nabla \left(\frac{1}{\sqrt{x^2 + y^2 + z^2}} \right) \\ &= \vec{i} \frac{\partial}{\partial x} \left(\frac{1}{\sqrt{x^2 + y^2 + z^2}} \right) + \vec{j} \frac{\partial}{\partial y} \left(\frac{1}{\sqrt{x^2 + y^2 + z^2}} \right) + \vec{k} \frac{\partial}{\partial z} \left(\frac{1}{\sqrt{x^2 + y^2 + z^2}} \right) \\ &= \left\{ -\frac{1}{2} (x^2 + y^2 + z^2)^{-\frac{3}{2}} 2x \right\} \vec{i} + \left\{ -\frac{1}{2} (x^2 + y^2 + z^2)^{-\frac{3}{2}} 2y \right\} \vec{j} \\ &\quad + \left\{ -\frac{1}{2} (x^2 + y^2 + z^2)^{-\frac{3}{2}} 2z \right\} \vec{k} = \frac{-x\vec{i} - y\vec{j} - z\vec{k}}{(x^2 + y^2 + z^2)^{\frac{3}{2}}} = -\frac{\vec{r}}{r^3} \end{aligned}$$

Exercise2: Show that $\nabla r^n = nr^{n-2} \vec{r}$.

$$\odot. \nabla r^n = \nabla \left(\sqrt{x^2 + y^2 + z^2} \right)^n = \nabla \left(x^2 + y^2 + z^2 \right)^{\frac{n}{2}}$$

Vector Analysis

$$\begin{aligned}
 &= \vec{i} \frac{\partial}{\partial x} \left\{ (x^2 + y^2 + z^2)^{\frac{n}{2}} \right\} + \vec{j} \frac{\partial}{\partial y} \left\{ (x^2 + y^2 + z^2)^{\frac{n}{2}} \right\} + \vec{k} \frac{\partial}{\partial z} \left\{ (x^2 + y^2 + z^2)^{\frac{n}{2}} \right\} \\
 &= \vec{i} \left\{ \frac{n}{2} (x^2 + y^2 + z^2)^{\frac{n}{2}-1} 2x \right\} + \vec{j} \left\{ \frac{n}{2} (x^2 + y^2 + z^2)^{\frac{n}{2}-1} 2y \right\} \\
 &\quad + \vec{k} \left\{ \frac{n}{2} (x^2 + y^2 + z^2)^{\frac{n}{2}-1} 2z \right\} = n (x^2 + y^2 + z^2)^{\frac{n}{2}-1} (x\vec{i} + y\vec{j} + z\vec{k}) \\
 &= n (r^2)^{\frac{n}{2}-1} \vec{r} = nr^{n-2} \vec{r}
 \end{aligned}$$

Exercise3: Show that $\vec{\nabla}\phi$ is a vector perpendicular to the surface $\phi(x, y, z) = c$, where c is a constant.

☺. Let $\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$ be the position vector to any point $P(x, y, z)$ on the surface. Then $d\vec{r} = dx\vec{i} + dy\vec{j} + dz\vec{k}$ lies in the tangent plane to the surface at P.

$$\text{But } d\phi = \frac{\partial\phi}{\partial x} dx + \frac{\partial\phi}{\partial y} dy + \frac{\partial\phi}{\partial z} dz = 0$$

$$\text{or, } \left(\frac{\partial\phi}{\partial x} \vec{i} + \frac{\partial\phi}{\partial y} \vec{j} + \frac{\partial\phi}{\partial z} \vec{k} \right) \cdot (dx\vec{i} + dy\vec{j} + dz\vec{k}) = 0$$

or, $\vec{\nabla}\phi \cdot d\vec{r} = 0$, so that $\vec{\nabla}\phi$ is perpendicular to $d\vec{r}$ and therefore to the surface.

Exercise4: Find a unit normal to the surface $x^2y + 2xz = 4$ at the point $(2, -2, 3)$.

$$\text{☺. } \vec{\nabla}(x^2y + 2xz) = (2xy + 2z)\vec{i} + x^2\vec{j} + 2x\vec{k}.$$

$$\text{At } (2, -2, 3), \vec{\nabla}(x^2y + 2xz) = -2\vec{i} + 4\vec{j} + 4\vec{k}$$

Then a unit normal to the surface $x^2y + 2xz = 4$ at $(2, -2, 3)$ is

$$\frac{-2\vec{i} + 4\vec{j} + 4\vec{k}}{\sqrt{(-2)^2 + 4^2 + 4^2}} = -\frac{1}{3}\vec{i} + \frac{2}{3}\vec{j} + \frac{2}{3}\vec{k}.$$

Another unit normal is $\frac{1}{3}\vec{i} - \frac{2}{3}\vec{j} - \frac{2}{3}\vec{k}$ having direction opposite to above.

Exercise5: Show that greatest rate of change of ϕ , i.e. the maximum directional derivative, takes place in the direction of, and has the magnitude of the vector $\vec{\nabla}\phi$.

$$\begin{aligned}
 \text{☺. Now, } \frac{d\phi}{ds} &= \frac{\partial\phi}{\partial x} \frac{dx}{ds} + \frac{\partial\phi}{\partial y} \frac{dy}{ds} + \frac{\partial\phi}{\partial z} \frac{dz}{ds} \\
 &= \left(\frac{\partial\phi}{\partial x} \vec{i} + \frac{\partial\phi}{\partial y} \vec{j} + \frac{\partial\phi}{\partial z} \vec{k} \right) \cdot \left(\frac{dx}{ds} \vec{i} + \frac{dy}{ds} \vec{j} + \frac{dz}{ds} \vec{k} \right) \\
 &= \vec{\nabla}\phi \cdot \frac{d\vec{r}}{ds}
 \end{aligned}$$

Vector Analysis

$\therefore \frac{d\phi}{ds}$ is the projection of $\vec{\nabla}\phi$ in the direction $\frac{d\vec{r}}{ds}$.

This projection will be a maximum when $\vec{\nabla}\phi$ and $\frac{d\vec{r}}{ds}$ have the same direction. Then the maximum value of $\frac{d\phi}{ds}$ takes place in the direction of $\vec{\nabla}\phi$ and its magnitude is $|\vec{\nabla}\phi|$.

Exercise6: Find the directional derivative of $\phi = x^2yz + 4xz^2$ at $(1, -2, -1)$ in the direction $2\vec{i} - \vec{j} - 2\vec{k}$.

$$\odot \cdot \vec{\nabla}\phi = \vec{\nabla}(x^2yz + 4xz^2) = (2xyz + 4z^2)\vec{i} + x^2z\vec{j} + (x^2y + 8xz)\vec{k}$$

At $(1, -2, -1)$, $\vec{\nabla}\phi = 8\vec{i} - \vec{j} - 10\vec{k}$

The unit vector in the direction of $2\vec{i} - \vec{j} - 2\vec{k}$ is

$$\vec{a} = \frac{2\vec{i} - \vec{j} - 2\vec{k}}{\sqrt{(2)^2 + (-1)^2 + (-2)^2}} = \frac{2}{3}\vec{i} - \frac{1}{3}\vec{j} - \frac{2}{3}\vec{k}$$

Then the required directional derivative is

$$\vec{\nabla}\phi \cdot \vec{a} = (8\vec{i} - \vec{j} - 10\vec{k}) \cdot \left(\frac{2}{3}\vec{i} - \frac{1}{3}\vec{j} - \frac{2}{3}\vec{k}\right) = \frac{16}{3} + \frac{1}{3} + \frac{20}{3} = \frac{37}{3}$$

Exercise7:(a) In what direction from the point $(2, 1, -1)$ is the directional derivative of $\phi = x^2yz^3$ a maximum?

