Refactoring the nls() function in R

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Abstract

This article reports the particular activities of our Google Summer of Code project "Improvements to nls()" that relate to R code for that function, which is intended for the estimation of models written as a formula that has at least one parameter that is not estimable via solving a set of linear equations. A companion document "Variety in Nonlinear Least Squares Codes" presents an overview of methods for the problem which takes a much wider view of the problem of minimizing a function that can be written as a sum of squared terms.

Our work has not fully addressed all the issues that we would like to see resolved, but we believe we have made sufficient progress to demonstrate that there are worthwhile improvements that can be made to the R function nls(). An important overall consideration in our work has been the maintainability of the code

base that supports the nls() functionality, as we believe that the existing code makes maintenance and improvement very difficult.

The existing nls() function: strengths and shortcomings

nls() is the tool in base R (the distributed software package from https://cran.r-project.org) for estimating nonlinear statistical models. The function was developed mainly in the 1980s and 1990s by Doug Bates et al., initially for S (https://en.wikipedia.org/wiki/S_%28programming_language%29). The ideas spring primarily from the book by D. M. Bates and Watts (1988).

The nls() function has a remarkable and quite comprehensive set of capabilities for estimating nonlinear models that are expressed as formulas. In particular, we note that it - handles formulas that include R functions - allows data to be subset - permits parameters to be indexed over a set of related data - produces measures of variability (i.e., standard error estimates) for the estimated parameters - has related profiling capabilities for exploring the likelihood surface as parameters are changed

With such a range of features and a long history, it is not surprising that code has become untidy and overly patched. It is, to our mind, essentially unmaintainable. Moreover, its underlying methods can and should be improved. Let us review some of the issues. We will then propose corrective actions, some of which we have carried out.

Issue: Convergence and termination tests

Within the standard documentation (manual or ".Rd" file) nls() warns

The default settings of nls generally fail on artificial "zero-residual" data problems.

The nls function uses a relative-offset convergence criterion that compares the numerical imprecision at the current parameter estimates to the residual sum-of-squares. This performs well on data of the form

$$y = f(x, \theta) + eps$$

(with var(eps) > 0). It fails to indicate convergence on data of the form

$$y = f(x, \theta)$$

because the criterion amounts to comparing two components of the round-off error. To avoid a zero-divide in computing the convergence testing value, a positive constant scaleOffset should be added to the denominator sum-of-squares; it is set in control; this does not yet apply to algorithm = "port."

It turns out that this issue can be quite easily resolved. The key "convergence test" – more properly a "termination test" for the **program** rather than testing for convergence of the underlying **algorithm** – is the Relative Offset Convergence Criterion (see Douglas M. Bates and Watts (1981)). This works by projecting the proposed step in the parameter vector on the gradient and estimating how much the sum of squares loss function will decrease. To avoid scale issues, we use the current size of the loss function as a measure and divide by it. When we have "converged," the estimated decrease is very small, as usually is its ratio to the sum of squares. However, in some cases we have the possibility of an exact fit and the sum of squares is (almost) zero and we get the possibility of a zero-divide failure.

The issue is easily resolved by adding a small quantity to the loss function. To preserve legacy behaviour, in 2021, one of us (JN) proposed that nls.control() have an additional parameter scaleOffset with a default value of zero for legacy behaviour. Setting it to a small number – 1.0 is a reasonable choice – allows small-residual problems (i.e., near-exact fits) to be dealt with easily. We call this the safeguarded relative offset convergence criterion.

We are pleased to report that this improvement is in the R-devel distributed code at time of writing and will migrate to the base R distribution when updated.

Example of a small-residual problem

```
rm(list=ls())
t <- -10:10
y <- 100/(1+.1*exp(-0.51*t))
lform < -y \sim a/(1+b*exp(-c*t))
ldata<-data.frame(t=t, y=y)</pre>
plot(t,y)
lstartbad < -c(a=1, b=1, c=1)
lstart2 < -c(a=100, b=10, c=1)
nlsr::nlxb(lform, data=ldata, start=lstart2)
nls(lform, data=ldata, start=lstart2, trace=TRUE)
# Fix with scaleOffset
nls(lform, data=ldata, start=lstart2, trace=TRUE, control=list(scaleOffset=1.0))
sessionInfo()
Edited output of running this function follows:
> rm(list=ls())
> t <- -10:10
> y <- 100/(1+.1*exp(-0.51*t))
> 1 form <-y^a/(1+b*exp(-c*t))
> ldata<-data.frame(t=t, y=y)</pre>
> plot(t,y)
> lstart2<-c(a=100, b=10, c=1)
> nlsr::nlxb(lform, data=ldata, start=lstart2)
nlsr object: x
residual sumsquares = 1.007e-19 on 21 observations
    after 13
                 Jacobian and 19 function evaluations
  name
                  coeff
                                  SE
                                            tstat
                                                                  gradient
                                                                              JSingval
                                                       pval
                      100
                              2.679e-11 3.732e+12 1.863e-216
                                                                 -6.425e-11
                                                                                   626.6
a
                      0.1
                               3.78e-13 2.646e+11 9.125e-196
                                                                 -3.393e-08
                                                                                   112.3
b
                    0.51
                                6.9e-13 7.391e+11 8.494e-204
                                                                   1.503e-08
                                                                                   2.791
# Note that this has succeeded. The test in nlsr recognizes small residual problems.
> nls(lform, data=ldata, start=lstart2, trace=TRUE)
          (1.08e+00): par = (100 10 1)
40346.
11622.
          (2.93e+00): par = (101.47 \ 0.49449 \ 0.71685)
          (1.08e+01): par = (102.23 \ 0.38062 \ 0.52792)
5638.0
          (1.04e+01): par = (102.16 \ 0.22422 \ 0.41935)
642.08
97.712
          (1.79e+01): par = (100.7 \ 0.14774 \ 0.45239)
22.250
          (1.78e+02): par = (99.803 \ 0.093868 \ 0.50492)
0.025789 (1.33e+03): par = (100.01 0.10017 0.50916)
6.0571e-08 (7.96e+05): par = (100 0.1 0.51)
4.7017e-19 (1.86e+04): par = (100 0.1 0.51)
1.2440e-27 (5.71e-01): par = (100 0.1 0.51)
```

```
1.2440e-27 (5.71e-01): par = (100 0.1 0.51)
Error in nls(lform, data = ldata, start = lstart2, trace = TRUE) :
 number of iterations exceeded maximum of 50
> nls(lform, data=ldata, start=lstart2, trace=TRUE, control=list(scaleOffset=1.0))
40346.
            (1.08e+00): par = (100 10 1)
11622.
            (2.91e+00): par = (101.47 \ 0.49449 \ 0.71685)
5638.0
            (9.23e+00): par = (102.23 \ 0.38062 \ 0.52792)
642.08
            (5.17e+00): par = (102.16 \ 0.22422 \ 0.41935)
            (2.31e+00): par = (100.7 \ 0.14774 \ 0.45239)
97.712
22.250
            (1.11e+00): par = (99.803 \ 0.093868 \ 0.50492)
            (3.79e-02): par = (100.01 \ 0.10017 \ 0.50916)
0.025789
6.0571e-08 (5.80e-05): par = (100 0.1 0.51)
4.7017e-19 (1.62e-10): par = (100 0.1 0.51)
Nonlinear regression model
  model: y \sim a/(1 + b * exp(-c * t))
   data: ldata
            h
     а
100.00
         0.10
                0.51
residual sum-of-squares: 4.7e-19
```

```
Number of iterations to convergence: 8
Achieved convergence tolerance: 1.62e-10
> sessionInfo()
R version 4.1.0 (2021-05-18)
Platform: x86_64-pc-linux-gnu (64-bit)
Running under: Linux Mint 20.2
```

