

2.) It is the image above. *0x20000132 = 02 00 32 20 Cycle = 0x20NEntries = 0x32 $Switch_Hit = 0x00$ DutyCounter = 0x023.) main code below ;************ main.s ********* ; Program written by: ***Michael Hernandez and Arkan Abuyazid ; Date Created: 2/14/2017 ; Last Modified: 3/01/2017 ; Brief description of the program ; The LED toggles at 8 Hz and a varying duty-cycle ; Repeat the functionality from Lab2-3 but now we want you to ; insert debugging instruments which gather data (state and timing) ; to verify that the system is functioning as expected. ; Hardware connections (External: One button and one LED)

; PE1 is Button input (1 means pressed, 0 means not pressed)

```
; PEO is LED output (1 activates external LED on protoboard)
; PF2 is Blue LED on Launchpad used as a heartbeat
; Instrumentation data to be gathered is as follows:
; After Button(PE1) press collect one state and time entry.
; After Buttin(PE1) release, collect 7 state and
; time entries on each change in state of the LED(PEO):
; An entry is one 8-bit entry in the Data Buffer and one
; 32-bit entry in the Time Buffer
; The Data Buffer entry (byte) content has:
; Lower nibble is state of LED (PEO)
; Higher nibble is state of Button (PE1)
; The Time Buffer entry (32-bit) has:
; 24-bit value of the SysTick's Current register (NVIC ST CURRENT R)
; Note: The size of both buffers is 50 entries. Once you fill these
    entries you should stop collecting data
; The heartbeat is an indicator of the running of the program.
; On each iteration of the main loop of your program toggle the
; LED to indicate that your code(system) is live (not stuck or dead).
GPIO_PORTE_DATA_R EQU 0x400243FC
GPIO_PORTE_DIR_R EQU 0x40024400
```

GPIO_PORTE_AFSEL_R EQU 0x40024420

GPIO_PORTE_DEN_R EQU 0x4002451C

GPIO PORTF DATA R EQU 0x400253FC

GPIO_PORTF_DIR_R EQU 0x40025400

GPIO_PORTF_AFSEL_R EQU 0x40025420

GPIO_PORTF_PUR_R EQU 0x40025510

GPIO_PORTF_DEN_R EQU 0x4002551C

SYSCTL_RCGCGPIO_R EQU 0x400FE608

ENTRIES EQU 50

DATA_RESET EQU 0xFF

TIME_RESET EQU 0xFFFFFFF

TERM EQU 0x00030B00; one millisecond 2867C (hardware lab 2-3), 30B00 (software), 28A9C (hardware for lab 4)

SHORT EQU 0x00000FFF

BIG EQU 0x00300000

; RAM Area

AREA DATA, ALIGN=2

;-UUU-Declare $% \left(1\right) =\left(1\right) \left(1\right) +\left(1\right) \left(1\right) \left(1\right) +\left(1\right) \left(1\right) \left($

; and any variables (like pointers and counters) here

DataBuffer SPACE ENTRIES * 1

TimeBuffer SPACE ENTRIES * 4

DataPt SPACE 4

TimePt SPACE 4

CYCLE SPACE 1

NEntries SPACE 1

Switch_Hit SPACE 1

DutyCounter SPACE 1

ALIGN

; ROM Area

IMPORT TExaS_Init

IMPORT SysTick_Init

;-UUU-Import routine(s) from other assembly files (like SysTick.s) here

AREA |.text|, CODE, READONLY, ALIGN=2

THUMB

EXPORT Start

```
Start
   BL
                     TExaS_Init
                                          ; voltmeter, scope on PD3
        BL
               SysTick_Init
  CPSIE
                                          ; TExaS voltmeter, scope runs on interrupts
        BL
                            Initialization;
        BL
                     Debug_Init;
       LDR R1, =DutyCounter;
        AND R0, R0, #0;
        STRB R0, [R1];
       LDR R1, =NEntries;
  STRB RO, [R1];
loop
                     HIT;
   BL
   BL
                     LED_ON;
        BL
                            Debug_Capture;
        BL
                            DELAY_ON;
        BL
                            LED_OFF;
        BL
                            Debug_Capture;
        BL
                            DELAY_OFF;
        BL
                            HeartBeat;
```

