

# Greedy Algorithms

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# Changelog

## □ Rev. 1

- Used a more consistent notation (i.e.,  $f_x$  and  $f_y$ ) for frequency of  $x$  and  $y$  nodes. (slide 26)

## □ Rev. 2

- If it *is* different ... (slide 9)

# Overview

- ❑ Introduction
- ❑ Fractional knapsack problem
- ❑ Activity-selection problem
- ❑ Huffman codes
- ❑ Sample problems

# Introduction

- ❑ Greedy algorithms, like dynamic programming, used to solve optimization problems.
  - Dynamic programming is powerful but yet overkill for certain problems.
- ❑ Problems of interest must exhibit
  - Optimal substructure (like dynamic programming).
  - The **greedy-choice** property.
    - When we have a choice to make, make the one that looks best *right now*.
    - Make a **locally optimal choice** in hope of getting a **globally optimal solution**.
- ❑ Clearly, greedy algorithms don't always yield optimal solutions.
  - ...but for many problems they do 😊



Greedy Algorithms

# Fractional Knapsack Problem

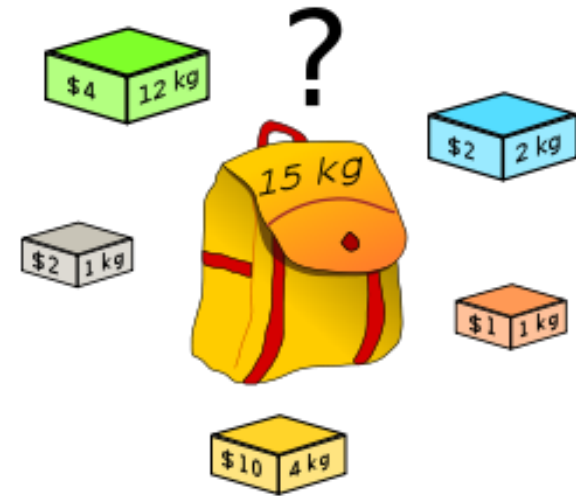
# Fractional Knapsack Problem

□ Given  $n$  objects, with weights  $w_1, w_2, \dots, w_n$  and values  $v_1, v_2, \dots, v_n$ .

□ **0-1 knapsack problem:** Objects can be taken as a whole.

$$\begin{aligned} &\text{Maximize } \sum_{i=1}^n x_i v_i \\ &\text{subject to } \sum_{i=1}^n x_i w_i \leq W \text{ and } x_i \in \{0, 1\} \end{aligned}$$

➤ Solution: Dynamic programming. We have seen it before.



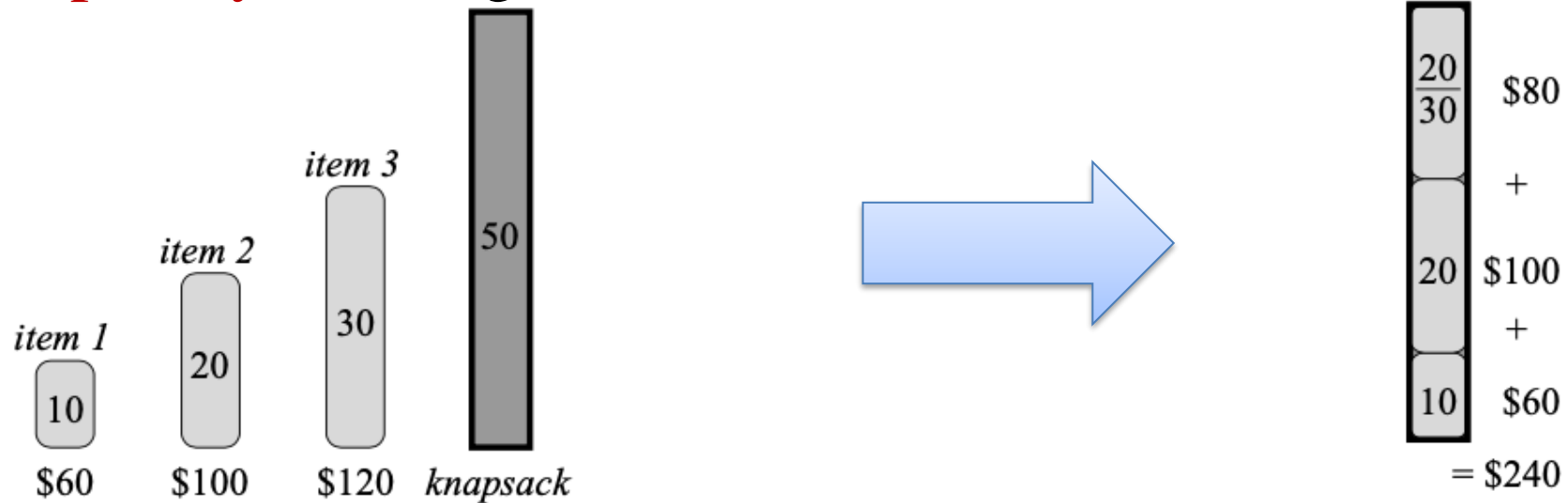
□ **Fractional knapsack problem:** Objects can be taken partially.

$$\begin{aligned} &\text{Maximize } \sum_{i=1}^n x_i v_i \\ &\text{subject to } \sum_{i=1}^n x_i w_i \leq W \text{ and } 0 \leq x_i \leq 1 \end{aligned}$$

➤ Solution: Greedy algorithm. Let's see how it works.