More general termination tests

The single convergence criterion of nls() leaves out some possibilities that could be useful for some problems. The package nlsr (John C. Nash and Murdoch (2019)) already offers both the safeguarded relative offset test (roffset) as well as a small sum of squares test (smallsstest) that compares the latest evaluated sum of squared (weighted) residuals to a very small multiple of the initial sum of squares. The multiple uses a control setting offset which defaults to 100.0 and we compute the 4th power of the machine epsilon times this offset.

```
epstol<-100*.Machine$double.eps
e4 <- epstol^4
e4</pre>
```

```
## [1] 2.430865e-55
```

We do note that nls() stops after maxiter "iterations." However, for almost all iterative algorithms, the meaning of "iteration" requires careful examination of the code. Instead, we prefer to record the number of times the residuals or the jacobian have been computed and put upper limits on these. Our codes exit (terminate) when these limits are reached. Generally we prefer larger limits than the default maxiter=50 of nls(), but that may simply reflect our history of dealing with more difficult problems as we are the tool-makers users consult when things go wrong.

Issue: Failure when Jacobian is computationally singular

This is the infamous "singular gradient" termination. A Google search of

```
R nls "singular gradient"
```

gets over 4000 hits that are spread over the years. In some cases this is due to failure of the simple finite difference approximation of the Jacobian in the numericDeriv() function that is a part of nls(). nlsr can use analytic derivatives, and we can import this functionality to the nls() code as an improvement. See below in the section Jacobian computation.

However, the more common source of the issue is that the Jacobian is very close to singular for some values of the model parameters. In such cases we need to find an alternative algorithm to the Gauss-Newton iteration of nls(). The most common work-around is the Levenberg-Marquardt stabilization (Marquardt (1963), Levenberg1944, jn77ima). Versions of this have been implemented in packages minpack.lm and nlsr. and we have preliminary versions of an nls replacement that can incorporate a version of the Levenberg-Marquardt stabilization. (There are some issues of integration with other code structures and of complexity of the computations that suggest we should use a simplified LM stabilization.)

