ARMAN POURGHORBAN

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\$\mathcal{B}\$ EPIC 2152, 9201 University City Boulevard

\$\mathcal{D}\$ Charlotte, NC

\$\mathcal{B}\$ www.researchgate.net/profile/Arman-Pourghorban

\$\mathcal{B}\$ = 1-140 Approved

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EXPERIENCE

Controls Engineer

Tecla

Sept 2025 - Current

Brooklyn Park, MN

 Path planning and Motion Controls; Model predictive control and dynamicsbased trajectory optimization.

Controls Engineer Intern

Tesla

☐ Jan 2025 - Aug 2025

Brooklyn Park, MN

- Developing and implementing control algorithms for 6-DOF robotic systems.
- Testing and verifying electrical wiring (safety circuits, IO, communications, etc.)
- Collaborating on PLC programming and HMI/SCADA system development.

Research Assistant in Controls & Robotics

University of North Carolina at Charlotte

- ☐ Sept 2021 Dec 2024
- Charlotte, NC
- Target Defense with an Obstacle Distributed Environment: A Reinforcement Learning approach (PPO)
- Consensus Multi-agent Pursuit-Evasion Games with Communication Constraint
- Pursuit-Evasion Games with Limited Agent Observation using Discretetime Extended Kalman Filter
- Information-Theoretic Abstractions for Environment Planning in Pursuit Evasion Games
- Multi-Robot Path Planning with Convex Optimization Approaches
- Competitive Perimeter Defense with Sensing Capabilities
- Human Follower Robot.
- Stability and Bounds of a State Feedback Control for Trajectory Tracking
- Obstacle avoidance with Feedback-based approach using Opti-Track system
- Reinforcement Learning-based Switching Controller For UAV Wind and Airflow Precision

Teaching Assistant

University of North Carolina at Charlotte

- ☐ Sept 2021 Dec 2024
- Charlotte, NC
- Convex Optimization (ECGR 4115-5115)
- Network Theory II (ECGR 2112)

Teaching Lab Assistant

University of North Carolina at Charlotte

☐ Sept 2021 - Dec 2024

Charlotte, NC

EDUCATION

in Control Systems & Robotics (Ph.D. Candidate)

University of North Carolina at Charlotte

Dec 2025

MSEE in Electrical Engineering, Minor in Control Systems & Robotics

Ph.D. in Electrical Engineering, Minor

University of North Carolina at Charlotte

BSc in Electrical Engineering

Isfahan University of Technology

□ Dec 2020

FANUC KUKA

SKILLS

• Systems & Electronics Lab (ECGR 3155)

Internship Instrumentation Researcher and Developer Isfahan innovation Tech- Esfahan's Mobarakeh Steel Company

May 2020 - Aug 2020

Isfahan, Iran

- Designed and manufactured a sensor to detect the proportion of the slag in melted steel
- Developed the HMI for the sensor

Researcher and Programmer Isfahan Science and Technology Town

May 2018 - May 2020

Isfahan, Iran

- Designed and manufactured Signal conditioner known as Pre-Amplifier
- Designed a controller for the Linear Machine

PLC Programmer

Technical and Vocational Training Organization

Aug 2016 - May 2018

Isfahan, Iran

- Automation for a brick company in Dolat Abad industrial region
- Level control of 16 reservoirs in Isfahan Science and Technology Town

HONORS AND AWARDS

- Rank 157 Among 162k, Iran National Entrance Exam for Universities
- Scholarship, Tuition Fee waiver Bachelors
- Rank 1, Control Group Students in Bachelors
- Scholarship, Tuition Fee waiver + Stipend Coverage Doctorate Program
- Funded Research, 2-Year Research Assistant supported by the ARL grant (Army Research Lab)
- Best Student Research Award DTS 2023
- Conference Chair ACC 2025 session "Control Applications II"
- Recognized Intern, Tesla Spring 2025

PAPER REVIEW

- Springer Nature Journal: Autonomous Agents and Multi-Agent Systems
- 2023 62nd IEEE Conference on Decision and Control (CDC)
- 2024 American Control Conference (ACC)
- 2024 63rd IEEE Conference on Decision and Control (CDC)
- 2025 64th IEEE Conference on Decision and Control (CDC)

SELECTED COURSES

- Reinforcement Learning and Optimal Control (4/4)
- Real Analysis I Linear Algebra Applied Probability I (4/4)
- Machine Learning (4/4)
- Convex Optimization (4/4)
- Information Theory (4/4)
- Artificial Neural Network (4/4)
- Intelligent (Fuzzy) Control (4/4)
- Dynamic System Estimation (4/4)
- Robotics (4/4)
- Modern & Non-linear Control (4/4)
- Instrumentation (4/4)
- Mechatronics (4/4)

PUBLICATIONS

Journal Articles

- A. Pourghorban and D. Maity, "Target defense against multiple arriving intruders," IEEE Transactions on Robotics, Submitted 2024.
- A. Pourghorban and D. Maity, "Target defense in conical environments with sensing limitations," IEEE Robotics and Automation Letters, Submitted 2024.
- A. Pourghorban and D. Maity, "Consensusbased target defense with simultaneous attacker capture," IEEE Control Systems Letters, 2024.

Conference Proceedings

- A. Pourghorban and D. Maity, "Two attacker one defender target defense with deception," in 2025 American Control Conference (ACC), IEEE, Submitted 2024.
- A. Pourghorban, P. Smith, and D. Maity, "Target defense against sequentially arriving intruders:algorithm for agents with dubins dynamics," in 2025 IEEE International Conference on Robotics and Automation (ICRA), IEEE, Submitted 2024.
- A. Pourghorban and D. Maity, "Target defense against a sequentially arriving cooperative intruder team," in Open Architecture/Open Business Model Net-Centric Systems and Defense Transformation 2023, SPIE, vol. 12544, 2023, pp. 65-77.
- A. Pourghorban and D. Maity, "Target defense against periodically arriving intruders," in 2023 American Control Conference (ACC), 2023, pp. 1673–1679. DOI: 10.23919/ACC55779.2023.10156423.
- A. Pourghorban, M. Dorothy, D. Shishika, A. Von Moll, and D. Maity, "Target defense against sequentially arriving intruders," in 2022 IEEE 61st Conference on Decision and Control (CDC), IEEE, 2022, pp. 6594–6601.

PRESENTATION

2nd annual Defense Technology Summit (DTS) hosted by the Office of US Senator Thom Tillis, Office of US Senator Ted Budd

Resilient Autonomy for Tactical Behaviors

Fayetteville Technical Community College

U July 2023

Fayetteville, NC