

MDI341 Structured Data

Energy-based approaches via multi-class classification

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From multi class classification to structured prediction

- Scoring functions:
 - Model of the form: $h(x) = \arg \max_{y \in \mathcal{Y}} \text{score}(x, y)$
- (1) Solve the problem for multiple classes
- (2) Solve the problem in general for any structured prediction problem (next session)

Document classification

Example 1

- INPUT : ". . . run a health care insurance program ..."
- OUTPUT : politics

Example 2

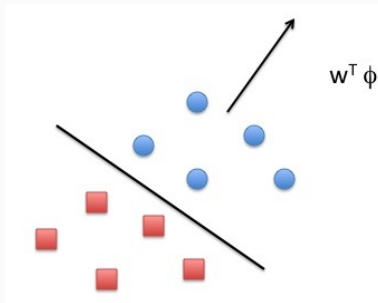
- INPUT: ". . . run the marathon ..."
- OUTPUT : sports

A binary classification task

Two classes: **politics**, **sports**

Using a linear model

- Input features: for instance, bag of words
- Prediction: $h_w(x) = \text{sgn}(w^T \phi(x))$

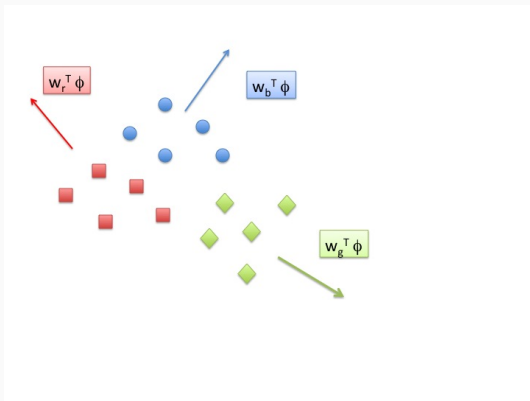


Now a multiclass classification task

Multiple classes : economics, politics, sports

- Each class y defined by a linear model of the following form:

$$h_y(x) = w_y^T \phi(x)$$



Joint Feature Map for Multiclass classification

With p classes:

$$\begin{aligned}\phi(x, y)^T &= [0 \dots 0 \ \phi(x)^T \ 0 \dots 0] \\ w^T &= [\mathbf{w}_1^T \dots, \mathbf{w}_y^T, \dots \mathbf{w}_p^T] g\end{aligned}$$

Remember : **here** y is a class label

$$g(x_i, y, w) = \mathbf{w}^T \phi(x_i, y) = \mathbf{w}_y^T \phi(x_i)$$

- Whatever y , w_y 's have the same dimension, say p .
- The vector \mathbf{w} is the stack of all \mathbf{w}_y with $y \in$ the finite set \mathcal{Y}
- NB : we will note: $\phi(x_i, y) = \phi_i(y)$

Linear Models for Multiclass Classification using Joint Feature Maps

Scoring methods for multiclass classification

$$g(x_i, y, \mathbf{w}) = \mathbf{w}^T \phi(x_i, y) = \mathbf{w}^T \phi_i(y)$$

$$prediction(x_i, \mathbf{w}) = \arg \max_{y \in \mathcal{Y}} \mathbf{w}^T \phi_i(y)$$

Learning Methods

- Structured Perceptron (Collins , EMNLP 2002)
- Logistic regression, CRF (Collins, EMNLP 2002)
- Struct-SVM : Crammer and Singer 2001, Tsochantaridis et al. 2005

1 - Learning linear models: the perceptron rule

Simple discriminative method

$$y' = \arg \max_y \mathbf{w}^T \phi_i(y) \quad (1)$$

If $y' \neq y_i$ then, $\mathbf{w} \leftarrow \mathbf{w} + \eta(\phi_i(y_i) - \phi_i(y'))$

Remember the idea of perceptron: if there is a mistake, I add the right vector and subtract the wrong vector. If no mistake, I do nothing.