Issue: Jacobian computation

nls(), with the numericDeriv() function, computes the Jacobian as the "gradient" attribute of the residual vector. This is implemented as a mix of R and C code, but we have created a rather more compact version entirely in R in this Google Summer of Code project. See the document **DerivsNLS.pdf**.

```
# File: badJ2.R
# A problem illustrating poor numeric Jacobian
form<-y ~ 10*a*(8+b*log(1-0.049*c*x)) # the model formula</pre>
```

```
# This model uses log near a small argument, which skirts the dangerous
\# value of 0. The parameters a, b, c could all be 1 "safely" as a start.
x<-3*(1:10) # define x
np<-length(x)</pre>
a<-1.01
b<-.9
eps<-1e-6
c<-1/(max(x)*.049)-eps
cat("c =",c,"\n")
## c = 0.6802711
y \leftarrow 10*a*(8+b*log(1-0.049*c*x))+0.2*runif(np) # compute a y
df<-data.frame(x=x, y=y)</pre>
plot(x,y) # for information
                            0
                                   0
                                           0
                                                   0
                                                                  0
     9
                                                                          0
     0
                                                                                  0
                 5
                              10
                                          15
                                                       20
                                                                    25
                                                                                 30
                                               Χ
st<-c(a=1, b=1,c=c) # set the "default" starting vector
nO<-try(nls(form, start=st, data=df)) # and watch the fun as this fails.
summary(n0)
##
## Formula: y \sim 10 * a * (8 + b * log(1 - 0.049 * c * x))
##
## Parameters:
      Estimate Std. Error
                            t value Pr(>|t|)
## a 1.011e+00 3.460e-04 2.923e+03
                                       <2e-16 ***
## b 8.989e-01 2.228e-03 4.035e+02
                                       <2e-16 ***
## c 6.803e-01 3.498e-08 1.945e+07
                                       <2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
\#\# Residual standard error: 0.05069 on 7 degrees of freedom
##
```

```
## Number of iterations to convergence: 3
## Achieved convergence tolerance: 1.167e-06
library(nlsr) # but this will work
n1<-nlxb(form, start=st, data=df)</pre>
n1
## nlsr object: x
## residual sumsquares = 0.017983 on 10 observations
##
       after 4
                  Jacobian and 5 function evaluations
##
                     coeff
                                    SE
                                                        pval
                                                                  gradient
                                                                              JSingval
## a
                     1.0115
                                 0.000346
                                                2923 1.448e-22
                                                                                9017122
                                                                  1.033e-08
## b
                   0.898877
                                 0.002228
                                                                  3.449e-08
                                                                                  218.5
                                               403.5 1.516e-16
## c
                                            19348537 2.602e-49
                   0.680271
                                3.516e-08
                                                                   0.002315
                                                                                   22.6
coef(n1)-coef(n0)
##
## -2.6370e-12 -4.1497e-11 -1.6764e-14
## attr(,"pkgname")
## [1] "nlsr"
jmod<-model2rjfun(form, pvec=st,data=data.frame(x=x, y=y)) # extract the model
Jatst<-jmod(st) # compute this at the start from package nlsr</pre>
Jatst<-attr(Jatst, "gradient") # and extract the Jacobian</pre>
# Now try to compute Jacobian produced by nls()
env<-environment(form) # We need the environment of the formula
eform<-eval(form, envir=env) # and the evaluated expression
localdata<-list2env(as.list(st), parent=env)</pre>
jnlsatst<-numericDeriv(form[[3L]], theta=names(st), rho=localdata)</pre>
Jnls<-attr(jnlsatst, "gradient")</pre>
Jnls # from nls()
##
            [,1]
                      [,2]
                                  [,3]
##
  [1,] 78.946
                 -1.0536 -1.6333e+00
## [2,] 77.769
                 -2.2314 -3.6750e+00
## [3,] 76.433
                  -3.5667 -6.3000e+00
## [4,] 74.892
                 -5.1082 -9.8000e+00
## [5,] 73.069
                  -6.9315 -1.4700e+01
## [6,] 70.837
                  -9.1629 -2.2050e+01
## [7,] 67.960 -12.0397 -3.4300e+01
## [8,] 63.906 -16.0943 -5.8800e+01
## [9,] 56.974 -23.0257 -1.3230e+02
## [10,] -54.302 -134.3025 -1.0051e+07
Jatst # from nlsr -- analytic derivative
##
              а
                         b
                                     С
##
  [1,] 78.946
                 -1.0536 -1.6333e+00
## [2,] 77.769
                  -2.2314 -3.6750e+00
## [3,] 76.433
                   -3.5667 -6.3000e+00
## [4,] 74.892
                  -5.1082 -9.8000e+00
## [5,] 73.069
                  -6.9315 -1.4700e+01
## [6,] 70.837
                  -9.1629 -2.2050e+01
## [7,] 67.960 -12.0397 -3.4300e+01
## [8,] 63.906 -16.0943 -5.8800e+01
```

```
## [9,] 56.974 -23.0257 -1.3230e+02
## [10,] -54.302 -134.3025 -1.0000e+07
max(abs(Jnls-Jatst))
## [1] 51029
svd(Jnls)$d
## [1] 1.0051e+07 2.1596e+02 2.2607e+01
svd(Jatst)$d
## [1] 1.0000e+07 2.1596e+02 2.2607e+01
# Even start at the solution?
nOc<-try(nls(form, start=coef(n1), data=data.frame(x=x, y=y), trace=TRUE))
## 0.017983 (5.64e-09): par = (1.0115 0.89888 0.68027)
summary(n0c)
##
## Formula: y \sim 10 * a * (8 + b * log(1 - 0.049 * c * x))
## Parameters:
   Estimate Std. Error t value Pr(>|t|)
## a 1.01e+00 3.46e-04
                            2923
                                   <2e-16 ***
## b 8.99e-01 2.23e-03
                            404
                                   <2e-16 ***
## c 6.80e-01 3.50e-08 19446458
                                   <2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 0.0507 on 7 degrees of freedom
## Number of iterations to convergence: 0
## Achieved convergence tolerance: 5.64e-09
## attempts with nlsi
library(nlsj)
##
## Attaching package: 'nlsj'
## The following object is masked from 'package:stats':
##
##
      numericDeriv
nOjn<-try(nlsj(form, start=st, data=df, trace=TRUE,control=nlsj.control(derivmeth="numericDeriv")))
## Warning in nlsj(form, start = st, data = df, trace = TRUE, control =
## nlsj.control(derivmeth = "numericDeriv")): Forcing numericDeriv
## nlsj: Using default algorithm
## lhs has just the variable y
## 1 / 2 203.95 :(1 1 0.68027 ) rofftest= 106.49
## fac before = 1 after= 1
## fac= 1 ssnew=0.042144
\#\# < 2 / 3 0.042144 :(1.0115 0.89771 0.68027 ) rofftest= 1.1591
## fac before = 1 after= 1
## fac= 1 ssnew=0.017983
```

```
## < 3 / 4 0.017983 :(1.0115 0.89888 0.68027 ) rofftest= 0.00023057
## fac before = 1 after= 1
## fac= 1 ssnew=0.017983
## < 4 / 5 0.017983 :(1.0115 0.89888 0.68027 ) rofftest= 1.1675e-06
summary(n0jn)
##
## Formula: y \sim 10 * a * (8 + b * log(1 - 0.049 * c * x))
## Parameters:
## Estimate Std. Error t value Pr(>|t|)
## a 1.01e+00 3.46e-04
                            2923 <2e-16 ***
## b 8.99e-01 2.23e-03
                          404
                                  <2e-16 ***
## c 6.80e-01 3.50e-08 19446458
                                  <2e-16 ***
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 0.0507 on 7 degrees of freedom
## [1] TRUE
## attr(,"cmsg")
## [1] "Termination msg: Relative offset less than 1e-05 &&"
## attr(,"ctol")
## [1] 1.1675e-06
## attr(,"nres")
## [1] 4
## attr(,"njac")
## [1] 5
# tmp<-readline("more.")</pre>
n0ja<-try(nlsj(form, start=st, data=df, trace=TRUE,control=nlsj.control(derivmeth="default")))
## nlsj: Using default algorithm
## lhs has just the variable y
## 1 / 2 203.95 :(1 1 0.68027 ) rofftest= 106.49
## fac before = 1 after= 1
## fac= 1 ssnew=0.042248
## < 2 / 3 0.042248 :(1.0115 0.89771 0.68027 ) rofftest= 1.1616
## fac before = 1 after= 1
## fac= 1 ssnew=0.017983
## < 3 / 4 0.017983 :(1.0115 0.89888 0.68027 ) rofftest= 4.7825e-05
## fac before = 1 after= 1
## fac= 1 ssnew=0.017983
## < 4 / 5 0.017983 :(1.0115 0.89888 0.68027 ) rofftest= 7.4741e-09
summary(n0ja)
##
## Formula: y \sim 10 * a * (8 + b * log(1 - 0.049 * c * x))
##
## Parameters:
## Estimate Std. Error t value Pr(>|t|)
## a 1.01e+00 3.46e-04
                            2923 <2e-16 ***
## b 8.99e-01 2.23e-03
                            404
                                  <2e-16 ***
## c 6.80e-01 3.52e-08 19348536 <2e-16 ***
## ---
```

```
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.0507 on 7 degrees of freedom
## [1] TRUE
## attr(,"cmsg")
## [1] "Termination msg: Relative offset less than 1e-05 &&"
## attr(,"ctol")
## [1] 7.4741e-09
## attr(,"nres")
## [1] 4
## attr(,"njac")
## [1] 5
```

