

# Basic Mathematics , Fall 2020

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# WELCOME TO Basic Mathematics!

- Course: **Basic Mathematics**, Credits: **6**
- Lectures: **Tuesday & Wednesday 18:30-19:50**
- Instructor: Karen Keryan
- Grading Policy:

$$\text{Total} = 0.1 * (\text{HW}) + 0.25 * (\text{M1} + \text{M2}) + 0.4 * \text{F}$$

- Lectures:  
Tuesdays & Wednesday, 18:30-19:50 (Sep & Oct)  
Tuesday, 18:30-19:50 (Nov & Dec)
- Homeworks: weekly (except the exam weeks)
- No late Homework! (Except for some exceptional cases)

## Course Content

- Linear Algebra
- Calculus
- Probability theory

## Textbooks

- Mathematics for Machine Learning by Marc Peter Deisenroth, A Aldo Faisal, and Cheng Soon Ong.  
<https://mml-book.github.io/>

## Additional textbooks:

- Linear Algebra: A Modern Introduction, 4th Ed, by David Poole
- Calculus, 7th Ed, by James Stewart
- A First Course in Probability, 8th Ed, by Sheldon Ross

Find other interesting stuff on the syllabus!

## Definition

With  $m, n \in \mathbb{N}$  a real-valued  $(m, n)$  matrix  $A$  is matrix an  $m \cdot n$ -tuple of elements  $a_{ij}$ ,  $i = 1, \dots, m$ ,  $j = 1, \dots, n$ , which is ordered in  $m$  rows and  $n$  columns:

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}, a_{ij} \in \mathbb{R}.$$

$(1, n)$ -matrices are called **rows**,  $(m, 1)$ -matrices are called **columns**. These special matrices are also called **row/column vectors**.

$\mathbb{R}^{m \times n}$  is the set of all real-valued  $(m, n)$ -matrices.  $A \in \mathbb{R}^{m \times n}$  can be equivalently represented as  $a \in \mathbb{R}^{mn}$  by stacking all  $n$  columns of the matrix into a long vector.



# Matrix Multiplication

## Definition

*If  $A$  is an  $m \times n$  matrix and  $B$  is an  $n \times r$  matrix, then the product  $C = AB$  is an  $m \times r$  matrix. The  $(i, j)$  entry of the product is computed as follows:*

$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{in}b_{nj} = \sum_{k=1}^n a_{ik}b_{kj}.$$

## Remark

- 1. The number of columns of  $A$  must be the same as the number of rows of  $B$ .*
- 2. The  $(i, j)$  entry of the matrix  $AB$  is the dot product of the  $i$ th row of  $A$  and the  $j$ th column of  $B$  :*

$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{in}b_{nj}$$

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{i1} & a_{i2} & \dots & a_{in} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} b_{11} & \dots & b_{1j} & \dots & b_{1r} \\ b_{21} & \dots & b_{2j} & \dots & b_{2r} \\ \vdots & & \vdots & & \vdots \\ b_{n1} & \dots & b_{nj} & \dots & b_{nr} \end{bmatrix}$$

## Example

Compute  $AB$  if

$$A = \begin{bmatrix} 2 & 3 & 1 \\ 3 & -1 & 0 \end{bmatrix}, \quad \text{and} \quad B = \begin{bmatrix} 1 & -3 \\ 4 & 0 \\ 2 & -2 \end{bmatrix}$$

Check that  $AB \neq BA$ .

## Definition

In  $\mathbb{R}^{n \times n}$ , we define the **identity matrix**

$$I_n = \begin{bmatrix} 1 & 0 & 0 \dots & 0 \\ 0 & 1 & 0 \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 \dots & 1 \end{bmatrix} \in \mathbb{R}^{n \times n}$$

as the  $n \times n$ -matrix containing 1 on the diagonal and 0 everywhere else.

With this,  $A \cdot I_n = A = I_n \cdot A$  for all  $A \in \mathbb{R}^{n \times n}$ .

