# **Rockchip Linux System Test User Guide**

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Rockchip Electronics Co., Ltd.

No.18 Building, A District, No.89, software Boulevard Fuzhou, Fujian, PRC

Website: <u>www.rock-chips.com</u>

Customer service Tel: +86-4007-700-590

Customer service Fax: +86-591-83951833

Customer service e-Mail: fae@rock-chips.com

## Preface

## Overview

The document mainly presents Rockchip Linux SDK system testing method, it is designed to guide and help customers quickly understand and get started with products developed based on Rockchip Linux SDK, and perform necessary software and hardware stability testing before mass production and release.

## **Intended Audience**

This document (this guide) is mainly intended for:

**Test Engineers** 

Software Development Engineers

Hardware Development Engineers

## **Revision History**

Date	Version	Date	Change Description
2017-01-15	V1.0.0	CQ	Initial version
2020-03-24	V1.1.0	CQ	Update test items
2020-03-30	V1.1.1	Caesar Wang	Update the format
2020-08-02	V1.1.2	Ruby Zhang	Update the format
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2022-12-01	V2.0.0	Nickey Yang	Added software and hardware stability test instructions, Fixed part descriptions and pictures
2022-12-05	V2.0.1	Nickey Yang	Fixed part descriptions
2024-05-16	V2.0.2	Ruby Zhang	Fixed part of descriptions

#### Contents

## Rockchip Linux System Test User Guide

- 1. Functions Test
  - 1.1 Buildroot
    - 1.1.1 Video
    - 1.1.2 Recording
    - 1.1.3 Wi-Fi Connecting
    - 1.1.4 Music Player
    - 1.1.5 System Time
    - 1.1.6 RTC Clock
    - 1.1.7 Video Playback
    - 1.1.8 SD Card Upgrade and Boot
    - 1.1.9 Search the File
    - 1.1.10 Check Memories
    - 1.1.11 Check Memory Usage
  - 1.2 Debian
    - 1.2.1 Terminal Position
    - 1.2.2 Wi-Fi Connection
    - 1.2.3 Dual-screen with Different Display
    - 1.2.4 Dual-screen with Different Audio
    - 1.2.5 Display Rotation
- 2. Performance Test
  - 2.1 Disk Read and Write Test
    - 2.1.1 eMMC Read and Write
    - 2.1.2 U disk Read and Write
  - 2.2 Set Performance Mode
  - 2.3 Check CPU DDR Frequency
  - 2.4 glmark2 Performance Score
- 3. Hardware Stability Test
  - 3.1 IO-DOMAINS
  - 3.2 Power Supply
  - 3.3 Signal
  - 3.4 High and Low Temperature Test
- 4. Software Stability Test
  - 4.1 Basic Tools
    - 4.1.1 stressapptest
      - 4.1.1.1 Overview
      - 4.1.1.2 Usage
    - 4.1.2 memtester
      - 4.1.2.1 Overview
      - 4.1.2.2 Usage
  - 4.2 Rockchip Test
    - 4.2.1 Configuration Enablement
    - 4.2.2 Test List
    - 4.2.3 Testing Scale
    - 4.2.4 Testing Methods
      - 4.2.4.1 Rockchip Test
      - 4.2.4.2 Execute Directly
    - 4.2.5 Test Details
      - 4.2.5.1 DDR Testing
        - 4.2.5.1.1 DDR Frequency Scaling
        - 4.2.5.1.2 stressapptest\_test
        - 4.2.5.1.3 Memtester Test
      - 4.2.5.2 CPU Testing
        - 4.2.5.2.1 CPU Frequency Scaling
      - 4.2.5.3 Flash Testing
      - 4.2.5.4 Standby&Wake-up Test
      - 4.2.5.5 Reboot Testing
      - 4.2.5.6 GPU Testing
      - 4.2.5.7 Camera Testing
      - 4.2.5.8 Video Testing 4.2.5.9 Wi-Fi BT Testing
  - 4.3 User Scenario Testing
- 5. TO DO
  - 5.1 Adding Common Problem Analysis Methods
  - 5.2 Adding NPU, Recovery, Audio, Browser, Power-off Test Instructions

## 1. Functions Test

### 1.1 Buildroot

#### 1.1.1 Video

Video:

```
rkisp_demo --device=/dev/video1 --output=/tmp/isp.yuv --iqfile=/etc/iqfiles/0V5695.xml
```

Play video:

Pull the file in the /tmp/cif.yuv directory to PC: adb pull /tmp/cif.yuv /tmp/cif.yuv , and play it through a YUV tool.