It should be noted that the selfStart models in the ./src/library/stats/R/zzModels.R file provide the Jacobian in the "gradient" attribute of the "one-sided" formula that defines each model, and these Jacobians are the analytic forms. The nls() function, after computing the "right hand side" or rhs of the residual, then checks to see if the "gradient" attribute is defined, and, if not, uses numericDeriv to compute a Jacobian into that attribute. This code is within the nlsModel() or nlsModel.pliner() functions.

Issue: Subsetting

nls() accepts an argument subset. Unfortunately, this acts through the mediation of model.frame and is not clearly obvious in the source code files /src/library/stats/R/nls.R and /src/library/stats/src/nls.C.

- implementation via weights
- implementation via model.frame
- other concerns

Issue: na.action

na.action is an argument to the nls() function, but it does not appear in obviously in the source code ...

Issue: model frame

model is an argument to the nls() function, but it does not appear obviously in the source code ...

Issue: documentation of results

We have noticed that there are some important issues relating to the documentation of residuals, fits, and related objects computed by R modeling functions.

The functions resid() (an alias for residuals()) and fitted() and lhs() are UNWEIGHTED. But if we return ans from nls() or minpack.lm::nlsLM or our new nlsj (interim package), then ans\$m\$resid() is WEIGHTED.

Issue: sources of data

nls() can be called without specifying the data argument. In this case, it will search in the available environments (i.e., workspaces) for suitable data objects. We do NOT like this approach. R allows users to leave many objects in the default (.GlobalEnv) workspace. Moreover, users have to actively suppress saving this workspace (.RData) on exit, and any such file in the path when R is launched will be loaded.

Nevertheless, to provide compatible behaviour with nls(), we will need to ensure that equivalent behaviour is guaranteed.

Issue: missing start vector and self-starting models

Nonlinear estimation algorithms are almost all iterative and need a set of starting parameters. nls() offers a special class of modeling formulae called **selfStart** models. There are a number of these in base R (see list below) and others in R packages such as CRAN package nlraa (Miguez (2021)). Unfortunately, the structure of the programming of these is such that the methods by which initial parameters are computed is entangled with the particularities of the nls() code. Though there is a getInitial() function, this is not easy to use to simply compute the initial parameter estimates.

The following example shows how the SSlogis selfStart function can generate a set of initial parameters for a 3-parameter logistic curve. The form used by SSlogis is

```
y ~ Asym/(1+exp((xmid-tt)/scal))
```

The example shows how these starting parameters can be transformed to those of another form of the model, namely,

```
y \sim b1/(1 + b2*exp(-b3*t))
weed <- c(5.308, 7.24, 9.638, 12.866, 17.069, 23.192, 31.443,
          38.558, 50.156, 62.948, 75.995, 91.972)
tt <- 1:12
NLSformula0 <- y ~ b1/(1+b2*exp(-b3*tt))
NLSformula <- y ~ SSlogis(tt, Asym, xmid, scal)
NLStestdata <- data.frame(y=weed, tt=tt) # should we use standard name?
NLSstart <- getInitial(NLSformula, NLStestdata)</pre>
s0 <- getInitial(NLSformula, NLStestdata)
print(s0)
       Asym
                xmid
                         scal
## 196.1862 12.4173
                       3.1891
library(nlsj)
s1<-list(b1=s0[1], b2=exp(s0[2]/s0[3]), b3=1/s0[3])
print(as.numeric(s1))
## [1] 196.18624 49.09163
                             0.31357
hobblog<-nlsj(NLSformula0, data=NLStestdata, start=s1)
## Warning in nlsj(NLSformulaO, data = NLStestdata, start = s1): Forcing
## numericDeriv
hobblog
## Nonlinear regression model
     model: y \sim b1/(1 + b2 * exp(-b3 * tt))
##
      data: NULL
##
##
        b1
                b2
                        b3
## 196.186 49.092
                     0.314
## residual sum-of-squares: 2.59
## [1] TRUE
## attr(,"cmsg")
## [1] "Termination msg: Relative offset less than 1e-05 &&"
## attr(,"ctol")
## [1] 1.1145e-06
## attr(,"nres")
## [1] 1
```

```
## attr(,"njac")
## [1] 2
```

In the event that a selfStart model is not available, nls() sets all the starting parameters to 1. This is, in our view, tolerable, but could possibly be improved by using a set of values that are slightly different e.g., in the case of a model

$$y\tilde{a} * exp(-b * x) + c * exp(-d * x)$$

it would be useful to have b and d values different so the Jacobian is not singular. Thus some sort of sequence like 1.0, 1.1, 1.2, 1.3 for the four parameters might be better and it can be provided quite simply instead of all 1s.

selfStart models in base R

?? how much information to include

SSasymp SSasympOff SSasympOrig SSbiexp SSfol SSfpl SSlogis SSmicmen SSgompertz2 SSweibull

Strategic issues in selfStart models

Because the Gauss-Newton algorithm is rather unreliable from many starting sets of parameters, selfStart models are more than an accessory to nls() but a part of the infrastructure. However, creating such functions is a lot of work, and their documentation (file ./src/library/stats/man/selfStart.Rd) is quite complicated.

