Tensorlib: A Spatial Accelerator Generation Framework for Tensor Algebra

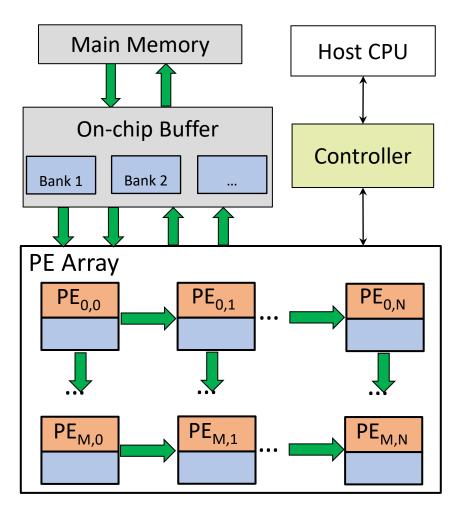
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Spatial Accelerator Architecture

Typical Architecture for Spatial Accelerators



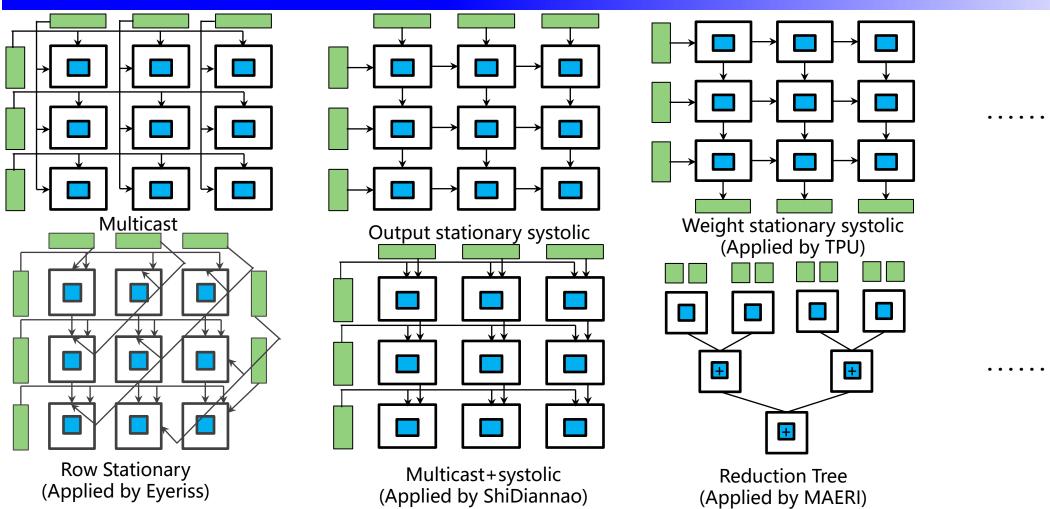
PE Array

On-Chip Buffer

Controller



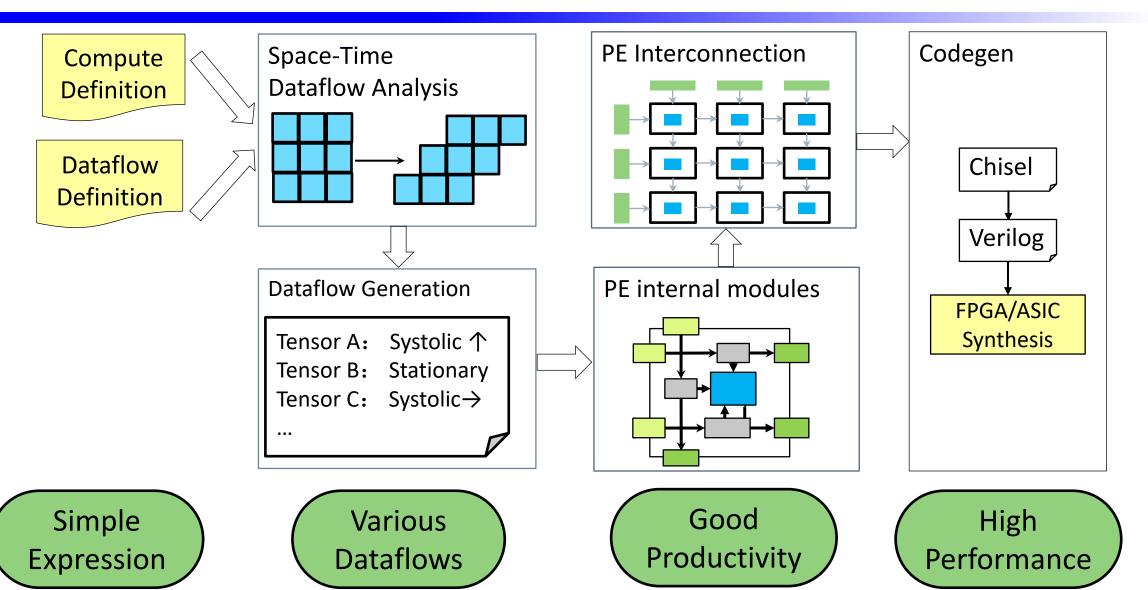
Various Hardware Dataflows



Jouppi, Norman P., et al. "In-datacenter performance analysis of a tensor processing unit." ISCA 2017 Chen, Yu-Hsin, et al. "Eyeriss: An energy-efficient reconfigurable accelerator for deep convolutional neural networks." JSSC 2016 Du, Zidong, et al. "ShiDianNao: Shifting vision processing closer to the sensor." ISCA 2015



