

## ▼ Table Structure Detection and Data Extraction

### ▶ 1. Business Problem

↳ 6 cells hidden

### ▼ 2. Data Information :

- We will be using the **MARMOT Dataset** for training and evaluating our models.
- It consists of about **500 images** and their corresponding table & column annotations. Annotation files are present in xml format.
- We will use these annotations to generate the table & column segmentation masks for each image.

### ▼ 3. ML Problem Formulation :

#### ▼ Type of Machine Learning Problem :

For extracting data from table(s) present in an Image :

- The columns and tables have to be segmented from the image. Thus it is an **Image Segmentation** i.e pixel-wise classification task.
- Then we need to pass the table and column segments through an OCR(Object Character Recognition) tool in order to retrieve the text present in the table cells.

## ▼ Performance Metrics :

The evaluation metric used in this classification task is F1-score :

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F1 is calculated as follows:

$$F_1 = 2 * \frac{\text{precision} * \text{recall}}{\text{precision} + \text{recall}}$$

where:

$$\text{precision} = \frac{TP}{TP + FP}$$

$$\text{recall} = \frac{TP}{TP + FN}$$

---

- *Precision is the measure of the correctly identified positive cases from all the predicted positive cases*
- *Recall is the measure of the correctly identified positive cases from all the actual positive cases*
- *F1-Score is the harmonic mean of Precision and Recall. This used as a evaluation metric since it penalizes false positives and false negatives equally. It is a **preferred metric** in cases where class imbalance exists.*

## ► 4. Exploratory Data Analysis

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## ► Preparing Train and Test Data

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## ▼ Model Building :

```
from datetime import datetime
from tensorflow.keras import Model, Sequential
from tensorflow.keras.layers import Activation, Dense, Dropout, Input, Embedding, Flatten, Conv2DTranspose, concatenate, UpS
```

## ▼ TABLENET :

```
class tbl_decoder(tf.keras.layers.Layer):
    def __init__(self, name = "Table_mask"):
        super().__init__(name = name)
        self.conv1 = Conv2D(filters=512, kernel_size=(1,1), activation='relu')
        self.umsample1 = UpSampling2D(size = (2,2),)
        self.umsample2 = UpSampling2D(size = (2,2),)
        self.umsample3 = UpSampling2D(size = (2,2),)
        self.umsample4 = UpSampling2D(size = (2,2),)
        self.convtranspose = Conv2DTranspose( filters=3, kernel_size=3, strides=2, padding = 'same')

    def call(self, X):

        input,pool_3,pool_4 = X[0],X[1],X[2]
        x = self.conv1(input)
        x = self.umsample1(x)
        x = concatenate([x, pool_4])
        x = self.umsample2(x)
        x = concatenate([x, pool_3])
        x = self.umsample3(x)
        x = self.umsample4(x)
        x = self.convtranspose(x)

        return x
```

```
class col_decoder(tf.keras.layers.Layer):
```

```

def __init__(self, name = "Column_mask"):
    super().__init__(name = name)
    self.conv1 = Conv2D(filters=512, kernel_size=(1,1), activation='relu')
    self.drop = Dropout(0.8)
    self.conv2 = Conv2D(filters=512, kernel_size=(1,1), activation='relu')
    self.upsample1 = UpSampling2D(size = (2,2),)
    self.upsample2 = UpSampling2D(size = (2,2),)
    self.upsample3 = UpSampling2D(size = (2,2),)
    self.upsample4 = UpSampling2D(size = (2,2),)
    self.convtranspose = Conv2DTranspose( filters=3, kernel_size=3, strides=2, padding = 'same')

```

```

def call(self, X):

    input,pool_3,pool_4 = X[0],X[1],X[2]
    x = self.conv1(input)
    x = self.drop(x)
    x = self.conv2(x)
    x = self.upsample1(x)
    x = concatenate([x, pool_4])
    x = self.upsample2(x)
    x = concatenate([x, pool_3])
    x = self.upsample3(x)
    x = self.upsample4(x)
    x = self.convtranspose(x)

    return x

```

```

input = Input(shape=(1024,1024,3))
vgg19 = tf.keras.applications.VGG19(include_top=False, weights = 'imagenet', input_tensor=input, classes= 1000)

```

```

x = vgg19.output
pool_3 = vgg19.get_layer('block3_pool').output
pool_4 = vgg19.get_layer('block4_pool').output

```

```

x = Conv2D(512, (1, 1), activation = 'relu', name='block6_conv1')(x)
x = Dropout(0.8, name='block6_dropout1')(x)
x = Conv2D(512, (1, 1), activation = 'relu', name='block6_conv2')(x)
x = Dropout(0.8, name = 'block6_dropout2')(x)

```

```

Table_Decoder = tbl_decoder()
Column_Decoder = col_decoder()

output1 = Table_Decoder([x, pool_3, pool_4])
#output1 = Activation(activation='relu', name = "Table_mask")(output1)
output2 = Column_Decoder([x, pool_3, pool_4])
#output2 = Activation(activation='relu', name = "Column_mask")(output2)

model = Model(inputs = input, outputs= [output1,output2], name = "TableNet")
model.summary()

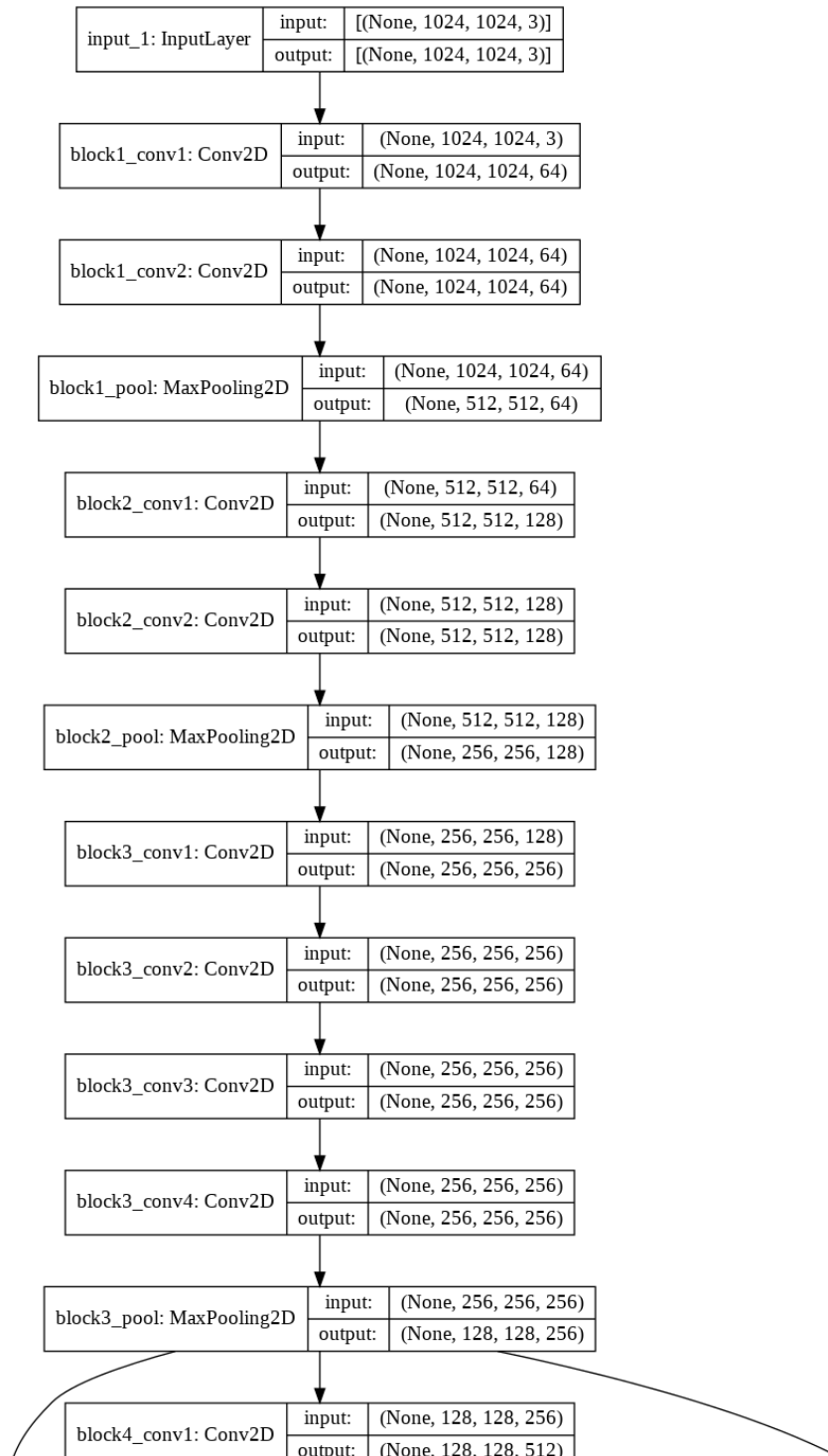
```

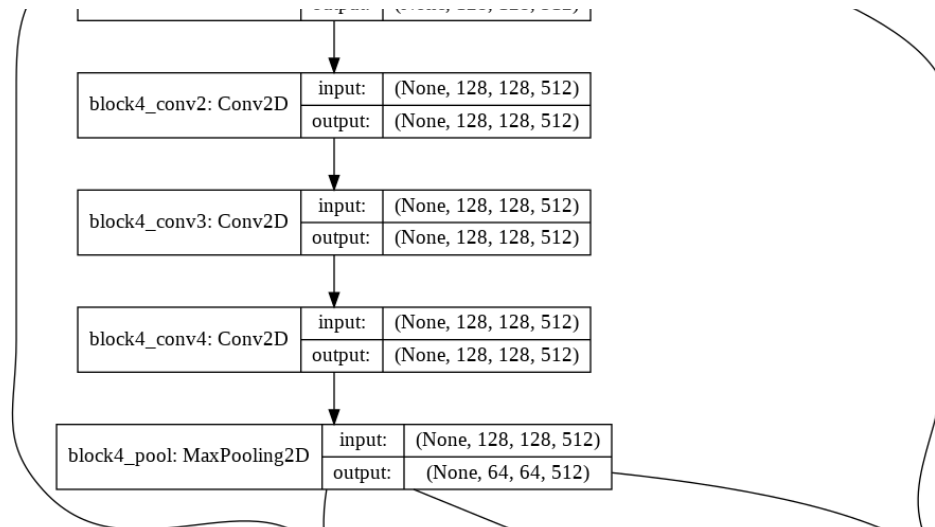
Model: "TableNet"