Issue: documentation of the results of running nls()

The output of nls() is an object of class "nls" which has the following structure:

nls() result output according to the documentation

```
A list of:
```

m an nlsModel object incorporating the model.

data the expression that was passed to nls as the data argument. The actual data values are present in the environment of the m components, e.g., environment(m\$conv).

call the matched call with several components, notably algorithm.

na.action the "na.action" attribute (if any) of the model frame.

dataClasses the "dataClasses" attribute (if any) of the "terms" attribute of the model frame.

model if model = TRUE, the model frame.

```
weights
            if weights is supplied, the weights.
              a list with convergence information.
convInfo
control
            the control list used, see the control argument.
There are also two deprecated items if algorithm = "port" fit only. These are
convergence (a code = 0 for convergence) and message. These are available from convInfo.
```

Example output

str(result)

To illustrate, let us run the Croucher example.

```
# Croucher example
xdata \leftarrow c(-2,-1.64,-1.33,-0.7,0,0.45,1.2,1.64,2.32,2.9)
ydata \leftarrow c(0.699369, 0.700462, 0.695354, 1.03905, 1.97389, 2.41143, 1.91091, 0.919576, -0.730975, -1.42001)
p1<- 1; p2<-0.2; NLSstart<-list(p1=p1,p2=p2)
NLSformula <- ydata ~ p1*cos(p2*xdata) + p2*sin(p1*xdata)
NLSdata<-data.frame(xdata, ydata)</pre>
# Try full output version of nls
library(nlspkg) # use the packaged version of nls()
## Registered S3 methods overwritten by 'nlspkg':
##
     method
                      from
##
     anova.nls
                       stats
##
     coef.nls
                       stats
     confint.nls
##
                      stats
     deviance.nls
                       stats
     df.residual.nls
##
                       stats
##
    fitted.nls
                      stats
    formula.nls
##
                      stats
##
    logLik.nls
                       stats
##
     nobs.nls
                       stats
##
    plot.profile.nls stats
##
     predict.nls
##
     print.nls
                       stats
##
     print.summary.nls stats
##
     profile.nls
                       stats
##
     residuals.nls
                       stats
##
     summary.nls
                       stats
##
     vcov.nls
                       stats
##
     weights.nls
                       stats
##
## Attaching package: 'nlspkg'
## The following object is masked from 'package:nlsj':
##
##
       numericDeriv
## The following objects are masked from 'package:stats':
##
       nls, nls.control, numericDeriv
```

result<-nls(NLSformula, data=NLSdata, start=NLSstart, model=TRUE)</pre>

```
## List of 7
  $ m
               :List of 16
##
##
                 :function ()
     ...- attr(*, "srcref")= 'srcref' int [1:8] 327 15 327 30 22 37 975 975
##
    ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
                 :function ()
    ..$ fitted
     ... - attr(*, "srcref")= 'srcref' int [1:8] 328 16 328 29 23 36 976 976
     ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
##
     ..$ formula
                 :function ()
     ...- attr(*, "srcref")= 'srcref' int [1:8] 329 17 329 31 24 38 977 977
##
     ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
     ..$ deviance :function ()
##
     ....- attr(*, "srcref")= 'srcref' int [1:8] 330 18 330 31 25 38 978 978
##
    ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
##
                  :function ()
##
     ... - attr(*, "srcref")= 'srcref' int [1:8] 331 13 331 26 20 33 979 979
    ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
##
    ..$ gradient :function ()
     ...- attr(*, "srcref")= 'srcref' int [1:8] 332 18 332 57 25 64 980 980
##
##
     ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
    ..$ conv
                  :function ()
     ... - attr(*, "srcref")= 'srcref' int [1:8] 333 14 333 34 21 41 981 981
     ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
##
     ..$ incr
                  :function ()
    ....- attr(*, "srcref")= 'srcref' int [1:8] 334 14 334 42 21 49 982 982
##
     ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
     ..$ setVarying:function (vary = rep_len(TRUE, np))
    ... - attr(*, "srcref")= 'srcref' int [1:8] 335 20 358 7 27 14 983 1006
##
    ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
     ..$ setPars :function (newPars)
     ... - attr(*, "srcref")= 'srcref' int [1:8] 359 17 366 7 24 14 1007 1014
##
##
    ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
                 :function ()
     ... - attr(*, "srcref")= 'srcref' int [1:8] 367 17 367 36 24 43 1015 1015
##
##
     ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
    ..$ getAllPars:function ()
##
     ... - attr(*, "srcref")= 'srcref' int [1:8] 368 20 368 39 27 46 1016 1016
##
     ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
                  :function ()
     ..$ getEnv
     ... - attr(*, "srcref")= 'srcref' int [1:8] 369 16 369 29 23 36 1017 1017
##
     ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
                  :function ()
     ...- attr(*, "srcref")= 'srcref' int [1:8] 370 15 376 7 22 14 1018 1024
##
    ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
                  :function ()
     ...- attr(*, "srcref")= 'srcref' int [1:8] 377 14 377 32 21 39 1025 1025
##
    ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
##
                 :function (newdata = list(), qr = FALSE)
##
     ... - attr(*, "srcref")= 'srcref' int [1:8] 378 17 379 56 24 56 1026 1027
    ..... attr(*, "srcfile")=Classes 'srcfilealias', 'srcfile' <environment: 0x5613c8ea8628>
##
    ..- attr(*, "class")= chr "nlsModel"
##
## $ convInfo :List of 5
##
    ..$ isConv : logi TRUE
    ..$ finIter
##
                   : int 7
```

```
##
     ..$ finTol
                   : num 2.19e-06
    ..$ stopCode
##
                   : int 0
##
    ..$ stopMessage: chr "converged"
                : symbol NLSdata
##
   $ data
##
   $ call
                : language nls(formula = NLSformula, data = NLSdata, start = NLSstart, model = TRUE,
   $ dataClasses: Named chr "numeric"
##
    ..- attr(*, "names")= chr "xdata"
##
   $ model
                :List of 2
##
    ..$ ydata: num [1:10] 0.699 0.7 0.695 1.039 1.974 ...
##
     ..$ xdata: num [1:10] -2 -1.64 -1.33 -0.7 0 0.45 1.2 1.64 2.32 2.9
    ..- attr(*, "terms")=Classes 'terms', 'formula' language ~ydata + xdata
     ..... attr(*, "variables")= language list(ydata, xdata)
##
    .. .. - attr(*, "factors")= int [1:2, 1:2] 1 0 0 1
##
    .. .. .. - attr(*, "dimnames")=List of 2
##
##
     .. .. .. ... : chr [1:2] "ydata" "xdata"
##
    ..... s: chr [1:2] "ydata" "xdata"
##
    ..... attr(*, "term.labels")= chr [1:2] "ydata" "xdata"
##
    ..... attr(*, "order")= int [1:2] 1 1
     .. .. - attr(*, "intercept")= int 1
##
    .. .. ..- attr(*, "response")= int 0
##
##
    ..... attr(*, ".Environment")=<environment: R_GlobalEnv>
     ..... attr(*, "predvars")= language list(ydata, xdata)
     ..... attr(*, "dataClasses")= Named chr [1:2] "numeric" "numeric"
##
    ..... attr(*, "names")= chr [1:2] "ydata" "xdata"
##
                :List of 7
##
   $ control
##
    ..$ maxiter
                   : num 50
##
     ..$ tol
                   : num 1e-05
##
    ..$ minFactor : num 0.000977
##
    ..$ printEval : logi FALSE
##
    ..$ warnOnly
                   : logi FALSE
##
     ..$ scaleOffset: num 0
##
    ..$ nDcentral : logi FALSE
   - attr(*, "class")= chr "nls"
```

