

# CSE 344: Computer Vision

Homework 3 ; Arka Sarkar 2018222

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## Question 1

Steps to implement background subtraction :

1. Calculate background frame → Mean, Median, Mode methods
2. Calculate Frame difference of all the frames.
3. Take otsu threshold of all the frames

## Algorithm

```
def calculate_background(frames, method = "mean"):
    if(method == "mean"):
        mean = np.zeros(frames[0].shape)

        for frame in frames:
            mean = mean + frame

        mean = mean//len(frames)
        return mean
    elif(method == "median"):
        median = np.stack([f for f in frames])
        median = np.median(median, axis = 0)
        return median
    elif(method == "mode"):
        mode = np.stack([f for f in frames])
        mode = stats.mode(mode, axis = 0)
        mode = np.squeeze(mode[0])
        return mode
    else:
        raise Exception("Not a valid method")

def background_subtraction( frames, method = "mean", loc = 0):

    if(method == "mean"):
        mean = calculate_background(frames, "mean")

        count = 0
        for frame in frames:
            curr = abs(frame - mean)
            thres = np.mean(curr,2)
            val = filters.threshold_otsu(curr)
            thres[thres >= val] = 255
            thres[thres < val] = 0
            B = curr[:, :, 0]
            G = curr[:, :, 1]
            R = curr[:, :, 2]
            B[thres == 255] = 255
            G[thres == 255] = 255
            R[thres == 255] = 0
            final_image = np.dstack((R,G,B))
```

```

if(loc == 0):
    cv2.imwrite("bgsub/dynamic/mean/frame%d.jpg" % count, final_image)
