

## Theorem

*For a linear mapping  $T : V \rightarrow W$ , ordered bases*

$$B = (\mathbf{b}_1, \dots, \mathbf{b}_n), \quad \tilde{B} = (\tilde{\mathbf{b}}_1, \dots, \tilde{\mathbf{b}}_n)$$

*of  $V$  and*

$$C = (\mathbf{c}_1, \dots, \mathbf{c}_m), \quad \tilde{C} = (\tilde{\mathbf{c}}_1, \dots, \tilde{\mathbf{c}}_m)$$

*of  $W$ , and a transformation matrix  $A_T$  of  $T$  with respect to  $B$  and  $C$ , the corresponding transformation matrix  $\tilde{A}_T$  with respect to the bases  $\tilde{B}$  and  $\tilde{C}$  is given as*

$$\tilde{A}_T = L^{-1} A_T S$$

*Here,  $S \in \mathbb{R}^{n \times n}$  ( $L \in \mathbb{R}^{m \times m}$ ) is the transformation matrix of  $id_V$  ( $id_W$ ) that maps coordinates with respect to  $\tilde{B}$  ( $\tilde{C}$ ) onto coordinates with respect to  $B$  ( $C$ ).*

## Definition

Matrices  $A, \tilde{A} \in \mathbb{R}^{m \times n}$  are **equivalent** if there exist regular matrices  $P \in \mathbb{R}^{n \times n}$  and  $Q \in \mathbb{R}^{m \times m}$  such that

$$\tilde{A} = Q^{-1}AP$$

## Definition

Matrices  $A, \tilde{A} \in \mathbb{R}^{n \times n}$  are **similar** if there exists a regular matrix  $Q \in \mathbb{R}^{n \times n}$  such that

$$\tilde{A} = Q^{-1}AQ.$$

## Remark

*Similar matrices are always equivalent. However, equivalent matrices are not necessarily similar.*

## Definition

*For  $T : V \rightarrow W$ , we define the kernel/null space*

$$\ker(T) := T^{-1}(\mathbf{0}_W) = \{\mathbf{v} \in V : T(\mathbf{v}) = \mathbf{0}_W\}$$

*and the image/range*

$$\text{Im}(T) := T(V) = \{\mathbf{w} \in W \mid \exists \mathbf{v} \in V : T(\mathbf{v}) = \mathbf{w}\}$$

*We also call  $V$  and  $W$  also the domain and codomain of  $T$ , respectively*

## Proposition

- $T(\mathbf{0}_V) = \mathbf{0}_W$  and, therefore,  $\mathbf{0}_V \in \ker(T)$
- $\text{Im}(T) \subset W$  is a subspace of  $W$ , and  $\ker(T) \subset V$  is a subspace of  $V$
- $T$  is injective (one-to-one) if and only if  $\ker(T) = \{0\}$

## Definition

Let  $A \in \mathbb{R}^{m \times n}$  be a matrix with columns  $\mathbf{a}_1, \dots, \mathbf{a}_n$ , then

- $\text{span}[\mathbf{a}_1, \dots, \mathbf{a}_n] \subset \mathbb{R}^m$  is called **column space**
- $\{A\mathbf{x} = 0; \mathbf{x} \in \mathbb{R}^n\} \subset \mathbb{R}^n$  is called **null space**

Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear mapping with its transformation matrix  $A \in \mathbb{R}^{m \times n}$ , i.e.  $T(\mathbf{x}) = A\mathbf{x}$ .

- If  $A = [\mathbf{a}_1, \dots, \mathbf{a}_n]$ , then  $\text{Im}(T) = \{A\mathbf{x}; \mathbf{x} \in \mathbb{R}^n\} = \{x_1\mathbf{a}_1 + \dots + x_n\mathbf{a}_n; x_1, \dots, x_n \in \mathbb{R}\} = \text{span}[\mathbf{a}_1, \dots, \mathbf{a}_n]$
- The image  $\text{Im}(T)$  is a subspace of  $\mathbb{R}^m$
- $\text{rk}(A) = \dim(\text{Im}(T))$
- The kernel  $\ker(T)$  is a subspace of  $\mathbb{R}^n$
- The kernel  $\ker(T)$  is the null space of  $A$

## Example

Find a basis for image and kernel of the linear transformation  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  given by

$$T \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 + 2x_2 - x_3 \\ x_2 + 3x_3 \end{bmatrix}$$

## Rank-Nullity Theorem

For vector spaces  $U, V$  and a linear mapping  $T : U \rightarrow V$  it holds that

$$\dim(\ker(T)) + \dim(\operatorname{Im}(T)) = \dim(U),$$

equivalently for a matrix  $A \in \mathbb{R}^{n \times m}$

$$\text{nullity}(A) + \text{rank}(A) = m,$$

where  $\text{nullity}(A)$  is the dimension of the null space  $\text{null}(A)$ .