# A Greedy Solution

- ❑ In every step, take as much as possible of any remaining object with the highest  $\frac{v_i}{w_i}$ .
- ❑ **Greedy choice:** Taking an object with the highest  $\frac{v_i}{w_i}$ .
- ❑ **Runtime complexity:**  $O(n \log n)$
- ❑ Example:



**But does it yield an optimum solution?**

# Proof of Optimality

- Assume object indices are sorted with decreasing order by  $\frac{v_i}{w_i}$ .
- Suppose by **contradiction**,  $ALG = \{p_1, p_2, \dots, p_n\}$  is a greedy algorithm which isn't optimal, whereas  $OPT = \{q_1, q_2, \dots, q_n\}$  is. In other words,  $\sum_{i=1}^n p_i v_i < \sum_{i=1}^n q_i v_i$ .
- Let  $i$  be the smallest index where  $p_i \neq q_i$ .
  - Greedy choice tell us than  $p_i > q_i$ .
  - By the optimality of  $OPT$ , there exists a  $j$  where  $p_j < q_j$ .
- Now consider another solution  $OPT' = \{q'_1, q'_2, \dots, q'_n\}$ , where  $q'_k = q_k$  for all  $k \neq i, j$ .
  - $OPT'$  takes a little more of item  $i$  and a little less of item  $j$  compared to  $OPT$ :
    - $q'_i = q_i + \varepsilon$  ( $q'_i \leq 1$ ) and  $q'_j = q_j - \varepsilon w_i/w_j$ . The total weight remains the same:  $\sum_{i=1}^n q'_i w_i = \sum_{i=1}^n q_i w_i$ .
    - Total value increases though:  $\sum_{i=1}^n q'_i v_i = \sum_{i=1}^n q_i v_i + \varepsilon v_i - \varepsilon \frac{w_i}{w_j} v_j > \sum_{i=1}^n q_i v_i$ .
- $OPT'$  is a better solution than  $OPT$ , which is a **contradiction**. Hence,  $ALG$  is optimum.



# A Way to Prove Optimality of Greedy Algorithms

- ❑ Use contradiction.
- ❑ Find the most similar solution to the greedy solution.
  - If it's identical to the greedy solution, the problem is solved.
  - If it is different than the greedy solution, make another solution, which is not worse than the optimal solution but is more similar to the greedy solution.
    - Use this new solution arrive reach a contradiction.

# Wrap Up

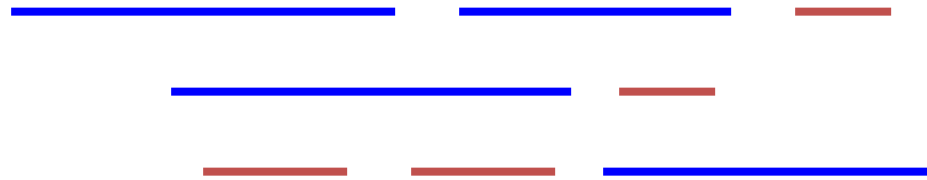
- ❑ Define the greedy choice.
- ❑ Prove that the greedy choice is optimal.
- ❑ Due to the optimal subproblem property, the remaining smaller problem is still similar to the original problem. Hence, using recursing and the greedy choice, one can solve the entire problem.
  - Usually, it's easy (and recommended) to convert a recursive greedy algorithm to iterative.

Greedy Algorithms

# Activity-Selection Problem

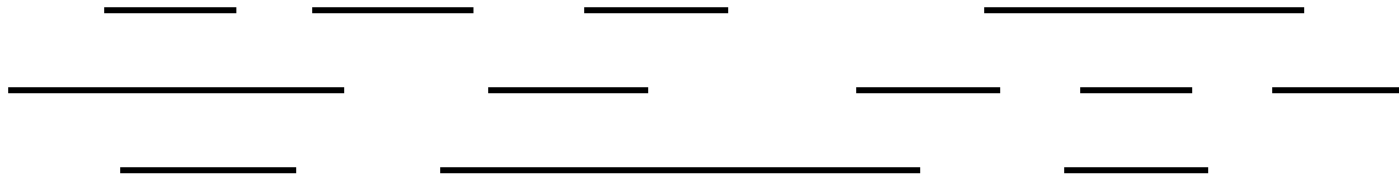
# Activity-Selection Problem

- **Given:**  $n$  activities with start and finish times denoted by  $[s_i, f_i]$ .
- **Problem:** Find a maximum set of compatible activities. Activity  $i$  and  $j$  are compatible if they don't overlap, i.e., either  $f_i < s_j$  or  $f_j < s_i$ .
- **Example:**