Concerns with content of the nls result object

The nls object contains some elements that are awkward to produce by other algorithms. Moreover, some information that would be useful is not presented obviously.

In the following, we use result as the returned object from nls().

The data return element is an R symbol. To actually access the data from this element, we need to use syntax

```
eval(parse(text=result$data))
```

However, if the call is made with model=TRUE, then there is a returned element model which contains the data, and we can see its contents using

```
ls(result$model)
```

and if there is an element called xdata, it can be accessed as result\$model\$xdata.

Information that is NOT in the nls result object

nlsr::nlxb() solves ostensibly the same problem as nls() but only returns

coefficients A named vector giving the parameter values at the supposed solution.

```
The sum of squared residuals at this set of parameters.

The residual vector at the returned parameters.

jacobian The jacobian matrix (partial derivatives of residuals w.r.t. the parameters) at the returned parameters.

feval The number of residual evaluations (sum of squares computations) used.

jeval The number of Jacobian evaluations used.
```

This is a much smaller result object than the one nls() returns. On the other hand, nlxb explicitly returns the sum of squares as well as the residual vector and Jacobian. The counts of evaluations are also returned.

Issue: partially linear models and their specification

Specifying a model to a solver should, ideally, use the same syntax across solver tools. Unfortunately, R allows multiple approaches.

One obvious case is that nonlinear modeling tools are a superset of linear ones. Yet the explicit model

```
y \sim a*x + b
```

does not work with the linear modeling function 1m(), which requires this model to be specified as

```
y ~ x
```

