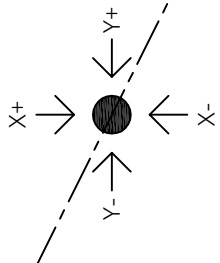
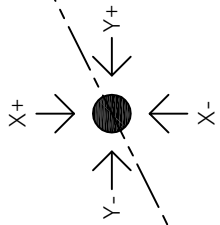


Calibration Graph for Freenove Quadruped Robot

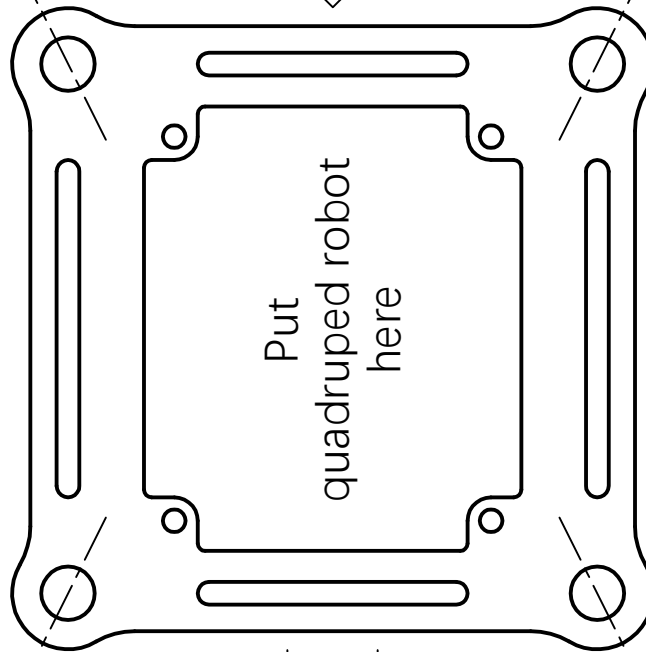


Leg 1



Leg 2

100mm
Print this graph on A4 paper with the proportion of 1:1



Put
quadruped robot
here

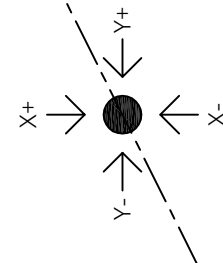
USB port
is here



Align the bottom of
robot to this shape

Z+: perpendicular to this paper and upward
Z-: Perpendicular to this paper and down

Leg 3



Leg 4