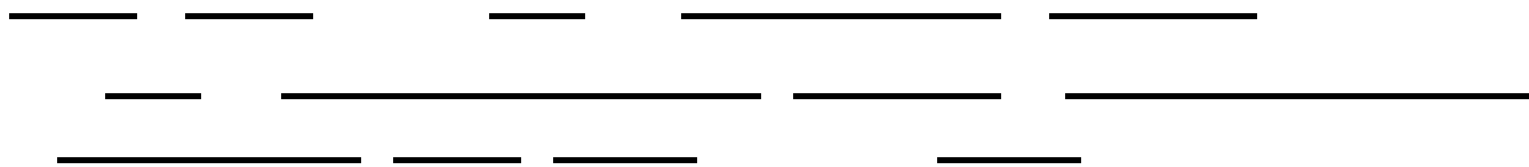


# Greedy Choices: A Few Examples

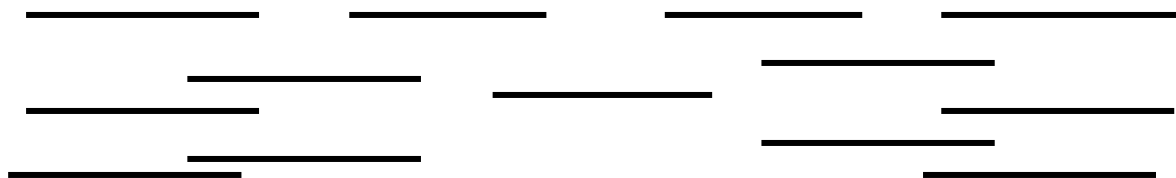
- ❑ Schedule earliest starting task



- ❑ Schedule shortest available task

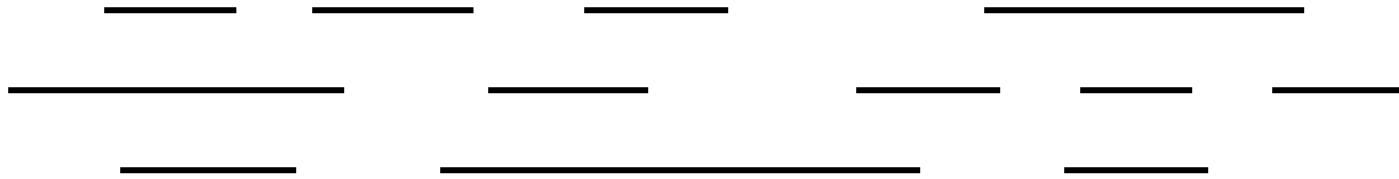


- ❑ Schedule task with fewest conflicting tasks

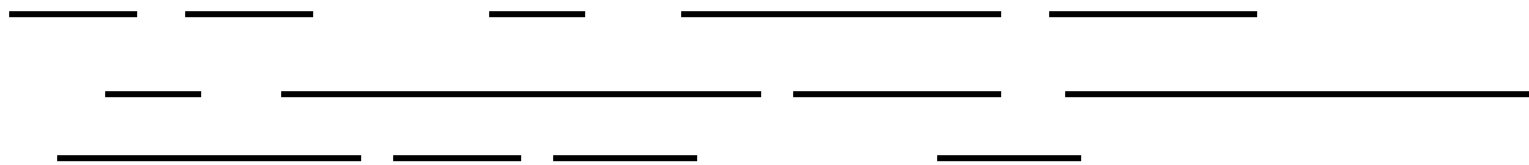


# Greedy Choices: Earliest Finish Time

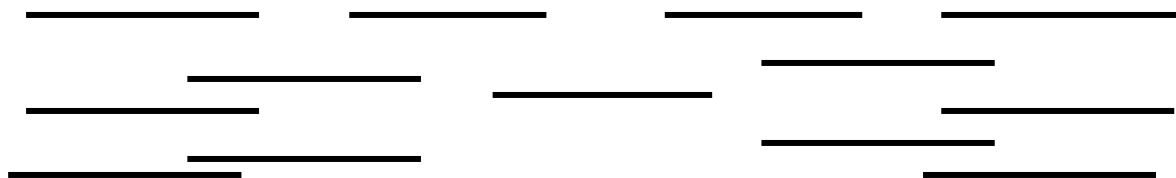
## □ Example 1



## □ Example 2



## □ Example 3



# Greedy Algorithm

□ Runtime complexity:  $O(n)$

➤ Considering the sort runtime complexity:  $O(n \log n)$

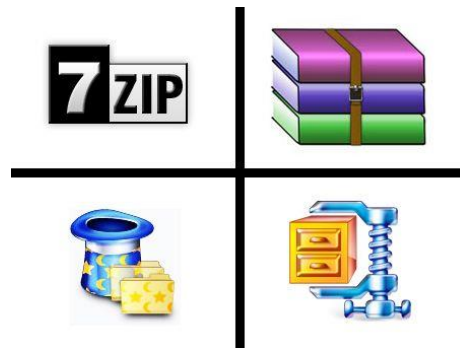
```
ActivitySelector(s, f) {  
    n = s.length  
    A = {a1}  
    k = 1  
    for m = 2 to n {  
        if s[m] ≥ f[k] {  
            A = A ∪ {am}  
            k = m  
        }  
    }  
    return A  
}
```

# Proof of Optimality

- Suppose  $A = \{a_1, a_2, \dots, a_p\}$  be a greedy solution,  $B = \{b_1, b_2, \dots, b_q\}$  be the maximum-size subset of mutually compatible activities which, and  $|A| < |B|$ .
  - Among all optimum solutions,  $B$  is chosen such that it has the most common intervals with  $A$ .
  - Both  $A$  and  $B$  activities are sorted in increasing order of finish time.
- $a_i$  and  $b_i$  are the first different activities in  $A$  and  $B$ .
- One can create  $B'$  as follows:  $B' = B - \{b_i\} \cup \{a_i\}$ .
  - $B'$  is still a set of compatible activities because all activities would start after  $b_i$  finishes which happens after  $a_i$  finishes.
  - $|B'| = |B|$
- This process can continue until  $B$  becomes identical to  $A$ , i.e.,  $|A| = |B|$ , which is a contradiction. Hence, the greedy solution is optimum.