(b) What is the magnitude of this maximum?

$$\odot \cdot \vec{\nabla}\phi = \vec{\nabla}(x^2yz^3) = 2xyz^3\vec{i} + x^2z^3\vec{j} + 3x^2yz^2\vec{k}$$

At $(2, 1, -1)$, $\vec{\nabla}\phi = -4\vec{i} - 4\vec{j} + 12\vec{k}$

(a) the directional derivative is a maximum in the direction

$$\vec{\nabla}\phi = -4\vec{i} - 4\vec{j} + 12\vec{k}.$$

(b) the magnitude of this maximum is

$$|\vec{\nabla}\phi| = \sqrt{(-4)^2 + (-4)^2 + (12)^2} = \sqrt{176} = 4\sqrt{11}.$$

Exercise8: Find the angle between the surface $x^2 + y^2 + z^2 = 9$ and $z = x^2 + y^2 - 3$ at the point $(2, -1, 2)$

\odot . The angle between the surface at the point is the angle between the normal to the surface at the point.

A normal to $x^2 + y^2 + z^2 = 9$ at $(2, -1, 2)$ is

$$\vec{\nabla}\phi_1 = \vec{\nabla}(x^2 + y^2 + z^2) = 2x\vec{i} + 2y\vec{j} + 2z\vec{k} = 4\vec{i} - 2\vec{j} + 4\vec{k}.$$

A normal to $z = x^2 + y^2 - 3$ or $x^2 + y^2 - z = 3$ at $(2, -1, 2)$ is

$$\vec{\nabla}\phi_2 = \vec{\nabla}(x^2 + y^2 - z) = 2x\vec{i} + 2y\vec{j} - \vec{k} = 4\vec{i} - 2\vec{j} - \vec{k}$$

$$(\vec{\nabla}\phi_1) \cdot (\vec{\nabla}\phi_2) = |\vec{\nabla}\phi_1| |\vec{\nabla}\phi_2| \cos \theta, \text{ where } \theta \text{ is the required angle.}$$

$$\text{Then } (4\vec{i} - 2\vec{j} + 4\vec{k}) \cdot (4\vec{i} - 2\vec{j} - \vec{k}) = |4\vec{i} - 2\vec{j} + 4\vec{k}| |4\vec{i} - 2\vec{j} - \vec{k}| \cos \theta$$

Vector Analysis

$$\text{or, } 16 + 4 - 4 = \sqrt{(4)^2 + (-2)^2 + (4)^2} \sqrt{(4)^2 + (-2)^2 + (-1)^2} \cos \theta$$

$$\text{or, } \cos \theta = \frac{16}{6\sqrt{21}} = \frac{8\sqrt{21}}{63} = 0.5819; \text{ thus the acute angle is}$$

$$\theta = \cos^{-1}(0.5819) = 54^\circ 25'.$$

Exercise9: Given $\phi = 2x^3y^2z^4$. (a) Find $\vec{\nabla} \cdot \vec{\nabla} \phi$ (or $\text{divgrad } \phi$). (b) Show that $\vec{\nabla} \cdot \vec{\nabla} \phi = \vec{\nabla}^2 \phi$, where $\vec{\nabla}^2 \phi \equiv \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$ denotes the Laplacian operator.

$$\begin{aligned} \odot \cdot \text{(a) } \vec{\nabla} \phi &= \vec{i} \frac{\partial}{\partial x} (2x^3y^2z^4) + \vec{j} \frac{\partial}{\partial y} (2x^3y^2z^4) + \vec{k} \frac{\partial}{\partial z} (2x^3y^2z^4) \\ &= 6x^2y^2z^4\vec{i} + 4x^3yz^4\vec{j} + 8x^3y^2z^3\vec{k}. \end{aligned}$$

$$\begin{aligned} \text{Then } \vec{\nabla} \cdot \vec{\nabla} \phi &= \left(\frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) \cdot (6x^2y^2z^4\vec{i} + 4x^3yz^4\vec{j} + 8x^3y^2z^3\vec{k}) \\ &= \frac{\partial}{\partial x} (6x^2y^2z^4) + \frac{\partial}{\partial y} (4x^3yz^4) + \frac{\partial}{\partial z} (8x^3y^2z^3) \\ &= 12xy^2z^4 + 4x^3z^4 + 24x^3y^2z^2 \end{aligned}$$

$$\begin{aligned} \text{(b) } \vec{\nabla} \cdot \vec{\nabla} \phi &= \left(\frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) \cdot \left(\frac{\partial \phi}{\partial x} \vec{i} + \frac{\partial \phi}{\partial y} \vec{j} + \frac{\partial \phi}{\partial z} \vec{k} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{\partial \phi}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial \phi}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial \phi}{\partial z} \right) \\ &= \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} \\ &= \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \phi = \vec{\nabla}^2 \phi. \end{aligned}$$

Exercise10: Prove that $\vec{\nabla}^2 \left(\frac{1}{r} \right) = 0$

$$\odot \cdot \vec{\nabla}^2 \left(\frac{1}{r} \right) = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \left(\frac{1}{\sqrt{x^2 + y^2 + z^2}} \right)$$

$$\begin{aligned} \frac{\partial^2}{\partial x^2} \left(\frac{1}{\sqrt{x^2 + y^2 + z^2}} \right) &= -\frac{\partial}{\partial x} \left[x(x^2 + y^2 + z^2)^{-\frac{3}{2}} \right] \\ &= \frac{3}{2} x(x^2 + y^2 + z^2)^{-\frac{5}{2}} (2x) - (x^2 + y^2 + z^2)^{-\frac{3}{2}} \\ &= \frac{3x^2 - x^2 - y^2 - z^2}{(x^2 + y^2 + z^2)^{\frac{5}{2}}} \\ &= \frac{2x^2 - y^2 - z^2}{(x^2 + y^2 + z^2)^{\frac{5}{2}}} \end{aligned}$$

Vector Analysis

$$\frac{\partial^2}{\partial y^2} \left(\frac{1}{\sqrt{x^2 + y^2 + z^2}} \right) = \frac{2y^2 - z^2 - x^2}{(x^2 + y^2 + z^2)^{\frac{5}{2}}}$$

$$\text{and } \frac{\partial^2}{\partial z^2} \left(\frac{1}{\sqrt{x^2 + y^2 + z^2}} \right) = \frac{2z^2 - x^2 - y^2}{(x^2 + y^2 + z^2)^{\frac{5}{2}}}$$

$$\begin{aligned} \text{Then by addition } \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \left(\frac{1}{\sqrt{x^2 + y^2 + z^2}} \right) \\ = \frac{2x^2 - y^2 - z^2 + 2y^2 - z^2 - x^2 + 2z^2 - x^2 - y^2}{(x^2 + y^2 + z^2)^{\frac{5}{2}}} = 0. \end{aligned}$$

The equation $\vec{\nabla}^2 \phi = 0$ is called Laplace's equation. It follows that $\phi = \frac{1}{r}$ is a solution of this equation.