However, even within nls(), we see annoying inconsistencies. Consider the following FOUR different calling sequences for the same problem, though the second is to illustrate how one intuitive choice will not work. In this failed attempt, putting the Asym parameter in the model causes the plinear algorithm to try to add another term to the model. We believe this is unfortunate, and would like to see a consistent syntax. At the time of writing (end of July 2021) we do not have any resolution in mind for this issue.

```
DNase1 <- subset(DNase, Run == 1)</pre>
## using a selfStart model
fm1DNase1 <- nls(density ~ SSlogis(log(conc), Asym, xmid, scal), DNase1)
summary(fm1DNase1)
##
## Formula: density ~ SSlogis(log(conc), Asym, xmid, scal)
##
## Parameters:
##
       Estimate Std. Error t value Pr(>|t|)
        2.3452
                     0.0782
                               30.0 2.2e-13 ***
## Asym
                     0.0814
                               18.2 1.2e-10 ***
## xmid
        1.4831
## scal
         1.0415
                     0.0323
                               32.3 8.5e-14 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.0192 on 13 degrees of freedom
##
## Number of iterations to convergence: 0
## Achieved convergence tolerance: 8.24e-06
## the coefficients only:
coef(fm1DNase1)
```

```
Asvm
           xmid
## 2.3452 1.4831 1.0415
## including their SE, etc:
coef(summary(fm1DNase1))
       Estimate Std. Error t value Pr(>|t|)
## Asym
         2.3452 0.078154 30.007 2.1655e-13
## xmid
        1.4831
                  0.081353 18.230 1.2185e-10
## scal
          1.0415
                   0.032271 32.272 8.5069e-14
## using conditional linearity
fm2DNase1 <- nls(density ~ 1/(1 + exp((xmid - log(conc))/scal)),</pre>
                 data = DNase1,
                 start = list(xmid = 0, scal = 1),
                 algorithm = "plinear")
summary(fm2DNase1)
## Formula: density ~ 1/(1 + exp((xmid - log(conc))/scal))
##
## Parameters:
       Estimate Std. Error t value Pr(>|t|)
## xmid 1.4831 0.0814
                              18.2 1.2e-10 ***
## scal 1.0415
                    0.0323
                               32.3 8.5e-14 ***
                               30.0 2.2e-13 ***
## .lin 2.3452
                    0.0782
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 0.0192 on 13 degrees of freedom
##
## Number of iterations to convergence: 5
## Achieved convergence tolerance: 1.1e-06
## using conditional linearity AND Asym -- why otherwise?? JN
fm2aDNase1 <- try(nls(density ~ Asym/(1 + exp((xmid - log(conc))/scal)),</pre>
                 data = DNase1,
                 start = list(Asym=3, xmid = 0, scal = 1),
                 algorithm = "plinear",
                 trace = TRUE))
## 0.71393 (6.72e-01): par = (3 0 1 0.48462)
## 0.11356
            (5.38e-01): par = (-15668537 \ 1.5459 \ 1.3209 \ -1.5264e-07)
## 0.010700 (1.73e+00): par = (-5.4588e+13 1.7343 1.0882 -4.7563e-14)
## 0.0084583 (1.51e-01): par = (1.4866e+20 1.3115 1.008 1.4747e-20)
## 0.0048018 (9.42e-01): par = (9.8031e+25 1.4766 1.0414 2.3863e-26)
## 0.0048018 (8.87e-01): par = (1.5159e+29 1.4766 1.0414 1.5432e-29)
## Error in nls(density ~ Asym/(1 + exp((xmid - log(conc))/scal)), data = DNase1, :
     step factor 0.000488281 reduced below 'minFactor' of 0.000976562
summary(fm2aDNase1)
##
                            Mode
     Length
                 Class
           1 try-error character
## without conditional linearity
fm3DNase1 <- nls(density ~ Asym/(1 + exp((xmid - log(conc))/scal)),</pre>
                 data = DNase1,
```

```
start = list(Asym = 3, xmid = 0, scal = 1))
summary(fm3DNase1)
##
## Formula: density ~ Asym/(1 + exp((xmid - log(conc))/scal))
##
## Parameters:
##
        Estimate Std. Error t value Pr(>|t|)
                     0.0782
                               30.0 2.2e-13 ***
          2.3452
## Asym
## xmid
          1.4831
                     0.0814
                               18.2
                                    1.2e-10 ***
## scal
          1.0415
                     0.0323
                               32.3 8.5e-14 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.0192 on 13 degrees of freedom
##
## Number of iterations to convergence: 6
## Achieved convergence tolerance: 1.88e-06
## using Port's nl2sol algorithm
fm4DNase1 <- try(nls(density ~ Asym/(1 + exp((xmid - log(conc))/scal)),</pre>
                 data = DNase1,
                 start = list(Asym = 3, xmid = 0, scal = 1),
                 algorithm = "port"))
summary(fm4DNase1)
##
## Formula: density ~ Asym/(1 + exp((xmid - log(conc))/scal))
##
## Parameters:
##
       Estimate Std. Error t value Pr(>|t|)
## Asym
         2.3452
                     0.0782
                               30.0 2.2e-13 ***
## xmid
         1.4831
                     0.0814
                               18.2 1.2e-10 ***
## scal
          1.0415
                     0.0323
                               32.3 8.5e-14 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.0192 on 13 degrees of freedom
##
## Algorithm "port", convergence message: relative convergence (4)
```

Further comments on partially linear models

Ideally, we believe it would be best to specify all models with a complete set of parameters. That is, the model is as it would be written down for use, rather than for estimation. Furthermore, we ask if it is possible for us to devise code that will detect linearity, rather than expecting the user to provide the special structure and algorithm=plinear setting. Some ideas about a Linear and Nonlinear Discoverer have been proposed by Zhang, Cheng, and Liu (2011), but these seem to relate to an independent (and hence confusing) use of the same term for a class of models that have almost nothing in common with the present issue). We have yet (end of July 2021) to consider how we might translate any ideas to code in an improved nls() or similar function.

Issue: code structure

The nls() code is structured in a way that inhibits both maintenance and improvement. In particular, the iterative setup is such that introduction of Marquardt stabilization is not easily available.

To obtain performance, a lot of the code is in C with consequent calls and returns that complicate the code. Over time, R has become much more efficient on modern computers, and the need to use compiled C and Fortran is less critical. Moreover, the burden for maintenance could be much reduced by moving code entirely to R.

Issue: code documentation for maintenance

setPars() - explain weaknesses. Only used by profile.nls()

The paucity of documentation is exacerbated by the mixed R/C/Fortran code base.

Following is an email to Dr. Heather Turner from John Nash.

I'm afraid that I don't know the purpose of the recursive call either. I know that I wrote the code to for the response, covariates, etc., but I don't recall anything like a recursive call being necessary.

If the R sources were in a git repository I might try to use `git blame` to find out when and by whom to but they are in an SVN repository, I think, and I haven't used it for a long, long time.

I don't think I will be of much help. My R skills have atrophied to the point where I wouldn't even kn exploring what is happening in the first call as opposed to the recursive call.

On Tue, Jun 29, 2021 at 11:50 AM John Nash <Nashjc@uottawa.ca <mailto:Nashjc@uottawa.ca>> wrote:

Thanks.

```
https://gitlab.com/nashjc/improvenls/-/blob/master/Croucher-expandednlsnoc.R <a href="https://gitlab.com/nashjc/improvenls/-/blob/master/Croucher-expandednlsnoc.R">https://gitlab.com/nashjc/improvenls/-/blob/master/Croucher-expandednlsnoc.R</a>
```

This has the test problem and the expanded code. Around line 367 is where we are scratching our heads. The function code (from nlsModel()) is in the commented lines below the call. This is

```
# > setPars
# function(newPars) {
# setPars(newPars)
# resid <<- .swts * (lhs - (rhs <<- getRHS())) # envir = thisEnv {2 x}
# dev <<- sum(resid^2) # envir = thisEnv
# if(length(gr <- attr(rhs, "gradient")) == 1L) gr <- c(gr)
# QR <<- qr(.swts * gr) # envir = thisEnv
# (QR$rank < min(dim(QR$qr))) # to catch the singular gradient matrix
# }</pre>
```

I'm anticipating that we will be able to set up a (possibly inefficient) code with documentation that will be easier to follow and test, then gradually figure out how to make it more efficient.

```
The equivalent from minpack.lm is
setPars = function(newPars) {
    setPars(newPars)
```

