

Optimization

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December 4, 2020

Newton's Method

Let $f \in \mathbb{C}^2(\mathbb{R}^n)$ and our aim is to find the minimizer of f .

Let $x^{(0)} \in \mathbb{R}^n$ be the starting point. Then we construct a quadratic function that matches its value, first and second derivatives at $x^{(0)}$ with that of the function f . This quadratic function has the form

$$q(x) = f(x^{(0)}) + \nabla f(x^{(0)})^T (x - x^{(0)}) + \frac{1}{2} (x - x^{(0)})^T \nabla^2 f(x^{(0)}) (x - x^{(0)}).$$

Then, instead of minimizing f , we minimize its approximation q .

The FONC for q yields

$$\nabla q(x) = \nabla f(x^{(0)}) + \nabla^2 f(x^{(0)}) (x - x^{(0)}) = 0.$$

The solution of this system

$$x^{(1)} = x^{(0)} - \left[\nabla^2 f(x^{(0)}) \right]^{-1} \nabla f(x^{(0)})$$

will be our next approximation. Reapplying this procedure we get the sequence defined by Newton's Method

$$x^{(k+1)} = x^{(k)} - \left[\nabla^2 f(x^{(k)}) \right]^{-1} \nabla f(x^{(k)}), \quad k = 0, 1, \dots$$

The k -th iteration can be written in two steps:

1. Solve $\nabla^2 f(x^{(k)}) d^{(k)} = -\nabla f(x^{(k)})$.
2. Set $x^{(k+1)} = x^{(k)} + d^{(k)}$.

- The convergence is local.
- Suppose that $f \in C^3$ and $x^* \in \mathbb{R}^n$ is a point such that $\nabla f(x^*) = 0$ and $\nabla^2 f(x^*)$ is invertible. Then, for all $x^{(0)}$ sufficiently close to x^* , Newton's method is well-defined for all k and converges to x^* with an order of convergence at least 2.
- The direction of search is

$$d^{(k)} = - \left[\nabla^2 f \left(x^{(k)} \right) \right]^{-1} \nabla f \left(x^{(k)} \right).$$

If $\nabla^2 f(x^{(k)})$ is positive definite, then $d^{(k)}$ is a descent direction.

Modification of Newton's method

The step size is usually $\alpha_k = 1$ but sometimes one takes other step size and gets

$$x^{(k+1)} = x^{(k)} - \alpha_k \left[\nabla^2 f \left(x^{(k)} \right) \right]^{-1} \nabla f \left(x^{(k)} \right), \quad k = 0, 1, \dots$$

For example we can take

$$\alpha_k = \arg \min_{\alpha \geq 0} f \left(x^{(k)} - \alpha \left[\nabla^2 f \left(x^{(k)} \right) \right]^{-1} \nabla f \left(x^{(k)} \right) \right)$$

to ensure that $f \left(x^{(k+1)} \right) < f \left(x^{(k)} \right)$.

Stopping conditions

- $\|\nabla f(x^{(k)})\| < \varepsilon$
- $\|x^{(k+1)} - x^{(k)}\| < \varepsilon$ or $\frac{\|x^{(k+1)} - x^{(k)}\|}{\|x^{(k)}\|} < \varepsilon$ if $\|x^{(k)}\| \neq 0$
- $|f(x^{(k+1)}) - f(x^{(k)})| < \varepsilon$ or $\frac{|f(x^{(k+1)}) - f(x^{(k)})|}{|f(x^{(k)})|} < \varepsilon$ if $f(x^{(k)}) \neq 0$.

Example

Assume we want to use the Newton's Method to minimize

$$f(x_1, x_2) = 2x_1^2 + x_2^2 - 2x_1x_2.$$

We start with $x^{(0)} = (1, 1)^T$. Calculate $x^{(2)}$ by using the Newton's Method. Explain why after one iteration we have that $\nabla f(x^{(1)}) = 0$.