Exercise 11: Prove (a) $\vec{\nabla} \times (\vec{A} + \vec{B}) = \vec{\nabla} \times \vec{A} + \vec{\nabla} \times \vec{B}$

(b) $\vec{\nabla} \times (\phi \vec{A}) = \vec{\nabla} \phi \times \vec{A} + \phi (\vec{\nabla} \times \vec{A})$

☺ . Let $\vec{A} = A_1 \vec{i} + A_2 \vec{j} + A_3 \vec{k}$, $\vec{B} = B_1 \vec{i} + B_2 \vec{j} + B_3 \vec{k}$.

$$\begin{aligned} \text{Now, } \vec{\nabla} \times ((A_1 + B_1) \vec{i} + (A_2 + B_2) \vec{j} + (A_3 + B_3) \vec{k}) \\ = \left[\frac{\partial}{\partial y} (A_3 + B_3) - \frac{\partial}{\partial z} (A_2 + B_2) \right] \vec{i} + \left[\frac{\partial}{\partial z} (A_1 + B_1) - \frac{\partial}{\partial x} (A_3 + B_3) \right] \vec{j} \\ + \left[\frac{\partial}{\partial x} (A_2 + B_2) - \frac{\partial}{\partial y} (A_1 + B_1) \right] \vec{k} \\ = \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \vec{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \vec{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \vec{k} + \left(\frac{\partial B_3}{\partial y} - \frac{\partial B_2}{\partial z} \right) \vec{i} + \left(\frac{\partial B_1}{\partial z} - \frac{\partial B_3}{\partial x} \right) \vec{j} \\ + \left(\frac{\partial B_2}{\partial x} - \frac{\partial B_1}{\partial y} \right) \vec{k} = \vec{\nabla} \times \vec{A} + \vec{\nabla} \times \vec{B}. \end{aligned}$$

(b) Let $\vec{A} = A_1 \vec{i} + A_2 \vec{j} + A_3 \vec{k}$

$$\vec{\nabla} \times (\phi \vec{A}) = \vec{\nabla} \times (\phi A_1 \vec{i} + \phi A_2 \vec{j} + \phi A_3 \vec{k})$$

$$\begin{aligned} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \phi A_1 & \phi A_2 & \phi A_3 \end{vmatrix} \\ &= \left[\frac{\partial}{\partial y} (\phi A_3) - \frac{\partial}{\partial z} (\phi A_2) \right] \vec{i} + \left[\frac{\partial}{\partial z} (\phi A_1) - \frac{\partial}{\partial x} (\phi A_3) \right] \vec{j} + \left[\frac{\partial}{\partial x} (\phi A_2) - \frac{\partial}{\partial y} (\phi A_1) \right] \vec{k} \\ &= \left[\frac{\partial \phi}{\partial y} A_3 + \phi \frac{\partial A_3}{\partial y} - \frac{\partial \phi}{\partial z} A_2 - \phi \frac{\partial A_2}{\partial z} \right] \vec{i} + \left[\frac{\partial \phi}{\partial z} A_1 + \phi \frac{\partial A_1}{\partial z} - \frac{\partial \phi}{\partial x} A_3 - \phi \frac{\partial A_3}{\partial x} \right] \vec{j} \\ &+ \left[\frac{\partial \phi}{\partial x} A_2 + \phi \frac{\partial A_2}{\partial x} - \frac{\partial \phi}{\partial y} A_1 - \phi \frac{\partial A_1}{\partial y} \right] \vec{k} \end{aligned}$$

Vector Analysis

$$\begin{aligned}
 &= \phi \left[\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \vec{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \vec{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \vec{k} \right] \\
 &+ \left[\left(\frac{\partial \phi}{\partial y} A_3 - \frac{\partial \phi}{\partial z} A_2 \right) \vec{i} + \left(\frac{\partial \phi}{\partial z} A_1 - \frac{\partial \phi}{\partial x} A_3 \right) \vec{j} + \left(\frac{\partial \phi}{\partial x} A_2 - \frac{\partial \phi}{\partial y} A_1 \right) \vec{k} \right] \\
 &= \phi (\vec{\nabla} \times \vec{A}) + \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} \\
 &= \phi (\vec{\nabla} \times \vec{A}) + (\vec{\nabla} \phi \times \vec{A})
 \end{aligned}$$

Exercise12: Prove (a) $\vec{\nabla} \times (\vec{\nabla} \phi) = \vec{0}$ (curl grad $\phi = \vec{0}$),

(b) $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$ (div curl $\vec{A} = 0$)

$$\begin{aligned}
 \odot \cdot \text{(a)} \quad \vec{\nabla} \times (\vec{\nabla} \phi) &= \vec{\nabla} \times \left(\frac{\partial \phi}{\partial x} \vec{i} + \frac{\partial \phi}{\partial y} \vec{j} + \frac{\partial \phi}{\partial z} \vec{k} \right) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{vmatrix} \\
 &= \left[\frac{\partial}{\partial y} \left(\frac{\partial \phi}{\partial z} \right) - \frac{\partial}{\partial z} \left(\frac{\partial \phi}{\partial y} \right) \right] \vec{i} + \left[\frac{\partial}{\partial z} \left(\frac{\partial \phi}{\partial x} \right) - \frac{\partial}{\partial x} \left(\frac{\partial \phi}{\partial z} \right) \right] \vec{j} + \left[\frac{\partial}{\partial x} \left(\frac{\partial \phi}{\partial y} \right) - \frac{\partial}{\partial y} \left(\frac{\partial \phi}{\partial x} \right) \right] \vec{k} \\
 &= \left(\frac{\partial^2 \phi}{\partial y \partial z} - \frac{\partial^2 \phi}{\partial z \partial y} \right) \vec{i} + \left(\frac{\partial^2 \phi}{\partial z \partial x} - \frac{\partial^2 \phi}{\partial x \partial z} \right) \vec{j} + \left(\frac{\partial^2 \phi}{\partial x \partial y} - \frac{\partial^2 \phi}{\partial y \partial x} \right) \vec{k} = \vec{0}, \text{ provided we}
 \end{aligned}$$

assume that ϕ has continuous second order partial derivatives so that the order of differentiation is immaterial.

(b) Let $\vec{A} = A_1 \vec{i} + A_2 \vec{j} + A_3 \vec{k}$

$$\begin{aligned}
 \text{Then, } \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) &= \vec{\nabla} \cdot \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} \\
 &= \vec{\nabla} \cdot \left[\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \vec{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \vec{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \vec{k} \right] \\
 &= \frac{\partial}{\partial x} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + \frac{\partial}{\partial y} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + \frac{\partial}{\partial z} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \\
 &= \frac{\partial^2 A_3}{\partial x \partial y} - \frac{\partial^2 A_2}{\partial x \partial z} + \frac{\partial^2 A_1}{\partial y \partial z} - \frac{\partial^2 A_3}{\partial y \partial x} + \frac{\partial^2 A_2}{\partial z \partial x} - \frac{\partial^2 A_1}{\partial z \partial y} \\
 &= 0, \text{ assuming that } \vec{A} \text{ has continuous second order partial derivatives.}
 \end{aligned}$$

Exercise13: Find $\text{curl}(\vec{r}f(r))$, where $f(r)$ is differentiable.