## Definition

Given a vector space  $V$ , a **norm** on  $V$  is a function  $\|\cdot\| : V \rightarrow [0, +\infty)$  with the following properties: For all  $\mathbf{x}, \mathbf{y} \in V$ , and all  $\lambda \in \mathbb{R}$

- $\|\mathbf{x} + \mathbf{y}\| \leq \|\mathbf{x}\| + \|\mathbf{y}\|$  ( triangle inequality)
- $\|\lambda \mathbf{x}\| = |\lambda| \|\mathbf{x}\|$  (absolutely homogeneous)
- $\|\mathbf{x}\| \geq 0$  and  $\|\mathbf{x}\| = 0$  iff  $\mathbf{x} = 0$  (positive definite)

### Example

The **Manhattan norm** on  $\mathbb{R}^n$  is defined for  $\mathbf{x} \in \mathbb{R}^n$  as

$$\|\mathbf{x}\|_1 := \sum_{i=1}^n |x_i|$$

The Manhattan norm is also called  $\ell_1$  **norm**.

### Example

The length of a vector  $\mathbf{x} \in \mathbb{R}^n$  is given by

$$\|\mathbf{x}\|_2 := \sqrt{\sum_{i=1}^n x_i^2} = \sqrt{\mathbf{x}^T \mathbf{x}}.$$

This norm is called the **Euclidean norm**. The Euclidean norm is also called  $\ell_2$  **norm**.

## Definition

A function  $f : V \times V \rightarrow \mathbb{R}$  is called **bilinear** if

$$f(a\mathbf{x} + b\mathbf{y}, \mathbf{z}) = af(\mathbf{x}, \mathbf{z}) + bf(\mathbf{y}, \mathbf{z})$$

$$f(\mathbf{x}, a\mathbf{y} + b\mathbf{z}) = af(\mathbf{x}, \mathbf{y}) + bf(\mathbf{x}, \mathbf{z})$$

## Definition

A function  $\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{R}$  is called **inner product on  $V$** , if

- $\langle \mathbf{x}, \mathbf{y} \rangle = \langle \mathbf{y}, \mathbf{x} \rangle$  (symmetric)
- $\langle \mathbf{x}, \mathbf{x} \rangle \geq 0$  and  $\langle \mathbf{x}, \mathbf{x} \rangle = 0$  iff  $\mathbf{x} = 0$  (positive definite)
- $\langle \cdot, \cdot \rangle$  is a bilinear function



## Example

*The scalar product/dot product in  $\mathbb{R}^n$ , which is given by*

$$\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^T \mathbf{y} = \sum_{i=1}^n x_i y_i.$$

*The dot product is an inner product.*

$\mathbb{R}^n$  with the dot product is called **Euclidean vector space**.

## Example

*If we define for  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^2$*

$$\langle \mathbf{x}, \mathbf{y} \rangle := x_1 y_1 - (x_2 y_1 + x_1 y_2) + 2x_2 y_2$$

*then  $\langle \cdot, \cdot \rangle$  is an inner product but different from the dot product.*

# Symmetric, Positive Definite Matrices

## Definition

A symmetric matrix  $A \in \mathbb{R}^{n \times n}$  is called **positive definite**, if

$$\mathbf{x}^T A \mathbf{x} > 0, \quad \mathbf{x} \in \mathbb{R}^n, \mathbf{x} \neq \mathbf{0}$$

The matrix  $A$  is called **positive semi-definite**, if

$$\mathbf{x}^T A \mathbf{x} \geq 0, \quad \mathbf{x} \in \mathbb{R}^n.$$

## Example

Which of the following matrices is positive definite?

$$A = \begin{bmatrix} 4 & -4 \\ -4 & 5 \end{bmatrix}, \quad B = \begin{bmatrix} 4 & -4 \\ -4 & 2 \end{bmatrix}$$

## Proposition

Let  $V$  be an  $n$ -dimensional vector space with an inner product  $\langle \cdot, \cdot \rangle$  and a basis  $B = (\mathbf{b}_1, \dots, \mathbf{b}_n)$ . Prove that

$$\langle \mathbf{x}, \mathbf{y} \rangle = [\mathbf{x}]_B^T A [\mathbf{y}]_B,$$

where  $A_{ij} = \langle \mathbf{b}_i, \mathbf{b}_j \rangle$ . Conclude that the matrix  $A$  is positive definite.

## Theorem

For a real-valued, finite-dimensional vector space  $V$  and a basis  $B$  of  $V$  it holds that  $\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{R}$  is an inner product if and only if there exists a symmetric, positive definite matrix  $A \in \mathbb{R}^{n \times n}$  with

$$\langle \mathbf{x}, \mathbf{y} \rangle = [\mathbf{x}]_B^T A [\mathbf{y}]_B,$$