Layer (type)	Output Shape	Param #	Connected to
=====			
input_1 (InputLayer)	[(None, 1024, 1024, 0		
block1_conv1 (Conv2D)	(None, 1024, 1024, 6 1792		input_1[0][0]
block1_conv2 (Conv2D)	(None, 1024, 1024, 6 36928		block1_conv1[0][0]
block1_pool (MaxPooling2D)	(None, 512, 512, 64) 0		block1_conv2[0][0]
block2_conv1 (Conv2D)	(None, 512, 512, 128 73856		block1_pool[0][0]
block2_conv2 (Conv2D)	(None, 512, 512, 128 147584		block2_conv1[0][0]
block2_pool (MaxPooling2D)	(None, 256, 256, 128 0		block2_conv2[0][0]
block3_conv1 (Conv2D)	(None, 256, 256, 256 295168		block2_pool[0][0]
block3_conv2 (Conv2D)	(None, 256, 256, 256 590080		block3_conv1[0][0]
block3_conv3 (Conv2D)	(None, 256, 256, 256 590080		block3_conv2[0][0]
block3_conv4 (Conv2D)	(None, 256, 256, 256 590080		block3_conv3[0][0]
block3_pool (MaxPooling2D)	(None, 128, 128, 256 0		block3_conv4[0][0]
block4_conv1 (Conv2D)	(None, 128, 128, 512 1180160		block3_pool[0][0]

block4_conv2 (Conv2D)	(None, 128, 128, 512)	2359808	block4_conv1[0][0]
block4_conv3 (Conv2D)	(None, 128, 128, 512)	2359808	block4_conv2[0][0]
block4_conv4 (Conv2D)	(None, 128, 128, 512)	2359808	block4_conv3[0][0]
block4_pool (MaxPooling2D)	(None, 64, 64, 512)	0	block4_conv4[0][0]
block5_conv1 (Conv2D)	(None, 64, 64, 512)	2359808	block4_pool[0][0]
block5_conv2 (Conv2D)	(None, 64, 64, 512)	2359808	block5_conv1[0][0]
block5_conv3 (Conv2D)	(None, 64, 64, 512)	2359808	block5_conv2[0][0]
block5_conv4 (Conv2D)	(None, 64, 64, 512)	2359808	block5_conv3[0][0]
block5_pool (MaxPooling2D)	(None, 32, 32, 512)	0	block5_conv4[0][0]
block6_conv1 (Conv2D)	(None, 32, 32, 512)	262656	block5_pool[0][0]
block6_dropout1 (Dropout)	(None, 32, 32, 512)	0	block6_conv1[0][0]
block6_conv2 (Conv2D)	(None, 32, 32, 512)	262656	block6_dropout1[0][0]
block6_dropout2 (Dropout)	(None, 32, 32, 512)	0	block6_conv2[0][0]
Table_mask (tbl_decoder)	(None, 1024, 1024, 3)	297219	block6_dropout2[0][0] block3_pool[0][0] block4_pool[0][0]

tf.keras.utils.plot\_model(model, show\_shapes=True, show\_layer\_names=True)







```
from google.colab import drive
drive.mount('/content/drive')
```

Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force\_remo

## ▼ Model Training:

```
!rm -rf ./logs/fit/
```

```
!rm -rf ./model_save/
```

```
train_dataloader, test_dataloader, train_steps, val_steps = load_data(BATCH_SIZE = 1, BUFFER_SIZE = 10)
```

```
losses = {"Table_mask" : tf.keras.losses.SparseCategoricalCrossentropy(from_logits = True),
          "Column_mask" : tf.keras.losses.SparseCategoricalCrossentropy(from_logits = True)}
```

```
loss_weights = {"Table_mask" : 2.0,
                 "Column_mask" : 1.0}
```

```
model.compile(optimizer= tf.keras.optimizers.Adam(0.0001, beta_1=0.8), loss = losses, loss_weights=loss_weights, metrics = [
```

```
filepath="model_save/weights-{epoch:02d}-{val_loss:.4f}.hdf5"
checkpoint = tf.keras.callbacks.ModelCheckpoint(filepath=filepath , monitor='val_loss' ,save_best_only=True, mode='auto', v
```

```
hist = model.fit(train_dataloader, epochs =50, steps_per_epoch=train_steps, \
    validation_data=test_dataloader, validation_steps=val_steps, callbacks=[checkpoint])
```

```
395/395 [=====] - 145s 367ms/step - loss: 0.1995 - Table_mask_loss: 0.0598 - Column_mask_lc
```

```
Epoch 00028: val_loss did not improve from 0.69926
```

```
Epoch 29/50
```

```
395/395 [=====] - 145s 367ms/step - loss: 0.1928 - Table_mask_loss: 0.0571 - Column_mask_lc
```

```
Epoch 00029: val_loss did not improve from 0.69926
```

```
Epoch 30/50
```

```
395/395 [=====] - 145s 368ms/step - loss: 0.1930 - Table_mask_loss: 0.0569 - Column_mask_lc
```

```
Epoch 00030: val_loss did not improve from 0.69926
```

```
Epoch 31/50
```

```
395/395 [=====] - 145s 367ms/step - loss: 0.2848 - Table_mask_loss: 0.0893 - Column_mask_lc
```

```
Epoch 00031: val_loss did not improve from 0.69926
```

```
Epoch 32/50
```

```
395/395 [=====] - 145s 368ms/step - loss: 0.2041 - Table_mask_loss: 0.0616 - Column_mask_lc
```

```
Epoch 00032: val_loss did not improve from 0.69926
```

```
Epoch 33/50
```

```
395/395 [=====] - 145s 367ms/step - loss: 0.1874 - Table_mask_loss: 0.0544 - Column_mask_lc
```

```
Epoch 00033: val_loss did not improve from 0.69926
```

```
Epoch 34/50
```

```
395/395 [=====] - 145s 368ms/step - loss: 0.1993 - Table_mask_loss: 0.0595 - Column_mask_lc
```

```
Epoch 00034: val_loss did not improve from 0.69926
```

```
Epoch 35/50
```

```
395/395 [=====] - 145s 367ms/step - loss: 0.1981 - Table_mask_loss: 0.0576 - Column_mask_lc
```

```
Epoch 00035: val_loss did not improve from 0.69926
```

```
Epoch 36/50
```

```
395/395 [=====] - 145s 368ms/step - loss: 0.1861 - Table_mask_loss: 0.0534 - Column_mask_lc
```

```
Epoch 00036: val_loss improved from 0.69926 to 0.64264, saving model to model_save/weights-36-0.6426.hdf5
```

```

Epoch 37/50
395/395 [=====] - 145s 368ms/step - loss: 0.1664 - Table_mask_loss: 0.0464 - Column_mask_loss: 0.0732

Epoch 00037: val_loss improved from 0.64264 to 0.63377, saving model to model_save/weights-37-0.6338.hdf5
Epoch 38/50
395/395 [=====] - 145s 368ms/step - loss: 0.1547 - Table_mask_loss: 0.0411 - Column_mask_loss: 0.0725

Epoch 00038: val_loss did not improve from 0.63377
Epoch 39/50
395/395 [=====] - 145s 367ms/step - loss: 0.1557 - Table_mask_loss: 0.0412 - Column_mask_loss: 0.0725

Epoch 00039: val_loss improved from 0.63377 to 0.60328, saving model to model_save/weights-39-0.6033.hdf5
Epoch 40/50
395/395 [=====] - 145s 368ms/step - loss: 0.1539 - Table_mask_loss: 0.0394 - Column_mask_loss: 0.0725

Epoch 00040: val_loss did not improve from 0.60328
Epoch 41/50
395/395 [=====] - 145s 368ms/step - loss: 0.1732 - Table_mask_loss: 0.0491 - Column_mask_loss: 0.0725

Epoch 00041: val_loss did not improve from 0.60328
Epoch 42/50
395/395 [=====] - 146s 368ms/step - loss: 0.1369 - Table_mask_loss: 0.0334 - Column_mask_loss: 0.0725

```

```

losses = {"Table_mask" : tf.keras.losses.SparseCategoricalCrossentropy(from_logits = True),
          "Column_mask" : tf.keras.losses.SparseCategoricalCrossentropy(from_logits = True)}

```

```

loss_weights = {"Table_mask" : 1.0,
                "Column_mask" : 1.0}

```

```

model.compile(optimizer= tf.keras.optimizers.Adam(0.0001, beta_1=0.8), loss = losses, loss_weights=loss_weights, metrics = [

```

```

filepath="model_save/weights-{epoch:02d}-{val_loss:.4f}.hdf5"

```

```

checkpoint = tf.keras.callbacks.ModelCheckpoint(filepath=filepath , monitor='val_loss' ,save_best_only=True, mode='auto', v

```

```

csvlog = tf.keras.callbacks.CSVLogger("/content/results.csv")

```

```

hist = model.fit(train_dataloader, epochs =80, steps_per_epoch=train_steps, \
                 validation_data=test_dataloader, validation_steps=val_steps, callbacks=[checkpoint, csvlog])

```

Epoch 13/80  
395/395 [=====] - 281s 712ms/step - loss: 0.1111 - Table\_mask\_loss: 0.0403 - Column\_mask\_loss: 0.0298  
Epoch 00013: val\_loss improved from 0.29042 to 0.25956, saving model to model\_save/weights-13-0.2596.hdf5  
Epoch 14/80  
395/395 [=====] - 281s 711ms/step - loss: 0.0850 - Table\_mask\_loss: 0.0270 - Column\_mask\_loss: 0.0220  
Epoch 00014: val\_loss improved from 0.25956 to 0.24460, saving model to model\_save/weights-14-0.2446.hdf5  
Epoch 15/80  
395/395 [=====] - 281s 711ms/step - loss: 0.0786 - Table\_mask\_loss: 0.0236 - Column\_mask\_loss: 0.0200  
Epoch 00015: val\_loss did not improve from 0.24460  
Epoch 16/80  
395/395 [=====] - 280s 710ms/step - loss: 0.0747 - Table\_mask\_loss: 0.0216 - Column\_mask\_loss: 0.0190  
Epoch 00016: val\_loss did not improve from 0.24460  
Epoch 17/80  
395/395 [=====] - 280s 708ms/step - loss: 0.0723 - Table\_mask\_loss: 0.0206 - Column\_mask\_loss: 0.0180  
Epoch 00017: val\_loss did not improve from 0.24460  
Epoch 18/80  
395/395 [=====] - 280s 710ms/step - loss: 0.0722 - Table\_mask\_loss: 0.0203 - Column\_mask\_loss: 0.0179  
Epoch 00018: val\_loss did not improve from 0.24460  
Epoch 19/80  
395/395 [=====] - 281s 713ms/step - loss: 0.1537 - Table\_mask\_loss: 0.0702 - Column\_mask\_loss: 0.0333  
Epoch 00019: val\_loss improved from 0.24460 to 0.18593, saving model to model\_save/weights-19-0.1859.hdf5  
Epoch 20/80  
395/395 [=====] - 280s 709ms/step - loss: 0.0865 - Table\_mask\_loss: 0.0285 - Column\_mask\_loss: 0.0220  
Epoch 00020: val\_loss did not improve from 0.18593  
Epoch 21/80  
395/395 [=====] - 280s 710ms/step - loss: 0.0714 - Table\_mask\_loss: 0.0208 - Column\_mask\_loss: 0.0179  
Epoch 00021: val\_loss did not improve from 0.18593  
Epoch 22/80  
395/395 [=====] - 281s 712ms/step - loss: 0.0673 - Table\_mask\_loss: 0.0190 - Column\_mask\_loss: 0.0169  
Epoch 00022: val\_loss did not improve from 0.18593  
Epoch 23/80  
395/395 [=====] - 280s 709ms/step - loss: 0.0647 - Table\_mask\_loss: 0.0178 - Column\_mask\_loss: 0.0160

```

Epoch 00023: val_loss did not improve from 0.18593
Epoch 24/80
395/395 [=====] - 280s 708ms/step - loss: 0.0724 - Table_mask_loss: 0.0229 - Column_mask_loss: 0.0444

Epoch 00024: val_loss did not improve from 0.18593
Epoch 25/80
395/395 [=====] - 280s 710ms/step - loss: 0.0879 - Table_mask_loss: 0.0328 - Column_mask_loss: 0.0444

Epoch 00025: val_loss did not improve from 0.18593
Epoch 26/80
395/395 [=====] - 281s 712ms/step - loss: 0.0643 - Table_mask_loss: 0.0182 - Column_mask_loss: 0.0444

Epoch 00026: val_loss did not improve from 0.18593
Epoch 27/80
395/395 [=====] - ETA: 0s - loss: 0.0610 - Table_mask_loss: 0.0167 - Column_mask_loss: 0.0444