$$\odot \cdot \text{curl}(\vec{r}f(r)) = \vec{\nabla} \times (\vec{r}f(r))$$

$$\begin{aligned}
 &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xf(r) & yf(r) & zf(r) \end{vmatrix} \\
 &= \left(z \frac{\partial f}{\partial y} - y \frac{\partial f}{\partial z} \right) \vec{i} + \left(x \frac{\partial f}{\partial z} - z \frac{\partial f}{\partial x} \right) \vec{j} + \left(y \frac{\partial f}{\partial x} - x \frac{\partial f}{\partial y} \right) \vec{k} \\
 \frac{\partial f}{\partial x} &= \frac{\partial f}{\partial r} \frac{\partial r}{\partial x} = \frac{\partial f}{\partial r} \frac{\partial}{\partial x} \left(\sqrt{x^2 + y^2 + z^2} \right) = \frac{\partial f}{\partial r} \frac{2x}{2\sqrt{x^2 + y^2 + z^2}} = \frac{xf'}{\sqrt{x^2 + y^2 + z^2}} = \frac{xf'}{r}
 \end{aligned}$$

Similarly, $\frac{\partial f}{\partial y} = \frac{yf'}{\sqrt{x^2 + y^2 + z^2}} = \frac{yf'}{r}$ and $\frac{\partial f}{\partial z} = \frac{zf'}{r}$

Therefore, $\text{curl}(\vec{r}f(r)) = \left(\frac{zyf'}{r} - \frac{yzf'}{r} \right) \vec{i} + \left(\frac{xzf'}{r} - \frac{zxf'}{r} \right) \vec{j} + \left(\frac{yxf'}{r} - \frac{xyf'}{r} \right) \vec{k} = \vec{0}$

Exercise14: Prove $\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = -\vec{\nabla}^2 \vec{A} + \vec{\nabla}(\vec{\nabla} \cdot \vec{A})$

☺ . Let $\vec{A} = A_1 \vec{i} + A_2 \vec{j} + A_3 \vec{k}$

$$\begin{aligned}
 \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) &= \vec{\nabla} \times \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} \\
 &= \vec{\nabla} \times \left[\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \vec{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \vec{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \vec{k} \right] \\
 &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} & \frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} & \frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \end{vmatrix} \\
 &= \left[\frac{\partial}{\partial y} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) - \frac{\partial}{\partial z} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \right] \vec{i} + \left[\frac{\partial}{\partial z} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) - \frac{\partial}{\partial x} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \right] \vec{j} \\
 &\quad + \left[\frac{\partial}{\partial x} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) - \frac{\partial}{\partial y} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \right] \vec{k} \\
 &= \left(-\frac{\partial^2 A_1}{\partial y^2} - \frac{\partial^2 A_1}{\partial z^2} \right) \vec{i} + \left(-\frac{\partial^2 A_2}{\partial z^2} - \frac{\partial^2 A_2}{\partial x^2} \right) \vec{j} + \left(-\frac{\partial^2 A_3}{\partial x^2} - \frac{\partial^2 A_3}{\partial y^2} \right) \vec{k} \\
 &\quad + \left(\frac{\partial^2 A_2}{\partial y \partial x} + \frac{\partial^2 A_3}{\partial z \partial x} \right) \vec{i} + \left(\frac{\partial^2 A_3}{\partial z \partial y} + \frac{\partial^2 A_1}{\partial x \partial y} \right) \vec{j} + \left(\frac{\partial^2 A_1}{\partial x \partial z} + \frac{\partial^2 A_2}{\partial y \partial z} \right) \vec{k}
 \end{aligned}$$

Vector Analysis

$$\begin{aligned}
 &= \left(-\frac{\partial^2 A_1}{\partial x^2} - \frac{\partial^2 A_1}{\partial y^2} - \frac{\partial^2 A_1}{\partial z^2} \right) \vec{i} + \left(-\frac{\partial^2 A_2}{\partial x^2} - \frac{\partial^2 A_2}{\partial y^2} - \frac{\partial^2 A_2}{\partial z^2} \right) \vec{j} + \\
 &\quad \left(-\frac{\partial^2 A_3}{\partial x^2} - \frac{\partial^2 A_3}{\partial y^2} - \frac{\partial^2 A_3}{\partial z^2} \right) \vec{k} + \left(\frac{\partial^2 A_1}{\partial x^2} + \frac{\partial^2 A_2}{\partial y \partial x} + \frac{\partial^2 A_3}{\partial z \partial x} \right) \vec{i} \\
 &\quad + \left(\frac{\partial^2 A_1}{\partial x \partial y} + \frac{\partial^2 A_2}{\partial y^2} + \frac{\partial^2 A_3}{\partial z \partial y} \right) \vec{j} + \left(\frac{\partial^2 A_1}{\partial x \partial z} + \frac{\partial^2 A_2}{\partial y \partial z} + \frac{\partial^2 A_3}{\partial z^2} \right) \vec{k} \\
 &= - \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) (A_1 \vec{i} + A_2 \vec{j} + A_3 \vec{k}) + \left\{ \frac{\partial}{\partial x} \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) \right\} \vec{i} \\
 &\quad + \left\{ \frac{\partial}{\partial y} \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) \right\} \vec{j} + \left\{ \frac{\partial}{\partial z} \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) \right\} \vec{k} \\
 &= -\nabla^2 \vec{A} + \vec{\nabla} \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) \\
 &= -\nabla^2 \vec{A} + \vec{\nabla} (\vec{\nabla} \cdot \vec{A})
 \end{aligned}$$

Exercise15: Prove $\vec{\nabla} \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\vec{\nabla} \times \vec{A}) - \vec{A} \cdot (\vec{\nabla} \times \vec{B})$

☺ . Let $\vec{A} = A_1 \vec{i} + A_2 \vec{j} + A_3 \vec{k}$, $\vec{B} = B_1 \vec{i} + B_2 \vec{j} + B_3 \vec{k}$

$$\begin{aligned}
 \vec{A} \times \vec{B} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \end{vmatrix} \\
 &= (A_2 B_3 - B_2 A_3) \vec{i} + (A_3 B_1 - B_3 A_1) \vec{j} + (A_1 B_2 - B_1 A_2) \vec{k} \\
 \therefore \vec{\nabla} \cdot (\vec{A} \times \vec{B}) &= \frac{\partial}{\partial x} (A_2 B_3 - B_2 A_3) + \frac{\partial}{\partial y} (A_3 B_1 - B_3 A_1) + \frac{\partial}{\partial z} (A_1 B_2 - B_1 A_2) \\
 &= B_1 \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + B_2 \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + B_3 \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) - A_1 \left(\frac{\partial B_3}{\partial y} - \frac{\partial B_2}{\partial z} \right) \\
 &\quad - A_2 \left(\frac{\partial B_1}{\partial z} - \frac{\partial B_3}{\partial x} \right) - A_3 \left(\frac{\partial B_2}{\partial x} - \frac{\partial B_1}{\partial y} \right) \\
 &= (B_1 \vec{i} + B_2 \vec{j} + B_3 \vec{k}) \cdot \left[\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \vec{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \vec{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \vec{k} \right] \\
 &\quad - (A_1 \vec{i} + A_2 \vec{j} + A_3 \vec{k}) \cdot \left[\left(\frac{\partial B_3}{\partial y} - \frac{\partial B_2}{\partial z} \right) \vec{i} + \left(\frac{\partial B_1}{\partial z} - \frac{\partial B_3}{\partial x} \right) \vec{j} + \left(\frac{\partial B_2}{\partial x} - \frac{\partial B_1}{\partial y} \right) \vec{k} \right] \\
 &= \vec{B} \cdot \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} - \vec{A} \cdot \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ B_1 & B_2 & B_3 \end{vmatrix} \\
 &= \vec{B} \cdot (\vec{\nabla} \times \vec{A}) - \vec{A} \cdot (\vec{\nabla} \times \vec{B})
 \end{aligned}$$