else:
    cv2.imwrite("bgsub/static/mean/frame%d.jpg" % count, final_image)
    count = count + 1
elif(method == "median"):
    median = calculate_background(frames, "median")

    count = 0
    for frame in frames:
        curr = abs(frame - median)
        thres = np.mean(curr, 2)
        val = filters.threshold_otsu(curr)
        thres[thres >= val] = 255
        thres[thres < val] = 0
        B = curr[:, :, 0]
        G = curr[:, :, 1]
        R = curr[:, :, 2]
        B[thres == 255] = 255
        G[thres == 255] = 255
        R[thres == 255] = 0
        final_image = np.dstack((R, G, B))
    if(loc == 0):
        cv2.imwrite("bgsub/dynamic/median/frame%d.jpg" % count, final_image)
    else:
        cv2.imwrite("bgsub/static/median/frame%d.jpg" % count, final_image)
        count = count + 1

elif(method == "mode"):
    mode = calculate_background(frames, "mode")

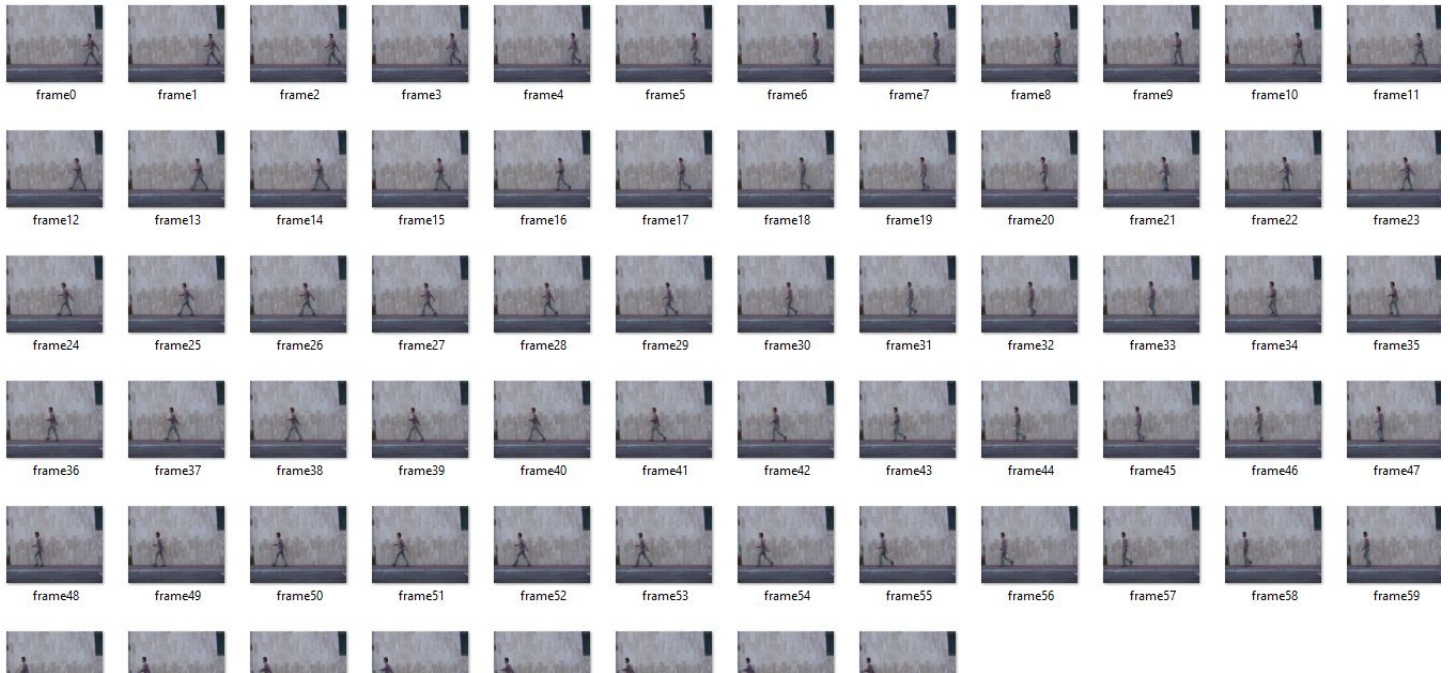
    count = 0
    for frame in frames:
        curr = abs(frame - mode)
        thres = np.mean(curr, 2)
        val = filters.threshold_otsu(curr)
        thres[thres >= val] = 255
        thres[thres < val] = 0
        B = curr[:, :, 0]
        G = curr[:, :, 1]
        R = curr[:, :, 2]
        B[thres == 255] = 255
        G[thres == 255] = 255
        R[thres == 255] = 0
        final_image = np.dstack((R, G, B))
    if(loc == 0):
        cv2.imwrite("bgsub/dynamic/mode/frame%d.jpg" % count, final_image)
    else:
        cv2.imwrite("bgsub/static/mode/frame%d.jpg" % count, final_image)
        count = count + 1
else:
    raise Exception("Not a valid method")