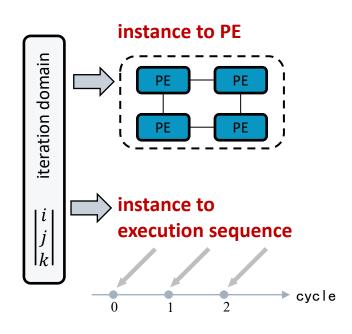
Overview of Tensorlib



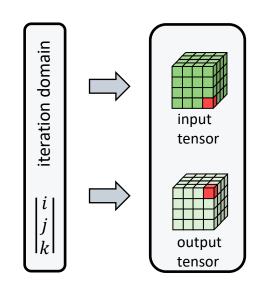
Dataflow Analysis



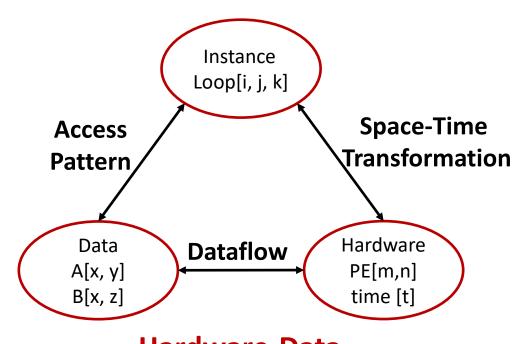
Data Relations in Spatial Accelerators



Instance-Hardware



Instance-Data



Space-Time Transformation

loop nest: for (i = 0; i < 3; i++) for (j = 0; j < 3; j++) for (k = 0; k < 3; k++) instance [i,j,k]: Y[i,j] += A[i,k] * B[k,j];</pre>

Space-Time Transformation (STT):

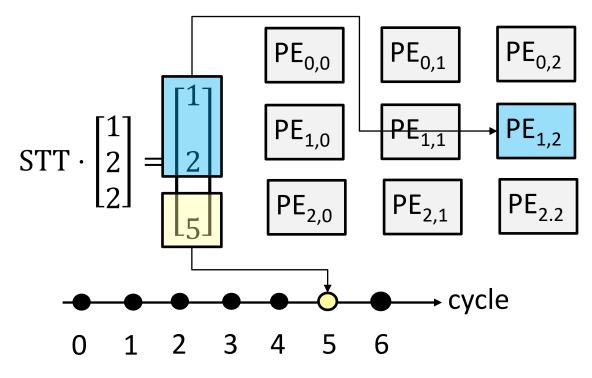
Transform loop iteration domain into hardware space-time domain

Can be expressed with Matrix Multiplication

$$STT\begin{bmatrix} i \\ j \\ k \end{bmatrix} = \begin{bmatrix} x \\ y \\ t \end{bmatrix}$$

Example:

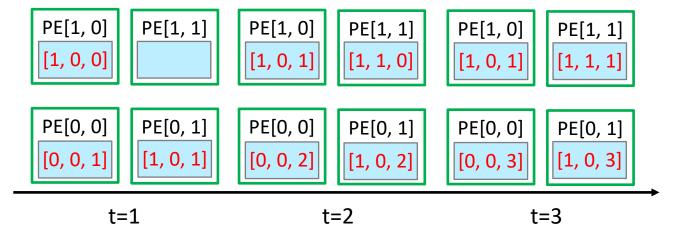
$$STT = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \text{ Index: } \begin{bmatrix} i \\ j \\ k \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$$



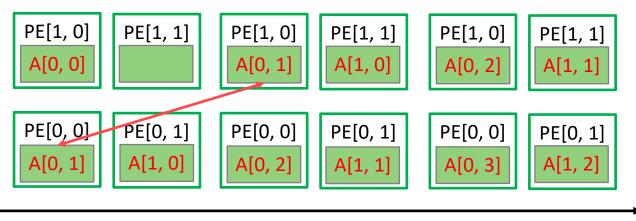


Formulating Hardware-Data Relation

Step 1: space-time domain -> instance domain



Step 2: instance domain -> tensor index domain



Step 1: Inverse Space-Time Transformation:

$$STT^{-1} \begin{bmatrix} x \\ y \\ t \end{bmatrix} = \begin{bmatrix} i \\ j \\ k \end{bmatrix}$$

Step 2: Tensor Access Formula:

$$TA \begin{bmatrix} i \\ j \\ k \end{bmatrix} = \begin{bmatrix} m \\ n \end{bmatrix}$$

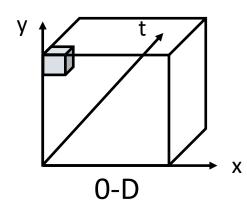
Combine two steps together:

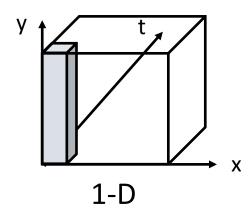
$$TA \cdot STT^{-1} \begin{bmatrix} x \\ y \\ t \end{bmatrix} = \begin{bmatrix} m \\ n \end{bmatrix}$$

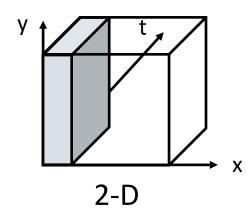


Reuse Space and PE-Memory Interconnection

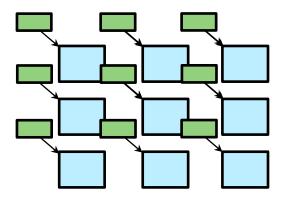
Reuse subspace In (x, y, t) domain

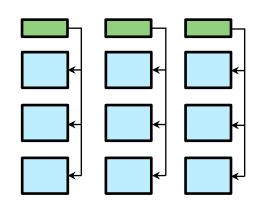


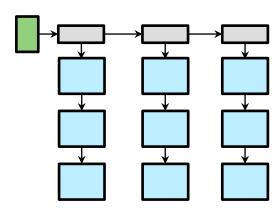




PE-Memory Interconnection Example







Each PE reads data once from memory bank No data reuse

Reuse subspace forms a line in space-time

Reuse subspace forms a plane



1-D Reuse Type Identification

1-D reuse type forms a vector in space-time domain

Reuse direction
$$x = \begin{bmatrix} \vec{p} \\ t \end{bmatrix}$$
 space partition time part

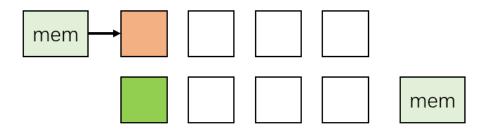
Reuse Vector Direction	$\vec{p} = \vec{0}$ $t \neq 0$	$\vec{p} \neq \vec{0}$ $t \neq 0$	$\vec{p} \neq \vec{0}$ $t = 0$
PE Behavior		—	
	Stay in the same PE during execution stage	Delay data before send to the next PE	Data arrive at PEs at the same time
Dataflow Type	Stationary	Systolic Multicast	

10

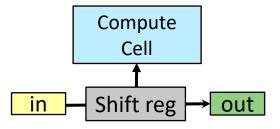
Hardware Generation

Systolic Dataflow

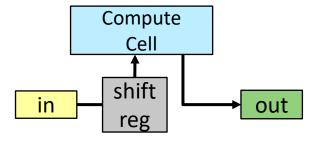
Reuse Vector
$$x = \begin{bmatrix} \vec{p} \\ t \end{bmatrix} \leftarrow \begin{array}{c} \vec{p} \neq \vec{0} \\ \leftarrow t \neq 0 \end{array}$$



