Code	Name and Key Concents
MMu1t1	Name and Key Concepts  Functions and graphs: Lines, Quadratics, Inverse Proportions, Poly-
MMu1t2	nomials, Relations, Translations and Dilations  Trigonometric functions: Unit Circle, Radians, SOH CAH TOA, Sine Rule, Exact Values, Amplitude/Period/Phase, Sum of Angles Identities
MMu1t3	Counting and probability: Binomial Coefficients, Set Complement Intersection and Union, Probability, $P(A \cup B) = P(A) + P(B) - P(A \cap B)$
MMu2t1	B), Conditional Probability, Independance  Exponential functions: Index Laws, Fractional Indices, Functions, Asymptotes, Graphs
MMu2t2	Arithmetic and geometric sequences and series: Arithmetic and Geometric Sequences as Recurrence Relations, Limiting Behaviour, and Partial Sum Formulae, Growth and Decay
MMu2t3	Introduction to differential calculus Average Rate of Change, First Principles, Leibniz Notation, Instantaneous Rate of Change, Slope of
MMu3t1	Tangent, Derivitive of Polynomials, Linearity of Differentiation, Optimisation, Anti-Derivitives, Interpret Position-Time Graphs  Further differentiation and applications: Define $e$ as $a$ s.t.
MMu3t2	$\lim_{h\to 0} \frac{a^h-1}{h} = 1$ , Derivitives of $e^x \sin(x)$ and $\cos(x)$ , Chain Product and Quotient Rules, Second Derivitives Integrals: Integrate Polynomial Exponential and Trigonometric Func-
IVIIVIU3t2	tions, Linearity of Integration, Determine Displacement given Velocity, Definite Integrals, Fundamental Theorem of Calculus, (signed) Area Un-
MMu3t3	der a Curve  Discrete random variables: Frequencies, General Properties, Expected Value, Variance, Standard Deviation, Bernoulli and Binomial
MMu4t1	Distribtions  The logarithmic function: Logs as Inverse of Exponentials, Log-
MMu4t2	Scales, Log Function Graphs, Natural Log, $\frac{d}{dx}\ln(x) = \frac{1}{x}$ , $\int \frac{1}{x}dx = \ln(x) + c$ for $x > 0$ Continuous random variables and the normal distribution: Prob-
	ability Density Function, Cumulative Distribution Function, Probabilites Expected Value, Variance and Standard Deviation as Integrals, Linear Transformation of Random Variables, Normal Distribution using Tech-
MMu4t3	nology Interval estimates for proportions Simple Random Sampling, Bias,
	Sample Proportion, Normal Approximation to the Binomial Proportion, Wald Confidence Interval, Trade-Off Between Width and Level of Confidence
SMu1t1	Combinatorics Multiplication of Possibilities, Factorial Notation, Permutations with and without Repeated Objects, Union of Three Sets,
SMu1t2	Pigeon-Hole Principle, Combinations, Pascals Triangle  Vectors in the plane: Magnetude and Direction, Scalar Multiplica-
	tion, Addition and Substraction as a Triangle, Vector Notation, $a{f i}+b{f j}$ Notation, Scalar Dot Product, Projection, Parallel and Perpendicular Vectors
SMu1t3	<b>Geometry</b> : Notation for Implication ( $\Rightarrow$ ) and Equivalence ( $\Leftrightarrow$ ), Converse ( $B \Rightarrow A$ ) Negation ( $\neg A \Rightarrow \neg B$ ) and Contrapositive ( $\neg B \Rightarrow \neg A$ ), Proof by Contradiction, $\forall$ and $\exists$ Notation, Counter-Examples, Circle
