

Stalls and Performance

The BIG Picture

- Stalls reduce performance
 - But are required to get correct results
- Compiler can arrange code to avoid hazards and stalls
 - Requires knowledge of the pipeline structure



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Control Hazards

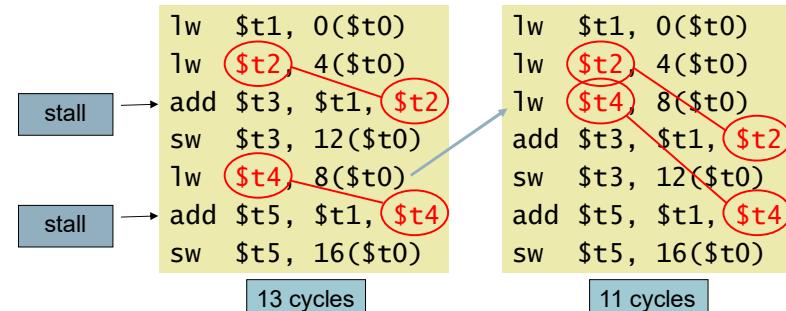
- Branch determines flow of control
 - Fetching next instruction depends on branch outcome
 - Pipeline can't always fetch correct instruction
 - Still working on ID stage of branch
- In MIPS pipeline
 - Need to compare registers and compute target early in the pipeline
 - Add hardware to do it in ID stage



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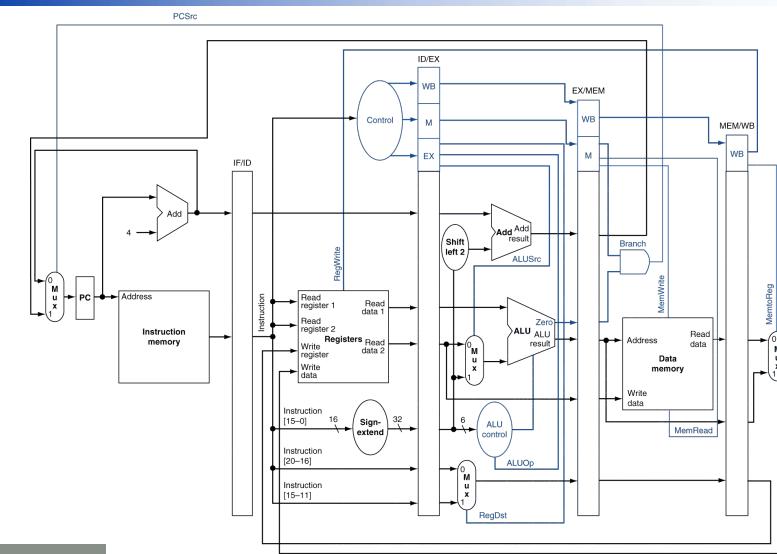
Code Scheduling to Avoid Stalls

- Reorder code to avoid use of load result in the next instruction
- C code for $A = B + E; C = B + F;$



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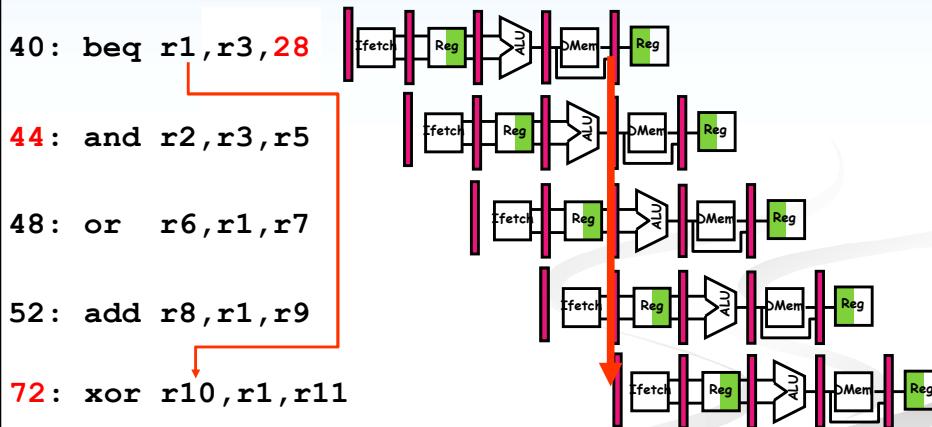
Pipelined Control



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Control Hazard on Branches

Three Stage Stall



Assume branch decision made on MEM stage.