### 1.1.2 Recording

```
arecord -c channel -r sampling frequency -f sampling bits -d recording duration/recording storage path/recording file name.
```

Channel ch\_tbl="2 4 6 8"

Sampling frequency: fs\_tbl="8000 11025 16000 22050 32000 44100 48000 64000 88200 96000 176400 192000"

Sampling bits: bits\_tbl="S16\_LE S24\_LE S32\_LE"

Package format "wmv, wav, mp3, etc."

For example:

Time-limited recording- after recording for 10 seconds will exit and save automatically:

```
arecord -c 2 -r 44100 -f S16_LE -d 10 /tmp/record.wav
```

#### Unlimited time recording -ctrl+c: exit to save:

```
arecord -c 2 -r 44100 -f S16_LE /tmp/record.wav
```

## Play recording files:

```
aplay /tmp/record.wav
```

## 1.1.3 Wi-Fi Connecting

Method 1: wifi\_start.sh script

If the sdk integrates the wifi\_start.sh script, you can add ssid and password directly after the script.

```
wifi_start.sh WiFi-AP password
```

## Method 2: Modify the configuration file

```
$ vi /data/cfg/wpa_supplicant.conf
ctrl_interface=/var/run/wpa_supplicant #It is not recommended to modify by default!
ap scan=1
update_config=1 #This configuration enables the hotspots configured by the wpa_cli command to be saved in the
conf file (wpa_cli save_config)
#Encrypted wi-fi
network={
   ssid="WiFi-AP" # Wi-Fi name
psk="password" # Wi-Fi password
    key_mgmt=WPA-PSK # Authentication method
#Unencrypted Wi-Fi:
network={
    ssid="WiFi-AP" # Wi-Fi name
    key_mgmt=NONE  # Authentication method
#Let the wpa_supplicant process re-read the above configuration:
wpa_cli -i wlan0 -p /var/run/wpa_supplicant reconfigure
#Initiate connection:
wpa_cli -i wlan0 -p /var/run/wpa_supplicant reconnect
```

```
#EncryptedWi-Fi:
wpa_cli -i wlan0 -p /var/run/wpa_supplicant remove_network 0
wpa_cli -i wlan0 -p /var/run/wpa_supplicant ap_scan 1
wpa_cli -i wlan0 -p /var/run/wpa_supplicant add_network
wpa_cli -i wlan0 -p /var/run/wpa_supplicant set_network 0 ssid "WiFi-AP"
wpa_cli -i wlan0 -p /var/run/wpa_supplicant set_network 0 key_mgmt WPA-PSK
wpa_cli -i wlan0 -p /var/run/wpa_supplicant set_network 0 psk '"password"'
wpa_cli -i wlan0 -p /var/run/wpa_supplicant select_network 0
wpa_cli -i wlan0 -p /var/run/wpa_supplicant save_config #Save the above configuration to the conf file
#Unencrypted Wi-Fi:
wpa_cli -i wlan0 -p /var/run/wpa_supplicant remove_network 0
wpa_cli -i wlan0 -p /var/run/wpa_supplicant ap_scan 1
wpa_cli -i wlan0 -p /var/run/wpa_supplicant add_network
wpa_cli -i wlan0 -p /var/run/wpa_supplicant set_network 0 ssid "WiFi-AP"
wpa_cli -i wlan0 -p /var/run/wpa_supplicant set_network 0 key_mgmt NONE
wpa_cli -i wlan0 -p /var/run/wpa_supplicant select_network 0
wpa_cli -i wlan0 -p /var/run/wpa_supplicant save_config
```

#### Check connection status:

```
wpa_cli -i wlan0 -p /var/run/wpa_supplicant status
```

For details, please refer to Rockchip\_Developer\_Guide\_Linux\_WIFI\_BT\_CN.pdf

### 1.1.4 Music Player

```
aplay /media/usb0/musicdemo.wmv
```

## 1.1.5 System Time

```
date #check system time
date --set='2018-12-24 15:17:42' #Set system time
hwclock --show #check hardware time
hwclock --systohc #synchronous display of hardware time and system time
```