SMu2t1	Theorems, Quadrilateral Proofs in $\mathbb{R}^2$ Trigonometry: Graph and Solve Trig Functions, Prove Various Trig
SMu2t2	Indentities, Reciprocal Trig Functions  Matrices: Notation, Addition and Scalar Multiplication of Matrices,  Multiplicative Identity and Inverse, Determinant, Matrices as Transfor-
SMu2t3	mations  Real and complex numbers: Rationality and Irrationality, Induction $i = \sqrt{-1}$ . Complex Numbers $a + bi$ and Arithmetic $(+ - + + + + + + + + + + + + + + + + + +$
Cra ~	tion, $i = \sqrt{-1}$ , Complex Numbers $a + bi$ and Arithmetic $(+, -, \times, \div)$ , Complex Conjugates, Complex Plane, Complex Conjugate Roots of Polynomials
SMu3t1	<b>Complex numbers</b> : Modulus and Argument, Arithmetic ( $\times$ , $\div$ , and $z^n$ ) in Polar Form, Convert between Polar and Cartesian Form, De Moivre's Theorem, Roots of Complex Numbers, Factorising Polynomials
SMu3t2	Functions and sketching graphs: Composition of Functions, One-to-One, Inverse Functions, Absolute Value Function, Rational Functions
SMu3t3	<b>Vectors in three dimensions</b> : $a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$ Notation, Equation for Spheres, Parameterised Vector Equations, Equations of Lines, the Cross Product, Equation for a Plane, Systems of Linear Equation (Elimina-
SMu4t1	tion Method) and Geometric Interpretation of Solutions, Kinematics via Differentiation of Vector Equations, Projectile and Circular Motion Integration and applications of integration Substitution, $\int \frac{1}{x} dx =$
_	$\ln  x  + c$ for $x \neq 0$ , Inverse Trig Functions and their Derivitives, Integrate $\frac{\pm 1}{\sqrt{a^2 - x^2}}$ and $\frac{a}{a^2 + x^2}$ , Partial Fractions, Integration by Parts, Volume of
SMu4t2	Solids of Revolution, Numerical Integration using Technology  Rates of change and differential equations: Implicit Differentiation, First-Order Seperable Differential Equations, The Logistic Equatio
SMu4t3	tion, Kinematics (Rates of Change)  Statistical inference: Central Limit Theorem and the Resulting Confidence Interval for a Mean
S1M1	Functions and graphs: Equations for a Line, Slope, y-intercept, In-
S1M2	tersection of Lines, Reciprocal Function, Asymptotes, Functions vs Relations, Domain, Range, Function Notation  Polynomials: Quadratic Equations in Vertex and Factorised Forms,
S1M3	Quadratic Formula, Completing the Square, The Leading Coefficient and Degree of a Polynomials, Cubics, Quartics  Trigonometry: Pythagoras, SOH CAH TOA, Cosine Rule, Sine Rule,
	Unit Circle, Sine and Cosine Functions, Radians, Length of Arc, Area of Sector, Amplitude, Period, Phase, $\tan(x) = \frac{\sin(x)}{\cos(x)}$
S1M4	Counting and statistics: Factorial, Permutations, Multiplication Principle, Combinations, Discrete vs Continuous Random Variables, Mean, Median, Mode, Range, Interquartile Range, Standard Deviation, Normal
S1M5	Distribution,  Growth and decay: Index and Logarithm Laws, Exponential Functions
S1M6	and their Graphs Introduction to differential calculus: Average Rate of Change, First Principles, Notation $f'(x) = \frac{df}{dx}$ , $\frac{d}{dx}x^n = nx^{n-1}$ , Linearity of Differential Change, Figure 1.