Exercise16: Prove $\vec{\nabla} \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \vec{\nabla}) \vec{A} - \vec{B} (\vec{\nabla} \cdot \vec{A}) - (\vec{A} \cdot \vec{\nabla}) \vec{B} + \vec{A} (\vec{\nabla} \cdot \vec{B})$

☺ . Let $\vec{A} = A_1 \vec{i} + A_2 \vec{j} + A_3 \vec{k}$, $\vec{B} = B_1 \vec{i} + B_2 \vec{j} + B_3 \vec{k}$

Vector Analysis

$$\text{and } \vec{C} = \vec{A} \times \vec{B} = C_1 \vec{i} + C_2 \vec{j} + C_3 \vec{k}.$$

$$\begin{aligned} \text{Then } \vec{\nabla} \times (\vec{A} \times \vec{B}) &= \vec{\nabla} \times \vec{C} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ C_1 & C_2 & C_3 \end{vmatrix} \\ &= \left(\frac{\partial C_3}{\partial y} - \frac{\partial C_2}{\partial z} \right) \vec{i} + \left(\frac{\partial C_1}{\partial z} - \frac{\partial C_3}{\partial x} \right) \vec{j} + \left(\frac{\partial C_2}{\partial x} - \frac{\partial C_1}{\partial y} \right) \vec{k} \\ &= \left(\frac{\partial C_2}{\partial x} \vec{k} - \frac{\partial C_3}{\partial x} \vec{j} \right) + \left(\frac{\partial C_3}{\partial y} \vec{i} - \frac{\partial C_1}{\partial y} \vec{k} \right) + \left(\frac{\partial C_1}{\partial z} \vec{j} - \frac{\partial C_2}{\partial z} \vec{i} \right) \\ &= \vec{i} \times \frac{\partial \vec{C}}{\partial x} + \vec{j} \times \frac{\partial \vec{C}}{\partial y} + \vec{k} \times \frac{\partial \vec{C}}{\partial z} \end{aligned}$$

$$[\text{ Since, } \vec{i} \times \frac{\partial \vec{C}}{\partial x} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 0 \\ \frac{\partial C_1}{\partial x} & \frac{\partial C_2}{\partial x} & \frac{\partial C_3}{\partial x} \end{vmatrix} = \frac{\partial C_2}{\partial x} \vec{k} - \frac{\partial C_3}{\partial x} \vec{j} \text{ etc.}]$$

$$\begin{aligned} &= \sum \left(\vec{i} \times \frac{\partial \vec{C}}{\partial x} \right) \\ &= \sum \left\{ \vec{i} \times \frac{\partial}{\partial x} (\vec{A} \times \vec{B}) \right\} \\ &= \sum \left[\vec{i} \left\{ \left(\vec{A} \times \frac{\partial \vec{B}}{\partial x} \right) + \left(\frac{\partial \vec{A}}{\partial x} \times \vec{B} \right) \right\} \right] \\ &= \sum \left\{ \vec{i} \times \left(\vec{A} \times \frac{\partial \vec{B}}{\partial x} \right) \right\} + \sum \left[\vec{i} \times \left(\frac{\partial \vec{A}}{\partial x} \times \vec{B} \right) \right] \\ &= \sum \left\{ \left(\vec{i} \cdot \frac{\partial \vec{B}}{\partial x} \right) \vec{A} \right\} - \sum \left\{ (\vec{i} \cdot \vec{A}) \frac{\partial \vec{B}}{\partial x} \right\} + \sum \left\{ (\vec{i} \cdot \vec{B}) \frac{\partial \vec{A}}{\partial x} \right\} - \sum \left\{ \left(\vec{i} \cdot \frac{\partial \vec{A}}{\partial x} \right) \vec{B} \right\} \dots (1) \end{aligned}$$

$$\sum \left\{ \left(\vec{i} \cdot \frac{\partial \vec{B}}{\partial x} \right) \vec{A} \right\} = \left(\frac{\partial B_1}{\partial x} + \frac{\partial B_2}{\partial y} + \frac{\partial B_3}{\partial z} \right) \vec{A} = (\vec{\nabla} \cdot \vec{B}) \vec{A} \dots (2)$$

$$\text{Similarly, } \sum \left\{ \left(\vec{i} \cdot \frac{\partial \vec{A}}{\partial x} \right) \vec{B} \right\} = (\vec{\nabla} \cdot \vec{A}) \vec{B} \dots (3)$$

$$\begin{aligned} \sum \left\{ (\vec{i} \cdot \vec{A}) \frac{\partial \vec{B}}{\partial x} \right\} &= A_1 \frac{\partial \vec{B}}{\partial x} + A_2 \frac{\partial \vec{B}}{\partial y} + A_3 \frac{\partial \vec{B}}{\partial z} \\ &= \left(A_1 \frac{\partial}{\partial x} + A_2 \frac{\partial}{\partial y} + A_3 \frac{\partial}{\partial z} \right) \vec{B} = (\vec{A} \cdot \vec{\nabla}) \vec{B} \dots (4) \end{aligned}$$

$$\text{Similarly, } \sum \left\{ (\vec{i} \cdot \vec{B}) \frac{\partial \vec{A}}{\partial x} \right\} = (\vec{B} \cdot \vec{\nabla}) \vec{A} \dots (5)$$

Using (2),(3),(4) and (5) in (1) we have,

$$\vec{\nabla} \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \vec{\nabla}) \vec{A} - \vec{B} (\vec{\nabla} \cdot \vec{A}) - (\vec{A} \cdot \vec{\nabla}) \vec{B} + \vec{A} (\vec{\nabla} \cdot \vec{B})$$

Exercise 17: Prove that

$$\vec{\nabla} (\vec{A} \cdot \vec{B}) = (\vec{B} \cdot \vec{\nabla}) \vec{A} + (\vec{A} \cdot \vec{\nabla}) \vec{B} + \vec{B} \times (\vec{\nabla} \times \vec{A}) + \vec{A} \times (\vec{\nabla} \times \vec{B})$$

$$\odot \cdot \text{Let } \vec{A} = A_1 \vec{i} + A_2 \vec{j} + A_3 \vec{k}, \vec{B} = B_1 \vec{i} + B_2 \vec{j} + B_3 \vec{k}$$

$$\vec{\nabla} (\vec{A} \cdot \vec{B}) = \sum \left\{ \vec{i} \frac{\partial}{\partial x} (\vec{A} \cdot \vec{B}) \right\} = \sum \left\{ \vec{i} \left(\frac{\partial \vec{A}}{\partial x} \cdot \vec{B} \right) \right\} + \sum \left\{ \vec{i} \left(\vec{A} \cdot \frac{\partial \vec{B}}{\partial x} \right) \right\} \dots \dots \dots (1)$$