In both there is the recursive call, which must have a purpose I don't understand.

```
Cheers, JN
On 2021-06-29 12:33 p.m., Douglas Bates wrote:
> *Attention : courriel externe | external email*
> Thanks for contacting me, John. Can you point me to a file in the gitlab.com <a href="http://gitlab.com">http://gitlab.com</a>
<http://gitlab.com <http://gitlab.com>> repository that
> contains the definition of setPars?
> (By the way, it is probably best to use the email address dmbates@gmail.com <mailto:dmbates@gmail
<mailto:dmbates@gmail.com <mailto:dmbates@gmail.com>> for me. If email
> goes to bates@stat.wisc.edu <mailto:bates@stat.wisc.edu> <mailto:bates@stat.wisc.edu <mailto:bate
it should get forwarded to the gmail.com <a href="http://gmail.com">http://gmail.com">http://gmail.com</a>
> address but sometimes gmail decides that such mail looks suspicious and puts it in the spam folde
> a long time I used bates@stat.wisc.edu <mailto:bates@stat.wisc.edu <mailto:bates@stat.wisc.edu
<mailto:bates@stat.wisc.edu>> as my "From:" address because it had been my address
> since the 80's but even gmail got suspicious of mail from that address that did not appear to ori
wisc.edu <a href="http://wisc.edu">http://wisc.edu">
> <http://wisc.edu <http://wisc.edu>> domain.)
```

Goals of our effort

Here are some of the goals we hope to accomplish.

Code rationalization and documentation

We want

- to provide a packaged version of nls() (call it nlsalt) coded entirely in R that matches the version in base R or what is packaged in nlspkg as described in the "PkgFromRbase" document.
- try to obtain a cleaner structure for the overall nls() infrastructure. By this we mean a re-factoring of the routines so they are better suited to maintenance of both the existing nls() methods and features as well as the new features we would like to add.
- try to explain what we do, either in comments or separate maintainer documentation. Since we are complaining about the lack of explanatory material for the current code, we feel it incumbent on us to provide such material for our own work, and if possible for the existing code.

Provide tests

We need suitable tests in order:

• to ensure our new nlsalt or related packages work properly, in particular, giving results comparable to or better than the nls() in base R or nlspkg;

- to test individual solver functions to ensure they work across the range of calling mechanisms, that is, different ways of supplying inputs to the solver(s);
- to pose "silly" inputs to nonlinear least squares solvers (in R) to see if these bad input exceptions are caught by the programs.

A test runner program

When we have a "new" or trial solver function, we would like to know if it gives acceptable results on a range of sample problems of different types, starting parameters, input conditions, constraints, subsets, weights or other settings. Ideally we want to be able to get a summary that is easy to read and assess. For example, one approach would be to list the names of a set of tests with a red, green or yellow dot beside the name for FAILURE, SUCCESS, or "NOT APPLICABLE." In the last category would be a problem with constraints that the solver is not designed to handle.

To accomplish this, we need a suitable "runner" program that can be supplied with the name of a solver or solvers and a list of test problem cases. Problems generally have a base setup – a specification of the function to fit as a formula, some data and a default starting set of parameters. Other cases can be created by imposing bounds or mask constraints, subsets of the data, and different starts.

How to set up this "runner" and its supporting infrastructure is non-trivial. While the pieces are not as complicated as the inter-related parts of the solvers, especially nls(), the categorization of tests, their documentation, and the structuring to make running them straightforward and easy requires much attention to detail.

Some questions???

- do we need a "base" script for each family of test problem, with numbered particular cases?
- how should we document the families and cases? What tags do we need to allow us to quickly select lists of tests
- structure to output the results. AB's draft csv file and runner program.??

??? this is for the quick testing of sets of problems — documented in TestsDoc.

Output of the project

?? see Working Doc etc.

- formal reports
- informal reports
- problem sets
- code and documentation

Strategic choices in a nonlinear model estimation

A key difference in approach between nls() and nlsr::nlxb(), possibly the key difference, is that nls() builds a large infrastructure from which the Gauss-Newton iteration can be executed and other statistical information such as profiles can be computed, while nlxb() returns quite limited information, and in its execution computes what is needed on an as and when basis. This follows a path that one of us (JN) established almost 50 years ago with the software that became John C. Nash (1979), using setup, solver, and post-solution analysis phases to computation. Here, that last phase is not part of nlxb(), but is the domain of other functions in thenIsrpackage.nls()also has some similar functions, but they are much more tied into the infrastruction that is created mostly in thensIModel()' function.

The nls() approach, as implemented in the base R code and nlspkg leads to considerable entangling of the different functions and capabilities. This is to an extent that even after both the preparation for and carrying out of the present project, we do not feel confident to explain the code completely, nor to maintain

it. However, we have made some progress toward such a goal. Part of that has been to render the code in R. In this there remain some tasks to complete, and they are possibly difficult.

Opinion for discussion

To advance the stability and maintainability of R, we believe that the functions that carry out quite advanced calculations like those achieved by nls() should be organized to have their interactions as orderly as possible. The aspects of nls() that have given us the most trouble are as follows:

- The functions that compute the residuals and jacobians are frequently computed by presuming the current data and parameters for those functions are available in an environment. As long as the correct environment is used, this provides a surprisingly short syntax to invoke the calculations.
- Weights, subsets, and various contextual controls such as that for the na.action that tells our code
 what to do with undefined or missing numbers. Again, this makes for a very simple invocation of the
 calculation, but the context is hidden from the user and it can be difficult for those of us trying to
 maintain or improve the code to be certain we have the context correct.
- The mixing of R and C code makes for high performance, but without developer documentation leaves programmers with a lot of work to do to adjust the code. We believe in keeping code at least a runnable reference version in a single programming language. If necessary, by measuring ("profiling") the code, we can find bottlenecks and replace just those slower parts of the reference code.
- We believe that a setup, solve, and post-solution structure for complicated functions reduces the number of objects that must be kept in appropriate alignment at any one stage in a set of calculations.

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