

# Introduction to Cryptology - Bimal Roy

- crypt-hidden
- key-systematic way of studying

• Cryptology - systematic way of studying ways of hiding information

• Cryptology  $\begin{cases} \rightarrow \text{Cryptography (hiding the information)} \\ \rightarrow \text{Cryptanalysis (analyzing to find the hidden content)} \end{cases}$

• Cryptology is a 2-person game, and we never underestimate the opponent.

• key - chosen by the user.

• Story of "Dancing Figures" - Sherlock Holmes

• Brute Force Attack - Establishing all possible keys to break the code.

• FI-1, FI-2 (Encryption Algorithms)

• Assume that the algorithm to be used is not secret, key to be chosen by the user at runtime, and not involved in the algorithm.

• If key is a random number, it is difficult to break

• Mainly the security lies in the choice of the key.

• Public Key Cryptography - sender must be sure of the receiver and the receiver must be sure of the sender.  
[key wala suitcase]  $\rightarrow$  double keys

• Shannon's Entropy:  $[x+y = z \rightarrow \text{known, } x \text{ and } y \text{ cannot be calculated separately}]$

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- Privacy Preserving Computation - Adding secret key to amount spend and get a crypted message.

- Bank Locker Problem:-

- ① Digital Lock

- ② Divide key into two parts: → first part a number  $m$   
→ second part a number  $c$   
compute a straight line:  $y = mx + c$ .

Take two random points on the line; one to bank one to customer.

- ③ Consider circle: if bank locker is shared.  
key → radius

centre → bank

random two points on the circumference: one to one customer, other to the other customer  
(both customers share the locker)

→ • Secret Sharing of a Key. (who has the key)

→ • No important or secret information should be accessed by a single person. (Fundamental concept of secret sharing).

- Bitcoin - Distributed and Anonymous

↳ Sender and Receiver are Anonymous, leading to concept of Hash values.

↳ then public key encryption is used.

- ECC (Elliptic Curve Cryptography)

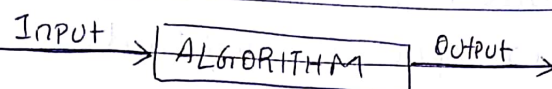


## Introductory Talks on Sorting and Searching

— Subhas Nandy

• An algorithm should be:

- clever: Efficient data structure
- Efficient: Space and Time complexity should be minimum, algorithm should be simple.



→ Correctness of algorithm

→ for every input  $n$ , there should be same number of steps in the algorithm, everytime it is run.

• We always consider worst case time complexity.

• Average Case Time Complexity: The input comes from a statistical distribution, where a probability is associated with each element in the distribution.

• Amortized Time Complexity is used when the inputs are known.

• Worst Case time complexity bounds the time complexity of an algorithm from above.

• Time Complexity is measured in terms of input a function of input size or output size, or both

Input → Input Sensitive

Output → Output sensitive

• Sorting: (Defn. from Cormen and RKP paper)

• Internal Sort: Data stored in Computer's main memory. we count the number of arithmetic and logical computations.

• External Sort: Sorting is done on data stored in some external memory. We compute the number of fetches.

• Inplace Sort: Amount of extra space required to sort the data is a small constant, and is not dependent of the input size. No external memory or space is required.

• Stable Sort: It ~~preserves~~ preserves relative order of ~~no~~ records with equal keys, key values should come in order of original input.

• Insertion Sort :-

```
(n-1) 1. for j ← 2 to n
(n-1) 2.   do Key = A[j]
(n-1) 3.   /* Insert A[j] in the sorted list A[1, 2, ..., j-1] */
n/2 + j 4.   i ← j - 1
" 5.   while i > 0 and A[i] > Key
" 6.   do A[i+1] ← A[i]
" 7.   i ← i - 1
" 8.   A[i+1] ← Key
Time Complexity: O(n²)
```

• Bubble Sort :-

```
for i ← 1 to n
do j = length(A) down to i + 1
  /* fill A[i] by min {A[j], j = i, i+1, ..., n} */
  do if A[i] A[j] < A[i] then exchange A[j], A[i]
```

Updated:

```
FLAG = false, i = 1
while FLAG = false do
  FLAG = true
  for j = length(A) down to i + 1 do
    /* fill A[i] by min {A[j], j = i, i+1, ..., n} */
    if A[j] < A[i] then
```

FLAG = false  
exchange ( $A[i]$ ,  $A[i-1]$ )

$i = i + 1$

\* Time complexity remains same. [Worst case: Ascending order given  $\rightarrow$  finding descending order]

• Quicksort :

$\rightarrow$  Quicksort ( $A, p, q$ ) // In text

1. If  $p \geq q$  EXIT.

2. Compute  $s \leftarrow$  correct position of  $A[p]$  in the sorted order of the elements of  $A$  from  $p$ -th location to  $q$ -th location.

3. Move the pivot  $A[p]$  into position  $A[s]$ .

4. Move the remaining elements of  $A[p-q]$  into appropriate sides.

5. Recursively sort the segments to the left and right of the pivot.

5a. QSORT ( $A, p, s-1$ )

5b. QSORT ( $A, s+1, q$ )

$\rightarrow$  QSORT ( $A, p, q$ ) // A bit more in detail.

1. If  $p \geq q$  EXIT.

2 and 4. Compute  $j \leftarrow$  correct position of  $A[p]$  in the sorted order of the elements of  $A$  from  $p$ -th location to  $q$ -th location.