## 1.1.6 RTC Clock

Check whether the time has changed in the current state or after restart.

```
cat /sys/class/rtc/rtc0/time
```

## 1.1.7 Video Playback

Video playback in single window:

```
gst-play-1.0 /oem/SampleVideo_1280x720_5mb.mp4
```

## Video playback in multi-window:

```
sh /rockchip-test/video/test_gst_multivideo.sh
```

### 1.1.8 SD Card Upgrade and Boot

- Insert the SD card into PC, execute the SD\_Firmware\_Tool.exe on PC, select firmware upgrade/SD boot, select firmware-update.img, and start creating.
- After the SDK enters the maskrom and erases the flash, power off.
- Insert the prepared SD card, power on the SDK, and it will automatically burn the firmware.



## 1.1.9 Search the File

```
find ./ -name ***
```

## 1.1.10 Check Memories

```
cat /proc/meminfo or free -h
```

## 1.1.11 Check Memory Usage

```
df -h
```

## 1.2 Debian

### 1.2.1 Terminal Position

Terminal position: start -> System Tools -> LXTerminal

### 1.2.2 Wi-Fi Connection

Enter the following command in the serial port:

```
nmcli r wifi on #steps 1: turn on Wi-Fi
nmcli dev wifi #steps 2: scan nearby AP
#steps 3: connect AP
nmcli dev wifi connect "DIR-803" password "839919060" ifname wlan0
nmcli r wifi off #steps 4: turn off Wi-Fi
```

## 1.2.3 Dual-screen with Different Display

Use xrandr to make sure how many display devices there are. For example, the following two devices, HDMI-1 and DP-1 can be detected:

```
root@linaro-alip:/# xrandr
Screen 0: minimum 320 x 200, current 1920 x 1920, maximum 16384 x 16384
HDMI-1 connected primary 1920 \times 1080 + 0 + 0 (normal left inverted right x axis y axis) 0mm x 0mm
  1920x1080 60.00 + 60.00* 50.00
1920x1080i 60.00 50.00 50.00
                                           30.00 24.00
  1280×1024 60.02
  1280x720
                60.00
                         50.00
                                   50.00
                        50.00
  720x576
                50.00
  720x576i 50.00
  -A+60 59.94
720x480i 50
                         59.94
HDMI-2 disconnected (normal left inverted right x axis y axis)
```

```
DSI-1 connected 1080x1920+0+0 (normal left inverted right x axis y axis) 0mm x 0mm
1080x1920 59.90*+
DP-1 disconnected (normal left inverted right x axis y axis)
DP-2 disconnected (normal left inverted right x axis y axis)
```

xrandr is used to set the relationship between the two screens:

```
su linaro-c "DISPLAY=:0 xrandr--output HDMI-1--above DSI-1"
```

The --above can be replaced by right-of, left-of, below, same-as, preferred, off, etc.

For more detals, please refer to Rockchip\_Developer\_Guide\_Linux\_Graphics\_CN.pdf

### 1.2.4 Dual-screen with Different Audio

Method 1: Open the Sound&Video---->PulseAudio Volume Control in the bottom left corner:



Method 2: Use aplay to confirm the sound card and select the sound card to play:

```
root@linaro-alip:/# aplay -1
**** List of PLAYBACK Hardware Devices ****
card 0: rockchipdp0 [rockchip,dp0], device 0: rockchip,dp0 spdif-hifi-0 [rockchip,dp0 spdif-hifi-0]
Subdevices: 1/1
Subdevice #0: subdevice #0
card 1: rockchipes8388 [rockchip-es8388], device 0: dailink-multicodecs ES8323.7-0011-0 [dailink-multicodecs
ES8323.7-0011-0]
Subdevices: 1/1
Subdevice #0: subdevice #0
card 2: rockchiphdmi0 [rockchip-hdmi0], device 0: rockchip-hdmi0 i2s-hifi-0 [rockchip-hdmi0 i2s-hifi-0]
Subdevices: 1/1
Subdevice #0: subdevice #0

dp0: aplay-Dplughw:0,0/dev/urandom
es8388: aplay-Dplughw:1,0/dev/urandom
hdmi0: aplay-Dplughw:2,0/dev/urandom
```

Method 3: Open a song and drag it from the main screen to the secondary screen, and then select a sound card to play in the same way on the main screen to complete the dual-screen with different audio function.