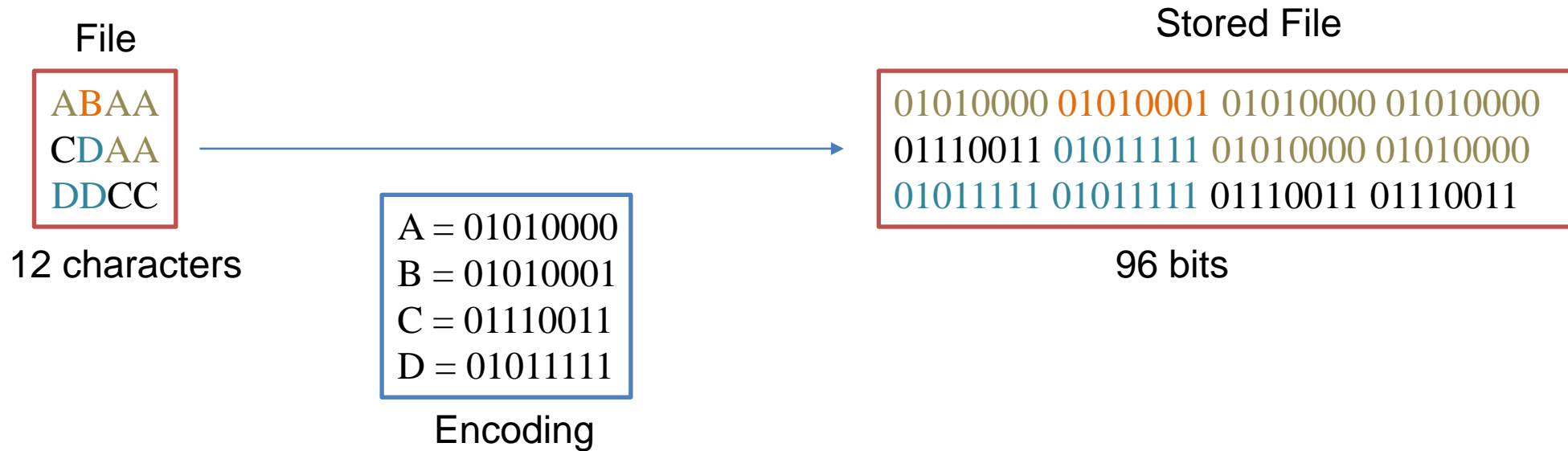


# Huffman Codes

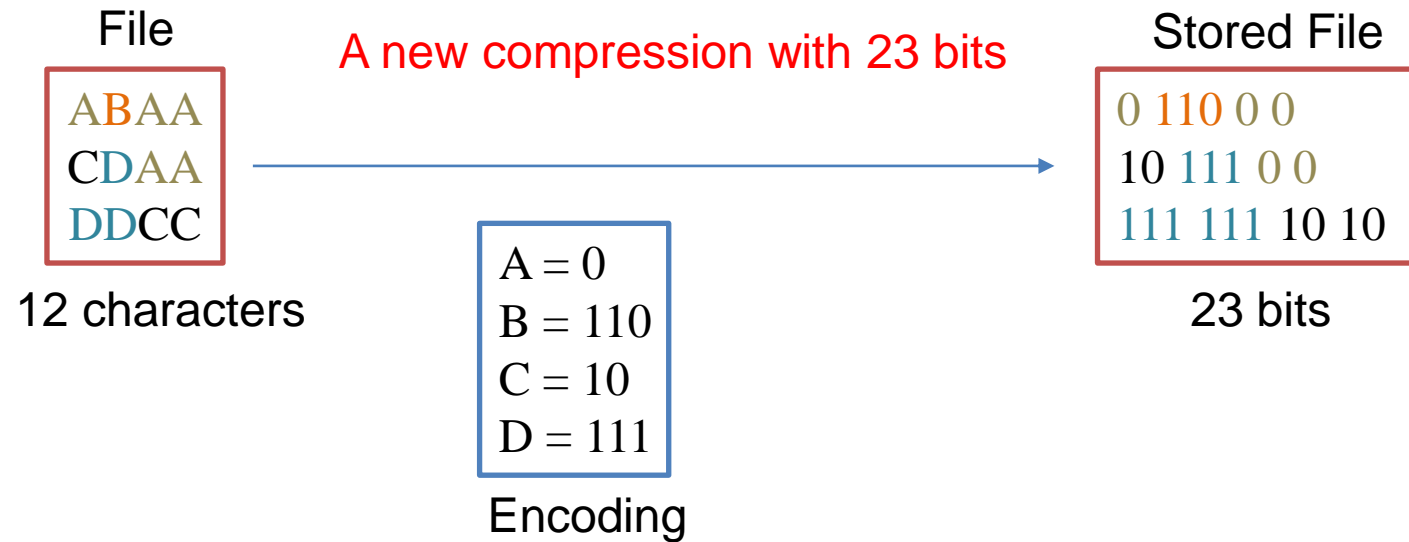


Some slides are courtesy of Dr. Mahini.