Note that later we will use the following notation:

$$\delta \phi_i(y') = (\phi_i(y_i) - \phi_i(y'))$$

Collins, 2002.

Learning linear models by minimizing a loss function

- What is a training error here ?
- $error = \sum_i step(\mathbf{w}^T \phi_i(y_i) - \max_{y \neq y_i} \mathbf{w}^T \phi_i(y))$
- with $step(z) = 1$ if $z < 0$ and 0, otherwise
 - zero-one loss : discontinuous, minimization is NP-complete
 - Turn to convexified losses

2 - Log loss, logistic loss

- Posterior probabilities

$$P(y|x, \mathbf{w}) = \frac{\exp(\mathbf{w}^T \phi(x, y))}{\sum_{y'} \exp(\mathbf{w}^T \phi(x, y'))}$$

- Maximize the log conditional likelihood of training data

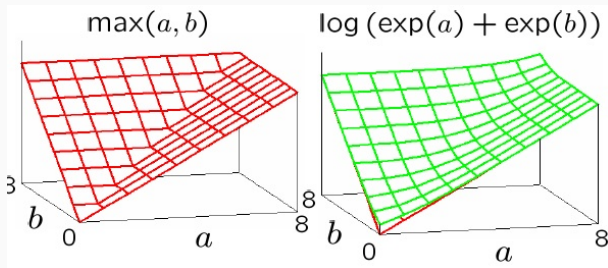
$$\begin{aligned} \max_{\mathbf{w}} \log \prod_i P(y_i | x_i, \mathbf{w}) &= \sum_i \log \left(\frac{\exp(\mathbf{w}^T \phi_i(y_i))}{\sum_y \exp(\mathbf{w}^T \phi_i(y))} \right) \\ \max_{\mathbf{w}} \sum_i (\mathbf{w}^T \phi_i(y_i) - \log \sum_y \exp(\mathbf{w}^T \phi_i(y))) \end{aligned}$$

Maximize log loss with regularization

$$\max_{\mathbf{w}} \sum_i (\mathbf{w}^T \phi_i(y_i) - \log \sum_y \exp(\mathbf{w}^T \phi_i(y))) - \lambda \|\mathbf{w}\|^2$$

equivalent to

$$\min_{\mathbf{w}} \lambda \|\mathbf{w}\|^2 - \sum_i (\mathbf{w}^T \phi_i(y_i) - \log \sum_y \exp(\mathbf{w}^T \phi_i(y)))$$



Let us notice the proximity between these two functions.

3 - Now let us try to maximize a margin

If we just want to separate the data we would impose:

$$\forall i, \forall y \neq y_i, \mathbf{w}^T \phi_i(y_i) \geq \mathbf{w}^T \phi_i(y)$$

but we define what is a good separator using the idea of geometric margin !

Now maximizing a margin

On our example:

$$\mathbf{w}^T \phi(\text{run the marathon, sports}) \geq \mathbf{w}^T \phi(\text{run the marathon, politics}) + \gamma$$

$$\mathbf{w}^T \phi(\text{run the marathon, sports}) \geq \mathbf{w}^T \phi(\text{run the marathon, economics}) + \gamma$$

$$\mathbf{w}^T \phi(\text{run the marathon, sports}) \geq \mathbf{w}^T \phi(\text{run the marathon, sports})$$

Let us take $\gamma = 1$ and $\Delta_i(y) = \Delta(y_i, y) = 0$ if $y = y_i$ and $\Delta(y_i, y) = \gamma = 1$, otherwise.

Here and there, $\Delta(y_i, y)$ measures how much y is far from the true output.