For more detals, please refer to Rockchip\_Developer\_Guide\_Linux\_Graphics\_CN.pdf

## 1.2.5 Display Rotation

Rotation normal/left/right:

```
vi /etc/X11/xorg.conf.d/20-modesetting.conf
```

Change the normal to left/right/ and it will take effect after reboot.

## 2. Performance Test

### 2.1 Disk Read and Write Test

Check the node before testing: fdisk -1.

root@linaro-alip:~# fdisk -1
Disk /dev/mmcblk0: 29.1 GiB, 31268536320 bytes, 61071360 sectors
Units: sectors of 1 \* 512 = 512 bytes
Sector size (logical/physical): 512 bytes / 512 bytes

Sector size (logical/physical): 512 bytes / 512 bytes I/O size (minimum/optimal): 512 bytes / 512 bytes

Disklabel type: gpt

Disk identifier: 1124E418-9008-41F8-9E3D-8D872216C8A1

 Device
 Start
 End
 Sectors
 Size Type

 /dev/mmcblk0p1
 16384
 24575
 8192
 4M unknown

 /dev/mmcblk0p2
 24576
 32767
 8192
 4M unknown

 /dev/mmcblk0p3
 32768
 163839
 131072
 64M unknown

 /dev/mmcblk0p4
 163840
 425983
 262144
 128M unknown

 /dev/mmcblk0p5
 425984
 491519
 65536
 32M unknown

 /dev/mmcblk0p6
 491520
 29851647
 29360128
 14G unknown

 /dev/mmcblk0p7
 29851648
 30113791
 262144
 128M unknown

 /dev/mmcblk0p8
 30507008
 61071295
 30564288
 14.6G unknown

Check that the partition that can be read and written is mmcblk0p8. The capacity of this partition is 14.6G. Generally, we will use the last partition as the userdata partition that can be read and written, so it can be used as an eMMC read and write performance test.

### 2.1.1 eMMC Read and Write

Write:

```
dd if=/dev/zero of=/dev/mmcblk0p8 bs=1M count=2000 oflag=direct,nonblock
```

Read:

```
dd if=/dev/mmcblk0p8 of=/dev/null bs=1M count=2000 iflag=direct,nonblock
```

### 2.1.2 U disk Read and Write

Write:

```
dd if=/dev/zero of=/dev/sda1 bs=1M count=2000 oflag=direct,nonblock
```

Read:

```
dd if=/dev/sda1 of=/dev/null bs=1M count=2000 iflag=direct,nonblock
```

## 2.2 Set Performance Mode

```
echo performance | tee $(find /sys/ -name *governor)
```

## 2.3 Check CPU DDR Frequency

```
cat /sys/kernel/debug/clk/clk_summary |grep -E "cpu|arm|ddr"
```

## 2.4 glmark2 Performance Score

## Buildroot glmark2

Display screen performance score:

```
sh /rockchip-test/gpu/test_fullscreen_glmark2.sh
```

Do not display screen performance score:

```
sh /rockchip-test/gpu/test_offscreen_glmark2.sh
```

## 3. Hardware Stability Test

### 3.1 IO-DOMAINS

The hardware supply voltage of all GPIO power domains is required to match the software configuration. Please re-examine the correctness of the project voltage configuration before mass production, especially the configuration of Wi-Fi, FLASH, and Ethernet IO power supplies. Otherwise, the following problems will occur:

- If the software configuration is 1.8V, but the hardware power supply is 3.3V, it will cause the low withstand voltage circuit working in overvoltage state, and the chipset will be damaged after long time working.
- If the software configuration is 3.3V, but the hardware power supply is 1.8V, the circuit will work abnormally;

For the configuration check method, please refer to the documentation under the corresponding chip platform. For example, for RK3568, please refer to: Rockchip\_RK356X\_Introduction\_IO\_Power\_Domains\_Configuration\_CN.pdf

## 3.2 Power Supply

It is recommended that the power supply design for the project's hardware use our reference design. If there are changes to the power supply solution or differences in component selection, especially when using discrete power supplies instead of our matched PMIC power supply solution, Necessary tests (includes testing the power-up sequence during cold starts and restarts, voltage, and ripple under high load conditions) need to be done on all core power supplies related to the chip booting, such as: VDD\_LOGIC, VDD\_ARM, VCC\_PMU, VCC\_DDR supplies, etc.