$$\begin{aligned} \text{Now, } \vec{B} \times (\vec{\nabla} \times \vec{A}) &= \vec{B} \times \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} \\ &= \vec{B} \times \left\{ \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \vec{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \vec{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \vec{k} \right\} \\ &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ B_1 & B_2 & B_3 \\ \frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} & \frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} & \frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \end{vmatrix} \\ &= \left\{ B_2 \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) - B_3 \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \right\} \vec{i} + \left\{ B_3 \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) - B_1 \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \right\} \vec{j} \\ &\quad + \left\{ B_1 \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) - B_2 \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \right\} \vec{k} \\ &= \left(\frac{\partial A_1}{\partial x} B_1 + \frac{\partial A_2}{\partial x} B_2 + \frac{\partial A_3}{\partial x} B_3 \right) \vec{i} + \left(\frac{\partial A_1}{\partial y} B_1 + \frac{\partial A_2}{\partial y} B_2 + \frac{\partial A_3}{\partial y} B_3 \right) \vec{j} + \\ &\quad \left(\frac{\partial A_1}{\partial z} B_1 + \frac{\partial A_2}{\partial z} B_2 + \frac{\partial A_3}{\partial z} B_3 \right) \vec{k} - \left(B_1 \frac{\partial A_1}{\partial x} + B_2 \frac{\partial A_1}{\partial y} + B_3 \frac{\partial A_1}{\partial z} \right) \vec{i} \\ &\quad - \left(B_1 \frac{\partial A_2}{\partial x} + B_2 \frac{\partial A_2}{\partial y} + B_3 \frac{\partial A_2}{\partial z} \right) \vec{j} - \left(B_1 \frac{\partial A_3}{\partial x} + B_2 \frac{\partial A_3}{\partial y} + B_3 \frac{\partial A_3}{\partial z} \right) \vec{k} \\ &= \left(\frac{\partial \vec{A}}{\partial x} \cdot \vec{B} \right) \vec{i} + \left(\frac{\partial \vec{A}}{\partial y} \cdot \vec{B} \right) \vec{j} + \left(\frac{\partial \vec{A}}{\partial z} \cdot \vec{B} \right) \vec{k} - \left(B_1 \frac{\partial}{\partial x} + B_2 \frac{\partial}{\partial y} + B_3 \frac{\partial}{\partial z} \right) (A_1 \vec{i} + A_2 \vec{j} + A_3 \vec{k}) \\ &= \sum \left(\frac{\partial \vec{A}}{\partial x} \cdot \vec{B} \right) \vec{i} - (\vec{B} \cdot \vec{\nabla}) \vec{A} \\ \therefore \sum \left(\frac{\partial \vec{A}}{\partial x} \cdot \vec{B} \right) \vec{i} &= \vec{B} \times (\vec{\nabla} \times \vec{A}) + (\vec{B} \cdot \vec{\nabla}) \vec{A} \dots \dots \dots (2) \end{aligned}$$

$$\text{Similarly, } \sum \left(\vec{A} \cdot \frac{\partial \vec{B}}{\partial x} \right) \vec{i} = \vec{A} \times (\vec{\nabla} \times \vec{B}) + (\vec{A} \cdot \vec{\nabla}) \vec{B} \dots \dots \dots (3)$$

Using (2),(3) in (1), we have

$$\vec{\nabla} (\vec{A} \cdot \vec{B}) = \vec{B} \times (\vec{\nabla} \times \vec{A}) + (\vec{B} \cdot \vec{\nabla}) \vec{A} + \vec{A} \times (\vec{\nabla} \times \vec{B}) + (\vec{A} \cdot \vec{\nabla}) \vec{B}$$

$$= (\vec{B} \cdot \vec{\nabla}) \vec{A} + (\vec{A} \cdot \vec{\nabla}) \vec{B} + \vec{B} \times (\vec{\nabla} \times \vec{A}) + \vec{A} \times (\vec{\nabla} \times \vec{B})$$

Exercise18: Prove $\vec{\nabla} \left(\frac{F}{G} \right) = \frac{G \vec{\nabla} F - F \vec{\nabla} G}{G^2}$ if $G \neq 0$.

$$\begin{aligned} \odot \cdot \vec{\nabla} \left(\frac{F}{G} \right) &= \left\{ \frac{\partial}{\partial x} \left(\frac{F}{G} \right) \right\} \vec{i} + \left\{ \frac{\partial}{\partial y} \left(\frac{F}{G} \right) \right\} \vec{j} + \left\{ \frac{\partial}{\partial z} \left(\frac{F}{G} \right) \right\} \vec{k} \\ &= \frac{G \frac{\partial F}{\partial x} - F \frac{\partial G}{\partial x}}{G^2} \vec{i} + \frac{G \frac{\partial F}{\partial y} - F \frac{\partial G}{\partial y}}{G^2} \vec{j} + \frac{G \frac{\partial F}{\partial z} - F \frac{\partial G}{\partial z}}{G^2} \vec{k} \\ &= \frac{G \left\{ \left(\frac{\partial F}{\partial x} \right) \vec{i} + \left(\frac{\partial F}{\partial y} \right) \vec{j} + \left(\frac{\partial F}{\partial z} \right) \vec{k} \right\} - F \left\{ \left(\frac{\partial G}{\partial x} \right) \vec{i} + \left(\frac{\partial G}{\partial y} \right) \vec{j} + \left(\frac{\partial G}{\partial z} \right) \vec{k} \right\}}{G^2} \\ &= \frac{G \vec{\nabla} F - F \vec{\nabla} G}{G^2} \end{aligned}$$

Exercise19: Find the constants a and b so that the surface $ax^2 - byz = (a+2)x$ will be orthogonal to the surface $4x^2y + z^3 = 4$ at the point $(1, -1, 2)$.

$\odot \cdot$ The given surfaces are $ax^2 - byz = (a+2)x$ i.e., $ax^2 - (a+2)x - byz = 0$ and $4x^2y + z^3 = 4$.

Let $\phi_1 = ax^2 - (a+2)x - byz$ and $\phi_2 = 4x^2y + z^3$.

Then $\vec{\nabla} \phi_1 = (2ax - a - 2)\vec{i} - bz\vec{j} - by\vec{k}$ and $\vec{\nabla} \phi_2 = 8xy\vec{i} + 4x^2\vec{j} + 3z^2\vec{k}$

At $(1, -1, 2)$, $\vec{\nabla} \phi_1 = (a - 2)\vec{i} - 2b\vec{j} + b\vec{k}$ and $\vec{\nabla} \phi_2 = -8\vec{i} + 4\vec{j} + 12\vec{k}$

The given surfaces will be orthogonal if $\vec{\nabla} \phi_1$ and $\vec{\nabla} \phi_2$ are orthogonal, that is if $\vec{\nabla} \phi_1 \cdot \vec{\nabla} \phi_2 = 0$ or if $-8(a - 2) - 8b + 12b = 0$

or if $-8a + 4b + 16 = 0$ or, if $2a - b = 4$ (1)

Since $(1, -1, 2)$ lies on the surface $ax^2 - (a+2)x - byz = 0$, therefore we

have $a - (a+2) + 2b = 0$ or, $b = 1$ and from (1) we have $a = \frac{5}{2}$

Thus the required values of a, b are $\frac{5}{2}, 1$

Exercise20: Prove $\vec{\nabla}^2 r^n = n(n+1)r^{n-2}$ where n is a constant.