Minimizing the norm of "canonical hyperplane

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2$$

s.t. :

$$\forall i, \forall y, \mathbf{w}^T \phi_i(y_i) \geq \mathbf{w}^T \phi_i(y) + \Delta(y_i, y)$$

Allowing for non-separability (adding slack variables)

Margin maximization with slack variables: Pb 1

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \xi_i$$

s.t. :

$$\forall i, \forall y, \mathbf{w}^T \phi_i(y_i) + \xi_i \geq \mathbf{w}^T \phi_i(y) + \Delta(y_i, y)$$

$$\forall i, \xi_i \geq 0$$

A min-max formulation (Tsochantaridis et al. 2005)

We solve ξ_i : $\forall i, \forall y, \xi_i \geq \mathbf{w}^T \phi_i(y) + \Delta(y_i, y) - \mathbf{w}^T \phi_i(y_i)$

$\forall i, \xi_i = \max_y [\mathbf{w}^T \phi_i(y) + \Delta(y_i, y)] - \mathbf{w}^T \phi_i(y_i)$

Pb 2

$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \max(0, \max_y [\mathbf{w}^T \phi_i(y) + \Delta(y_i, y)] - \mathbf{w}^T \phi_i(y_i))$

Compare max-margin and maxent (log-loss)

Maxent (in logistic regression)

$$\min_{\mathbf{w}} \lambda \|\mathbf{w}\|^2 - \sum_i (\mathbf{w}^T \phi_i(y_i) - \log(\sum_i y \exp(\mathbf{w}^T \phi_i(y))))$$

SVM

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \max(0, \max_y [\mathbf{w}^T \phi_i(y) + \Delta(y_i, y)] - \mathbf{w}^T \phi_i(y_i))$$

Both try to make the true score better than a function of the other score

What have we seen so far ?

- a simple way to define joint feature map (which will be used as well in structured prediction)
- the structured hinge loss:
$$\ell(y_i, \mathbf{w}^T \phi_i(y)) = \max(0, \max_y [\mathbf{w}^T \phi_i(y) + \Delta(y_i, y)] - \mathbf{w}^T \phi_i(y_i))$$
- its proximity with maxent in a logistic regression model

Interestingly the hinge loss allows to take into account the loss Δ between classes y

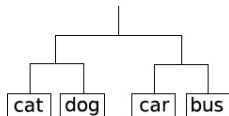
Structured output SVM for a hierarchy of classes

Hierarchical Multiclass Loss:

$$\Delta(y, y') := \frac{1}{2}(\text{distance in tree})$$

$$\Delta(\text{cat}, \text{cat}) = 0, \quad \Delta(\text{cat}, \text{dog}) = 1,$$

$$\Delta(\text{cat}, \text{bus}) = 2, \quad \text{etc.}$$



Solve:
$$\min_{w, \xi} \frac{1}{2} \|w\|^2 + \frac{C}{N} \sum_{n=1}^N \xi^n$$

subject to, for $i = 1, \dots, n$,

$$\langle w, \phi(x^n, y^n) \rangle - \langle w, \phi(x^n, y) \rangle \geq \Delta(y^n, y) - \xi^n \quad \text{for all } y \in \mathcal{Y}.$$

Tasks solved with this approach

Tsochantaridis, Joachims, Hofman and Altun. JMLR 2005.

This approach for multiple classes can be extended to other kinds of structure.

- multi-class classification
- hierarchical/structured classification
- sequence labelling

References for this lecture

- Crammer, Koby and Singer, Yoram, On the Algorithmic Implementation of Multiclass Kernel-based Vector Machines, J. Mach. Learn. Res., 3/1/2002.
- Tsochantaridis, I. and Joachims, T. and Hofmann, T. and Altun, Y., Large margin methods for structured and interdependent output variables, JMLR, 6,2005
- Collins, Michael, Discriminative Training Methods for Hidden Markov Models: Theory and Experiments with Perceptron Algorithms, Proceedings of the ACL-02 Conference on Empirical Methods in Natural Language Processing - Volume 10,2002.
- Ben Taskar, Learning structured prediction models, a large margin approach, PhD thesis (<http://www.seas.upenn.edu/~taskar/pubs/thesis.pdf>), U. Pennsylvania, USA, 2004.