Nonlinear Constrained Optimization

$$\begin{aligned} & \text{minimize} && f(x) \\ & \text{subject to} && x \in \Omega, \end{aligned} \tag{1}$$

where $f : \mathbb{R}^n \rightarrow \mathbb{R}$ and $\Omega \subset \mathbb{R}^n$. Here, we are going to consider minimization problems, for which the constraint set Ω is given by

$$\Omega = \{x \in \mathbb{R}^n : h_i(x) = 0, \text{ for } i = 1, \dots, m, g_j(x) \leq 0, \text{ for } j = 1, \dots, p\},$$

where $h_i : \mathbb{R}^n \rightarrow \mathbb{R}$ for $i = 1, \dots, m$, $m \leq n$ and $g_j : \mathbb{R}^n \rightarrow \mathbb{R}$ for $j = 1, \dots, p$ are given functions.

$$\begin{aligned}
& \text{minimize} && f(x) \\
& \text{subject to} && h_i(x) = 0, \quad i = 1, \dots, m, \\
& && g_j(x) \leq 0, \quad j = 1, \dots, p
\end{aligned}$$

or

$$\begin{aligned}
& \text{minimize} && f(x) \\
& \text{subject to} && h(x) = 0, \\
& && g(x) \leq 0,
\end{aligned}$$

where $h : \mathbb{R}^n \rightarrow \mathbb{R}^m$, $m \leq n$ and $g : \mathbb{R}^n \rightarrow \mathbb{R}^p$.

Example

Consider the following optimization problem:

$$\begin{array}{ll}\text{minimize} & (x_1 - 1)^2 + x_2 - 2 \\ \text{subject to} & x_2 - x_1 = 1, \\ & x_1 + x_2 \leq 2.\end{array}$$

Problems with equality constraints

$$\begin{array}{ll}\text{minimize} & f(x) \\ \text{subject to} & h_i(x) = 0, \quad i = 1, \dots, m.\end{array}$$

We will assume that f, h_i for $i = 1, \dots, m$ are continuously differentiable functions on \mathbb{R}^n .

Definition

A point x^* satisfying the constraints $h_i(x^*) = 0, i = 1, \dots, m$ is said to be a regular point of the constraints, if the gradient vectors $\nabla h_1(x^*), \dots, \nabla h_m(x^*)$ are linearly independent. When $m = 1$, this means $\nabla h_1(x^*) \neq 0$

Example

Consider following constraints $h_1(x) = x_1$ and $h_2(x) = x_2 - x_3^2$ on \mathbb{R}^3 . Show that all feasible points are regular points.

Theorem (Lagrange's Theorem, First Order Necessary Condition)

Let x^ be a local minimizer (maximizer) of $f : \mathbb{R}^n \rightarrow \mathbb{R}$ subject to $h_i(x) = 0$, $h_i : \mathbb{R}^n \rightarrow \mathbb{R}$, $i = 1, \dots, m$, $m \leq n$. Assume f, h_i for $i = 1, \dots, m$ are continuously differentiable functions and x^* is a regular point. Then, there exists $\lambda^* \in \mathbb{R}^m$ such that*

$$\nabla f(x^*) + \sum_{i=1}^m \lambda_i^* \nabla h_i(x^*) = 0.$$

We refer to the vector λ^* as the Lagrange multiplier vector, and its components as Lagrange multipliers.

It's convenient to introduce the Lagrangian function $\mathcal{L} : \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}$, given by

$$\mathcal{L}(x, \lambda) = f(x) + \sum_{i=1}^m \lambda_i h_i(x).$$

The necessary condition for x^* to be a local minimizer will be

$$\nabla \mathcal{L}(x^*, \lambda^*) = 0$$

for some $\lambda^* \in \mathbb{R}^m$.

Example

Consider the following optimization problem:

$$\begin{aligned} & \text{minimize} && f(x) \\ & \text{subject to} && h(x) = 0, \\ & \text{where } f(x) = x \text{ and } h(x) = && \begin{cases} x^2 & \text{if } x < 0, \\ 0 & \text{if } 0 \leq x \leq 1, \\ (x - 1)^2 & \text{if } x > 1. \end{cases} \end{aligned}$$

Example

Assume we want to find the extremum points of $f(x_1, x_2) = x_1^2 + x_2^2$ subject to $x_1^2 + 2x_2^2 = 2$. Use Lagrange's theorem to find all possible local extremum points.