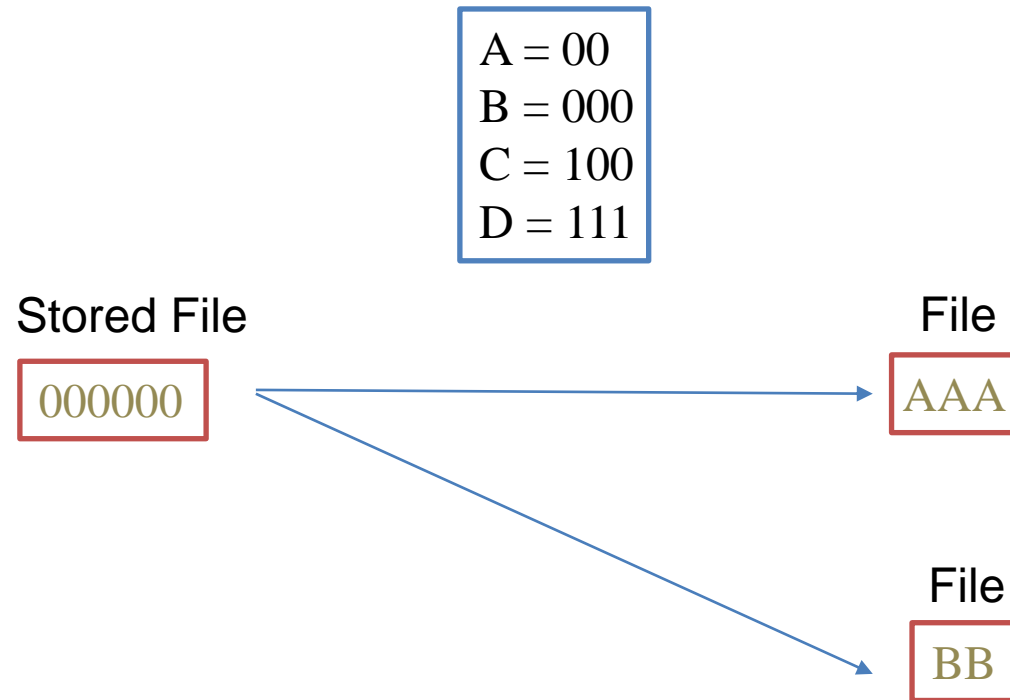
# Lossless Data Compression (1)



# Lossless Data Compression (2)



# What is lossless data compression?



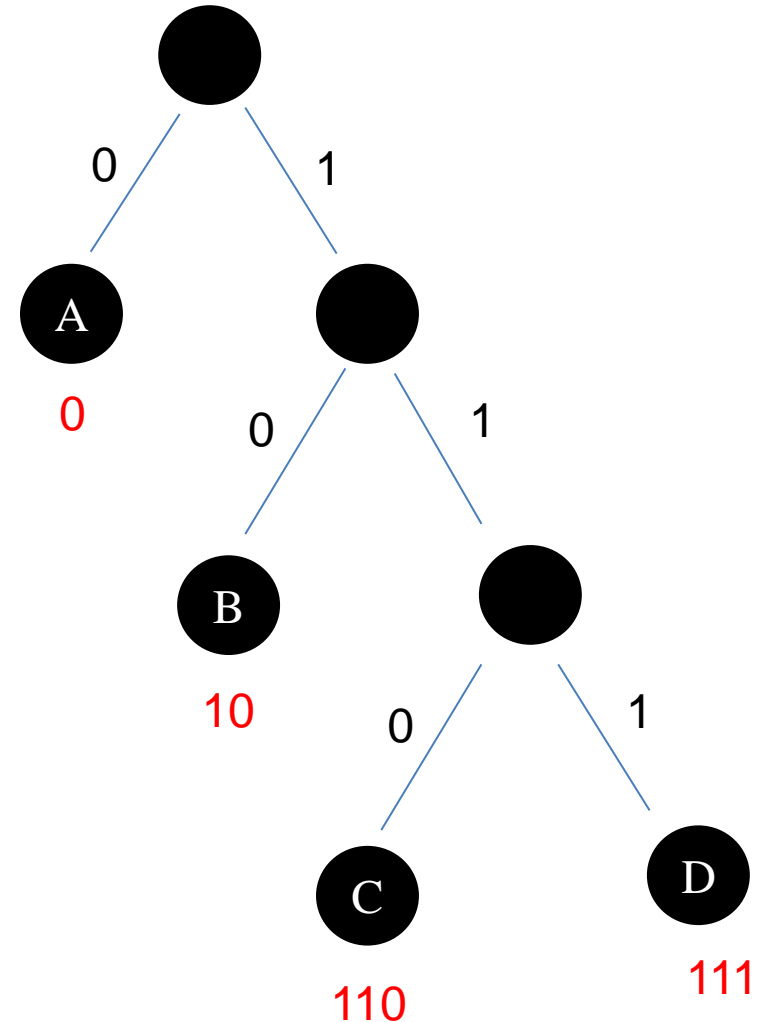
No code should be the prefix of the other one

# Lossless Data Compression: Problem

**Input:** a file with  $n$  characters such that the frequency of character  $i$  is  $f_i$

**Goal:** Assign code  $c_i$  with length of  $h_i$  to character  $i$  to minimize  $\sum h_i \times f_i$  (length of the stored file) such that no code is the prefix of the other one.