```

```
filepath="model_save/weights-{epoch:02d}-{val_loss:.4f}.hdf5"
```

```
checkpoint = tf.keras.callbacks.ModelCheckpoint(filepath=filepath, monitor='val_loss', save_best_only=True, mode='auto', verbose=1)
```

```
hist = model.fit(train_dataloader, epochs=60, steps_per_epoch=train_steps, \
                 validation_data=test_dataloader, validation_steps=val_steps, callbacks=[checkpoint])
```

```

Epoch 00002: val_loss improved from 0.14850 to 0.14367, saving model to model_save/weights-02-0.1437.hdf5
Epoch 3/60
395/395 [=====] - 280s 709ms/step - loss: 0.1029 - Table_mask_loss: 0.0391 - Column_mask_loss: 0.0444

Epoch 00003: val_loss did not improve from 0.14367
Epoch 4/60
395/395 [=====] - 280s 709ms/step - loss: 0.0981 - Table_mask_loss: 0.0345 - Column_mask_loss: 0.0444

Epoch 00004: val_loss did not improve from 0.14367
Epoch 5/60
395/395 [=====] - 280s 708ms/step - loss: 0.0762 - Table_mask_loss: 0.0222 - Column_mask_loss: 0.0444

Epoch 00005: val_loss improved from 0.14367 to 0.13915, saving model to model_save/weights-05-0.1391.hdf5
Epoch 6/60
395/395 [=====] - 279s 706ms/step - loss: 0.0707 - Table_mask_loss: 0.0197 - Column_mask_loss: 0.0444

Epoch 00006: val_loss did not improve from 0.13915
Epoch 7/60

```

```
Epoch 7/60
395/395 [=====] - 279s 707ms/step - loss: 0.0679 - Table_mask_loss: 0.0185 - Column_mask_loss: 0.0185

Epoch 00007: val_loss improved from 0.13915 to 0.13549, saving model to model_save/weights-07-0.1355.hdf5
Epoch 8/60
395/395 [=====] - 279s 707ms/step - loss: 0.0661 - Table_mask_loss: 0.0180 - Column_mask_loss: 0.0180

Epoch 00008: val_loss did not improve from 0.13549
Epoch 9/60
395/395 [=====] - 279s 708ms/step - loss: 0.0680 - Table_mask_loss: 0.0192 - Column_mask_loss: 0.0192

Epoch 00009: val_loss did not improve from 0.13549
Epoch 10/60
395/395 [=====] - 279s 707ms/step - loss: 0.0932 - Table_mask_loss: 0.0337 - Column_mask_loss: 0.0337

Epoch 00010: val_loss did not improve from 0.13549
Epoch 11/60
395/395 [=====] - 280s 709ms/step - loss: 0.0794 - Table_mask_loss: 0.0265 - Column_mask_loss: 0.0265

Epoch 00011: val_loss did not improve from 0.13549
Epoch 12/60
395/395 [=====] - 279s 707ms/step - loss: 0.0651 - Table_mask_loss: 0.0180 - Column_mask_loss: 0.0180

Epoch 00012: val_loss did not improve from 0.13549
Epoch 13/60
395/395 [=====] - 279s 707ms/step - loss: 0.0604 - Table_mask_loss: 0.0163 - Column_mask_loss: 0.0163

Epoch 00013: val_loss did not improve from 0.13549
Epoch 14/60
395/395 [=====] - 279s 706ms/step - loss: 0.0585 - Table_mask_loss: 0.0154 - Column_mask_loss: 0.0154

Epoch 00014: val_loss did not improve from 0.13549
Epoch 15/60
395/395 [=====] - 279s 706ms/step - loss: 0.0573 - Table_mask_loss: 0.0151 - Column_mask_loss: 0.0151

Epoch 00015: val_loss did not improve from 0.13549
Epoch 16/60
395/395 [=====] - 280s 709ms/step - loss: 0.1412 - Table_mask_loss: 0.0665 - Column_mask_loss: 0.0665

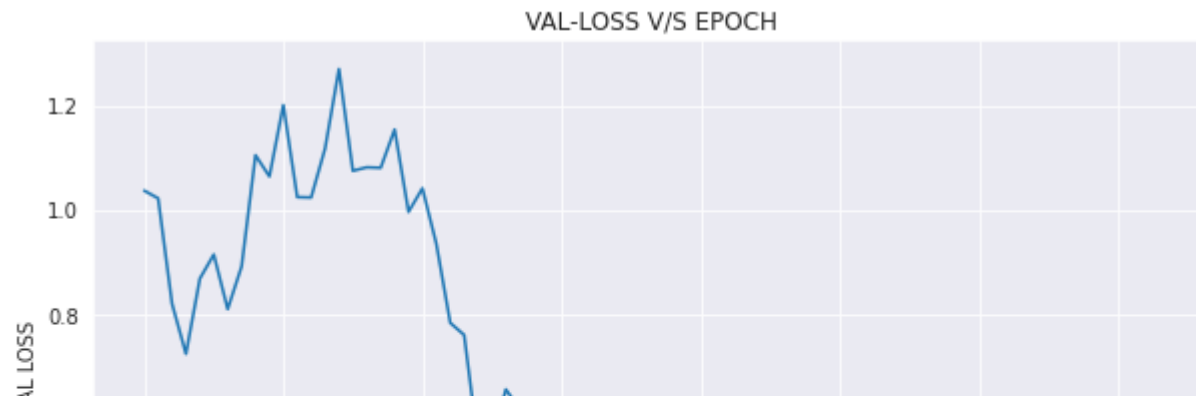
Epoch 00016: val_loss did not improve from 0.13549
```

## Plotting the metric curves :

```
df = pd.read_csv("/content/TrainingLogs.txt")
df.head()
```

	epoch	Column_mask_accuracy	Column_mask_loss	Table_mask_accuracy	Table_mask_loss	loss	val_Column_mask_accu
<b>0</b>	0	0.865139	0.314912	0.863160	0.352070	1.019052	0.884
<b>1</b>	1	0.882519	0.259748	0.881721	0.296116	0.851981	0.874
<b>2</b>	2	0.898247	0.189354	0.911400	0.199551	0.588457	0.884
<b>3</b>	3	0.905912	0.170238	0.924257	0.169564	0.509367	0.884
<b>4</b>	4	0.909222	0.160504	0.930152	0.152773	0.466050	0.874

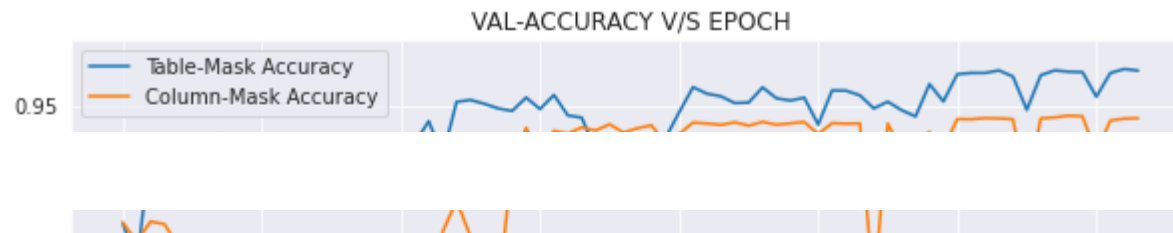
```
sns.set_style('darkgrid')
plt.figure(figsize=(10,6))
plt.plot("epoch", "val_loss", data = df)
plt.xlabel("EPOCHS")
plt.ylabel("VAL LOSS")
plt.title("VAL-LOSS V/S EPOCH")
plt.show()
```



```
plt.figure(figsize=(10,6))
```

```
plt.plot("epoch", "val_Table_mask_accuracy", data = df, label = "Table-Mask Accuracy")
plt.plot("epoch", "val_Column_mask_accuracy", data = df, label = "Column-Mask Accuracy")
plt.xlabel("EPOCHS")
plt.ylabel("VAL ACCURACY")
plt.title("VAL-ACCURACY V/S EPOCH")
plt.legend()
plt.show()
```





## ▼ Getting Predictions :

5

```
def get_mask(mask):
    mask = tf.argmax(mask, axis=-1)
    mask = mask[..., tf.newaxis]
    return mask[0]
```

0.70

```
number = 10
for image, mask in test_dataloader.take(number):
    plt.figure(figsize=(15, 15))
    mask1, mask2 = model.predict(image)
    table_mask, column_mask = get_mask(mask1), get_mask(mask2)
    image = image[0]
    lists = [image, table_mask, column_mask]
    title = ['Image', 'Table Mask', 'Column Mask']
    for i in range(len(lists)):
        plt.subplot(1, len(lists), i+1)
        plt.title(title[i])
        plt.imshow(tf.keras.preprocessing.image.array_to_img(lists[i]))
        plt.axis('off')
    plt.show()
```

The spread gain for arbitrary  $\alpha$  is derived from Equation 12 as follows:

$$R_{\text{spread}}(\alpha) = \frac{\sqrt{2\pi}}{\sqrt{1+\alpha^2}} \exp\left\{-\frac{\alpha^2}{2(1+\alpha^2)}\right\} \exp\left\{-\frac{\alpha^2}{2(1+\alpha^2)}\right\} \quad (15)$$

where  $R_{\text{spread}}(\alpha) = 1$  for the non-spread frequency function, i.e.,  $\alpha = 0$ ;  $R_{\text{spread}}(\alpha) = 0$  for  $\alpha \rightarrow \infty$ ;  $R_{\text{spread}}(\alpha) = 1$  for  $\alpha \rightarrow 0$ ; and  $R_{\text{spread}}(\alpha) = 0$  for  $\alpha \rightarrow \infty$ . We observe that  $R_{\text{spread}}(\alpha) < 1$  for  $\alpha > 0$ .