S1M7	tiation, Slope of Tangent, Increasing vs Decreasing, Local and Global Maxima and Minima, Stationary Points, Sign Diagram  Arithmetic and geometric sequences and series: Arithmetic and
	Geometric Series as Recurrance Relations and Explicit Expressions, Partial Sums, Limiting Behaviour
S1M8 S1M9	<b>Geometry</b> : Circle Properties, Proofs (Direct, Contradiction, and Contrapositive) <b>Vectors in the plane</b> : Component (column) vs $ai + bj$ Notation,
	Length and Direction, Linear Combinations of Vectors, Scalar Dot Product, Projection, Angle Between Two Vectors and Parallel/ Perpendicular, Geometric Proof
S1M10	Further Trigonometry: Sketch Trigonometric Functions with Translations and Dilations, Solve for Angles, Trigonometric Identities, Recip-
S1M11	rocal Trigonometric Functions  Matrices: Linear Combinations of Matrices, Matrix Multiplication, The Identity, Inverse Matrices, The $2\times2$ Inverse, The $2\times2$ Determinant, Lin-
S1M12	ear Transformations (including rotations, reflections and composition) Real and complex numbers: Rationals, Irrationals, Interval Notation, Induction, $i=\sqrt{-1}$ , Real and Imaginary Components, Complex
	Conjugates and Arithmetic, Argand Diagram, Modulus, Complex Roots of Polynomals
S2MM1	Further differentiation and applications: S1M6, Chain Product and Quotient Rules, $e=2.718\ldots$ , $\frac{d}{dx}e^x=e^x$ , $\frac{d}{dx}\sin(x)=\cos(x)$ ,
S2MM2	$\frac{d}{dx}\cos(x)=-\sin(x)$ , Second Derivatives, Concavity and Points of Inflection  Discrete random variables: Random Variables, Discrete vs Contin-
. <del>-</del>	uous, Probability Functions and Distributions, Properties of Probabilities, Frequency, Expected Value $E[X]=\sum xp(x)=\mu_X$ , Standard
S2MM3	Deviation $\sigma_X = \sqrt{\sum (x - \mu_X)^2 p(x)}$ , Uniform Bernoulli and Binomial Distributions Integral calculus: Anti-differentiation, If $F'(x) = f(x)$ then
	$\int f(x)dx = F(x) + c$ , Reversing Chain Rule for $\int f(ax+b)dx$ , Linearity of Integration, Finding the Constant of Integration, Area Under the Curve as Upper and Lower Sum Approximations, Definite Integral,
S2MM4	Area Between Two Functions and Between a Negative Function and the x-axis, Fundamental Theorem of Calculus,
S2MM4 S2MM5	Logarithmic functions: Sketching $y=a\ln(b(x-c))$ , $\frac{d}{dx}\ln(x)=\frac{1}{x}$ , For $x>0$ $\int \frac{1}{x}dx=\ln(x)+c$ Continuous random variables and the normal distribution:
	$P(X=x)=0$ , Probability Density Function, $\mu_X=\int_{-\infty}^{\infty}xf(x)dx$ , $\sigma_X=\int_{-\infty}^{\infty}(x-\mu_X)^2f(x)dx$ , $f(x)=\frac{1}{\sigma\sqrt{2\pi}}e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$ , Standard Normal
	$Z=rac{X-\mu}{\sigma}$ , Simple Random Sampling, For $X\sim (\mu,\sigma)$ and $X_i\sim iidX$ Sampling Distributions of $S_n=\sum_{i=1}^n X_i \ (n\mu,\sigma\sqrt{n})$ and $\bar{X}_n=rac{S_n}{n}$ $(\mu,rac{\sigma}{\sqrt{n}})$ , If $X$ is Normally Distributed, then so are $S_n$ and $\bar{X}_n$ , Centrally
S2MM6	tral Limit Theorem (CLT)  Sampling and confidence intervals: Confidence Interval for a Mean
	using CLT $\left(\bar{x}-z^*\frac{s}{\sqrt{n}}\right) \leq \mu \leq \left(\bar{x}+z^*\frac{s}{\sqrt{n}}\right)$ , Wald Interval for a Proportion