You can model “prefix codes” with a binary tree



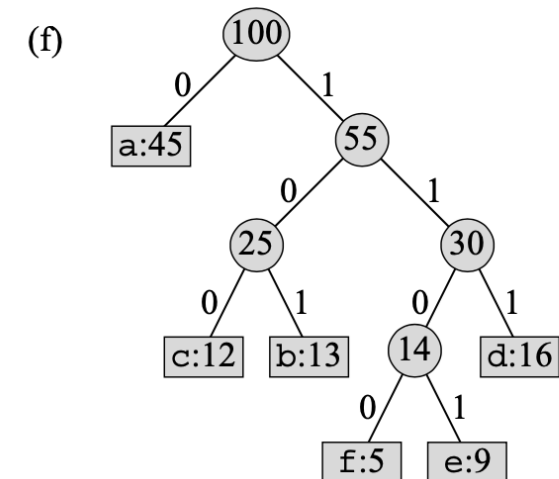
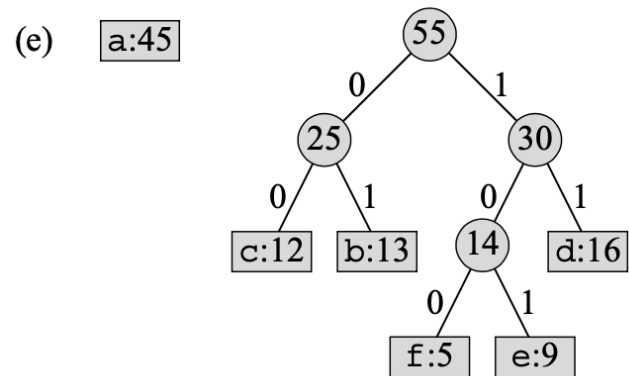
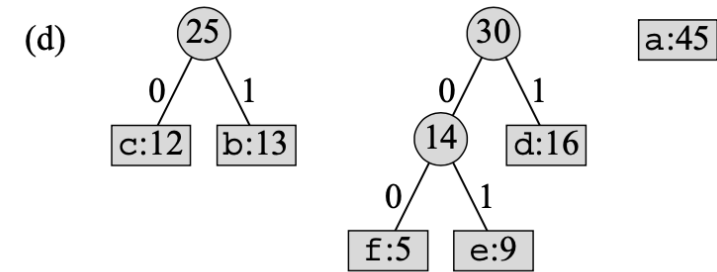
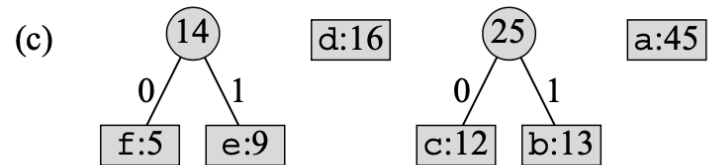
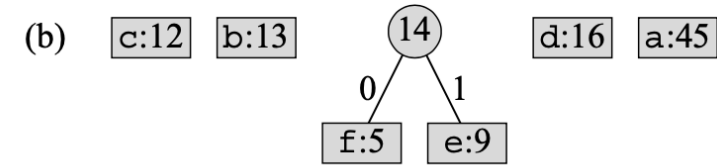
# Huffman Codes: A Greedy Algorithm

- ❑ Runtime complexity:  $O(n \log n)$
- ❑ Note that the heap doesn't correspond to the Huffman tree.

```
HuffmanCode(C) {  
    n = |C|  
    Q = C    // Q is a binary min-heap  
    for i = 1 to n - 1 {  
        allocate a new node z  
        z.left = x = Extract-Min(Q)  
        z.right = y = Extract-Min(Q)  
        z.freq = x.freq + y.freq  
        Insert(Q, z)  
    }  
    return Extract-Min(Q)  
}
```