The a priori SNR  $\hat{S}(n)$  is estimated recursively as

$$\hat{S}(n) = \alpha \hat{S}(n-1) + (1-\alpha) \hat{S}(n) \quad (16)$$

using the modification proposed in [20] to take into account speech presence uncertainty.

### 3.3. Optimal gain modification under speech presence uncertainty

In order to take into account the probability of speech presence, we derive the estimator for the optimum domain:

$$\hat{S}(n) = \frac{1}{2} \left( \hat{S}(n) + \hat{S}(n) \right) \quad (17)$$

Considering  $\hat{S}_1$ , the hypothesis of speech presence for source  $s_1$ , and  $\hat{S}_2$ , the hypothesis of speech presence for source  $s_2$ , the hypothesis of speech presence for source  $s_3$  is

$$\hat{S}(n) = \frac{1}{2} \left( \hat{S}_1(n) + \hat{S}_2(n) + \hat{S}_3(n) \right) \quad (18)$$

where  $\hat{S}_i(n)$  is the probability of speech at frequency  $i$ .

The optimally modified gain is then given by:

$$\hat{S}(n) = \frac{1}{2} \left( \hat{S}_1(n) + \hat{S}_2(n) + \hat{S}_3(n) \right) \quad (19)$$

where  $\hat{S}_i(n)$  is defined in Eq. 18, and  $\hat{S}_i(n)$  is the minimum gain allowed when speech is absent. Unlike the logarithmic case, it is possible to set  $\hat{S}_i(n) = 0$  without using any prior information. For  $\alpha = 1/3$ , this leads to:

$$\hat{S}(n) = \frac{1}{2} \left( \hat{S}_1(n) + \hat{S}_2(n) + \hat{S}_3(n) \right) \quad (20)$$

Setting  $\hat{S}_i(n) = 0$  means that there is no information about the presence of speech. Therefore, when the signal is known to be non-speech, the gain can be set to zero. This is particularly important when the background is also speech noise, unlike stationary noise, modified hidden states always result in residual noise.

The probability of speech presence is computed as

$$\hat{S}(n) = \frac{1}{2} \left( \frac{1}{2} \left( \hat{S}_1(n) + \hat{S}_2(n) \right) + \hat{S}_3(n) \right) \quad (21)$$

**Table 3. Log spectral deviation and temporal SNR for each of the 3 separated sources.**

Source	Log SD	Temporal SNR
Speech	0.1	10.0
Music	0.2	10.0
Background	0.3	10.0

where  $\hat{S}_i(n)$  is the a priori probability of speech presence for frequency  $i$ , and is defined as:

$$\hat{S}_i(n) = 1 - \hat{P}_{\text{non-speech}}(i) \quad (22)$$

where  $\hat{P}_{\text{non-speech}}(i)$ ,  $\hat{P}_{\text{speech}}(i)$  and  $\hat{P}_{\text{noise}}(i)$  are defined in [20] and correspond respectively to a speech measurement on the current frame for a fixed frequency window, a target frequency and for the whole frame.

## 4. RESULTS

The system is evaluated in a context of mobile vehicles, where an error of 10 milliseconds is considered as a reliable error. In order to test the system, 10000 frames of 100ms are used.

1. **Speech presence detection.** In a quiet environment, the background noise was recorded on a mobile phone and a computer of sample frequency and channel rate 48 kHz. Four speech rates recorded using the same microphone setup and the same setup were used to allow SNR and distortion.

2. **Speech presence detection.** In evaluating our gain filter, we use both the temporal SNR and the log spectral deviation LSD, which is defined as:

$$\text{LSD} = \frac{1}{N} \sum_{n=1}^N \left( \frac{1}{M} \sum_{m=1}^M \left( \frac{R(n, m)}{R(n, m)} \right)^2 \right) \quad (23)$$

where  $N$  is the number of frames,  $M$  is the number of the samples in one frame, and  $R(n, m)$  is the magnitude of the signal.

Table 3 compares the results for the separation of each of the 3 separated sources, both described in [11]. The first two sources were used to test the other sources, while the third source was used.

The improvement of our gain filter is shown in terms of SNR and LSD, which are compared by reference to the original.

The improvement for the first source (speech) is shown in Figure 1. Even though the two sources were stationary and the same frequency content as the signal of interest, we observe that our method outperforms the single-channel gain filter in terms of SNR and LSD.

Table 4 shows the results for the second source (speech), while not causing excessive distortion to the signal of interest.

## Image

## Table Mask

## Column Mask



## Image

## Table Mask

## Column Mask



## Image

## Table Mask

## Column Mask



**Packet fields.** Description

packet header: the destination's unique identifier

packet body: the destination's unique identifier

packet footer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

packet trailer: the destination's unique identifier

**Algorithm 1: RTR forwarding algorithm.**

1. **Input:** A packet header and body.

2. **Output:** A packet header and body.

3. **Input:** A packet header and body.

4. **Output:** A packet header and body.

5. **Input:** A packet header and body.

6. **Output:** A packet header and body.

7. **Input:** A packet header and body.

8. **Output:** A packet header and body.

9. **Input:** A packet header and body.

10. **Output:** A packet header and body.

11. **Input:** A packet header and body.

12. **Output:** A packet header and body.

13. **Input:** A packet header and body.

14. **Output:** A packet header and body.

15. **Input:** A packet header and body.

16. **Output:** A packet header and body.

17. **Input:** A packet header and body.

18. **Output:** A packet header and body.

19. **Input:** A packet header and body.

20. **Output:** A packet header and body.

21. **Input:** A packet header and body.

22. **Output:** A packet header and body.

Table 1 summarizes the parameters in our IWR algorithm and Algorithm 1 lists the pseudocode for the forwarding algorithm. Forwarding a message starts with a greedy search for a neighbor that improves the maximum distance we have seen so far. When forwarding the message, the current node (observed node) chooses among its neighbors the node that the maximum distance to the destination. We start using the  $k$  closest neighbors to the destination, and if there is no improvement, we incrementally drop neighbors from the candidate list.

If we do not find a neighbor that improves on  $d_{\text{observed}}$ , the only way to move is to back track. In back track mode, a node forwards the packet towards the source closer to the destination, i.e., it sends the packet to its parent in the corresponding broadcast tree. The packet will forward as usual, then attempting to forward the message greedily and failing.

The algorithm, as described so far, assumes that the originating node knows the coordinates of the intended destination. Depending on the application, it may be necessary for the originating node to first look up the coordinates by name, so we must provide a distance-mapping node identifier to coordinates. We describe a simple mechanism to achieve this functionality, but we have not focused on this mechanism in this paper. Our development uses the location as a set of string nodes. A consistent hashing [3] provides a mapping  $W \rightarrow \text{string}$  or backward from nodes to the set of locations. In all nodes store  $W$  locations, they make  $W$  entries, and consistently compute this mapping. The location set may then consist of these entries, each node  $k$  periodically publishes its coordinates to its corresponding location set.

Since the set of  $d_{\text{observed}}$  entries that change with every hop.

## Image

## Table Mask

## Column Mask

Principles of Infection Control and Protection During Military Deployment

TABLE 40.0

BASIC AND EXPANDED HIV POSTEXPOSURE PROPHYLAXIS REGIMENS<sup>1</sup>

Regimen Category	Application	Drug Regimen
Basic	Unexposed HIV exposures for which there is a recognized transmission risk	<p>z-AK (30 mL) of both zidovudine 300 mg every day (in divided doses) or 300 mg twice a day (50 mg three times a day) 100 mg every 8 h and lamivudine 150 mg twice a day</p> <p>Basic regimen plus either didanosine<sup>2</sup> 300 mg every 8 h or zalcitabine 360 mg 3 times a day<sup>3</sup></p>
Expanded	Unexposed HIV exposures that pose an increased risk for transmitting, longer exposure of blood and/or higher viral-load (undefined)	<p>Basic regimen plus either didanosine<sup>2</sup> 300 mg every 8 h or zalcitabine 360 mg 3 times a day<sup>3</sup></p>

<sup>1</sup>For all HIV exposures, a 1-week post-exposure prophylaxis (PEP) regimen should be initiated. The regimen is subject to change. <sup>2</sup>For all HIV exposures, a 1-week post-exposure prophylaxis (PEP) regimen should be initiated. The regimen is subject to change. <sup>3</sup>For all HIV exposures, a 1-week post-exposure prophylaxis (PEP) regimen should be initiated. The regimen is subject to change.

Immunization practices are now associated with high rates of immunity to most of these agents in US forces. However, there agents remain common in some parts of the world. Many members of military communities, even those with developed countries, are susceptible to some of these agents due to differences in immunization practices.

The likelihood of a US military health care worker being exposed to tuberculosis is significant in certain

refugee situations and may necessitate vaccination practices and postexposure prophylaxis. The military health-care system should also be prepared to provide prophylaxis in the event of exposure to immunological and other infections in addition to these diseases. Although information on basic terms such as the need for frequent handwashing and the use of barrier equipment remains central to proper occupational health in the deployed setting.



## ▼ Evaluating Performance :

```
model.load_weights("/content/model_save/weights-08-0.1101.hdf5")
```

```
def f1_score(true, pred):  
    ''' Returns F1-Score '''  
    re = tf.keras.metrics.Recall()  
    re.update_state(true, pred)  
    re = re.result().numpy()  
  
    pr = tf.keras.metrics.Precision()  
    pr.update_state(true, pred)
```

```
pr = pr.result().numpy()
```

```
f1 = 2*(re * pr)/(re + pr)
return f1
```

```
table , column = [] , []
predicted_table_mask , predicted_column_mask = list() , list()
for image, mask in test_dataloader.take(Test.shape[0]):
    table.append(mask['Table_mask'][0])
    column.append(mask['Column_mask'][0])

    mask1, mask2 = model.predict(image)
    table_mask, column_mask = get_mask(mask1),get_mask(mask2)

    predicted_table_mask.append(table_mask)
    predicted_column_mask.append(column_mask)

print("F1-Score for Table Masks : ",f1_score(table , predicted_table_mask))
print("-"*70)
print("F1-Score for Column Masks : ",f1_score(column , predicted_column_mask))

F1-Score for Table Masks :  0.9420742650539058
-----
F1-Score for Column Masks :  0.8512543315886713
```

## ▼ Extracting Data from Tables :

```
def get_mask(mask):
    mask = tf.argmax(mask, axis=-1)
    mask = mask[..., tf.newaxis]
    return mask[0]
```

```
def table_detection(path) :
    """Returns the table masks for the given path"""
```

```

"""Detects and returns the table(s) in an image"""
#reading , resizing and normalizing for image data
image = tf.io.read_file(path)
image = tf.image.decode_bmp(image, channels=3)
image = tf.image.resize(image, [1024, 1024]) #Decode a JPEG-encoded image to a uint8 tensor
image = tf.cast(image, tf.float32) / 255.0 # normalizing image

mask1, mask2 = model.predict(image[np.newaxis,:,:,:])
table_mask, column_mask = get_mask(mask1), get_mask(mask2)

im1=tf.keras.preprocessing.image.array_to_img(image)
im1.save('/content/Testing/image.png')

im2=tf.keras.preprocessing.image.array_to_img(table_mask)
im2.save('/content/Testing/table_mask.png')

im3=tf.keras.preprocessing.image.array_to_img(column_mask)
im3.save('/content/Testing/column_mask.png')

img_org = Image.open('/content/Testing/image.png')
img_org = img_org.resize((1024,1024),Image.ANTIALIAS)

print("\n")
print('\033[1m' + "INPUT IMAGE :" + '\033[0m')
print("\n")

plt.figure(figsize=(10,40))
plotting = plt.imshow(img_org,cmap='gray')
plt.show()

print("\n")
print("-"*90)
print("\n")

print("\n")
print('\033[1m' + "OUTPUT IMAGE :" + '\033[0m')
print("\n")