B loop;

```
;-----Debug_Init-----
```

; Resets both buffers, initializes the points

; of said buffers, and activates SysTick Timer

; Input: None

; Output: None

Debug_Init

DPointer RN 0

DElement RN 1

LDR

Count RN 2

LDR DPointer, =DataPt

R1, =DataBuffer

STR R1, [DPointer]

; Stores address of first data element

; to DataPt

LDR DPointer, [DPointer]

MOV DElement, #0xFFF

MOV Count, #0

Data_Clear

STRB DElement, [DPointer, Count]

ADD Count, Count, #1

CMP Count, #ENTRIES

BHS Time_Init

B Data_Clear

Time_Init

TPointer RN 0

TElement RN 1

LDR TPointer, =TimePt

LDR R1, =TimeBuffer

STR R1, [TPointer]

LDR TPointer, [TPointer]

LDR TElement, =0xFFFFFFF

MOV Count, #0

Time_Clear

STR TElement, [TPointer, Count]

ADD Count, Count, #4

```
CMP Count, #ENTRIES*4
        BHS
                     Owari
                     Time_Clear
   В
Owari
   PUSH {RO, LR}
                                                          ; ADDED THIS PUSH AND POP BECAUSE CODE BECAME STUCK IN ENDLESS LOOP
        BL
                     SysTick_Init
                                                  ; Initializes SysTick
        POP {RO, LR};
                     LR
        ВХ
Initialization
   LDR R1, =SYSCTL_RCGCGPIO_R
                                           ; TExaS_Init sets bus clock at 80 MHz
  LDR R0, [R1]
                                           ;Initialization
   ORR
              RO, RO, #0x30;
  STR R0, [R1];
   NOP;
   NOP;
   NOP;
   NOP;
```

```
LDR R1, =GPIO_PORTE_DIR_R;
LDR R0, [R1];
AND
           RO, RO, #0xFD;
ORR
           RO, RO, #0x01
                                               ; PE1 input and PE0 output
STR R0, [R1];
LDR R1, =GPIO_PORTE_AFSEL_R;
LDR R0, [R1];
AND
           RO, RO, #0x00;
STR R0, [R1];
LDR R1, =GPIO_PORTE_DEN_R;
LDR R0, [R1];
ORR
           R0, R0, #0x03
                                               ; enables just PEO and PE1
STR R0, [R1];
LDR R1, =GPIO_PORTF_DIR_R;
LDR R0, [R1];
     AND R0, R0, #0x00
                                               ; PF4 INPUT
     ORR RO, RO, #0x04
                                               ; PF2 OUTPUT
STR R0, [R1];
LDR R1, =GPIO_PORTF_AFSEL_R;
LDR R0, [R1];
AND
           RO, RO, #0x0000;
```

```
STR R0, [R1];
LDR R1, =GPIO_PORTF_PUR_R;
LDR R0, [R1];
ORR
           RO, RO, #0x10;
STR R0, [R1];
LDR R1, =GPIO_PORTF_DEN_R;
LDR R0, [R1];
ORR
           RO, RO, #0x14;
STR R0, [R1]
                                         ;END of initialization
                                                                       ; TExaS_Init sets bus clock at 80 MHz
AND
            R0, #0x0000;
ADD
            RO, RO, #16;
LDR R1, =CYCLE;
STRB
            RO, [R1]
                                                ;code to store 20% to duty cycle before running loop
     LDR R0, =Switch_Hit;
     AND R1, R1, #0x00;
     STRB R1, [R0];
     BX LR;
```

```
;;-----HIT-----
; Updates duty cycle
; Input: None
; Output: None
HIT
                                                      ; implement debug_Capture here
       PUSH {R0-R2, R3};
       LDR RO, =Switch_Hit;
       LDRB R1, [R0];
       CMP R1, #0;
       BNE
                           Still_Pressed;
       LDR RO, =GPIO_PORTE_DATA_R
                                       ; check for switch release
  LDRSB R1, [R0];
       AND R1, R1, #0x02;
       CMP R1, #0x02;
       BEQ
                           Store;
       POP
             {R0-R2, R3};
       ВХ
                           LR;
Store
  LDR R0, =Switch_Hit
```

```
AND R1, R1, #0;
        ADD R1, R1, #1;
       STRB R1, [R0];
        POP {R0-R2, R3};
        ВХ
                            LR;
Still_Pressed
  LDR RO, =GPIO_PORTE_DATA_R;
        LDR R1, [R0];
        AND R1, R1, #0x02;
        CMP R1, #0x02;
        BNE
                                    Update;
        POP {R0-R2, R3};
                            LR;
        ВХ
Update
  LDR RO, =Switch_Hit;
        AND R1, R1, #0x00;
        STRB R1, [R0];
        LDR RO, =CYCLE