# Huffman Codes: Example

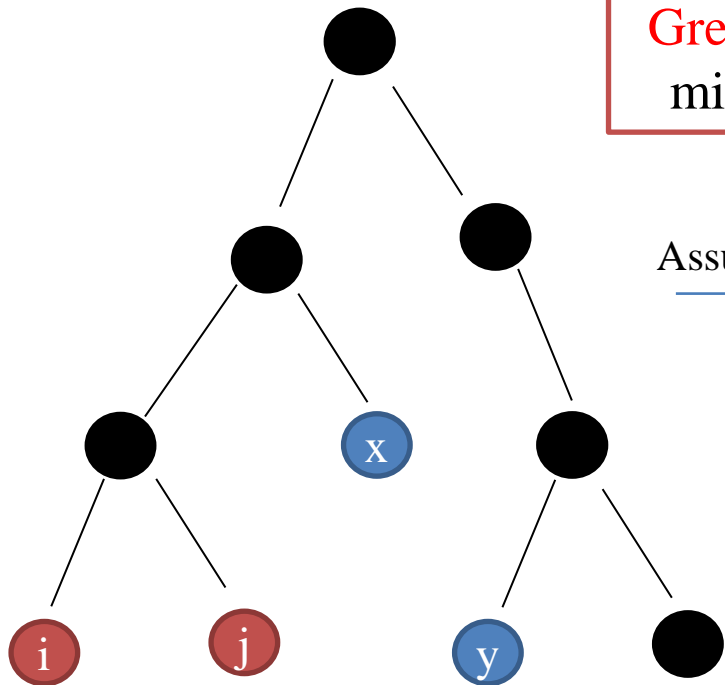
(a) f:5 e:9 c:12 b:13 d:16 a:45



# Greedy Choice

**Greedy choice:** The two characters with min frequency are siblings in the tree.

Assume  $x$  and  $y$  are characters with min frequency



$$f_X \times h_X + f_y \times h_y + f_i \times h_i + f_j \times h_j$$

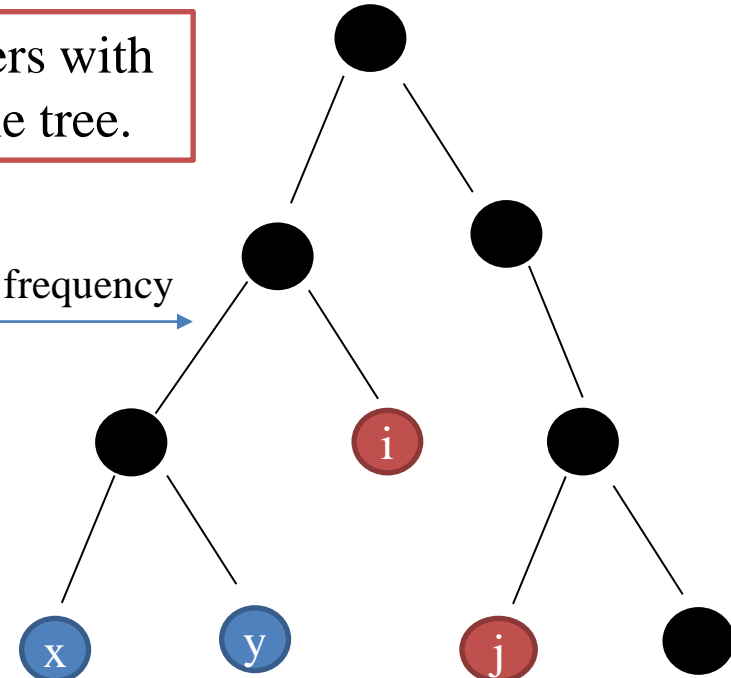
$$\begin{aligned} h_i &= h_j = h \\ h_X &= h' \\ h_Y &= h'' \end{aligned}$$

$$f_X \times h' + f_y \times h'' + f_i \times h + f_j \times h$$

$\geq$

$$f_X \times h + f_y \times h + f_i \times h' + f_j \times h''$$

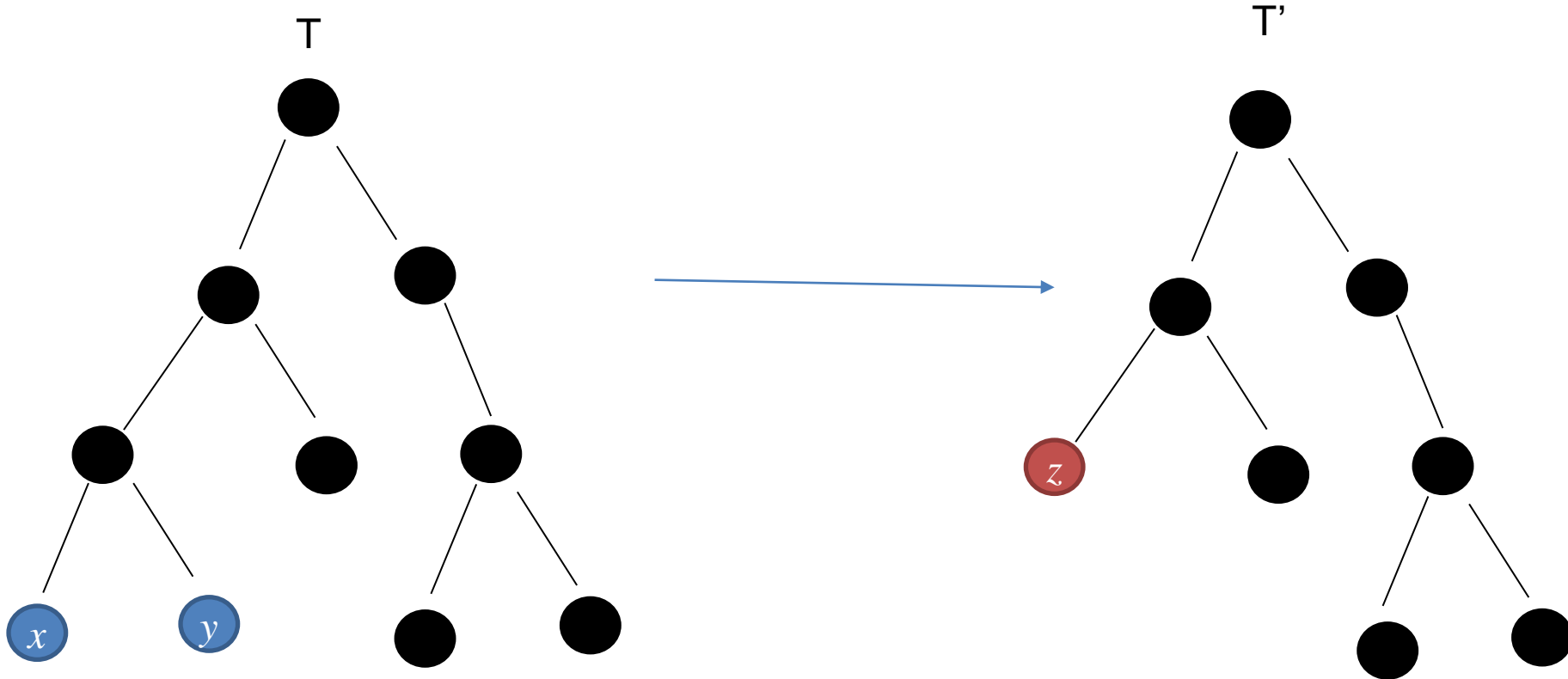
Exchanging the lowest nodes (i.e.,  $i$  and  $j$ ) with  $x$  and  $y$  does not increase the cost.