- Transfer to PE $x + \vec{p}$ from PE x after delaying t cycles
- Use register to delay input data in each PE



PE Dataflow for Input Tensor

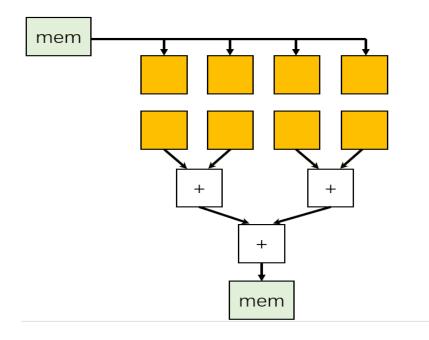


PE Dataflow for Output Tensor

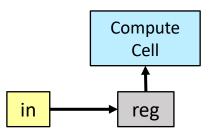
Multicast Dataflow

Reuse Vector
$$x = \begin{bmatrix} \vec{p} \\ t \end{bmatrix} \leftarrow \vec{p} = \vec{0}$$

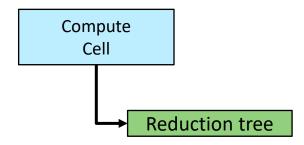
$$t \neq 0$$



- Transfer to PEs in the same line simultaneously
- Directly send to/from compute cell
- Use reduction tree for output communication



PE Dataflow for Input Tensor

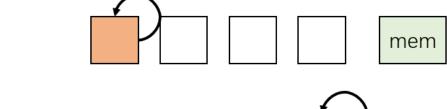


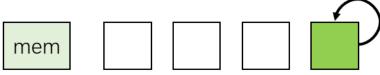
PE Dataflow for Output Tensor



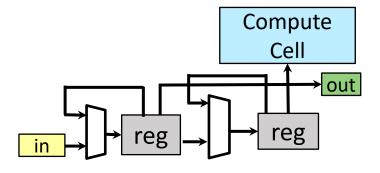
Stationary Dataflow

Reuse Vector
$$x = \begin{bmatrix} \vec{p} \\ t \end{bmatrix}$$
 $\leftarrow \quad \vec{p} = \vec{0}$

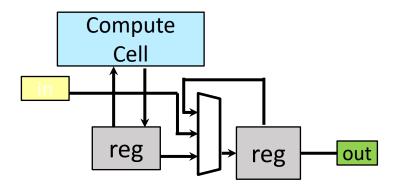




- Keep stationary inside PE during execution
- Requires systolic dataflow to move in/out to/from PE array
- Use double buffer for interleaving two dataflows