                                                 ; Duty Cycle subroutine
   LDRB
              R1, [R0];
  ADDS
              R1, #16
                                                 ; Duty cycle to next level
  CMP
              R1, #80
                                                 ; 0X60
```

```
BNE
                       Valid;
  STRB
             R1, [R0];
  SUBS
             R1, #80;
                            DONE;
   В
Valid
  CMP
             R1, #96;
                    RESET;
   BEQ
             R1, [R0];
  STRB
   В
                            DONE;
                                         ; GOES TO DELAY SUBROUTINE
RESET
  SUBS
             R1, #96;
  STRB
             R1, [R0];
DONE
  POP {R0-R2, R3};
   ВХ
             LR;
       ;-----Debug_Capture-----
; Updates buffers and pointers
; Input: None
```

```
; Output: None
Debug_Capture
                                                                             ; %= 0.00196 calculated as ((100) (.000002450))/.125
   PUSH {R0-R11, R12, LR}
  LDR R1, =NEntries;
       LDRB R0, [R1];
       CMP RO,
                    #50;
       BEQ
                           Full;
       LDR R11, =Switch_Hit;
       LDRB R10, [R11];
       CMP R10, #0;
       BNE
                           Next_Case;
       LDR R1, =DutyCounter;
       LDRB R0, [R1];
       CMP R0, #0;
       BEQ
                           skipped;
       CMP R0, #7;
       BNE
                            Run
       AND R0, R0, #0x0000
                                         ; this line may cause problems
       STR R0, [R1];
       B Clear;
```

```
Run
  ADD R0, R0, #1;
       STRB R0, [R1];
Clear
       LDR R1,
                   =GPIO_PORTE_DATA_R;
       LDR R0, [R1];
       LDR R3,
                   =0xE000E018;
       LDR R2, [R3];
       AND R4, R0, #0x02
                                       ; Port E bit 1
       AND R5, R0, #0X01
                                   ; Port E bit 0
       LSL R4, R4, #3;
       ORR R4, R4, R5;
       LDR R6,
                   =DataPt;
       LDR R7, [R6];
       STRB R4, [R7];
       ADD R7, R7, #1;
       STR R7, [R6];
       LDR R8,
                    =TimePt;
       LDR R9, [R8];
       STR R2, [R9];
       ADD R9, R9, #4;
```

```
STR R9, [R8]
                                          ; Assumes NVIC_ST_CURRENT_R is the time information
       LDR R1, =NEntries;
       LDRB R0, [R1];
        ADD R0, R0, #1
       STRB RO, [R1];
        POP {R0-R11, R12, PC}
Full
   POP {R0-R11, R12, PC}
Next_Case
       LDR R1, =DutyCounter;
       LDRB R0, [R1];
        CMP R0, #0;
   BEQ Run
skipped
   POP {R0-R11, R12, PC}
       ;-----HeartBeat-----
; Toggles PF2 Blue LED on and off
; Input: PF2
```

```
; Output: PF2
HeartBeat
  PUSH { RO-R3}
       LDR R1,
                   =GPIO_PORTF_DATA_R;
       LDR R0, [R1];
       EOR R0, R0, #0x04;
       STR R0, [R1];
       POP {R0-R3};
       BX LR;
;-----LED_ON-----
; Turns on LED
; Input: none
; Output: None
LED_ON
       PUSH {R0, R3}
       LDR RO, =GPIO_PORTE_DATA_R
                                       ;Turn on LED
       LDR R3, [R0];
```

```
ORR R3, #0X01;
       STR R3, [R0];
  POP {R0, R3}
       BX LR
;-----LED_OFF-----
; Turns off LED
; Input: none
; Output: None
LED_OFF
       PUSH {R0, R3}
       LDR RO, =GPIO_PORTE_DATA_R
                                    ;Turn on LED
       LDR R3, [R0];
       AND R3, #0XFE;
       STR R3, [R0];
       POP {R0, R3}
            LR
       ВХ
```

```
;-----DELAY_ON------
DELAY_ON
  PUSH {RO-R3}
                                          ;Delay subroutine
  LDR RO, =CYCLE
  LDRSB R1, [R0];
  CMP
             R1, #0;
   BEQ LEAVE;
REPEAT2
  LDR R2, =TERM;
REPEAT
  SUBS R2, #1
                                         ; Millisecond load
  CMP
             R2, #0;
   BNE
             REPEAT;
  SUBS
             R1, #8;
  CMP
             R1, #0
                                                ; on for duty cycle
   BNE
             REPEAT2;
```

