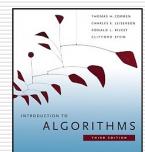
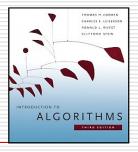
# Introduction to Algorithms (2<sup>nd</sup> edition)



by Cormen, Leiserson, Rivest & Stein

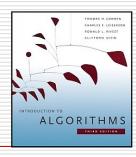
Chapter 2: Getting Started

(slides enhanced by N. Adlai A. DePano)



#### Overview

- Aims to familiarize us with framework used throughout text
- Examines alternate solutions to the sorting problem presented in Ch. 1
- Specify algorithms to solve problem
- Argue for their correctness
- Analyze running time, introducing notation for asymptotic behavior
- Introduce divide-and-conquer algorithm technique



#### The Sorting Problem

**Input:** A sequence of *n* numbers  $[a_1, a_2, ..., a_n]$ .

**Output:** A permutation or reordering  $[a'_1, a'_2, \dots, a'_n]$  of the input

sequence such that  $a'_1 \le a'_2 \le \dots \le a'_n$ .

An instance of the Sorting Problem:

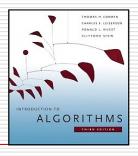
**Input:** A sequence of 6 number [31, 41, 59, 26, 41, 58].

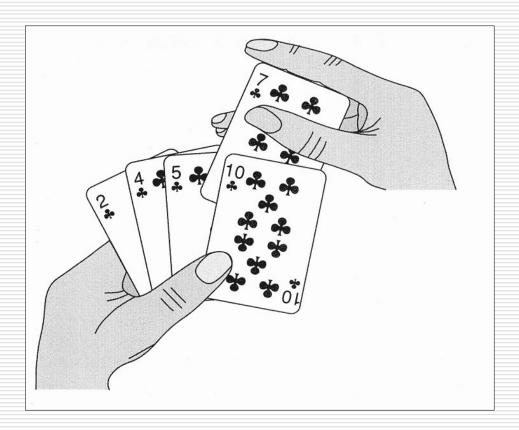
Expected output for given instance:

**Expected** 

**Output:** The permutation of the input [26, 31, 41, 41, 58, 59].

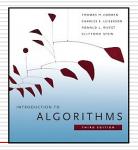
#### **Insertion Sort**

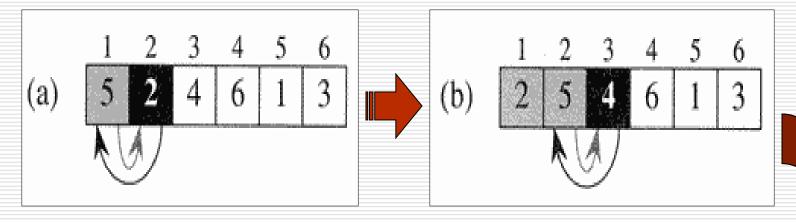


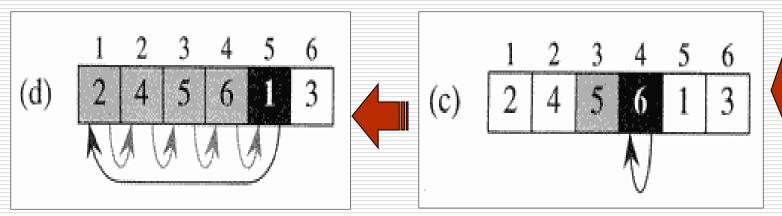


The main idea ...

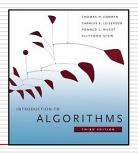
#### Insertion Sort (cont.)