S2SM1 S2SM2	Mathematical induction: Initial Case and Induction Step  Complex numbers: Cartesian vs Polar Form, Real and Imaginary Components, Modulus and Argument, Arithmetic in both Cartesian and Polar
	ponents, Modulus and Argument, Arithmetic in both Cartesian and Polar Forms, de Moivre's Theorem including Negative and Fractional Powers, Geometric Properties of the Argand Plane, Complex Arithmetic as
S2SM3	Transformations, $n^{\rm th}$ Roots of a Complex Number, Factorising Polynomials with Complex Roots  Functions and sketching graphs: Function Composition, Informal
	Intro to Domain and Range, One-to-One, Inverse Functions, Absolute Value Function, Graphing Rational Functions
S2SM4	<b>Vectors in three dimensions</b> : Notation, Equations of a Line in $\mathbb{R}^3$ , Scalar Dot Product, Vector Cross Product, $ \mathbf{a} \times \mathbf{b} $ is the Area of their Parallelogram, Equation for a Plane in $\mathbb{R}^3$ , Systems of Linear Equations,
S2SM5	Geometric Interpretation of No/Unique/Infinite Solutions to a System of Linear Equations in $\mathbb{R}^3$ Integration techniques and applications: Integration by Substitu-
JIV	tion, Using Trigonometric Identities for Integration, Derivatives of Inverse Trigonometric Functions (so $\int \frac{\pm 1}{\sqrt{a^2-x^2}} dx$ and $\int \frac{a}{a^2+x^2} dx$ , Integra-
S2SM6	tion by Parts, Area Between two Curves, Volume of Solids of Revolution Rates of change and differential equations: Implicit Differentiation, First-Order Seperable Differential Equations, The Logistic Differential Equations
	ential Equation, Parameterised Curves, Example: if $\mathbf{v} = \frac{d}{dt}(x(t), y(t))$ is Velocity, $ \mathbf{v} $ is Speed, and so the Arc Length along the Parameterised Curve is $\int_a^b \sqrt{\mathbf{v} \bullet \mathbf{v}} dt$ , Trigonometric Parameterisations (unit circle, and
<u>N</u> 1C1	non-circular parameterisations)
MS1 MS2	Numbers & Functions: Natural Numbers, Integers, Rational Numbers, Real Numbers, Functions, Intervals  Linear Functions: Equation for Linear Functions, Simultaneous Linear
MS3	Equations, Sketching Linear Inequalities <b>Quadratic Functions</b> : Sketching a Parabola, General Form of a Quadratic, Translations and Dilations
MS4 MS5	Rational Functions: Sketching Reciprocal Functions (Hyperbola), Lines of Symmetry, Limits and Asymptotes  Trigonometry I: Pythagoras, Similar Triangles, SOH CAH TOA,
	Trigonometric and Inverse Trigonometric Functions using Technology, Exact Values
MS6	<b>Trigonometry II</b> : Unit Circle, Sketching Trigonometric Functions, Finding all Solutions to Trigonometric Equations, The Sine Rule, The Cosine Rule, Introductory Trigonometric Identities, Radians
MS7 MS8	<b>Exponential Functions</b> : Index Laws, Sketching Exponential Functions, $e=2.718\ldots$ , Growth and Decay <b>Logarithms</b> : Natural Logarithm, Logarithm Laws, Using Logarithm to
	Fit Growth/Decay Functions, Half-Life/ Doubling Time
MT1	<b>Polynomials</b> : Polynomial Division and "Remainder Theorem", Factor Theorem Linking Zeros to Factors, Continuous vs Discontinuous Functions, Smoothness, Sketching Factorised Form of Polynomials, Factorised Form of Polynomia
MT2	ing Polynomials, The Quadratic Formula  Matrices: Order, Notation, Linear Combinations of Matrices, Matrix  Multiplication (Associative but not Commutative, Distributes across Lin-