LEAVE

```
;--------;
;
;
DELAY_OFF
PUSH {RO-R3}
LDR RO, =CYCLE;
```

R1, [R0];

R1, R1, #80;

LEAVE3;

POP {R0-R3}

BX LR

REPEAT4

LDRB

RSBS

BEQ

LDR R2, =TERM;

REPEAT5

```
; off for (duty cycle)!
  SUBS
              R2, #1
   CMP
              R2, #0;
   BNE
              REPEAT5;
   CMP
              R1, #0;
   BEQ
                      LEAVE3;
  SUBS
              R1, #8;
   \mathsf{CMP}
               R1, #0;
   BNE REPEAT4;
LEAVE3
   POP {R0-R3}
        BX LR
  ALIGN
                                                                                   ; make sure the end of this section is aligned
   END
                                                                                   ; end of file
```

```
Systick.s is below here
; SysTick.s
; Module written by: Arkan Abuyazid & Michael Hernandez
; Date Created: 2/14/2017
; Last Modified: 3/01/2017
; Brief Description: Initializes SysTick
NVIC_ST_CTRL_R
                   EQU 0xE000E010
NVIC_ST_RELOAD_R EQU 0xE000E014
NVIC_ST_CURRENT_R EQU 0xE000E018
TICKS
                              EQU 0x00FFFFF
   AREA |.text|, CODE, READONLY, ALIGN=2
   THUMB
; ;-UUU-Export routine(s) from SysTick.s to callers
              EXPORT SysTick_Init
;-----SysTick Init-----
; ;-UUU-Complete this subroutine
; Initialize SysTick with busy wait running at bus clock.
; Input: none
; Output: none
```

```
; Modifies: ??
SysTick_Init
                                                                                                                ; Set Enable bit to 0
       LDR
                      RO,=NVIC_ST_CTRL_R;
       LDR
                      R1, [R0];
                      R1, R1, #0xFE;
       AND
                      R1, [R0];
       STR
                                                                                                                ; 10 million ticks is .125
ms in 80MHz
       LDR
                      R0,=NVIC_ST_RELOAD_R;
       LDR
                      R1, =TICKS
       STR
                      R1, [R0];
                                                                                                                ; Reset Current Register
                      RO,=NVIC_ST_CURRENT_R;
       LDR
       STR
                      R1,[R0]
                                                                                                 ; Attempting to store a number in
CURRENT_R
                                                                                                                ; Resets it automatically
```