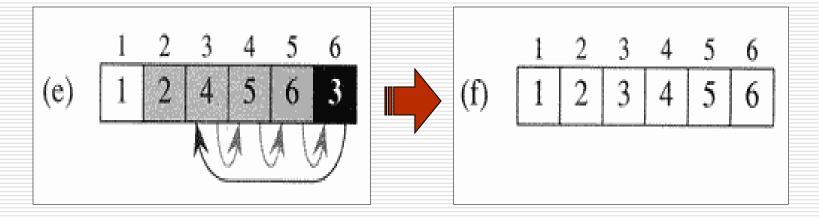


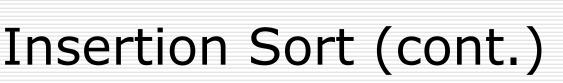


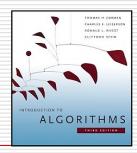


#### Insertion Sort (cont.)









The algorithm ...

```
INSERTION-SORT (A, n)

for j = 2 to n

key = A[j]

// Insert A[j] into the sorted sequence A[1 ... j - 1].

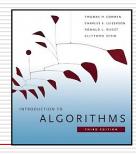
i = j - 1

while i > 0 and A[i] > key

A[i + 1] = A[i]

i = i - 1

A[i + 1] = key
```

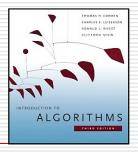


#### Loop Invariant

 $\square$  Property of A[1..j-1]

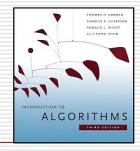
At the start of each iteration of the **for** loop of lines 1-8, the subarray A[1..j-1] consists of the elements originally in A[1..j-1] but in sorted order.

- Need to establish the following re invariant:
  - Initialization: true prior to first iteration
  - Maintenance: if true before iteration, remains true after iteration
  - Termination: at loop termination, invariant implies correctness of algorithm



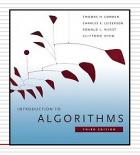
#### **Analyzing Algorithms**

- Has come to mean predicting the resources that the algorithm requires
- Usually computational time is resource of primary importance
- Aims to identify best choice among several alternate algorithms
- Requires an agreed-upon "model" of computation
- Shall use a generic, one-processor, random-access machine (RAM) model of computation



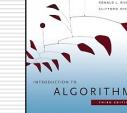
#### Random-Access Machine

- Instructions are executed one after another (no concurrency)
- Admits commonly found instructions in "real" computers, data movement operations, control mechanism
- Uses common data types (integer and float)
- Other properties discussed as needed
- Care must be taken since model of computation has great implications on resulting analysis



#### Analysis of Insertion Sort

- Time resource requirement depends on input size
- Input size depends on problem being studied; frequently, this is the number of items in the input
- Running time: number of primitive operations or "steps" executed for an input
- Assume constant amount of time for each line of pseudocode



#### Analysis of Insertion Sort

Time efficiency analysis ...

```
INSERTION-SORT (A, n)
                                                                  cost times
for j = 2 to n
                                                                 c_2 n-1
    key = A[j]
                                                                  0 n-1
     // Insert A[j] into the sorted sequence A[1...j-1].
    i = j - 1
                                                                  c_4 \quad n-1
                                                                 c_5 \qquad \sum_{j=2}^{n} t_j \\ c_6 \qquad \sum_{j=2}^{n} (t_j - 1)
    while i > 0 and A[i] > key
         A[i+1] = A[i]
                                                                  c_7 \sum_{j=2}^{n} (t_j - 1)
          i = i - 1
    A[i+1] = key
                                                                 c_8 \quad n-1
```

# THOUAS A COMEN CONTROL OF THE STATE OF THE S

#### Best Case Analysis

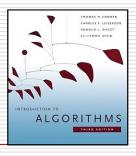
- Least amount of (time) resource ever needed by algorithm
- Achieved when incoming list is already sorted in increasing order
- Inner loop is never iterated
- Cost is given by:

$$T(n) = c_1 n + c_2 (n-1) + c_4 (n-1) + c_5 (n-1) + c_8 (n-1)$$

$$= (c_1 + c_2 + c_4 + c_5 + c_8) n - (c_2 + c_4 + c_5 + c_8)$$

$$= an + b$$

 $\square$  Linear function of n



#### Worst Case Analysis

- Greatest amount of (time) resource ever needed by algorithm
- Achieved when incoming list is in reverse order
- Inner loop is iterated the maximum number of times, i.e.,  $t_i = j$
- Therefore, the cost will be:

$$T(n) = c_1 n + c_2 (n-1) + c_4 (n-1) + c_5 ((n(n+1)/2) - 1) + c_6 (n(n-1)/2)$$

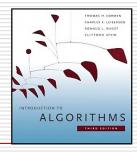
$$+ c_7 (n(n-1)/2) + c_8 (n-1)$$

$$= (c_5/2 + c_6/2 + c_7/2) n^2 + (c_1 + c_2 + c_4 + c_5/2 - c_6/2 - c_7/2 + c_8) n$$

$$- (c_2 + c_4 + c_5 + c_8)$$

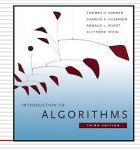
$$= an^2 + bn + c$$

Quadratic function of n



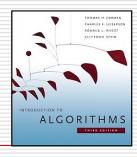
#### Future Analyses

- For the most part, subsequent analyses will focus on:
  - Worst-case running time
    - Upper bound on running time for any input
  - Average-case analysis
    - Expected running time over all inputs
- Often, worst-case and average-case have the same "order of growth"



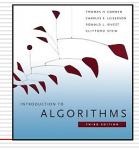
#### Order of Growth

- Simplifying abstraction: interested in rate of growth or order of growth of the running time of the algorithm
- Allows us to compare algorithms without worrying about implementation performance
- Usually only highest order term without constant coefficient is taken
- Uses "theta" notation
  - Best case of insertion sort is  $\Theta(n)$
  - Worst case of insertion sort is  $\Theta(n^2)$



## Designing Algorithms

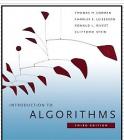
- Several techniques/patterns for designing algorithms exist
- Incremental approach: builds the solution one component at a time
- Divide-and-conquer approach: breaks original problem into several smaller instances of the same problem
  - Results in recursive algorithms
  - Easy to analyze complexity using proven techniques



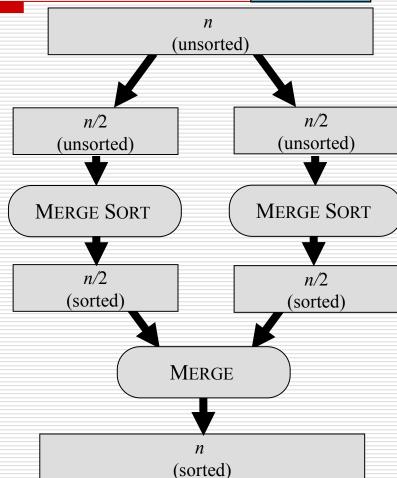
#### Divide-and-Conquer

- ☐ Technique (or paradigm) involves:
  - "Divide" stage: Express problem in terms of several smaller subproblems
  - "Conquer" stage: Solve the smaller subproblems by applying solution recursively – smallest subproblems may be solved directly
  - "Combine" stage: Construct the solution to original problem from solutions of smaller subproblem

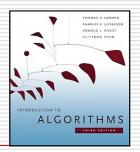


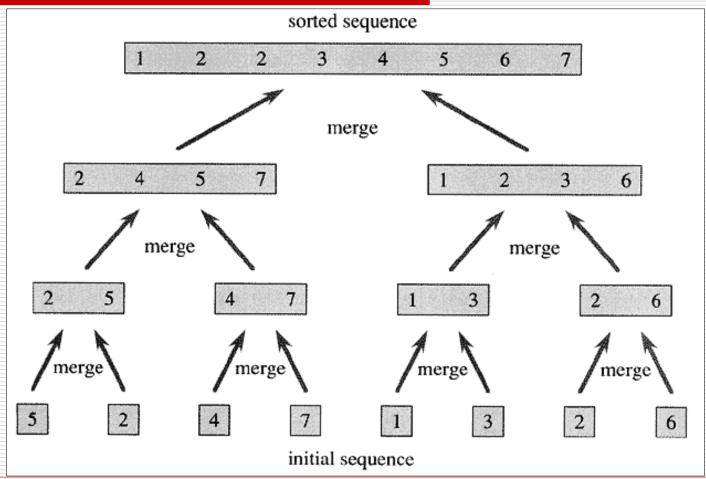


- □ Divide stage: Split the nelement sequence into two subsequences of n/2 elements each
- Conquer stage:
   Recursively sort the two subsequences
- Combine stage: Merge the two sorted subsequences into one sorted sequence (the solution)