## 3.3 Signal

After the project's hardware schematics are completed, it is recommended to submit them through the Redmine system for our engineers to review, especially the DDR section, which needs to strictly follow our template for design. At the same time, the selection of DDR, EMMC, and FLASH chips must be from our AVL, which can be obtained through Redmine.

## 3.4 High and Low Temperature Test

In addition to stability testing at room temperature, it is recommended that customers complete CPU stress, DDR stress, reboot stress, and cold boot tests in high and low temperature environments that are the actual working temperatures of the product to ensure the stability of the product in high and low temperature operating environments.

## 4. Software Stability Test

This section primarily introduces the basic tools utilized by the Rockchip test suite and And how to use the rockchip test suite to complete the software stability testing for products.

### 4.1 Basic Tools

## 4.1.1 stressapptest

### 4.1.1.1 Overview

Stressapptest will create threads to copy and directly read from and write to the disk. It tries to maximize the system's memory load as much as possible to conduct more effective testing. Additionally, it aims to randomize data from the processor and I/O to memory, creating a simulated real-world environment to test the stability of current hardware devices. It has been used at Google for some time and now it is available under the apache 2.0 license. stressapptest may be used for the following purposes:

- Stress test: as described here.
- Hardware qualification and debugging.
- · Memory interface test: see the Theory behind this.
- Disk testing.

## 4.1.1.2 Usage

To execute, a typical command would be:

```
stressapptest -s 20 -M 256 -m 8 -W  # Test 256MB, running 8 "warm copy" threads. Exit after 20 seconds. stressapptest --help  # list the available arguments.
```

- -M mbytes: megabytes of ram to test (auto-detect all memory available)
- -s seconds : number of seconds to run (20)
- -m threads: number of memory copy threads to run (auto-detect to number of CPUs)
- -W: Use more CPU-stressful memory copy (false)
- -n ipaddr: add a network thread connecting to system at 'ipaddr'. (none)
- --listen: run a thread to listen for and respond to network threads. (0)
- -f filename : add a disk thread with tempfile 'filename' (none)
- -F: don't result check each transaction, use libc memcpy instead. (false)

## Error handling

- -l logfile : log output to file 'logfile' (none)
- -v level: verbosity (0-20) (default: 8)

### 4.1.2 memtester

#### 4.1.2.1 Overview

A userspace utility for testing the memory subsystem for faults. It's portable and should compile and work on any 32- or 64-bit Unix-like system. (Yes, even weird, proprietary Unices, and even Mac OS X.) For embedded system developers, memtester can be told to test memory starting at a particular physical address as of memtester version 4.1.0.

## 4.1.2.2 Usage

```
memtester [-p physaddrbase [-d device]] <mem>[B|K|M|G] [loops]
```

Detailed test items within the loop:

```
Stuck Address
Random Value
Compare XOR
Compare SUB
Compare MUL
Compare DIV
Compare OR
Compare AND
Sequential Increment
Solid Bits
Block Sequential
Checkerboard
Bit Spread
Bit Flip
Walking Ones
Walking Zeroes
8-bit Writes
16-bit Writes
```

## 4.2 Rockchip Test

- The log output path for Rockchip test stress testing is /userdata/rockchip-test, so please ensure that the directory has read and write permissions before testing.
- A complete serial port log is helpful for better analysis and problem location. Therefore, during testing, the product needs to be connected with a serial port, and the serial port host machine should have the capability to save all logs.