```

```

table_mask = Image.open('/content/Testing/table_mask.png')
table_mask = table_mask.resize((1024,1024),Image.ANTIALIAS)
col_mask = Image.open('/content/Testing/column_mask.png')
#col_mask = col_mask.resize((1024,1024),Image.ANTIALIAS)

```

```

img_mask = table_mask.convert('L')
# img_mask = col_mask.convert('L')

```

```

img_org.putalpha(img_mask)

```

```

plt.figure(figsize=(10,40))
plotting = plt.imshow(img_org,cmap='gray')
plt.show()

```

```

img_org.save('/content/Testing/output.png')

```

```

return

```

```

def get_text():

```

```

#read your file
file=r'/content/Testing/output.png'
img = cv2.imread(file,0)

```

```

#thresholding the image to a binary image
thresh,img_bin = cv2.threshold(img,128,255,cv2.THRESH_BINARY | cv2.THRESH_OTSU)
#inverting the image
img_bin = 255-img_bin
cv2.imwrite('/content/Testing/cv_inverted.png',img_bin)

```

```

# Length(width) of kernel as 100th of total width
kernel_len = np.array(img).shape[1]//100
# Defining a vertical kernel to detect all vertical lines of image
ver_kernel = cv2.getStructuringElement(cv2.MORPH_RECT, (1, kernel_len))
# Defining a horizontal kernel to detect all horizontal lines of image
hor_kernel = cv2.getStructuringElement(cv2.MORPH_RECT, (kernel_len, 1))

```



```

hor_kernel = cv2.getStructuringElement(cv2.MORPH_RECT, (kernel_len, 1))
# A kernel of 2x2
kernel = cv2.getStructuringElement(cv2.MORPH_RECT, (2, 2))

#Use vertical kernel to detect and save the vertical lines in a jpg
image_1 = cv2.erode(img_bin, ver_kernel, iterations=3)
vertical_lines = cv2.dilate(image_1, ver_kernel, iterations=3)
cv2.imwrite("/content/Testing/vertical.jpg",vertical_lines)

#Use horizontal kernel to detect and save the horizontal lines in a jpg
image_2 = cv2.erode(img_bin, hor_kernel, iterations=3)
horizontal_lines = cv2.dilate(image_2, hor_kernel, iterations=3)
cv2.imwrite("/content/Testing/horizontal.jpg",horizontal_lines)

# Combine horizontal and vertical lines in a new third image, with both having same weight.
img_vh = cv2.addWeighted(vertical_lines, 0.9, horizontal_lines, 0.1, 0.0 )
#Eroding and thesholding the image
img_vh = cv2.erode(~img_vh, kernel, iterations=2)
thresh, img_vh = cv2.threshold(img_vh,128,255, cv2.THRESH_BINARY)
cv2.imwrite("/content/Testing/img_vh.jpg", img_vh)
bitxor = cv2.bitwise_xor(img,img_vh)
bitnot = cv2.bitwise_not(bitxor)

im1=tf.keras.preprocessing.image.array_to_img(bitnot[:, :, np.newaxis])
im1.save('/content/Testing/image1.png')

img_mask = Image.open('/content/Testing/column_mask.png')
img_mask = img_mask.resize((1024,1024),Image.ANTIALIAS)

img_mask = img_mask.convert('L')
im1 = Image.open('/content/Testing/image1.png')
im1 = im1.resize((1024,1024),Image.ANTIALIAS)

im1.putalpha(img_mask)
im1.save('/content/Testing/image1.png')

print("\n")
print("-"*99)

```

```
print( - 100)
print("\n")
print('\033[1m' + "RETRIEVED TEXT :" + '\033[0m')
print("\n")
```

```
text_list = pytesseract.image_to_string(Image.open('/content/Testing/image1.png'), lang='eng' )
text_list = text_list.split('\n')
while("" in text_list) :
    text_list.remove("")
while(" " in text_list) :
    text_list.remove(" ")
while("  " in text_list) :
    text_list.remove("  ")

for i in text_list:
    print(i)
```

```
!rm -rf ./content/Testing
```

## **EXAMPLE 1 :**

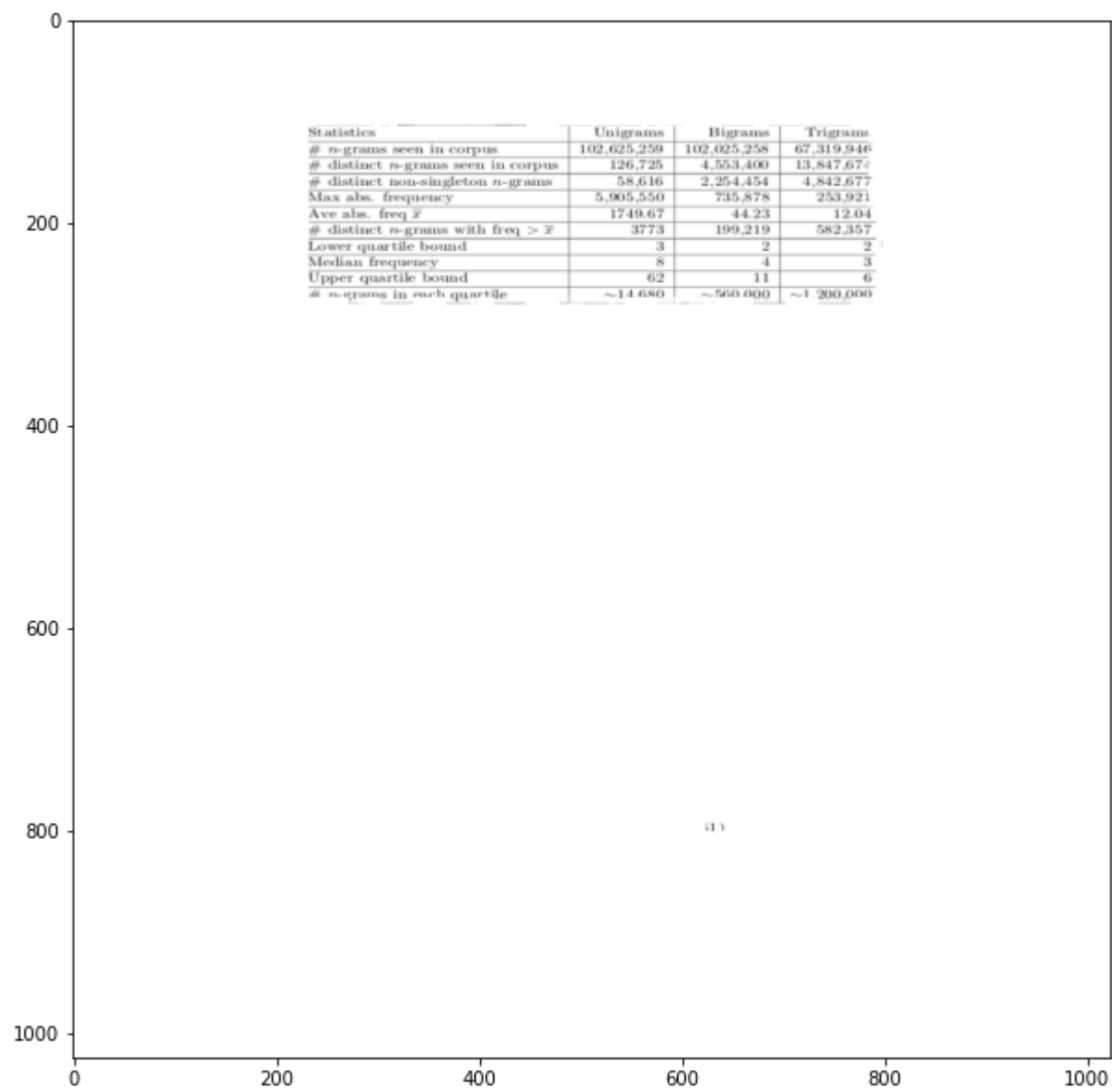
```
table_detection('/content/Data/10.1.1.1.2139_44.bmp')

get_text()
```

INPUT IMAGE :



OUTPUT IMAGE :



-----

RETRIEVED TEXT :

**EXAMPLE 2:**

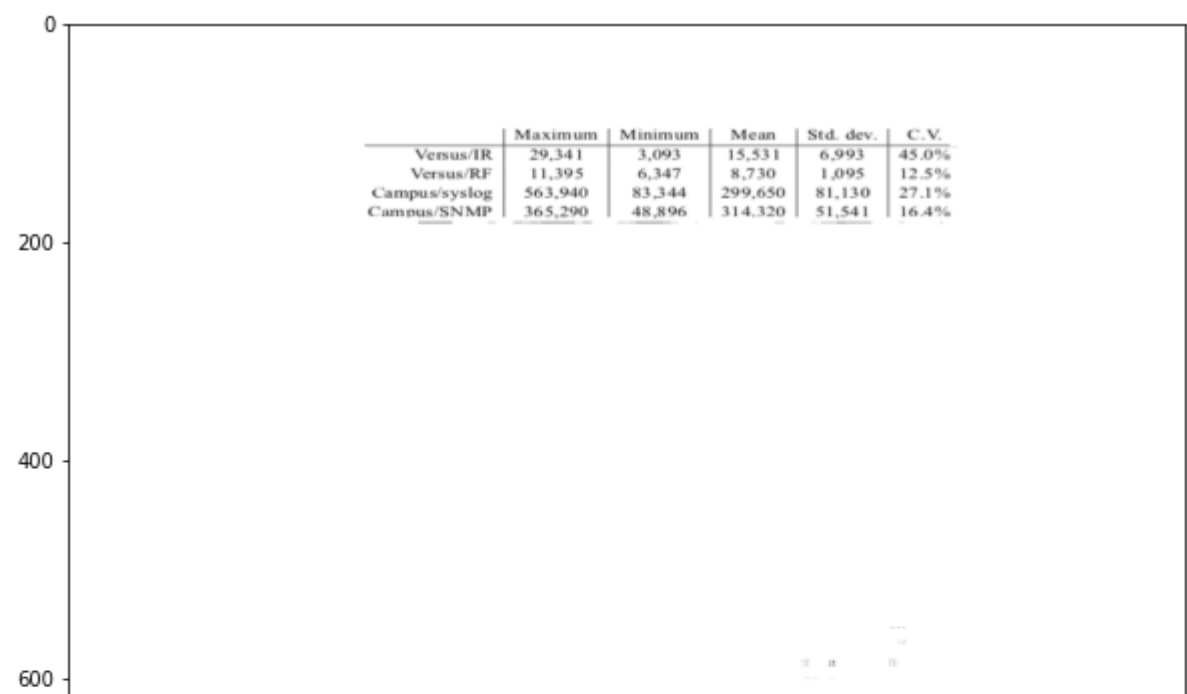
```
# Detects the image type and returns the image type and the image data
# Detects the image type and returns the image type and the image data
table_detection('/content/Data/10.1.1.1.2076_85.bmp')

get_text()
```