- Associativity:

$$\forall A \in \mathbb{R}^{m \times n}, B \in \mathbb{R}^{n \times p}, C \in \mathbb{R}^{p \times q} : (AB)C = A(BC)$$

- Distributivity:

$$\begin{aligned} \forall A, B \in \mathbb{R}^{m \times n}, C, D \in \mathbb{R}^{n \times p} : \quad & (A + B)C = AC + BC \\ & A(C + D) = AC + AD \end{aligned}$$

- Neutral element (identity element):

$$\forall A \in \mathbb{R}^{m \times n} : \quad I_m A = A I_n = A.$$

Note that  $I_m \neq I_n$  for  $m \neq n$ .

## Definition

*For a square matrix  $A \in \mathbb{R}^{n \times n}$  a matrix  $B \in \mathbb{R}^{n \times n}$  with  $AB = I_n = BA$  is called **inverse** and denoted by  $A^{-1}$ .*

Not every matrix  $A$  has an inverse  $A^{-1}$ . If this inverse does exist,  $A$  is called **regular/invertible/non-singular**, otherwise **singular/non-invertible**.

## Existence of the Inverse of a $2 \times 2$ -Matrix

Consider a matrix

$$A := \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \in \mathbb{R}^{2 \times 2}.$$

Then for  $B = \begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix}$  we get

$$AB = \begin{bmatrix} a_{11}a_{22} - a_{12}a_{21} & 0 \\ 0 & a_{11}a_{22} - a_{12}a_{21} \end{bmatrix} = (a_{11}a_{22} - a_{12}a_{21})I_2.$$

Therefore

$$A^{-1} = \frac{1}{a_{11}a_{22} - a_{12}a_{21}} \begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix},$$

if  $a_{11}a_{22} - a_{12}a_{21} \neq 0$ .

## Example

*The matrices*

$$A = \begin{bmatrix} 4 & 5 & 4 \\ 7 & 7 & 6 \\ 2 & 1 & 1 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & -1 & 2 \\ 5 & -4 & 4 \\ -7 & 6 & -7 \end{bmatrix}$$

*are inverse to each other since  $AB = I = BA$ .*

## Definition

*For  $A \in \mathbb{R}^{m \times n}$  the matrix  $B \in \mathbb{R}^{n \times m}$  with  $b_{ij} = a_{ji}$  is called the transpose of  $A$ . We write  $B = A^T$ .*

$A^T$  is achieved by any one of the following equivalent actions:

- reflect  $A$  over its main diagonal (which runs from top-left to bottom-right) to obtain  $A^T$ ,
- write the rows of  $A$  as the columns of  $A^T$ ,
- write the columns of  $A$  as the rows of  $A^T$ .



# Properties of inverses and transposes

- $AA^{-1} = I = A^{-1}A$
- $(AB)^{-1} = B^{-1}A^{-1}$
- $(A^T)^T = A$
- $(A + B)^T = A^T + B^T$
- $(AB)^T = B^T A^T$
- If  $A$  is invertible, then so is  $A^T$  and  $(A^{-1})^T = (A^T)^{-1}$

## Definition

*A square matrix  $A$  is symmetric if  $A = A^T$ .*

## Example

*Prove that for any square matrix  $A$  the matrices  $A + A^T$  and  $A \cdot A^T$  are symmetric.*

### Example

*Prove that for any symmetric matrices  $A, B$  the matrix  $A + B$  is symmetric.*

### Remark

*The product of two symmetric matrices is not symmetric in general, e.g. the matrices  $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$  and  $B = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ , but the matrix  $AB = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$  is not symmetric.*

# Multiplication by a Scalar

If  $A$  is an  $m \times n$  matrix and  $\lambda$  is a scalar, then the scalar multiple  $\lambda A$  is the  $m \times n$  matrix

$$\lambda A = \lambda[a_{ij}] = [\lambda a_{ij}].$$

- Distributivity:

$$(\lambda_1 + \lambda_2)C = \lambda_1 C + \lambda_2 C, \quad C \in \mathbb{R}^{m \times n}$$

$$\lambda(B + C) = \lambda B + \lambda C, \quad B, C \in \mathbb{R}^{m \times n}$$