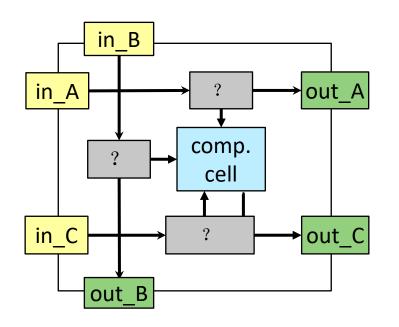


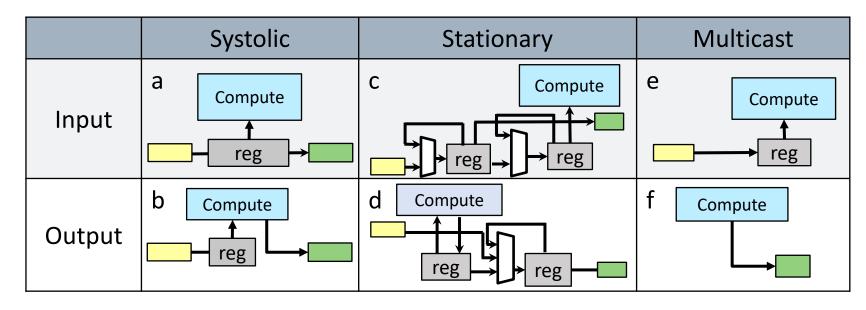
PE Dataflow for Input Tensor



PE Dataflow for Output Tensor

Building PE Inner Architecture



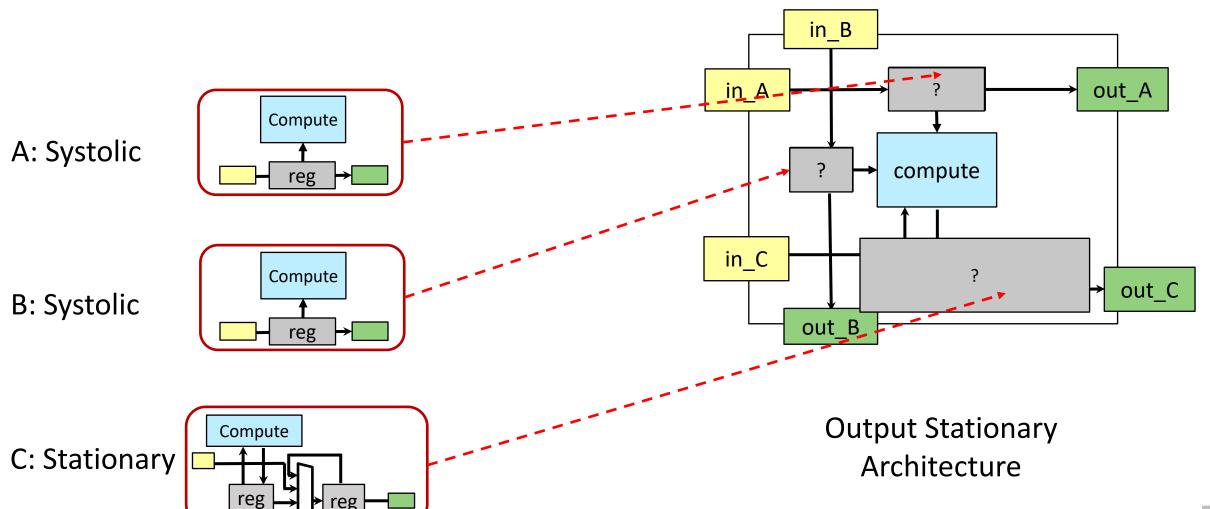


PE Basic Structure

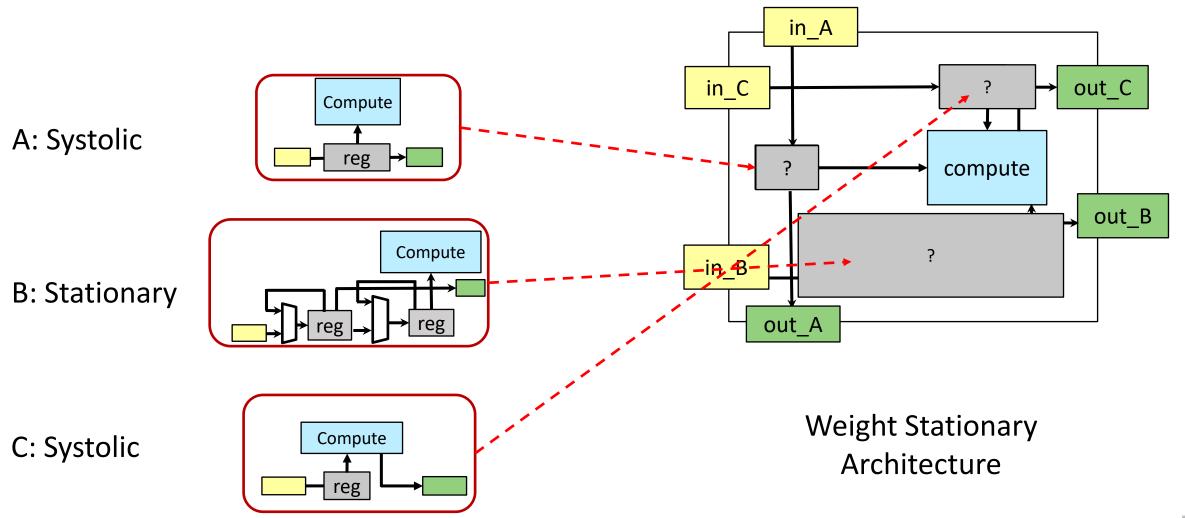
PE Dataflow Structure

Substitute each of the module to one of the 6 dataflow modules based on the dataflow of each tensor