INPUT IMAGE :



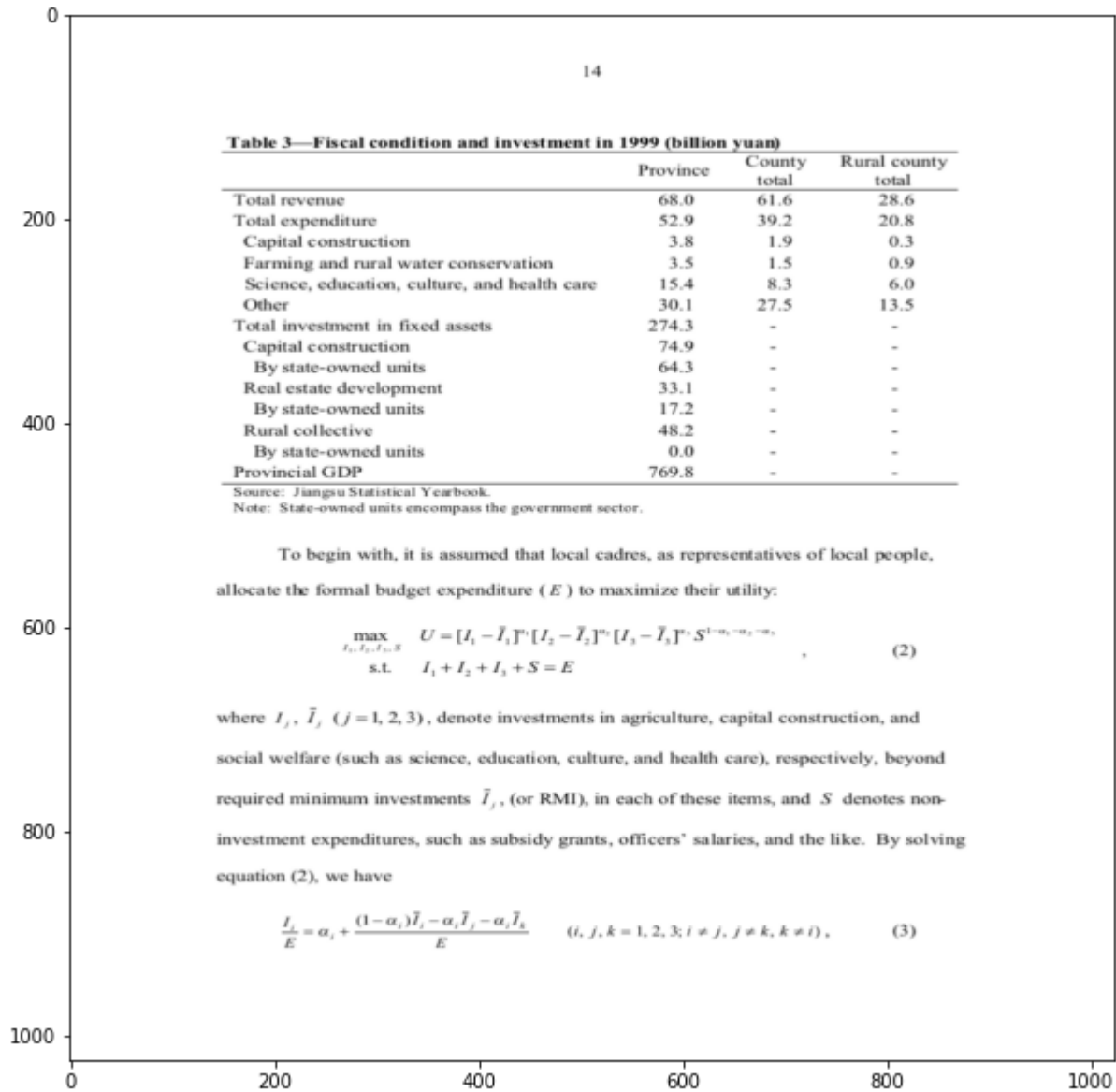
OUTPUT IMAGE :



EXAMPLE 3:

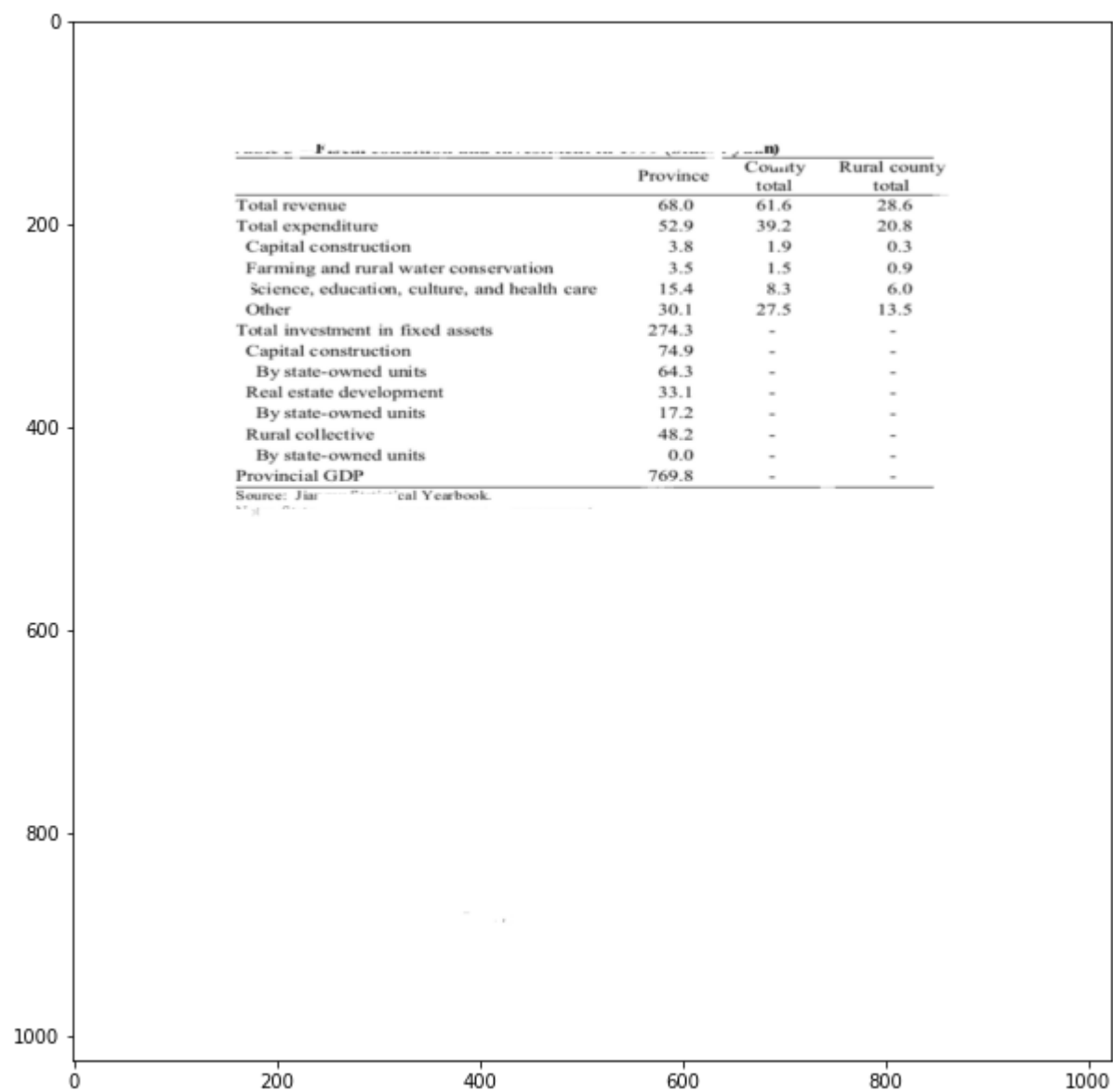
```
table_detection('content/Data/10.1.1.1.2084_18.bmp')  
  
get_text()
```

INPUT IMAGE :





OUTPUT IMAGE :



-----

**RETRIEVED TEXT :**

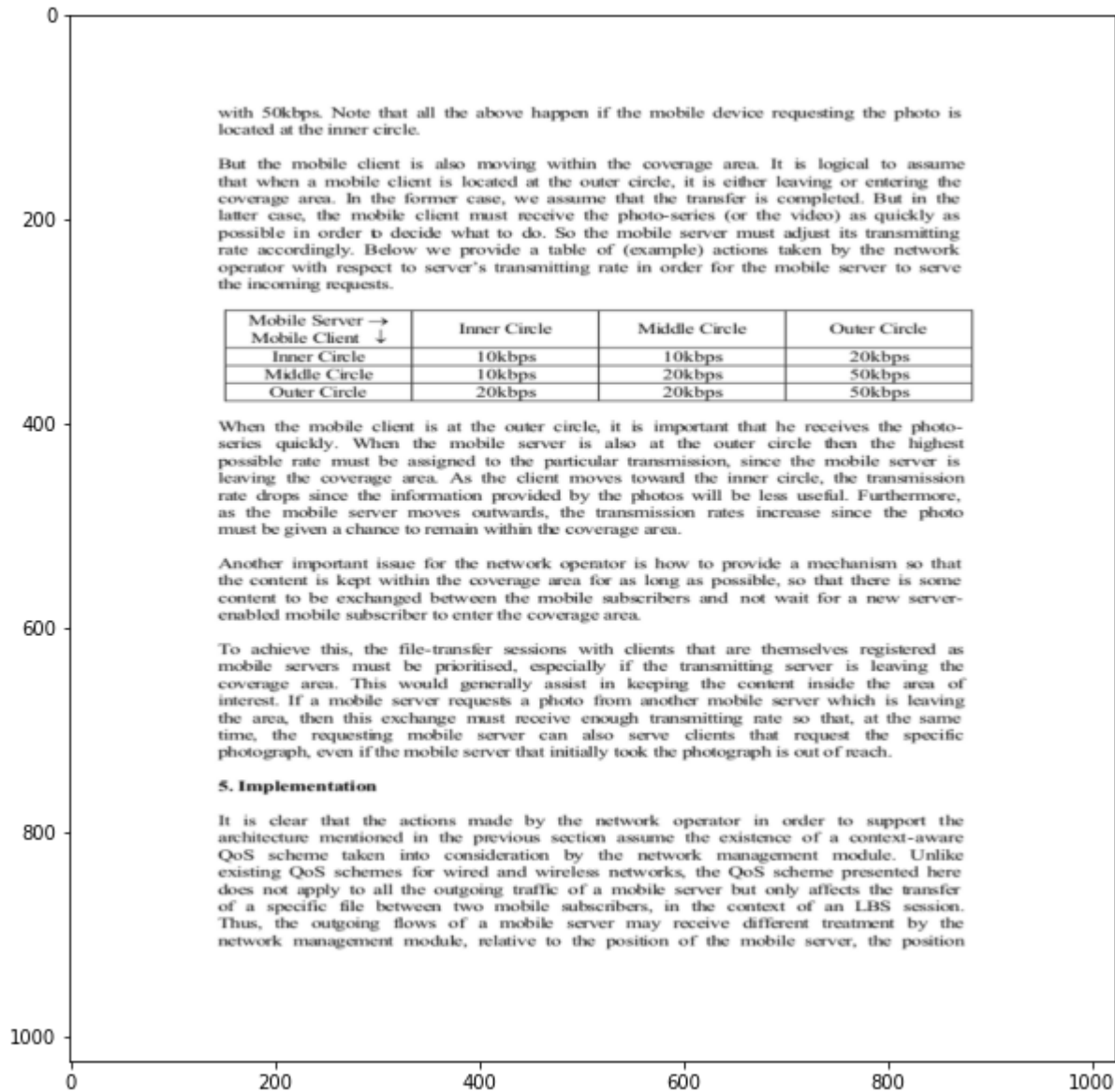
```
unity > ural county
total total
Total revenue 68.0 61.6 28.6
Total expenditure 52.9 39.2 20.8
Capital construction 3.8 1.9 0.3
arming and rural water conservation 3.5 1s 0.9
Science, education, culture, and health care 15.4 8.3 6.0
Other 30.1 27.5 13.5
Total investment in fixed assets 274.3 - -
Capital construction 74.9 - -
Capital construction 74.9 - -
```