; Turn on counter

LDR RO,=NVIC_ST_CTRL_R

LDR R1, [R0]

ORR R1, R1, #0x00000005 ; Enable bit = 1, Clock bit = 1

AND R1, R1, #0xFFFFFFFD ; Interrupt bit = 0;

STR R1, [R0]

BX LR ; return

ALIGN ; make sure the end of this section is aligned

END ; end of file

4.) CORRESPONDE 100)(.0000002450) - 0.00196

Paste from the saved File (50 entries)				count:	50									
020000042000DA								12 5	< - Time	per tick				
9CB	necentro	89014600	E024000		Adjust-er	D-1-	Differenc		· · · · · · · · · · · ·	per tiok		Switch	LED	
эсь 10007000AD0059FD70006BB21500CAD5D80							Ditteleuc	rimetms)				Jwitch	LED	
10007000AD0053FD70006BB21500CAD5D60 100080007D000F15B50096ED1C00EBA2C100							9974504	124.64476	/ S C-			1	- 1	
100090008400607B2900809EEC00D5539100								49.858013				0		
										time differe	nces	0		
1000A000540034018C0090B25B00DBF9E100 1000B000C30054D2490082632B00CDAAB10								74.786975 49.858013				0		
												0		
1000C000930046C6CA00AD779A00EE50020								74.786975						
1000D000020067296A009F286A00E001D200							3988641					0		
1000E000D200638B09009C1541000B1541000								74.787013				0		
1000F000A80070EDA80066C61000D5C51000							13137354	404.04474	4.1. 6					
100100007800DA28B00016DA7F007F6B6100						1895830	9971577					1 0		
10011000E700EC43C900F08A4F00591C31005								74.786138		time differ	ences			
0A012000B70084EDEE00D09EBE0093	2M63B/U	84EDEE00	DOSEBE	JU	0084C60B		3988704	49.8588				0		
00000001FF					00297B60			74.786138						
					00EC9E80		3988704	49.8588				0		
					009153D5			74.786138				_		
					005476F2			49.858838				0		
					008C0134		13137342	00 57005	4 11 1			0		
					005BB290		3165860					1		
					00E1F9DB			99.714263		time differ	ences	0		
					00C38B09			24.930625				0		
					0049D254			99.714263				0		
					002B6382			24.930625				0		
					00B1AACD			99.714263				0		
					00933BF8			24.930663				0		
					00CAC646		13137330					0		
					009A77AD		3165849					1		
					000250EE			124.64239		time differ	ences	0		
					00025026		200	0.0025				0		
					006A2967			124.64239				0		
					006A289F		200	0.0025				0		
					00D201E0			124.64239				0		
					00D20115			0.0025375				0		
					00098B63		13137330					0		
					0041159C		13137351					1		
					0041150B		145			time differ	ences	0		
					00A8EE01			124.64333				0		
					00A8ED70		145					0		
					00100666			124.64333				0	-	
					0010C5D5		145					0		
					00789EC8			124.64336				0		
					00B028DA		13137390					0		
					007FDA16		3165892					1		
					00616B7F			24.929888		time differ	ences	0		
					00E7B283		7977212	99.71515				0		
					00C943EC			24.929888				0		
					004F8AF0		7977212	99.71515				0		
					00311C59			24.929888				0		
					00B7635A		7977215	99.715188				0		
					00EEED84		13137366					0		
					00BE9ED0	12492496	3165876	39.57345				1		
												0	1	