```

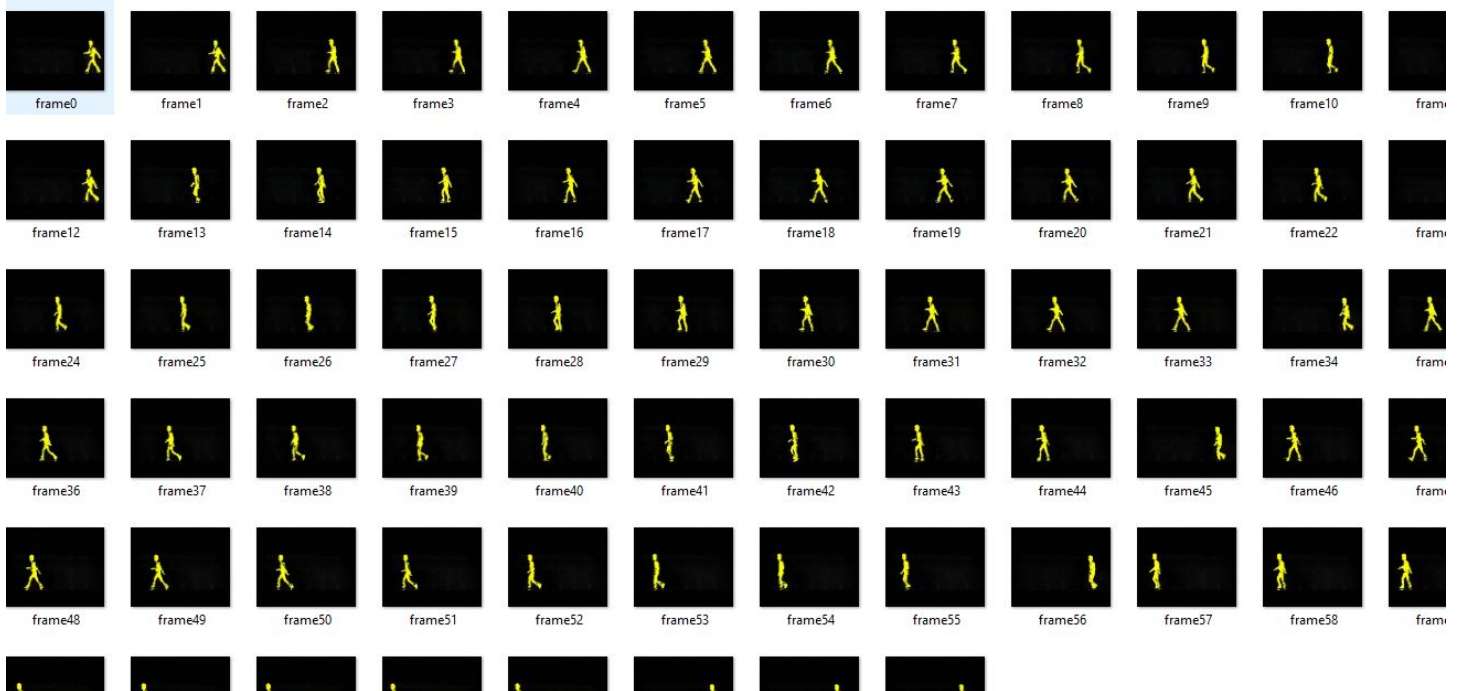
## Final Input/Output

### 1. Dynamic

#### Original frames

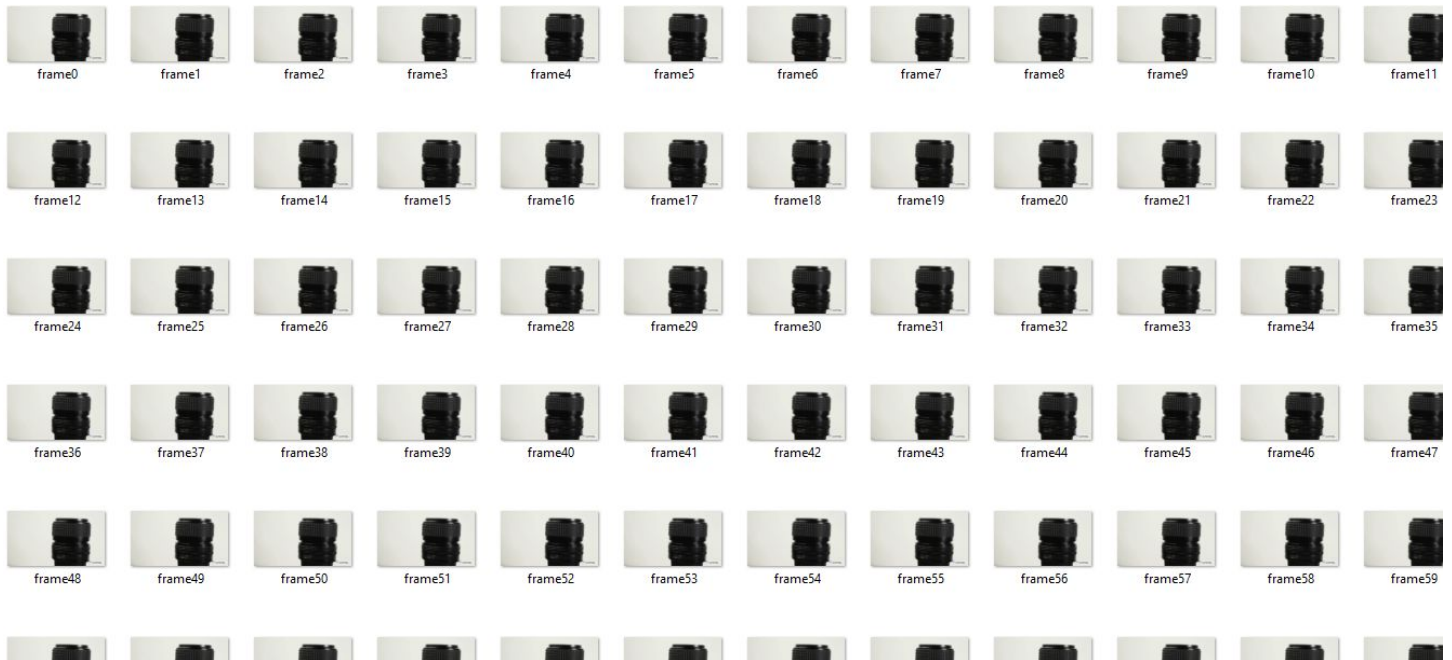


#### Background subtracted frames



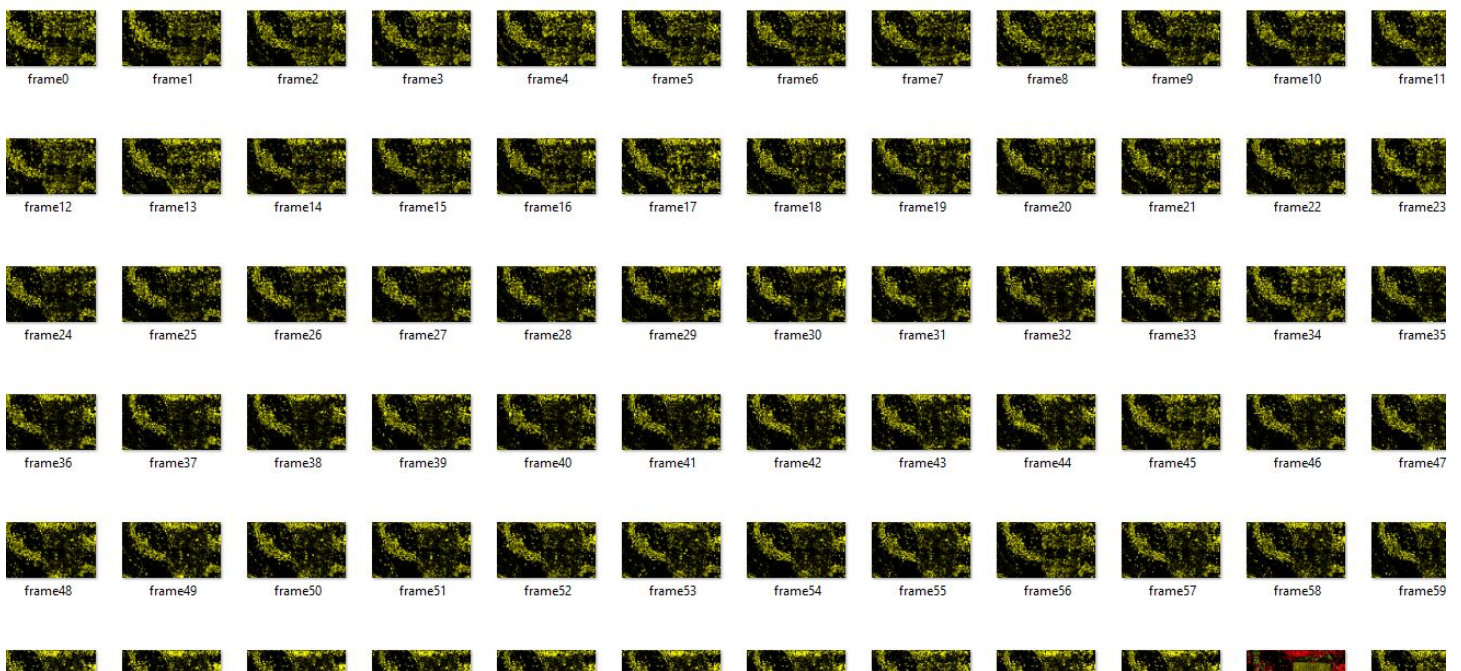
The foreground is moving much as compared to the background hence we get such a good subtraction, similar for both mean, median and mode.

## 2. Static



Original frames

Background subtracted Frames



We can see slight differences in the background subtraction because the camera lens is moving a bit to that makes a small difference, also these small differences are highlighted when otsu is applied hence can be seen here.