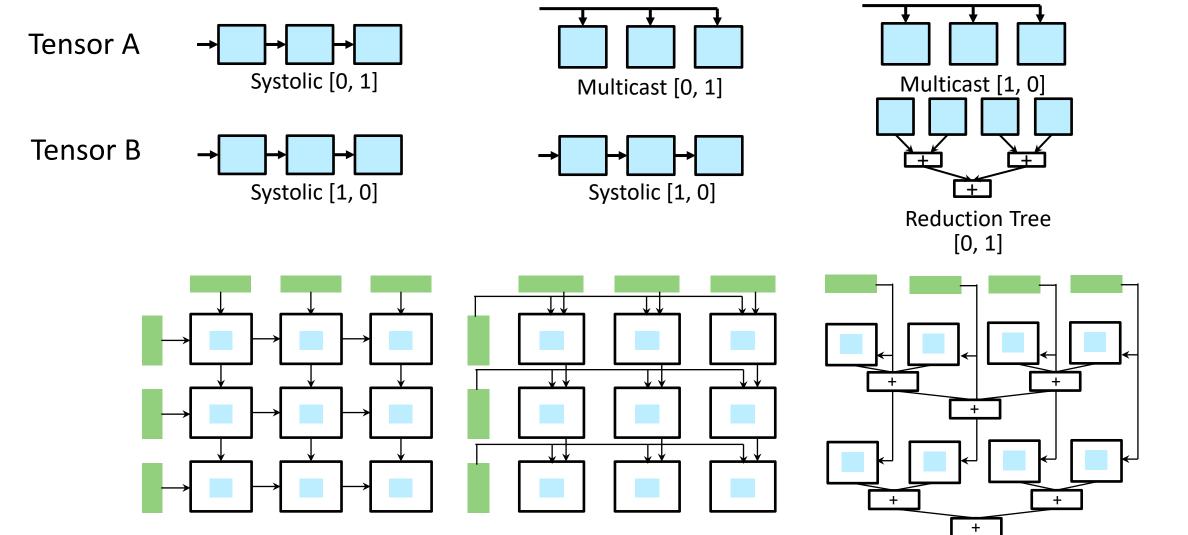
Building PE Architecture - Example



Building PE Architecture - Example

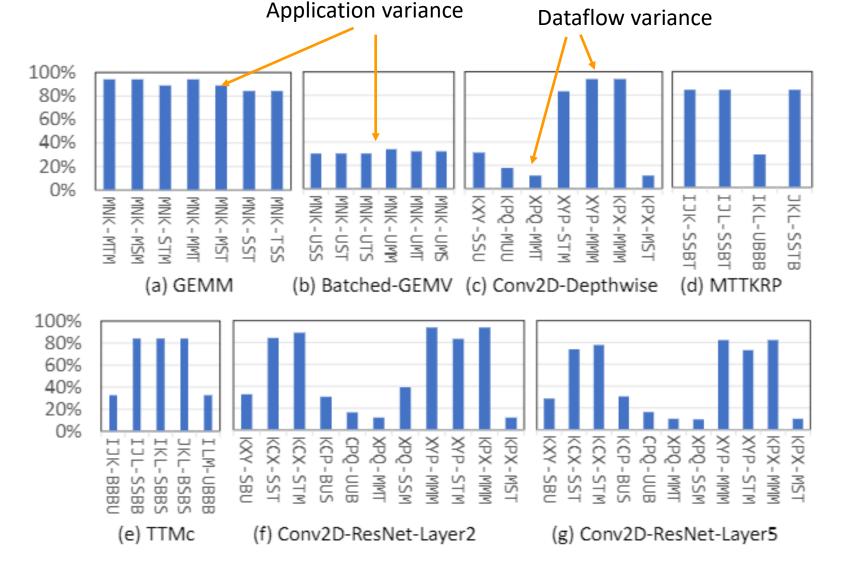


Building PE Array Interconnection - Example



Experiments and Evaluation

Dataflow Performance Evaluation



- Evaluated 6 tensor applications
- Included Systolic, Multicast, Stationary, Unicast, **Broadcast dataflows**
- Performance variance because of dataflow mapping and bandwidth