### 4.2.1 Configuration Enablement

In the buildroot, to enable the Rockchip-test package, the following configurations need to be enabled:

```
# - stress test on cpu and memory
BR2_PACKAGE_STRESSAPPTEST=y
# - memtest used to testing the memory subsystem for faults
BR2_PACKAGE_MEMTESTER=y
# - audio, reboot, bluetooth, ddr, dvfs, flash, suspend/resume, wifi
BR2_PACKAGE_ROCKCHIP_TEST=y
```

### 4.2.2 Test List

The currently supported stress test list is as follows:

### 4.2.3 Testing Scale

It is recommended that each test project is deployed for **10 units \* 24 hours** or more, with adjustments made according to the degree of stability required by the project.

## 4.2.4 Testing Methods

Below is an example of the testing methods for each unit in the DDR stress test using memtester. Unit testing can be executed from the rockchip\_test script or by directly running the corresponding script.

### 4.2.4.1 Rockchip Test

```
bash rockchip-test/rockchip_test.sh
```

• Enter the corresponding number 1 for DDR Test in the input stress test list

• Then enter the number 1 corresponding to the test item memtester to start the test.

## 4.2.4.2 Execute Directly

```
bash /rockchip-test/ddr/memtester_test.sh
```

#### 4.2.5 Test Details

### 4.2.5.1 DDR Testing

DDR stress testing supports the following five test scenarios:

```
"memtester: 1"
"stressapptest: 2"
"stressapptest + memtester: 3"
"DDR auto scaling: 4"
"stressapptest + memtester + DDR auto scaling: 5"
```

- If the product does not support frequency scaling, you can choose option 3, which is to use the stressapptest + memtester scaling for testing.
- If the product supports frequency scaling, you can choose option 5, which is to use the stressapptest + memtester + DDR automatic frequency variation scenario for testing.

CPU stress testing consists of the entry script ddr\_test.sh and the following three scripts:

```
/rockchip-test/ddr/ddr_freq_scaling.sh
/rockchip-test/ddr/memtester_test.sh
/rockchip-test/ddr/stressapptest_test.sh
```

4.2.5.1.1 DDR Frequency Scaling

**DDR Frequency Scaling Script** 

• When the script is executed without arguments, it will perform automatic frequency scaling.

```
bash /rockchip-test/ddr/ddr_freq_scaling.sh
cnt: 0, ddr freq: success change to 528000000 Hz
...
cnt:100, ddr freq: success change to 324000000 Hz
```

• When the script is executed with a frequency argument that is within the supported frequencies, it will scale to the corresponding frequency.

```
bash /rockchip-test/ddr/ddr_freq_scaling.sh 528000000
ddr freq: success change to 528000000 Hz
```

• If the script is executed with a frequency argument that is not within the supported frequencies, it will print the available frequencies and the current frequency.

```
bash /rockchip-test/ddr/ddr_freq_scaling.sh 1
ddr freq: 1 is not in available frequencies: 324000000 528000000
ddr freq: now 528000000 Hz
```

• Stop the test

```
killall bash
```

4.2.5.1.2 stressapptest\_test

The stressapptest script, by default, utilizes half of the system's available memory for testing and automatically stops after 24 hours.

• Stop the Test

```
killall stressapptest
```

4.2.5.1.3 Memtester Test

The memtester script, by default, uses half of the system's available memory for testing.

• Stop the Test

```
killall memtester
```

 Note: Memtester will not automatically stop the test if an error occurs; it is necessary to monitor the log of the program's running process.

### 4.2.5.2 CPU Testing

CPU stress testing supports the following three test scenarios:

```
"stressapptest test: 1"
"cpu auto scaling: 2"
"stressapptest + cpu auto scaling: 3"
```

- If the product does not support frequency variation, you can choose option 2, which is to use the stressapptest scenario for testing.
- If the product supports frequency variation, you can choose option 3, which is to use the stressapptest combined with CPU
  automatic frequency scaling for testing.

The CPU stress test consists of the entry scripts cpu\_test.sh and cpu\_freq\_scaling.sh.