$\odot \cdot$ Since $r = \sqrt{x^2 + y^2 + z^2}$ i.e., $r^2 = x^2 + y^2 + z^2$

Therefore, $\frac{\partial r}{\partial x} = \frac{x}{r}, \frac{\partial r}{\partial y} = \frac{y}{r}, \frac{\partial r}{\partial z} = \frac{z}{r}$

$$\frac{\partial}{\partial x} (r^n) = nr^{n-1} \frac{\partial r}{\partial x} = nr^{n-1} \frac{x}{r} = nr^{n-2} x$$

$$\frac{\partial^2}{\partial x^2} (r^n) = \frac{\partial}{\partial x} (nr^{n-2} x) = n(n-2)r^{n-3} \frac{x}{r} + nr^{n-2} = n(n-2)r^{n-4} x^2 + nr^{n-2}$$

Vector Analysis

Similarly, $\frac{\partial^2}{\partial y^2}(r^n) = n(n-2)r^{n-4}y^2 + nr^{n-2}$

and $\frac{\partial^2}{\partial z^2}(r^n) = n(n-2)r^{n-4}z^2 + nr^{n-2}$

$$\begin{aligned}\text{Therefore } \nabla^2 r^n &= \frac{\partial^2}{\partial x^2}(r^n) + \frac{\partial^2}{\partial y^2}(r^n) + \frac{\partial^2}{\partial z^2}(r^n) \\ &= n(n-2)r^{n-4}(x^2 + y^2 + z^2) + 3nr^{n-2} \\ &= n(n-2)r^{n-2} + 3nr^{n-2} = n(n+1)r^{n-2}\end{aligned}$$

Exercise21: (a) Prove $\nabla^2 f(r) = \frac{d^2 f}{dr^2} + \frac{2}{r} \frac{df}{dr}$. (b) Find $f(r)$ such that $\nabla^2 f(r) = 0$.

☺ . (a) Since $r = \sqrt{x^2 + y^2 + z^2}$ i.e., $r^2 = x^2 + y^2 + z^2$

Therefore, $\frac{\partial r}{\partial x} = \frac{x}{r}, \frac{\partial r}{\partial y} = \frac{y}{r}, \frac{\partial r}{\partial z} = \frac{z}{r}$

$$\frac{\partial}{\partial x}(f(r)) = \frac{df}{dr} \frac{\partial r}{\partial x} = \frac{x}{r} \frac{df}{dr}$$

$$\frac{\partial^2}{\partial x^2}(f(r)) = \frac{\partial}{\partial x} \left(\frac{x}{r} \frac{df}{dr} \right) = \frac{1}{r} \frac{df}{dr} - \frac{x}{r^2} \frac{\partial r}{\partial x} \frac{df}{dr} + \frac{x}{r} \frac{d^2 f}{dr^2} \frac{\partial r}{\partial x} = \frac{1}{r} \frac{df}{dr} - \frac{x^2}{r^3} \frac{df}{dr} + \frac{x^2}{r^2} \frac{d^2 f}{dr^2}$$

$$\text{Similarly, } \frac{\partial^2}{\partial y^2}(f(r)) = \frac{1}{r} \frac{df}{dr} - \frac{y^2}{r^3} \frac{df}{dr} + \frac{y^2}{r^2} \frac{d^2 f}{dr^2}$$

$$\text{and } \frac{\partial^2}{\partial z^2}(f(r)) = \frac{1}{r} \frac{df}{dr} - \frac{z^2}{r^3} \frac{df}{dr} + \frac{z^2}{r^2} \frac{d^2 f}{dr^2}$$

$$\begin{aligned}\nabla^2(f(r)) &= \frac{\partial^2}{\partial x^2}(f(r)) + \frac{\partial^2}{\partial y^2}(f(r)) + \frac{\partial^2}{\partial z^2}(f(r)) \\ &= \frac{3}{r} \frac{df}{dr} - \frac{x^2 + y^2 + z^2}{r^3} \frac{df}{dr} + \frac{x^2 + y^2 + z^2}{r^2} \frac{d^2 f}{dr^2} = \frac{2}{r} \frac{df}{dr} + \frac{d^2 f}{dr^2}\end{aligned}$$

$$(b) \nabla^2 f(r) = 0 \text{ implies } \frac{2}{r} \frac{df}{dr} + \frac{d^2 f}{dr^2} = 0$$

$$\text{or, } \frac{2}{r} \frac{df}{dr} + \frac{d}{dr} \left(\frac{df}{dr} \right) = 0 \text{ or, } \frac{d}{dr} \left(\frac{df}{dr} \right) = -\frac{2}{r} \frac{df}{dr}$$

$$\text{Integrating, } \log \frac{df}{dr} = -2 \log r + \log C = \log \frac{C}{r^2} \text{ i.e., } \frac{df}{dr} = \frac{C}{r^2}$$

Integrating again we have, $f(r) = -\frac{C}{r} + A = A + \frac{B}{r}$, where $A, B(-C)$ are constants.

Exercise22: Find the vorticity of the vector field $\vec{\alpha} = 3y\vec{i} + 4zx\vec{j}$ at the point $(0, 2, 1)$ in the positive direction of the z-axis.

$$\odot \cdot \vec{\nabla} \times \vec{a} = \vec{\nabla} \times (3y\vec{i} + 4zx\vec{j}) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3y & 4zx & 0 \end{vmatrix} = -4x\vec{i} + (4z-3)\vec{k}$$

At (0,2,1), $\vec{\nabla} \times \vec{a} = \vec{k}$. The unit vector along the positive direction of z-axis is \vec{k} . Thus the vorticity along the positive direction of z-axis is $\vec{k} \cdot \vec{k} = 1$

Exercise23: Prove that $\vec{a} \cdot \vec{\nabla} \left(\vec{b} \cdot \vec{\nabla} \left(\frac{1}{r} \right) \right) = \frac{3(\vec{a} \cdot \vec{r})(\vec{b} \cdot \vec{r})}{r^5} - \frac{(\vec{a} \cdot \vec{b})}{r^3}$ and where \vec{a} and \vec{b} are constant vectors and $r = |\vec{r}|$

\odot . Since $r = |\vec{r}| = \sqrt{x^2 + y^2 + z^2}$, therefore $\frac{\partial r}{\partial x} = \frac{x}{r}, \frac{\partial r}{\partial y} = \frac{y}{r}, \frac{\partial r}{\partial z} = \frac{z}{r}$.