- Associativity:

$$(\lambda_1 \lambda_2)C = \lambda_1(\lambda_2 C), \quad C \in \mathbb{R}^{m \times n}$$

$$\lambda(BC) = (\lambda B)C = B(\lambda C) = (BC)\lambda, \quad \begin{array}{l} B \in \mathbb{R}^{m \times n} \\ C \in \mathbb{R}^{n \times k} \end{array}$$

- $(\lambda C)^T = \lambda C^T$

## Example

*Check that*

$$(\lambda_1 + \lambda_2)C = \lambda_1 C + \lambda_2 C$$

*for any  $\lambda_1, \lambda_2 \in R$  and  $C := \begin{bmatrix} 1 & 3 \\ 5 & 7 \end{bmatrix}$ .*

# Compact Representations of Systems of Linear Equations

The system of linear equations

$$\begin{cases} 2x + 3y - 4z &= 5 \\ x - y + 3z &= -2 \\ -x + 2y + 5z &= 7 \end{cases}$$

can be written as vector equation

$$\begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} x + \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix} y + \begin{bmatrix} -4 \\ 3 \\ 5 \end{bmatrix} z = \begin{bmatrix} 5 \\ -2 \\ 7 \end{bmatrix},$$

and can be compactly written in matrix notation as follows

$$\begin{bmatrix} 2 & 3 & -4 \\ 1 & -1 & 3 \\ -1 & 2 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 5 \\ -2 \\ 7 \end{bmatrix}$$

Note that  $Ax$  is a linear combination of the columns of  $A$ :

$$\begin{bmatrix} 2 & 3 & -4 \\ 1 & -1 & 3 \\ -1 & 2 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} x + \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix} y + \begin{bmatrix} -4 \\ 3 \\ 5 \end{bmatrix} z$$

# Systems of Linear Equations

Let us introduce the general form of a system of linear equations,

$$\begin{aligned}a_{11}x_1 + \dots + a_{1n}x_n &= b_1 \\ \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n &= b_m\end{aligned}$$

where  $a_{ij} \in \mathbb{R}$  and  $b_i \in \mathbb{R}$  are known constants and  $x_j$  are unknowns,  $i = 1, \dots, m$ ,  $j = 1, \dots, n$ .

It can be written in matrix form  $A\mathbf{x} = \mathbf{b}$ , where

$$A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \\ a_{m1} & \dots & a_{mn} \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix}$$

# Particular and General Solution

Consider the following system of linear equations (SLE):

$$\begin{bmatrix} 1 & 0 & 7 & 2 \\ 0 & 1 & 3 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 5 \\ 8 \end{bmatrix}$$

or, equivalently  $\sum_{i=1}^4 x_i \mathbf{c}_i = \mathbf{b}$ , where  $\mathbf{c}_i$  is the  $i$ th column of the matrix and  $\mathbf{b}$  is the right-hand-side.

$[5, 8, 0, 0]^T$  is a solution, since  $\mathbf{b} = 5\mathbf{c}_1 + 8\mathbf{c}_2 + 0\mathbf{c}_3 + 0\mathbf{c}_4$ .

This solution is called a **particular solution** or **special solution**.



To capture all the other solutions, we express the third column using the first two columns

$$\begin{bmatrix} 7 \\ 3 \end{bmatrix} = 7 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \text{ equivalently } \mathbf{0} = 7\mathbf{c}_1 + 3\mathbf{c}_2 - 1\mathbf{c}_3 + 0\mathbf{c}_4$$

So  $(x_1, x_2, x_3, x_4) = (7, 3, -1, 0)$  produces the  $\mathbf{0}$  vector as well as any scaling of it by  $\lambda_1$ , i.e.  $\lambda_1(7, 3, -1, 0)$ .