#### 4.2.5.2.1 CPU Frequency Scaling

• When the script is executed without any arguments, it will perform automatic frequency scaling.

```
bash /rockchip-test/cpu/cpu_freq_scaling.sh
cnt: 0, cpu freq policy:0 success change to 816000 KHz
...
cnt: 100, cpu freq policy:0 success change to 1104000 KHz
```

• If the script is executed with a frequency argument that is within the supported frequencies, it will scale to the corresponding frequency.

```
bash /rockchip-test/cpu/cpu_freq_scaling.sh 1104000
cpu freq policy:0 success change to 1104000 KHz
```

• If the script is executed with a frequency argument that is not within the supported frequencies, it will print the supported frequency points as well as the current frequency.

```
bash /rockchip-test/cpu/cpu_freq_scaling.sh 1
cpu freq: 1 is not in available frequencies: 600000 816000 1008000 1104000 1416000
cpu freq: now 1104000 Hz
```

• Stop the test:

```
killall bash
```

## 4.2.5.3 Flash Testing

 Generate 7 random source data files within 5MB in \$test\_dir/src\_test\_data, copy them into the five subdirectories of \$test\_dir/des\_test\_data, and compare the md5 values, looping for 200 times.

### 4.2.5.4 Standby&Wake-up Test

- Enabling automatic standby&wake-up requires the presence of an RTC (Real-Time Clock) in the system, which must be functioning properly.
- By default, the system will execute the standby&wake-up process 10,000 times before exiting, with each wake-up period being a random number between 3 and 6 seconds.

## 4.2.5.5 Reboot Testing

- Default behavior is to stop testing after 10,000 reboots, with the system automatically shutting down 8 seconds after each startup.
- Stop of testing in advance

```
echo off > /userdata/rockchip_test/reboot_cnt
```

• If the system has CONFIG\_PSTORE\_RAM enabled, the script will check for logs of crashes or other abnormalities during the shutdown process after each booting, and will automatically stop the test if any are found.

## 4.2.5.6 GPU Testing

- The GPU stress test is based on glmark-es2, utilizing the test\_stress\_glmark2.sh script, which primarily executes glmark-es2 with the run-forever parameter.
- glmark-es2 is a benchmark for OpenGL ES 2.0. It only employs the subset of the OpenGL 2.0 API that is compatible with OpenGL ES 2.0.

### 4.2.5.7 Camera Testing

- Camera stress testing can be performed using either of the following two methods:
  - camera\_stresstest\_rkisp\_demo.sh

Ensure that the buildroot has the following configuration enabled:

```
BR2_PACKAGE_CAMERA_ENGINE_RKAIQ_RKISP_DEMO=y
```

Using rkisp\_demo does not require configuring the ISP pipeline through <code>media-ctl</code>. This method does not perform stress testing on the USB camera.

The testing process involves a loop that captures camera data from the ISP CIF interface for 100 frames each, but does not verify the file size.

2. camera\_stresstest\_v4l2.sh

Ensure that the buildroot has the following configuration enabled:

```
BR2_PACKAGE_LIBV4L_UTILS=y
```

Using v412-ct1 may require configuring the ISP pipeline through media-ct1. This method performs stress testing on the ISB camera

The testing process captures camera data from the USB ISP CIF interface in a loop at a resolution of 640x480 for 5 frames each and verifies the file size.

• Choose either of the above methods based on the actual application scenario.

#### 4.2.5.8 Video Testing

- Video stress testing involves continuously playing video files located in either the /mnt/udisk/videos or /userdata/videos directory.
- Before testing, place the video file to be tested in either of the directories mentioned above. The /userdata/videos directory is checked first. If neither of the two directories exists, the test will prompt a message and exit.

### 4.2.5.9 Wi-Fi BT Testing

• Wi-Fi BT testing involves automatic on and off testing.

## 4.3 User Scenario Testing

In addition to the aforementioned unit tests for system functionality, we can also simulate realistic scenarios to perform stress tests, serving as a supplement to system stability testing.

For example, for the product form of a dictionary pen, a typical user scenario might be:

PowerOn -> Scan Recognition -> Play Translation Result -> Place until the system enters the second-level standby -> Wake up and use the property of the prop

We can use the commands from the basic script mentioned above to construct this realistic scenario:

PowerOn -> loop (v4l2 capture -> aplay play back -> pm-suspend -> rtcwakeup), and during the wake-upperiod, randomly execute Walls and the properties of t

## 5. TO DO

## 5.1 Adding Common Problem Analysis Methods

## 5.2 Adding NPU, Recovery, Audio, Browser, Power-off Test Instructions