2a. pivot =  $A[p]$ ;  $i = p+1$ ,  $j = q$

2b. while ( $i < j$ ) do

2c. while  $A[i] \leq \text{pivot}$  do  $i = i + 1$

2d. while  $A[j] > \text{pivot}$  do  $j = j - 1$

2e. if  $i < j$  then SWAP ( $A[i]$ ,  $A[j]$ )

3. Move the pivot  $A[p]$  into the position  $A[j]$

3a. ~~Re~~ SWAP ( $A[p]$ ,  $A[j]$ )

5. Recursively sort the segments to the left and right of the pivot.

5a. QSORT ( $A, p, s-1$ )

5b. QSORT ( $A, s+1, q$ )

$\rightarrow$  An Inplace algorithm.

$\rightarrow$  Worst case:  $O(n^2)$  Average case:  $O(n \log n)$



→ Inductive proof of  $T(n) = O(n \log n)$

$$T(n) = \frac{1}{n} \left[ T(1) + T(n) + \sum_{q=1}^{n-1} (T(q) + T(n-q)) + O(n) \right]$$

→ Scope of improvement :-

~ In each level of recursion, total number of comparisons =  $O(n)$ .

~ We need to reduce the number of levels of recursion, to  $\log$

~ we split each sub-array under consideration into two equal halves using the median of that ~~sub~~ subarray as the pivot.

Reason: If there are  $k$  levels then  $2^k = n$   
 $\Rightarrow k = \log_2 n$

Median can be computed in  $O(n)$ .

Median computation needs extra workspace, which means that space complexity increases and quicksort does not remain inplace.

• Randomized Quick Sort -

→ Central Splitter

It is an index  $s$  such that the number of elements less than  $A[s]$  is at least  $n/4$ .

→ The randomized Quicksort chooses a random number as pivot and we use concept of probability to analyze the problem.

$$\rightarrow P[\text{Central Splitter}] = \frac{\text{No. of favourable cases}}{\text{Total no. of cases}} = \frac{n/2}{n} = 1/2$$

$\therefore$  Expected number of trials to get a central splitter = 2

$\therefore$  Expected time required to get ~~the~~ a central splitter =  $2n$ .

→ Worst-case size of each partition in  $j$ -th level of ~~recursion~~ recursion is bounded by  $n \times (3/4)^j$

$$n' \leq \frac{3n}{4} \quad n' \rightarrow \text{partition at next level.}$$

$$\frac{n'}{4} \leq n'' \leq \frac{3n'}{4} \leq \left(\frac{3}{4}\right)^2 n$$

$$\therefore n_j \leq \left(\frac{3}{4}\right)^j n.$$

Hence, we will get  $T(n) = 2T\left(\frac{3n}{4}\right) + O(n) = O(n \log n)$

$$T(n) = 2T\left(\frac{3n}{4}\right) + O(n)$$

$$= 4T\left(\left(\frac{3}{4}\right)^2 n\right) + 2O(n) + O(n)$$

⋮

$$= \cancel{2^R} 2^R T\left(\left(\frac{3}{4}\right)^R n\right) + R O(n)$$

$$= 2^{\log_{4/3} n} T(1) + \log_{4/3} n O(n)$$

$$= 2^c \log n + \cancel{c'} c' n \log n$$

$$= c' \log n + c'' n \log n$$

[ We use the result :  
 levels of recursion =  $\log_{4/3} n$   
 $= O(\log n)$  ]



## • Merge Sort —

- We divide the list into two halves and sort each half separately
- We merge the sorted halves into one sorted array
- We executed  $k$  steps, where each step took linear time.

$$2^k = n/2$$

$$\Rightarrow k = (\log_2 n - 1)$$

- Hence, total time =  $k \cdot n = O(n \log n) \Rightarrow$  Not inplace sort.

## • Heap —

- A heap is a complete binary tree with elements from a partially ordered set, such that the element at every node is less than or equal to the elements in the subtree rooted at that node.

- We represent the heaps in an array.

Children of  $i$ :  $2i, 2i+1$

Parents of  $i$ :  $\lfloor i/2 \rfloor$

- Heaps can be implemented in priority queue due to the parent-child property; the first priority being at the root.

- The ~~root~~ is at root is at location 1.

- A heap of height  $k$  will have elements between  $2^k$  and  $2^{k+1} - 1$ .

- Heap with height  $n$  elements has height  $\lfloor \log_2 n \rfloor$ .

- The minimum of the root heap is at the root. findmin() operation will have worst-case  $O(1)$ .

→

→ Heapify (A, i)

1.  $l \leftarrow \text{left}(i) = 2i$ ;  $r \leftarrow \text{right}(i) = 2i + 1$

2. if  $l \leq n$  and  $A[l] > A[i]$  then  $\text{largest} \leftarrow l$   
else  $\text{largest} \leftarrow i$

3. if  $r \leq n$  and  $A[r] > A[\text{largest}]$  then  $\text{largest} \leftarrow r$

4. if  $\text{largest} \neq i$  then SWAP ( $A[i]$ ,  $A[\text{largest}]$ )  
Heapify (A, largest)

→ Build Heap (A)

1. for  $i = \lfloor n/2 \rfloor$  down to 1

2. Heapify (A, i)

→

→ Heapify ( $A, i$ )

1.  $l \leftarrow \text{left}(i) = 2i$ ;  $r \leftarrow \text{right}(i) = 2i + 1$
2. if  $l \leq n$  and  $A[l] > A[i]$  then  $\text{largest} \leftarrow l$   
else  $\text{largest} \leftarrow r$
3. if  $r \leq n$  and  $A[r] > A[\text{largest}]$  then  $\text{largest} \leftarrow r$
4. if  $\text{largest} \neq i$  then SWAP ( $A[i], A[\text{largest}]$ );  
Heapify ( $A, \text{largest}$ )

→ Build Heap ( $A$ )

1. for  $i = \lfloor n/2 \rfloor$  down to 1
2. Heapify ( $A, i$ )