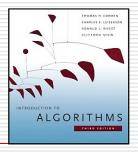


# Merging Sorted Sequences



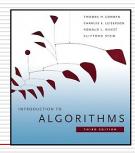


#### Merging Sorted Sequences



```
MERGE(A, p, q, r)
          n_1 = q - p + 1
\Theta(1)
          n_2 = r - q
          let L[1...n_1 + 1] and R[1...n_2 + 1] be new arrays
          for i = 1 to n_1
\Theta(n)
               L[i] = A[p+i-1]
          for j = 1 to n_2
               R[j] = A[q+j]
          L[n_1+1]=\infty
           R[n_2+1]=\infty
\Theta(1)
           i = 1
          \mathbf{for} \ k = p \ \mathbf{to} \ r
               if L[i] \leq R[j]
                    A[k] = L[i]
\Theta(n)
                    i = i + 1
               else A[k] = R[j]
                    j = j + 1
```

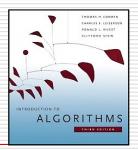
- Combines the sorted subarrays A[p..q] and A[q+1..r] into one sorted array A[p..r]
- Makes use of two working arrays L and R which initially hold copies of the two subarrays
- Makes use of sentinel
   value (∞) as last element
   to simplify logic



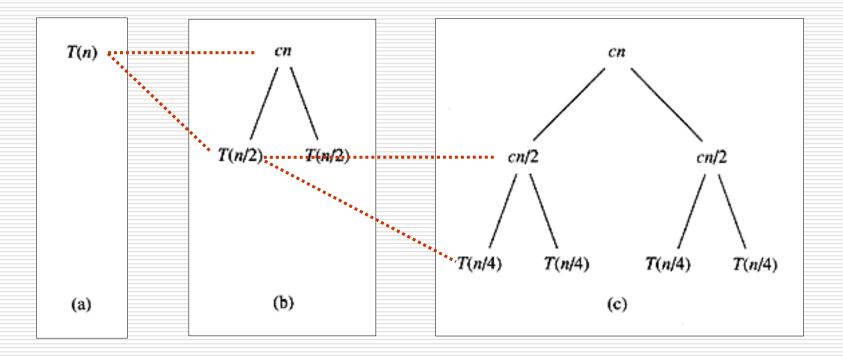
#### Merge Sort Algorithm

$$T(n) = 2T(n/2) + \Theta(n)$$

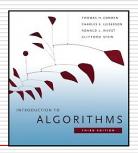
#### Analysis of Merge Sort

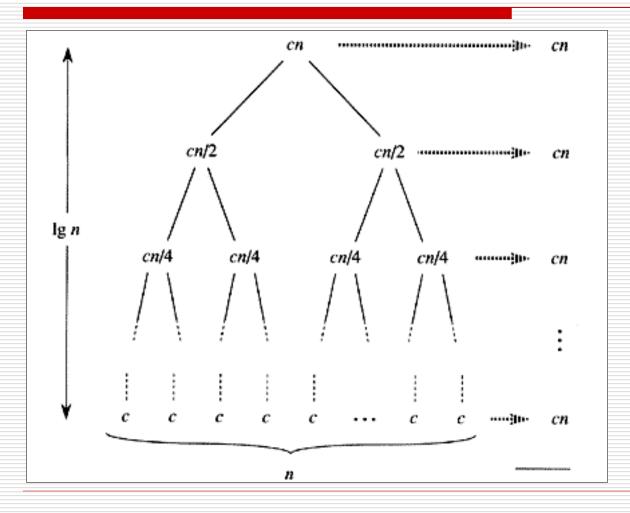


Analysis of recursive calls ...



### Analysis of Merge Sort





$$T(n) = cn(\lg n + 1)$$
$$= cn\lg n + cn$$

$$T(n)$$
 is  $\Theta(n \lg n)$