# Optimal Subproblem Property

□ Do we have the same sub-problem?



$$\text{Cost}(T) - \text{Cost}(T') = f_x h + f_y h - f_*(h - 1) = (f_x + f_y)h - (f_x + f_y)(h - 1) = f_x + f_y$$

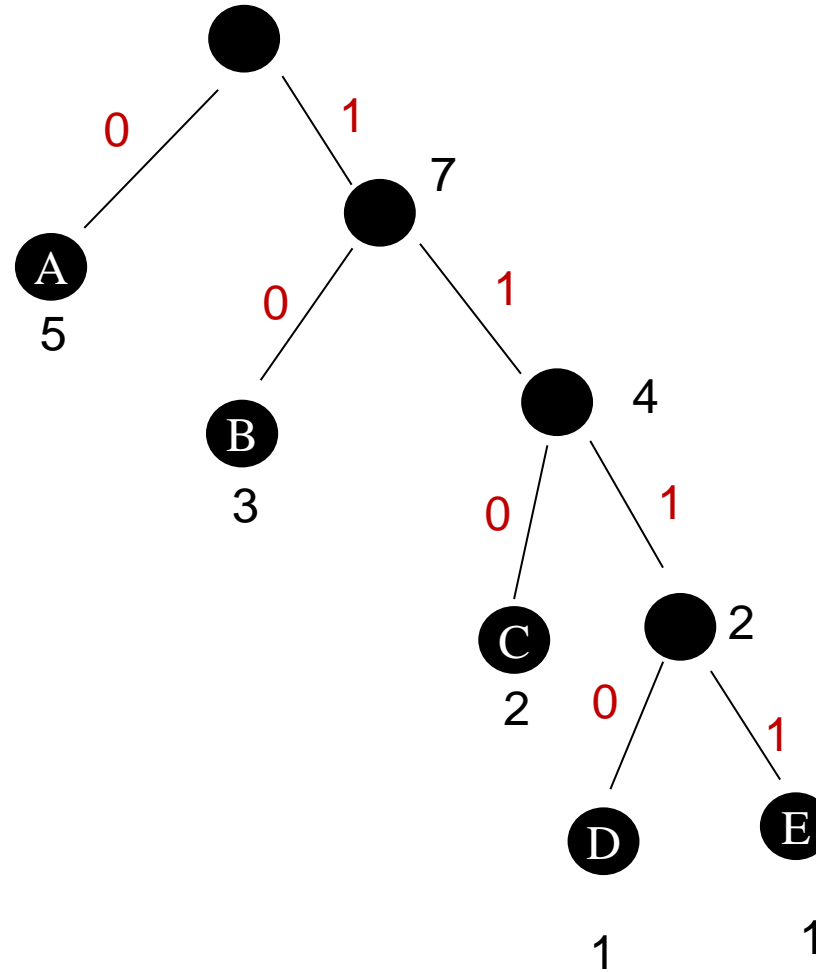
↑  
Constant

# Optimal Subproblem Property (cont'd)

- $T$  can be created from an optimal prefix tree  $T'$  by replacing a leaf node  $z$  with  $x$  and  $y$ .
- Suppose  $T$  does not represent an optimal prefix code, while  $T''$  does, i.e.,  $Cost(T'') < Cost(T)$ .
  - We can assume that  $x$  and  $y$  are sibling leaf nodes in  $T''$ . Why?
    - Due to greedy choice property.
- Now suppose  $T'''$  is created from  $T''$  by merging  $x$  and  $y$  into  $z$  leaf node:
  - $Cost(T''') = Cost(T'') - f_x - f_y < Cost(T) - f_x - f_y = Cost(T')$
  - This is a contradiction as we assumed  $T'$  is an optimal tree. Hence,  $T$  represents an optimal prefix code.

# Another Example

Character	Frequency	Code
A	5	0
B	3	10
C	2	110
D	1	1110
E	1	1111



# Sample Problems

# True or False?

- ❑ A greedy algorithm always makes the choice that looks best at the moment.
- ❑ Problems solved using dynamic programming cannot be solved thru greedy algorithms.
- ❑ If a problem can be solved using both the greedy method and dynamic programming, greedy will always give you a lower time complexity.

# Fill in the Blanks

- ❑ A \_\_\_\_\_ algorithm may produce an optimal solution when \_\_\_\_\_ algorithm cannot, because \_\_\_\_\_ algorithm will exclude some possible solutions while \_\_\_\_\_ algorithm will examine all possible solutions.
  - Use either “greedy” or “dynamic programming”.

# Coin/Money Change Problem: Greedy Algorithm

- ❑ The objective of the *Coin Problem* is to come up with the minimum number of coins to pay  $X$  cents.
  - Consider the greedy approach to solving the coin problem for US coins (25¢, 10¢, 5¢, and 1¢):
    - We start with the largest coin (25¢ coin) and use it as many times as possible, then use as many 10¢ coins as possible on the remainder, then 5¢, then 1¢.
    - Prove or disprove that “this greedy algorithm always gives an optimal solution”, i.e. gives the minimum number of coins to pay  $X$  cents.
  - Now suppose that 5¢ coins are not allowed, only 1¢, 10¢, and 25¢.
    - Prove or disprove that “the corresponding greedy approach (25¢ then 10¢ then 1¢) always gives an optimal solution”.

# Gradient Descent

- An approach used to find the local minimum of a function.