$$\begin{bmatrix} 1 & 0 & 7 & 2 \\ 0 & 1 & 3 & -4 \end{bmatrix} \left( \lambda_1 \begin{bmatrix} 7 \\ 3 \\ -1 \\ 0 \end{bmatrix} \right) = \lambda_1(7\mathbf{c}_1 + 3\mathbf{c}_2 - 1\mathbf{c}_3 + 0\mathbf{c}_4) = \mathbf{0}$$

Similarly,

$$\begin{bmatrix} 1 & 0 & 7 & 2 \\ 0 & 1 & 3 & -4 \end{bmatrix} \left( \lambda_2 \begin{bmatrix} 2 \\ -4 \\ 0 \\ -1 \end{bmatrix} \right) = \lambda_2(2\mathbf{c}_1 - 4\mathbf{c}_2 + 0\mathbf{c}_3 - 1\mathbf{c}_4) = \mathbf{0}$$

All solutions of the SLE, which is called the **general solution**, is the set

$$\left\{ \mathbf{x} \in \mathbb{R}^4; \mathbf{x} = \begin{bmatrix} 5 \\ 8 \\ 0 \\ 0 \end{bmatrix} + \lambda_1 \begin{bmatrix} 7 \\ 3 \\ -1 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 2 \\ -4 \\ 0 \\ -1 \end{bmatrix}, \lambda_1, \lambda_2 \in \mathbb{R} \right\}.$$

### The algorithm.

1. Find a particular solution to  $A\mathbf{x} = \mathbf{b}$ .
2. Find all solutions to  $A\mathbf{x} = \mathbf{0}$ .
3. Combine the solutions from 1. and 2. to the general solution.

# Elementary transformations

## Definition

Given a SLE

[illegible]

$$A := \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}$$

*is called the*  
**coefficient matrix**

and  $\left[ \begin{array}{c|c} A & \mathbf{b} \end{array} \right]$  is called the **augmented matrix**,

where  $\mathbf{b} = [b_1, b_2, \dots, b_n]^T$

## Definition

A matrix is in **row echelon form (REF)** if it satisfies the following properties:

1. Any rows consisting entirely of zeros are at the bottom.
2. In each nonzero row, the first nonzero entry (called the **leading entry** or **pivot**) is in a column to the left of any leading entries below it.

## Example

The following matrices are in row echelon form:

$$\begin{bmatrix} 1 & 3 & 5 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix} \quad \begin{bmatrix} 1 & -2 & 7 \\ 0 & 4 & 1 \\ 0 & 0 & 3 \end{bmatrix} \quad \begin{bmatrix} 3 & 1 & -2 & 7 \\ 0 & 0 & 5 & 1 \\ 0 & 0 & 0 & 4 \end{bmatrix}.$$

Assuming that each of these matrices is an augmented matrix, write out the corresponding SLE and solve them.

# Elementary Row Operations

## Definition

The following **elementary row operations** can be performed on a matrix:

1. *Interchange two rows.*
2. *Multiply a row by a nonzero constant.*
3. *Add a multiple of a row to another row.*

## Shorthand notation

1.  $R_i \leftrightarrow R_j$  means interchange rows  $i$  and  $j$ .
2.  $kR_i$  means multiply row  $i$  by  $k$ .
3.  $R_i + kR_j$  means add  $k$  times row  $j$  to row  $i$  (and replace row  $i$  with the result).

## Example

*Reduce the following matrix to echelon form:*

$$\begin{bmatrix} 1 & -1 & 2 & 4 \\ 3 & -1 & 8 & 15 \\ -2 & 0 & -4 & -2 \end{bmatrix}.$$

## Definition

The variables corresponding to the pivots in the row-echelon form are called **basic variables** or **leading variables**, the other variables are **free variables**.

## Example

Let the REF of the augmented matrix be

$$\begin{bmatrix} 1 & -1 & 2 & 4 \\ 0 & 0 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

The leading entries in row echelon form are  $x_1, x_3$ , and the free variable is  $x_2$ .