FPGA Performance Results

	Susy [ICCAD'20]		PolySA [ICCAD'18]		Tensorlib	
	Arria-10		Xilinx VU9P		Xilinx VU9P	
Application	GEMM	Conv	GEMM	Conv	GEMM	Conv
LUT(%)	40%	35%	49%	49%	68%	75%
DSP(%)	93%	84%	89%	89%	75%	75%
BRAM(%)	32%	30%	89%	71%	51%	73%
Freq(MHz)	202	220	229	229	263	245
Throughput (Gop/s)	547	551	555	548	673	626

21% Frequency Improvement15% Throughput Improvement

Framework Tutorial: Tensorlib API

■ Tensorlib provides API to define computation

Tensorlib API	Description		
genIterators(x)	Define x iterators and return the iterator list		
genTensors(x)	Define x tensors and return the tensor list		
setExpr(expr)	Define the compute expression with tensors and iterators		
iterator.setRange(x)	Set the range of iterators as x		
Tensor.setWidth(x)	Set the tensor data bitwidth as x		
setLatency(x)	Define the latency of computation pipeline		
useCustomKernel	Whether use customized IP for computation cell		

Framework Tutorial: GEMM

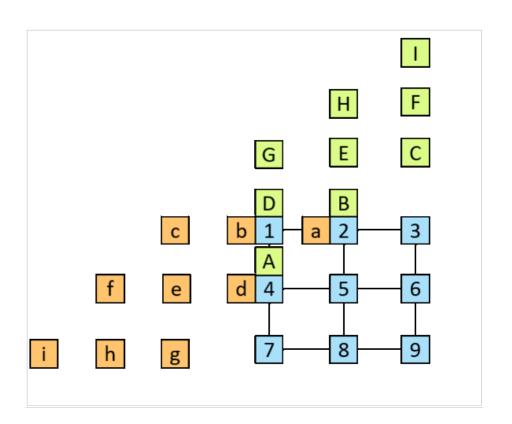
Example:

GEMM

Dataflow:

output stationary Systolic array

```
for (i = 0; i < 3; i++)
 for (j = 0; j < 3; j++)
   for (k = 0; k < 3; k++)
       C(i)(j) += A(i)(k) * B(k)(j)
```



Framework Tutorial: Example

Step 1: Workload Definition

```
val opSpec_Gemm = new OperatorSpec {
    val i :: j :: k :: Nil = genIterators(3)
    val A :: B :: C :: Nil = genTensor(3)
    setExpr(C(i)(j) += A(i)(k) * B(k)(j))
    i.setRange(8)
    k.setRange(20)
    j.setRange(8)
    setLatency(1)
    A.setWidth(16)
    B.setWidth(16)
    C.setWidth(16)
}
```

Step 2: Space-Time matrix definition

```
val stt = DenseMatrix(
  (1, 0, 0),
  (0, 1, 0),
  (1, 1, 1),
)
```

Step 3: Generate dataflow and Verilog code

```
val config = gen_dataflow(opSpec_Gemm,
stt)

chisel3.Driver.execute(args, () => new
PEArray(config))
```

Framework Tutorial: Using Pre-defined Configs

Running Tensorlib with Pre-defined dataflow configs

```
sbt "runMain tensorlib.ParseJson
examples/gemm.json output/output.v"
```

Config File Example (Can be generated by HASCO):

```
{
    "benchmark": "GEMM",
    "bitwidth": 16,
    "length":[8,8,8],
    "STT":[[1,0,0],[0,0,1],[1,1,1]]
}
```

Framework Tutorial: Customized Kernels

- Default Kernel: Integer Multiply-Add
- Can be substituted with userprovided IPs

Step 1: Choose to use customized kernel In computation definition

```
val opSpec = new OperatorSpec {
          .....
          useCustomKernel(true)
          .....
}
```

Step 2: Provide customized computation kernel & reduction kernel

```
module Reduction_Customized(
  input [15:0] io_in_a,
  input [15:0] io_in_b,
  output [15:0] io_out
);
```

Result Validation

Chisel Tester Validation

```
sbt "runMain tensorlib.Test Gemm"
```

Runs a validation program of tensorlib generated GEMM accelerator based on Chisel cycle-level simulator

```
[info] [1.554] reference result:
                193
176
     301
           247
                181
     262
           276
                203
                hardware output:
       [1.555]
           306
                193
     301
           247
                181
     262
           276
                148
          279
                203
       [1.556] result match
```