**EXAMPLE 4:**

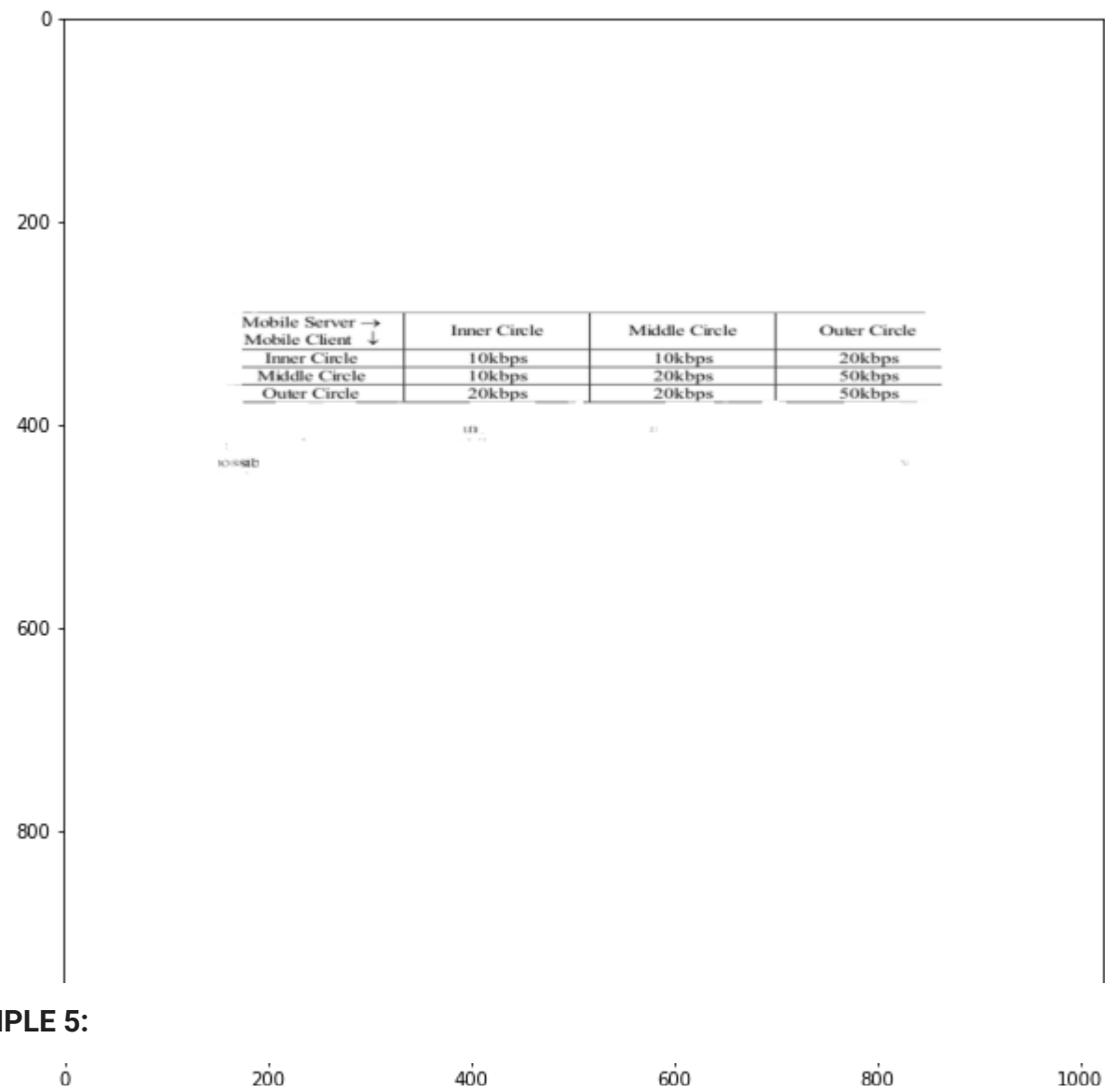
```
Rural collective 48 2 - -
table_detection('/content/Data/10.1.1.6.2366_6.bmp')

get_text()
```

INPUT IMAGE :



OUTPUT IMAGE :

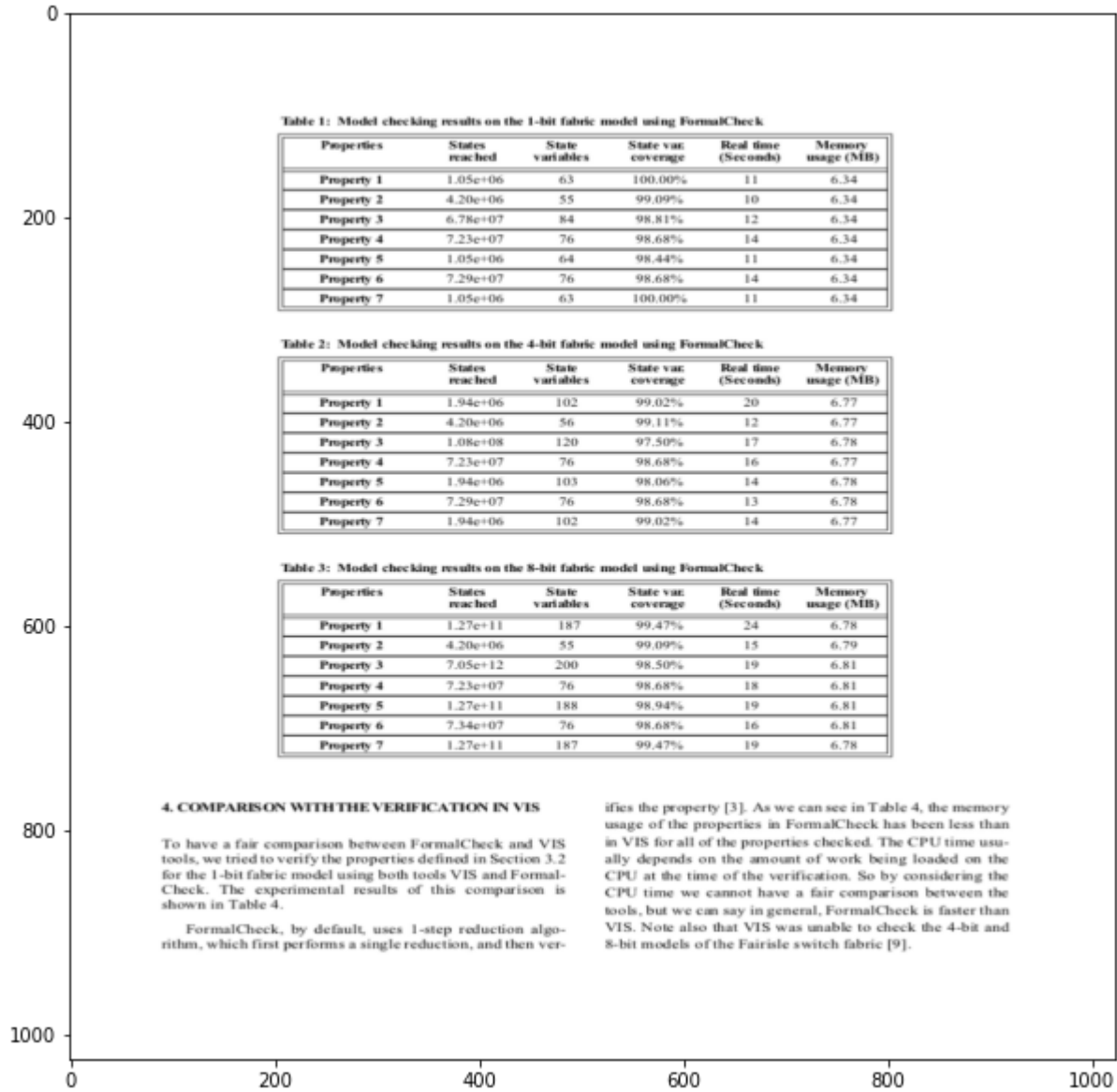


EXAMPLE 5:

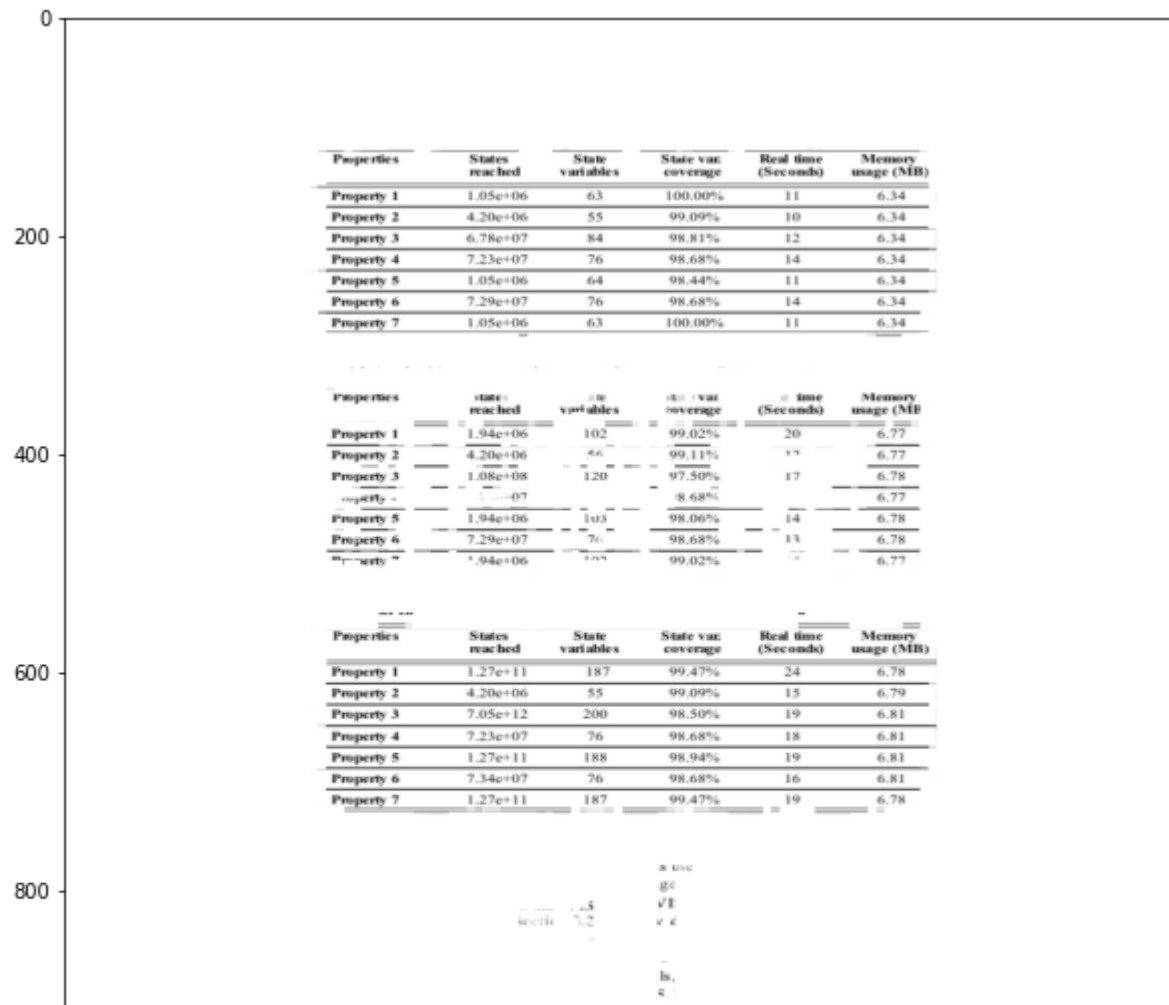
```
table_detection('/content/Data/10.1.1.8.2156_5.bmp')
```

get\_text()

INPUT IMAGE :



OUTPUT IMAGE :



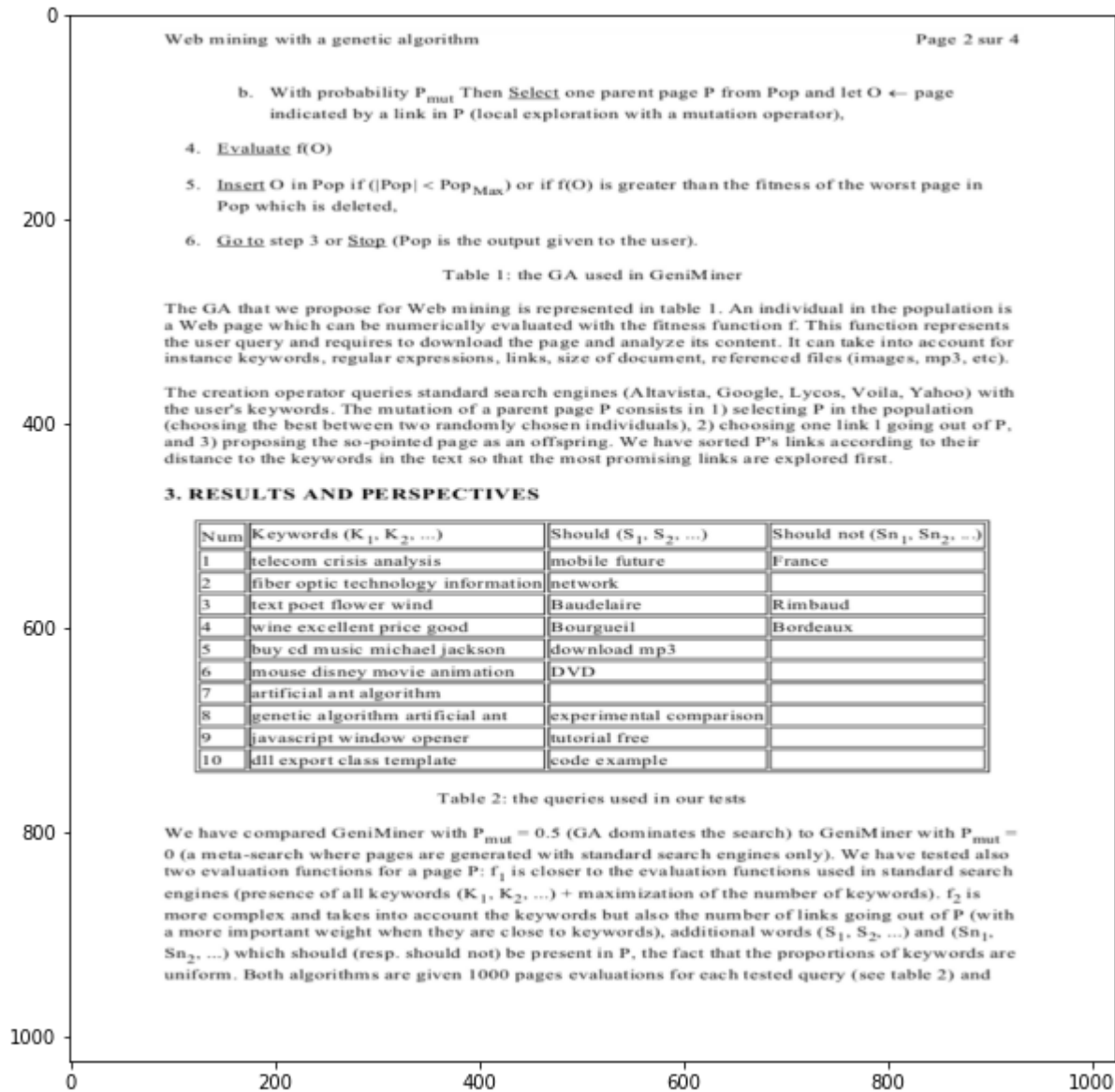
### EXAMPLE 6:

```
1000 |  
table_detection('/content/Data/10.1.1.12.797_2.bmp')  
  
get_text()
```





INPUT IMAGE :



OUTPUT IMAGE :



### ▼ TableNet(Using ResNet50 Encoder) :



```
class tbl_decoder(tf.keras.layers.Layer):
    def __init__(self, name = "Table_mask"):
        super().__init__(name = name)
        self.conv1 = Conv2D(filters=512, kernel_size=(1,1), activation='relu')
        self.umsample1 = UpSampling2D(size = (2,2),)
        self.umsample2 = UpSampling2D(size = (2,2),)
        self.umsample3 = UpSampling2D(size = (2,2),)
        self.umsample4 = UpSampling2D(size = (2,2),)
        self.convtranspose = Conv2DTranspose( filters=3, kernel_size=3, strides=2, padding = 'same')

    def call(self, X):
```

```

input,pool_3,pool_4 = X[0],X[1],X[2]
x = self.conv1(input)
x = self.upsample1(x)
x = concatenate([x, pool_4])
x = self.upsample2(x)
x = concatenate([x, pool_3])
x = self.upsample3(x)
x = self.upsample4(x)
x = self.convtranspose(x)

```

```

return x

```

```

class col_decoder(tf.keras.layers.Layer):
    def __init__(self, name = "Column_mask"):
        super().__init__(name = name)
        self.conv1 = Conv2D(filters=512, kernel_size=(1,1), activation='relu')
        self.drop = Dropout(0.8)
        self.conv2 = Conv2D(filters=512, kernel_size=(1,1), activation='relu')
        self.upsample1 = UpSampling2D(size = (2,2),)
        self.upsample2 = UpSampling2D(size = (2,2),)
        self.upsample3 = UpSampling2D(size = (2,2),)
        self.upsample4 = UpSampling2D(size = (2,2),)
        self.convtranspose = Conv2DTranspose( filters=3, kernel_size=3, strides=2, padding = 'same')

```

```

def call(self, X):

```

```

    input,pool_3,pool_4 = X[0],X[1],X[2]
    x = self.conv1(input)
    x = self.drop(x)
    x = self.conv2(x)
    x = self.upsample1(x)
    x = concatenate([x, pool_4])
    x = self.upsample2(x)
    x = concatenate([x, pool_3])
    x = self.upsample3(x)
    x = self.upsample4(x)
    x = self.convtranspose(x)

```

```

return x

```

```

input = Input(shape=(1024,1024,3))

resnet50 = tf.keras.applications.ResNet50(include_top=False, weights='imagenet', input_tensor=input, classes=1000)

x = resnet50.output
pool_3 = resnet50.get_layer('conv3_block4_out').output # (128,128)
pool_4 = resnet50.get_layer('conv4_block6_out').output # (64,64)

x = Conv2D(512, (1, 1), activation = 'relu', name='block6_conv1')(x)
x = Dropout(0.8, name='block6_dropout1')(x)
x = Conv2D(512, (1, 1), activation = 'relu', name='block6_conv2')(x)
x = Dropout(0.8, name = 'block6_dropout2')(x)

Table_Decoder = tbl_decoder()
Column_Decoder = col_decoder()

output1 = Table_Decoder([x, pool_3, pool_4])
output2 = Column_Decoder([x, pool_3, pool_4])

model = Model(inputs = input, outputs= [output1,output2], name = "TableNet")
model.summary()

```

Downloading data from [https://storage.googleapis.com/tensorflow/keras-applications/resnet/resnet50\\_weights\\_tf\\_dim\\_ordering\\_weights\\_tf\\_dim\\_ordering\\_tf\\_kernels/94773248/94765736](https://storage.googleapis.com/tensorflow/keras-applications/resnet/resnet50_weights_tf_dim_ordering_weights_tf_dim_ordering_tf_kernels/94773248/94765736) [=====] - 1s 0us/step  
 Model: "TableNet"

Layer (type)	Output Shape	Param #	Connected to
=====			
input_1 (InputLayer)	[(None, 1024, 1024, 0		
conv1_pad (ZeroPadding2D)	(None, 1030, 1030, 3 0		input_1[0][0]
conv1_conv (Conv2D)	(None, 512, 512, 64) 9472		conv1_pad[0][0]
conv1_bn (BatchNormalization)	(None, 512, 512, 64) 256		conv1_conv[0][0]
conv1_relu (Activation)	(None, 512, 512, 64) 0		conv1_bn[0][0]