When branch is taken, the following 3 instructions should not complete execution.

Less frequent than data hazards, but

No effective solution like "forwarding". Better to decide branch earlier.

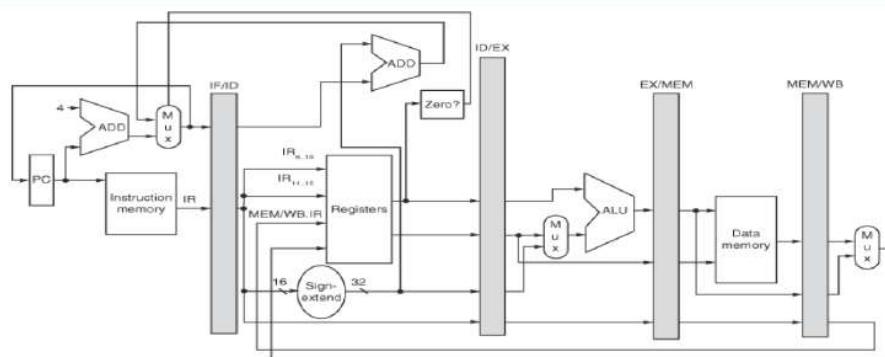
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Example: Branch Stall Impact

- If 30% branch, stall of 3 cycles is significant
- Two part solution:
 - Determine if branch is taken or not sooner,
 - AND compute taken branch address earlier
- MIPS Solution:
 - Move Zero test to ID/EX stage
 - Adder to calculate new PC in ID/EX stage
 - Result: 1 clock cycle penalty for branch instead of 3

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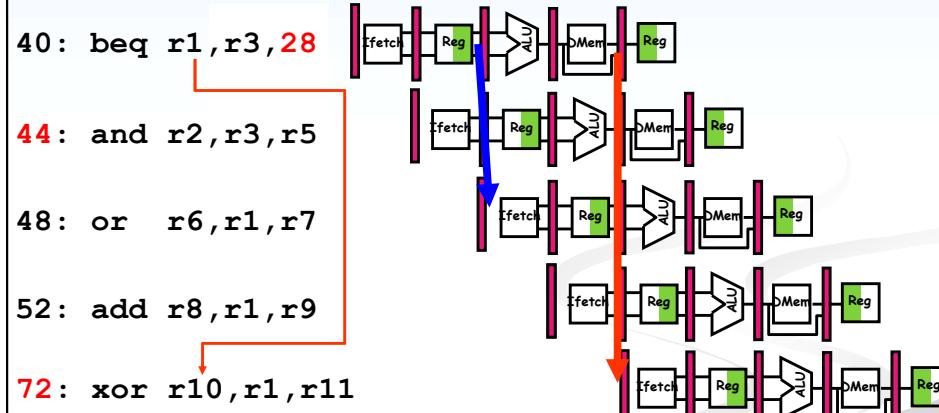
Reducing Branch Penalty by Anticipating the Branch Execution



- Branch-outcome resolution (zero test) and branch-target calculation moved into ID stage
 - PC is written in the IF stage using either the branch-target address computed during ID or the incremented PC computed during IF

Control Hazard on Branches

One Stage Stall



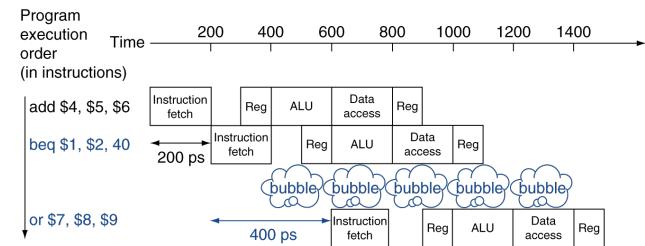
Branch decision made on ID stage.

When branch is taken, the following 1 instructions should not complete execution.

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Stall on Branch

- Wait until branch outcome determined before fetching next instruction



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