	ear Combinations), The Identity Matrix, Powers of Square Matrices, Matrix Transpose, Systems of Linear Equations, Matrix Inverse, $2\times 2$
MT3	determinant, The $2 \times 2$ Inverse, $n \times n$ Inverses, Elementary Row Operations, <b>Vectors and Applications</b> : Directed Line Segment Notation for Vec-
	• • • • • • • • • • • • • • • • • • • •
	tors, Magnetude/ Length and Direction, Linear Combinations of Vectors, Component and $a\mathbf{i} + b\mathbf{j}$ Notation, Vectors in $\mathbb{R}^2$ and $\mathbb{R}^3$ , Scalar Dot Product, Equation for a Plane in $\mathbb{R}^3$
MT4	tors, Component and $a\mathbf{i} + b\mathbf{j}$ Notation, Vectors in $\mathbb{R}^2$ and $\mathbb{R}^3$ , Scalar Dot Product, Equation for a Plane in $\mathbb{R}^3$ Systems of Linear Equations: Augmented Matrix for Systems of Linear Equations, Elementary Row Operations, Row-Echelon Form, So-
MT4	tors, Component and $a\mathbf{i} + b\mathbf{j}$ Notation, Vectors in $\mathbb{R}^2$ and $\mathbb{R}^3$ , Scalar Dot Product, Equation for a Plane in $\mathbb{R}^3$ Systems of Linear Equations: Augmented Matrix for Systems of Linear Equations, Elementary Row Operations, Row-Echelon Form, Solutions to Systems of Linear Equations and Geometric Interpretations in $\mathbb{R}^2$ and $\mathbb{R}^3$ , Matrix Inverses by Gauss-Jordan Elimination  Differentiation: Rates of Change, Gradient, First Principles, Limit
	tors, Component and $a\mathbf{i} + b\mathbf{j}$ Notation, Vectors in $\mathbb{R}^2$ and $\mathbb{R}^3$ , Scalar Dot Product, Equation for a Plane in $\mathbb{R}^3$ Systems of Linear Equations: Augmented Matrix for Systems of Linear Equations, Elementary Row Operations, Row-Echelon Form, Solutions to Systems of Linear Equations and Geometric Interpretations in $\mathbb{R}^2$ and $\mathbb{R}^3$ , Matrix Inverses by Gauss-Jordan Elimination
	tors, Component and $a\mathbf{i} + b\mathbf{j}$ Notation, Vectors in $\mathbb{R}^2$ and $\mathbb{R}^3$ , Scalar Dot Product, Equation for a Plane in $\mathbb{R}^3$ Systems of Linear Equations: Augmented Matrix for Systems of Linear Equations, Elementary Row Operations, Row-Echelon Form, Solutions to Systems of Linear Equations and Geometric Interpretations in $\mathbb{R}^2$ and $\mathbb{R}^3$ , Matrix Inverses by Gauss-Jordan Elimination Differentiation: Rates of Change, Gradient, First Principles, Limit Notation, Derivative Notation, $\frac{d}{dx}x^n = nx^{n-1}$ (including $n=0$ and $n=1$ ), Linearity of Differentiation, Product Rule, Quotient Rule, Chain Rule, Implicit Differentiation, Normal to a Curve Applications of Differentiation: Sketching Polynomials and Rational Functions (Intercepts and Asymptotes), Continuity, Sign Diagrams,
MT6	tors, Component and $a\mathbf{i} + b\mathbf{j}$ Notation, Vectors in $\mathbb{R}^2$ and $\mathbb{R}^3$ , Scalar Dot Product, Equation for a Plane in $\mathbb{R}^3$ Systems of Linear Equations: Augmented Matrix for Systems of Linear Equations, Elementary Row Operations, Row-Echelon Form, Solutions to Systems of Linear Equations and Geometric Interpretations in $\mathbb{R}^2$ and $\mathbb{R}^3$ , Matrix Inverses by Gauss-Jordan Elimination Differentiation: Rates of Change, Gradient, First Principles, Limit Notation, Derivative Notation, $\frac{d}{dx}x^n = nx^{n-1}$ (including $n=0$ and $n=1$ ), Linearity of Differentiation, Product Rule, Quotient Rule, Chain