$$\begin{aligned} \vec{\nabla} \left(\frac{1}{r} \right) &= \frac{\partial}{\partial x} \left(\frac{1}{r} \right) \vec{i} + \frac{\partial}{\partial y} \left(\frac{1}{r} \right) \vec{j} + \frac{\partial}{\partial z} \left(\frac{1}{r} \right) \vec{k} \\ &= \left(-\frac{1}{r^2} \right) \frac{x}{r} \vec{i} + \left(-\frac{1}{r^2} \right) \frac{y}{r} \vec{j} + \left(-\frac{1}{r^2} \right) \frac{z}{r} \vec{k} \\ &= -\frac{\vec{r}}{r^3} \end{aligned}$$

$$\vec{b} \cdot \vec{\nabla} \left(\frac{1}{r} \right) = -\frac{\vec{b} \cdot \vec{r}}{r^3}$$

$$\begin{aligned} \vec{\nabla} \left(\vec{b} \cdot \vec{\nabla} \left(\frac{1}{r} \right) \right) &= -\frac{\partial}{\partial x} \left(\frac{\vec{b} \cdot \vec{r}}{r^3} \right) \vec{i} - \frac{\partial}{\partial y} \left(\frac{\vec{b} \cdot \vec{r}}{r^3} \right) \vec{j} - \frac{\partial}{\partial z} \left(\frac{\vec{b} \cdot \vec{r}}{r^3} \right) \vec{k} \\ &= -\vec{b} \cdot \left\{ \frac{1}{r^3} \frac{\partial}{\partial x} (\vec{r}) - \frac{3}{r^4} \frac{x}{r} \vec{r} \right\} \vec{i} - \vec{b} \cdot \left\{ \frac{1}{r^3} \frac{\partial}{\partial y} (\vec{r}) - \frac{3}{r^4} \frac{y}{r} \vec{r} \right\} \vec{j} - \vec{b} \cdot \left\{ \frac{1}{r^3} \frac{\partial}{\partial z} (\vec{r}) - \frac{3}{r^4} \frac{z}{r} \vec{r} \right\} \vec{k} \\ &= -\frac{1}{r^3} \left\{ (\vec{b} \cdot \vec{i}) \vec{i} + (\vec{b} \cdot \vec{j}) \vec{j} + (\vec{b} \cdot \vec{k}) \vec{k} \right\} + \frac{3(\vec{b} \cdot \vec{r})}{r^5} (x\vec{i} + y\vec{j} + z\vec{k}) = -\frac{\vec{b}}{r^3} + \frac{3(\vec{b} \cdot \vec{r})}{r^5} \vec{r} \end{aligned}$$

$$\text{Therefore, } \vec{a} \cdot \vec{\nabla} \left(\vec{b} \cdot \vec{\nabla} \left(\frac{1}{r} \right) \right) = -\frac{(\vec{a} \cdot \vec{b})}{r^3} + \frac{3(\vec{a} \cdot \vec{r})(\vec{b} \cdot \vec{r})}{r^5}$$

Exercise24: Prove that $r^n \vec{r}$ is irrotational for all values of n .

\odot . Since $\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$ and $|\vec{r}| = \sqrt{x^2 + y^2 + z^2}$,

therefore $\frac{\partial r}{\partial x} = \frac{x}{r}, \frac{\partial r}{\partial y} = \frac{y}{r}, \frac{\partial r}{\partial z} = \frac{z}{r}$

$$\begin{aligned} \text{Now } \vec{\nabla} \times (r^n \vec{r}) &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ r^n x & r^n y & r^n z \end{vmatrix} \\ &= \left\{ \frac{\partial}{\partial y} (r^n z) - \frac{\partial}{\partial z} (r^n y) \right\} \vec{i} + \left\{ \frac{\partial}{\partial z} (r^n x) - \frac{\partial}{\partial x} (r^n z) \right\} \vec{j} + \left\{ \frac{\partial}{\partial x} (r^n y) - \frac{\partial}{\partial y} (r^n x) \right\} \vec{k} \end{aligned}$$

Vector Analysis

$$= \left(nr^{n-1} z \frac{y}{r} - nr^{n-1} y \frac{z}{r} \right) \vec{i} + \left(nr^{n-1} x \frac{z}{r} - nr^{n-1} z \frac{x}{r} \right) \vec{j} + \left(nr^{n-1} y \frac{x}{r} - nr^{n-1} x \frac{y}{r} \right) \vec{k} = \vec{0}$$

This shows that $r^n \vec{r}$ is irrotational for all values of n

Exercise25: (a) Find the constants a, b, c so that

$\vec{v} = (x + 2y + az)\vec{i} + (bx - 3y - z)\vec{j} + (4x + cy + 2z)\vec{k}$ is irrotational.

(b) Show that \vec{v} can be expressed as the gradient of a scalar function.

$$\odot \cdot (a) \text{ curl } \vec{v} = \vec{\nabla} \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x + 2y + az & bx - 3y - z & 4x + cy + 2z \end{vmatrix}$$

$$= (c+1)\vec{i} + (a-4)\vec{j} + (b-2)\vec{k}$$

This equal to zero vector when $a=4, b=2, c=-1$

and $\vec{v} = (x + 2y + 4z)\vec{i} + (2x - 3y - z)\vec{j} + (4x - y + 2z)\vec{k}$

(b) Assume $\vec{v} = \vec{\nabla}\phi = \frac{\partial\phi}{\partial x}\vec{i} + \frac{\partial\phi}{\partial y}\vec{j} + \frac{\partial\phi}{\partial z}\vec{k}$

Then we have, $\frac{\partial\phi}{\partial x} = x + 2y + 4z$

$$\frac{\partial\phi}{\partial y} = 2x - 3y - z$$

$$\frac{\partial\phi}{\partial z} = 4x - y + 2z$$

$$\begin{aligned} d\phi &= \frac{\partial\phi}{\partial x} dx + \frac{\partial\phi}{\partial y} dy + \frac{\partial\phi}{\partial z} dz \\ &= (x + 2y + 4z)dx + (2x - 3y - z)dy + (4x - y + 2z)dz \\ &= xdx - 3ydy + 2zdz + 2(ydx + xdy) + 4(zdx + xdz) - (zdy + ydz) \\ &= d\left(\frac{x^2}{2} - \frac{3y^2}{2} + z^2 + 2xy + 4zx - yz\right) \end{aligned}$$

$$\therefore \phi = \frac{x^2}{2} - \frac{3y^2}{2} + z^2 + 2xy + 4zx - yz + c, \text{ where } c \text{ is a constant.}$$

Exercises:

1. Define curl and divergence of a vector quantity.
2. Find the curl and divergence of the vector $\vec{v} = \frac{\hat{r}}{r}$, where \hat{r} is the unit vector in the direction of \vec{r} and $r = |\vec{r}|$
3. Find the maximum value of the directional derivative of $\phi = x^2 + z^2 - y^2$ at the point $(1, 3, 2)$. Find also the direction in which it occurs.
4. If \vec{A} and \vec{B} are irrotational, prove that $\vec{A} \times \vec{B}$ is solenoidal.
5. If $f(r)$ be differentiable, prove that $f(r) \vec{r}$ is irrotational.

6. If $\vec{\nabla} \cdot \vec{E} = 0$, $\vec{\nabla} \cdot \vec{H} = 0$, $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{H}}{\partial t}$, $\vec{\nabla} \times \vec{H} = \frac{\partial \vec{E}}{\partial t}$, show that \vec{E} and

$$\vec{H} \text{ satisfy } \vec{\nabla}^2 u = \frac{\partial^2 u}{\partial t^2}$$

7. Show that $\vec{A} = (6xy + z^3)\vec{i} + (3x^2 - z)\vec{j} + (3xz^2 - y)\vec{k}$ is irrotational.

Find ϕ such that $\vec{A} = \vec{\nabla}\phi$

8. Show that $\vec{E} = \frac{\vec{r}}{r^2}$ is irrotational. Find ϕ such that $\vec{E} = -\vec{\nabla}\phi$ and such that $\phi(a) = 0$ where $a > 0$.